

Homogeneity fusion for Sparse Grouped Network VAR models

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Motivation

- Multivariate time series show up in many modern applications:
 - Rumor spreading in a social network
 - Neural activity across brain regions
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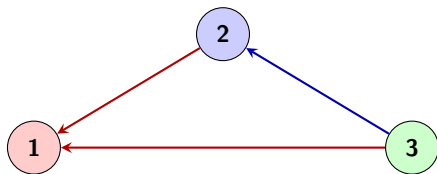
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- Sample size: dT
- If $d < T$, use standard OLS estimator.
- If $d > T$, OLS is impossible. Instead, assume structure:
 - Sparsity (Lasso) [Basu and Michailidis, 2015]
 - Low Rank (factor models) [Stock and Watson, 2011]
 - Network models with few parameters [Zhu et al., 2017]

Network Time Series

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$$Y_{1,t} = \nu_1 Y_{1,t-1} + \varepsilon_{1,t}$$

$$Y_{2,t} = \beta_{21} Y_{1,t-1} + \nu_2 Y_{2,t-1} + \varepsilon_{2,t}$$

$$Y_{3,t} = \beta_{31} Y_{1,t-1} + \beta_{32} Y_{2,t-1} + \nu_3 Y_{3,t-1} + \varepsilon_{3,t}$$

Related Work

- **Network VAR models** introduced by [Zhu et al., 2017], modeling temporal dependence through networks.
- Types of **group/community** structures incorporated in [Zhu and Pan, 2020, Chen et al., 2023, Zhu et al., 2023].
- **Unknown networks:** community detection in [Gudmundsson and Brownlee, 2021] (Blockbuster algorithm) and network estimation in [Martin et al., 2024] (NIRVAR model).

The GNAR model

- **Unknown** directed network with adjacency matrix $A = (a_{ij})_{1 \leq i, j \leq d}$.
- Latent partition $\mathbb{G} = \{G_1, \dots, G_K\}$ of $\{1, \dots, d\}$ into K groups. We denote the group membership of node i by g_i .

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- GNAR model [Zhu et al., 2023]:

$$Y_{i,t} = \sum_{j=1}^d \phi_{g_i g_j} \frac{a_{ij}}{n_i} Y_{j,t-1} + \nu_{g_i} Y_{i,t-1} + \varepsilon_{i,t}, \quad i \in [d], \quad t \in [T],$$

where $n_i = \sum_{j=1}^d a_{ij}$ the out-degree of i , and $\varepsilon_{i,t} \stackrel{\text{i.i.d.}}{\sim} N(0, \sigma^2)$.

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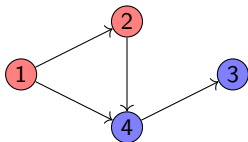
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- *Remark:* When $K = 1$, the model reduces to the original model of [Zhu et al., 2017] and there are two parameters: network effect ϕ and autoregressive effect ν .

Example



Updating equations:

$$\begin{cases} Y_{1,t} = \nu_1 Y_{1,t-1} + \frac{\phi_{11}}{2} Y_{2,t-1} + \frac{\phi_{12}}{2} Y_{4,t-1} + \varepsilon_{1,t} \\ Y_{2,t} = \nu_1 Y_{2,t-1} + \phi_{12} Y_{4,t-1} + \varepsilon_{2,t} \\ Y_{3,t} = \nu_2 Y_{3,t-1} + \varepsilon_{3,t} \\ Y_{4,t} = \phi_{22} Y_{3,t-1} + \nu_2 Y_{4,t-1} + \varepsilon_{4,t} \end{cases}$$

Fusion estimator

We want to solve the following optimization problem:

Fusion estimator

$$\begin{aligned} & \underset{\substack{A \in \{0,1\}^{d \times d}, \mathbb{G} \in [K]^d \\ \Phi \in \mathbb{R}^{K \times K}, \nu \in \mathbb{R}^K}}{\operatorname{argmin}} \sum_{t=2}^T \sum_{i=1}^d \left(Y_{i,t} - \sum_{j=1}^d \phi_{g_i g_j} \frac{a_{ij}}{n_i} Y_{j,t-1} - \nu_{g_i} Y_{i,t-1} \right)^2 \\ & \text{s.t.} \quad \sum_{i=1}^d \sum_{j=1}^d a_{ij} \leq s \end{aligned}$$

Theoretical goals

1. The misspecification probability for grouping/network goes to 0, i.e.,

$$\mathbb{P}(\mathbb{G}(\hat{B}) \neq \mathbb{G}(B^*)) \rightarrow 0, \quad \text{as } d, T \rightarrow \infty,$$

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2. Estimation and prediction errors go to 0, i.e.,

$$\|\hat{\beta}^{\text{ol}} - \beta^*\|_2 \rightarrow 0 \quad \text{and} \quad \|Z(\hat{\beta}^{\text{ol}} - \beta^*)\|_2 \rightarrow 0,$$

with specified convergence rates.

Roadmap

1. Bound the misspecification probability:

$$\begin{aligned} & \mathbb{P}\left(\mathbb{G}(\hat{B}) \neq \mathbb{G}(B^*)\right) \\ & \leq \sum_{\omega \in \{\mathbb{G}(B) \mid B \in \Theta(K^*, s^*), \mathbb{G}(B) \neq \mathbb{G}(B^*)\}} \mathbb{P}\left(\min_{\substack{\tilde{B} \in \Theta(K^*, s^*) \\ \mathbb{G}(\tilde{B}) = \omega}} \|\mathbf{Y} - Z\tilde{\beta}\|_2^2 < \|\mathbf{Y} - Z\hat{\beta}^{\text{ol}}\|_2^2\right) \end{aligned}$$

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2. Handle each term

$$\begin{aligned} & \mathbb{P} \left(\min_{\substack{\tilde{B} \in \Theta(K^*, s^*) \\ \mathbb{G}(\tilde{B}) = \omega}} \|\mathbf{Y} - Z\tilde{\beta}\|_2^2 < \|\mathbf{Y} - Z\hat{\beta}^{\text{ol}}\|_2^2 \right) = \mathbb{P} \left(\|\mathbf{Y} - Z\hat{\beta}\|_2^2 < \|\mathbf{Y} - Z\hat{\beta}^{\text{ol}}\|_2^2 \right) \\ & = \mathbb{P} \left(2\boldsymbol{\varepsilon}'(I - P_{\mathbb{G}(B)})Z\beta^* + \|(I - P_{\mathbb{G}(B)})Z\beta^*\|_2^2 - \boldsymbol{\varepsilon}'(P_{\mathbb{G}(B)} - P_{\mathbb{G}(B^*)})\boldsymbol{\varepsilon} < 0 \right), \end{aligned}$$

where $P_{\mathbb{G}(B)}$ is a $dT \times dT$ projection matrix including all lagged values.

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3. *Why joint estimation?*
 - A natural alternative idea: estimate the network structure first, and conditionally on that estimate groups and parameters.
 - Conditional estimation does not guarantee solution to the optimization problem of interest.
 - Our fusion estimator handles all components jointly, allowing for better theoretical guarantees.

Mixed Integer Programming

- *Idea*: formulate the original optimization problem as a MIP and use Gurobi to solve it, as in [Bertsimas et al., 2016].

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- General MIP formulation:

$$\min (\mathbf{x}'Q\mathbf{x} + \mathbf{x}'\mathbf{y}) \quad \text{s.t.} \quad \mathbf{x} \in \mathcal{X},$$

where \mathcal{X} is the feasible set and the vector \mathbf{x} includes:

- *Binary variables*: $x_i \in \{0, 1\}$ for $i \in \mathcal{I}$
- *Continuous variables*: $x_i \geq 0$ for $i \notin \mathcal{I}$

MIP formulation of GNAR optimization problem

$$\begin{aligned} \text{argmin}_{\substack{B \in \mathbb{R}^{d \times d}, A \in \{0,1\}^{d \times d} \\ \Phi \in \mathbb{R}^{K \times K}, \nu \in \mathbb{R}^K \\ \Omega \in \{0,1\}^{d \times d \times K \times K}}} \sum_{t=2}^T \sum_{i=1}^d \left(Y_{i,t} - \sum_{j=1}^d b_{ij} Y_{j,t-1} \right)^2 \end{aligned}$$

$$\text{s.t. } a_{ij} \in \{0,1\}, a_{ii} = 0, n_i = \sum_{j=1}^d a_{ij}, \quad i, j \in [d]$$

$$\omega_{ijkl} \in \{0,1\}, \quad i, j \in [d], k, l \in [K]$$

$$\sum_{k=1}^K \sum_{j=1}^d \sum_{l=1}^K \omega_{ijkl} = 1, \quad i \in [d]$$

$$\sum_{j=1}^d \sum_{l=1}^K \omega_{ijkl} (b_{ii} - \nu_k) = 0, \quad i \in [d], k \in [K]$$

$$\omega_{ijkl} (n_i b_{ij} - \phi_{kl} a_{ij}) = 0, \quad i, j \in [d], i \neq j, k, l \in [K]$$

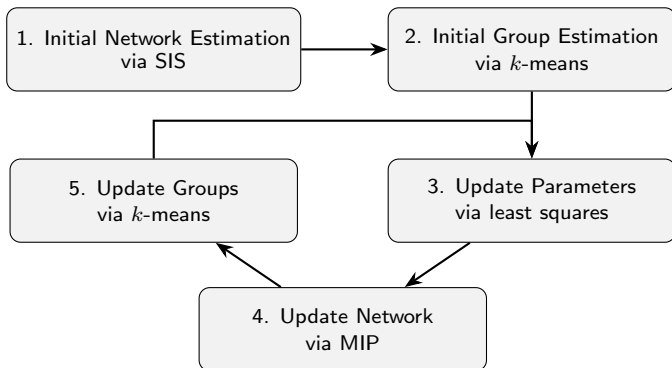
$$\sum_{i=1}^d \sum_{j=1}^d a_{ij} \leq s.$$

Implementation

- The previous MIP is often intractable in practice (e.g., for $d = 100$ and $K = 3$, it has over 100k variables, mostly binary).

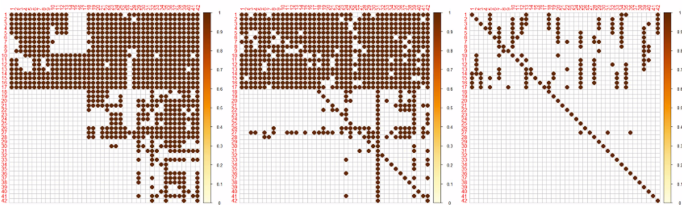
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- Instead, follow the iterative scheme:



Real Data: FRED-MD Example

- *Data*: 134 monthly U.S. macroeconomic variables.
- We focus on a subset of 42 variables in two groups:
 - Group 6: Interest & Exchange Rates (22 nodes)
 - Group 7: Prices (20 nodes)
- We treat variables as nodes in a network and apply our method to estimate:
 - The edge structure (adjacency matrix)
 - Group memberships



Estimated adjacency matrices. Left: Fusion, Middle: Best Subset, Right: Adaptive Lasso

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- We formulated our problem as a mixed integer program and developed a practical **iterative algorithm** to solve this problem at scale.
- Applied to real macroeconomic data, our method reveals interesting networks and groupings, complementing existing empirical approaches.

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