

Randomized and Other Algorithms for Maximum Weight Clique

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Algoritmos Avançados

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Abstract—The Maximum Weight Clique (MWC) problem seeks the subset of mutually adjacent vertices in a weighted graph with maximum total weight. As an NP-hard problem, MWC has motivated diverse algorithmic approaches trading optimality for efficiency. This paper presents a comprehensive study of 14 algorithms for MWC, with emphasis on randomized methods. Five randomized algorithms (random construction, random-greedy hybrid, iterative search, Monte Carlo, and Las Vegas), three reduction-based approaches, two exact branch-and-bound methods (WLMC, TSM-MWC), and three additional heuristics are implemented and evaluated. Experimental evaluation on 364 generated graphs with varying sizes (10–100 vertices) and densities (12.5%–75%) reveals surprising findings: simple random construction achieves optimal solutions on all test cases, while sophisticated algorithms like SCCWalk underperform simpler alternatives. Complexity analysis is provided, failure modes are identified, and practical recommendations are offered. FastWClq emerges as the best overall choice, balancing near-optimal solutions with excellent speed.

Index Terms—Maximum Weight Clique, Randomized Algorithms, Branch-and-Bound, Monte Carlo, Las Vegas, Graph Algorithms, Combinatorial Optimization

I. INTRODUCTION

The Maximum Weight Clique (MWC) problem is a fundamental combinatorial optimization problem with applications spanning social network analysis, bioinformatics, computer vision, and resource scheduling [1]. Given an undirected graph with weighted vertices, MWC seeks the subset of mutually adjacent vertices (clique) with maximum total weight.

As an NP-hard problem [2], MWC admits no polynomial-time exact algorithm unless P = NP. This intractability has motivated extensive research into both exact algorithms with exponential worst-case complexity and heuristic/approximation methods that trade optimality for efficiency [3].

This work presents a comprehensive study of algorithms for MWC, with particular emphasis on **randomized approaches**. Randomized algorithms [4] use random choices during execution, offering probabilistic guarantees or empirically good performance. Two paradigms are distinguished:

- **Monte Carlo algorithms:** Run in polynomial time but may return incorrect results with bounded probability.
- **Las Vegas algorithms:** Always return correct results but with variable (potentially unbounded) runtime.

The contributions of this work include:

- 1) Implementation and analysis of 14 algorithms spanning four categories:
 - Randomized algorithms (random construction, hybrid approaches, iterative search, Monte Carlo, Las Vegas)
 - Reduction-based methods (MWCRedu, MaxCliqueWeight variants)
 - Exact branch-and-bound (WLMC, TSM-MWC)
 - Additional heuristics (FastWClq, SCCWalk, MWCPeel)
- 2) Comprehensive experimental evaluation on generated graphs of varying sizes and densities
- 3) Analysis of solution quality, execution time, and scalability trade-offs
- 4) Practical recommendations for algorithm selection based on problem characteristics

The remainder of this paper is organized as follows: Section II formally defines the MWC problem. Section III presents the implemented algorithms with pseudocode and complexity analysis. Section IV describes the experimental methodology and results. Section V analyzes trade-offs and failure modes. Section VI summarizes findings and suggests future work.

II. PROBLEM (RE)DEFINITION

The **Maximum Weight Clique (MWC)** problem is a fundamental combinatorial optimization problem in graph theory with significant applications in social network analysis, bioinformatics, and resource allocation [1]. This section provides a formal definition of the problem and discusses its computational complexity.

A. Formal Definition

Let $G = (V, E)$ be an undirected graph where V is the set of vertices and $E \subseteq V \times V$ is the set of edges. Each vertex $v \in V$ is assigned a positive weight $w(v) > 0$. A *clique* $C \subseteq V$ is a subset of vertices such that every pair of distinct vertices in C is connected by an edge, i.e., $\forall u, v \in C, u \neq v \Rightarrow (u, v) \in E$. The *weight* of a clique is defined as $W(C) = \sum_{v \in C} w(v)$.

The MWC problem seeks to find a clique C^* with maximum weight:

$$C^* = \arg \max_{C \subseteq V, C \text{ is a clique}} W(C) \quad (1)$$

When all vertex weights are equal to 1, the MWC problem reduces to the classical *Maximum Clique* problem, which seeks the clique with the largest cardinality.

B. Computational Complexity

The Maximum Clique problem is one of Karp's 21 NP-complete problems [5], and the weighted variant inherits this intractability. More precisely, the decision version of MWC—determining whether a graph contains a clique of weight at least k —is NP-complete [2]. Furthermore, unless $P = NP$, the problem cannot be approximated within a factor of $n^{1-\epsilon}$ for any $\epsilon > 0$, making it one of the hardest problems to approximate [6].

This computational hardness motivates the development of both exact algorithms with exponential worst-case complexity (such as branch-and-bound methods) and heuristic/randomized algorithms that sacrifice optimality guarantees for practical efficiency. The present work investigates algorithms from both categories, with particular emphasis on randomized approaches that offer probabilistic guarantees or empirically good performance.

III. ALGORITHMS

This section presents the algorithms implemented for solving the Maximum Weight Clique problem. We organize them into four categories: randomized algorithms (our primary focus), reduction-based approaches, exact branch-and-bound methods, and additional heuristics.

A. Randomized Algorithms

Randomized algorithms use random choices during execution, offering a trade-off between solution quality and computational efficiency [4]. Five randomized approaches for MWC are implemented.

1) Random Construction: The Random Construction heuristic builds cliques by randomly selecting vertices that maintain the clique property. Starting from a random vertex, it iteratively adds randomly chosen compatible vertices until no more can be added.

Algorithm 1 Random Construction

```

Require: Graph  $G = (V, E)$ , weights  $w$ , max_iterations  $T$ 
Ensure: Best clique  $C^*$  found
1:  $C^* \leftarrow \emptyset$ ,  $W^* \leftarrow 0$ 
2: for  $t = 1$  to  $T$  do
3:    $v \leftarrow \text{RANDOMCHOICE}(V)$ 
4:    $C \leftarrow \{v\}$ 
5:   candidates  $\leftarrow V \setminus \{v\}$ 
6:   while candidates  $\neq \emptyset$  do
7:     compatible  $\leftarrow \{u \in \text{candidates} : \forall c \in C, (u, c) \in E\}$ 
8:     if compatible  $= \emptyset$  then break
9:     end if
10:     $u \leftarrow \text{RANDOMCHOICE}(compatible)$ 
11:     $C \leftarrow C \cup \{u\}$ , candidates  $\leftarrow \text{candidates} \setminus \{u\}$ 
12:  end while
13:  if  $W(C) > W^*$  then  $C^* \leftarrow C$ ,  $W^* \leftarrow W(C)$ 
14:  end if
15: end for
16: return  $C^*$ 
```

Complexity Analysis:

- *Time:* $O(T \cdot n^2)$ where T is the number of iterations and $n = |V|$. Each iteration constructs a clique in $O(n^2)$ time (checking compatibility).
- *Space:* $O(n)$ for storing the current clique and candidates.

2) Random Greedy Hybrid: This hybrid approach combines random exploration with greedy selection. Instead of purely random choices, it probabilistically selects from the top- k highest-weight compatible candidates.

Algorithm 2 Random Greedy Hybrid

```

Require: Graph  $G$ , weights  $w$ , num_starts  $S$ , top_k  $k$ , randomness  $\rho$ 
Ensure: Best clique  $C^*$  found
1:  $C^* \leftarrow \emptyset$ ,  $W^* \leftarrow 0$ 
2: for  $s = 1$  to  $S$  do
3:    $v \leftarrow \text{RANDOMCHOICE}(V)$ ,  $C \leftarrow \{v\}$ , candidates  $\leftarrow V \setminus \{v\}$ 
4:   while candidates  $\neq \emptyset$  do
5:     compatible  $\leftarrow \{(u, w(u)) : u \in \text{candidates}, \forall c \in C, (u, c) \in E\}$ 
6:     if compatible  $= \emptyset$  then break
7:     end if
8:     if  $\text{RANDOM}(0,1) < \rho$  then  $u \leftarrow \text{RANDOM-CHOICE}(compatible)$ 
9:     else
10:      top_k  $\leftarrow$  top  $k$  elements of compatible by weight
11:       $u \leftarrow \text{WEIGHTEDRANDOMCHOICE}(top_k)$ 
12:    end if
13:     $C \leftarrow C \cup \{u\}$ , candidates  $\leftarrow \text{candidates} \setminus \{u\}$ 
14:  end while
15:  if  $W(C) > W^*$  then  $C^* \leftarrow C$ ,  $W^* \leftarrow W(C)$ 
16: end if
17: end for
18: return  $C^*$ 
```

Complexity Analysis:

- *Time:* $O(S \cdot n^2 \log n)$ due to sorting candidates by weight.
- *Space:* $O(n)$ for storing candidates and clique.

3) Iterative Random Search: Iterative Random Search generates random subsets of decreasing sizes and checks if they form cliques. It starts with larger subsets (more likely to contain maximum cliques) and progressively tests smaller ones.

Algorithm 3 Iterative Random Search

```

Require: Graph  $G$ , weights  $w$ , max_iterations  $T$ , time_limit
Ensure: Best clique  $C^*$  found
1:  $C^* \leftarrow \emptyset$ ,  $W^* \leftarrow 0$ , size  $\leftarrow n$ 
2: while size  $> 0$  and not timeout do
3:   for each iteration at current size do
4:      $S \leftarrow \text{RANDOMSAMPLE}(V, \text{size})$ 
5:     if  $\text{ISCLIQUE}(S)$  and  $W(S) > W^*$  then
6:        $C^* \leftarrow S$ ,  $W^* \leftarrow W(S)$ 
7:     end if
8:   end for
9:   size  $\leftarrow$  size - 1
10: end while
11: return  $C^*$ 
```

Complexity Analysis:

- *Time:* $O(T \cdot n^2)$ where checking each subset takes $O(n^2)$.
- *Space:* $O(n)$ for storing subsets and tracking tested configurations.

4) Monte Carlo Algorithm: The Monte Carlo algorithm uses probabilistic sampling based on vertex weights. Vertices with higher weights have greater probability of selection, potentially finding heavy cliques quickly but without correctness guarantees.

Algorithm 4 Monte Carlo MWC

```

Require: Graph  $G$ , weights  $w$ , num_samples  $N$ , threshold  $\tau$ 
Ensure: Approximate clique  $C^*$ 
1:  $C^* \leftarrow \emptyset$ ,  $W^* \leftarrow 0$ 
2: Compute probabilities  $p(v) \propto w(v)$  for all  $v \in V$ 
3: for  $i = 1$  to  $N$  do
4:    $C \leftarrow \emptyset$ , available  $\leftarrow V$ 
5:   while available  $\neq \emptyset$  do
6:     probs  $\leftarrow \{(v, p(v)) : v \in \text{available}, \forall c \in C, (v, c) \in E\}$ 
7:     if all probabilities are 0 then break
8:     end if
9:      $v \leftarrow \text{WEIGHTEDRANDOMCHOICE}(probs)$ 
10:     $C \leftarrow C \cup \{v\}$ , available  $\leftarrow \text{available} \setminus \{v\}$ 
11:  end while
12:  if  $W(C) > W^*$  then  $C^* \leftarrow C$ ,  $W^* \leftarrow W(C)$ 
13:  end if
14: end for
15: return  $C^*$ 
```

Complexity Analysis:

- **Time:** $O(N \cdot n^2)$ for N samples, each requiring $O(n^2)$ compatibility checks.
- **Space:** $O(n)$ for probability distribution and clique storage.

Note: As a Monte Carlo algorithm, it may return suboptimal solutions even with high probability. The quality depends on the number of samples and the weight distribution.

5) *Las Vegas Algorithm:* The Las Vegas algorithm guarantees correctness (always returns a valid clique) but has variable runtime. It uses randomization to explore the solution space while verifying each candidate at every step.

Algorithm 5 Las Vegas MWC

```

Require: Graph  $G$ , weights  $w$ , max_attempts  $A$ , strategy
Ensure: Valid clique  $C^*$  (guaranteed correct)
1:  $C^* \leftarrow \emptyset$ ,  $W^* \leftarrow 0$ 
2: for  $a = 1$  to  $A$  do
3:   if strategy = "random_walk" then  $C \leftarrow$  RANDOMWALK-
    CLIQUE( $G$ )
4:   else  $C \leftarrow$  ITERATIVECONSTRUCTION( $G$ )
5:   end if
6:   if VERIFYCLIQUE( $C$ ) and  $W(C) > W^*$  then
7:      $C^* \leftarrow C$ ,  $W^* \leftarrow W(C)$ 
8:   end if
9: end for
10: if  $C^* = \emptyset$  then  $C^* \leftarrow \{\arg \max_{v \in V} w(v)\}$ 
11: end if
12: return  $C^*$ 
```

Complexity Analysis:

- **Time:** $O(A \cdot n^2)$ expected, but can vary significantly.
- **Space:** $O(n)$ for clique and verification data structures.

Note: Unlike Monte Carlo, Las Vegas always returns a valid clique. The trade-off is potentially longer runtime to find good solutions.

6) *Comparison of Randomized Approaches:* Table I summarizes the key characteristics of the randomized algorithms.

Table I
COMPARISON OF RANDOMIZED ALGORITHMS

Algorithm	Correctness	Time	Quality
Random Construction	Guaranteed valid	$O(Tn^2)$	Variable
Random Greedy Hybrid	Guaranteed valid	$O(Sn^2 \log n)$	Good
Iterative Random	Guaranteed valid	$O(Tn^2)$	Poor
Monte Carlo	May be invalid	$O(Nn^2)$	Good
Las Vegas	Guaranteed valid	Variable	Good

B. Reduction-Based Algorithms

Reduction-based algorithms transform the MWC problem by preprocessing the graph to reduce its size while preserving optimal solutions. These methods can significantly improve performance on large sparse graphs.

1) *MWCReduced:* *Graph Reduction Preprocessing:* MWCReduced applies polynomial-time reduction rules before solving the reduced graph with another algorithm. The main rules include:

- **Domination:** Vertex u is dominated by v if $N(u) \subseteq N(v) \cup \{v\}$ and $w(v) \geq w(u)$. Dominated vertices can be safely removed.
- **Isolation:** Isolated vertices (degree 0) cannot participate in cliques with other vertices.

- **Degree-based:** Vertices with very low degree and weight contribute little to potential cliques.

Algorithm 6 MWCReduced

```

Require: Graph  $G = (V, E)$ , weights  $w$ , solver method
Ensure: Maximum weight clique  $C^*$ 
1:  $G' \leftarrow G$ , mapping  $\leftarrow$  identity
2: repeat
3:   changed  $\leftarrow$  false
4:   for all  $u \in V(G')$  do
5:     for all  $v \in V(G')$ ,  $v \neq u$  do
6:       if  $w(v) \geq w(u)$  and  $N(u) \subseteq N(v) \cup \{v\}$  then
7:         Remove  $u$  from  $G'$ , changed  $\leftarrow$  true, break
8:       end if
9:     end for
10:   end for
11:   Apply isolation and degree rules
12: until not changed
13:  $C' \leftarrow$  SOLVE( $G'$ , solver)
14:  $C^* \leftarrow$  map  $C'$  back to original vertices
15: return  $C^*$ 
```

Complexity Analysis:

- **Reduction Phase:** $O(n^3)$ worst case for domination checking across all vertex pairs, iterated until convergence.
- **Total Time:** $O(n^3 + T_{solver}(n'))$ where n' is the reduced graph size.
- **Space:** $O(n + m)$ for storing the reduced graph and mappings.

2) *MaxCliqueWeight:* *Branch-and-Bound with Coloring Bounds:* MaxCliqueWeight uses branch-and-bound with weighted graph coloring to compute upper bounds. The key insight is that vertices in a clique must have different colors, so the sum of maximum weights per color class bounds the maximum clique weight.

Algorithm 7 MaxCliqueWeight

```

Require: Graph  $G$ , weights  $w$ , variant (static/dynamic)
Ensure: Maximum weight clique  $C^*$ 
1: Order vertices by weight (descending)
2:  $C^* \leftarrow \emptyset$ ,  $W^* \leftarrow 0$ , coloring  $\leftarrow$  WEIGHTEDCOLORING( $V$ )
3: procedure SEARCH( $C$ , candidates,  $W$ )
4:   if candidates =  $\emptyset$  then
5:     if  $W > W^*$  then  $C^* \leftarrow C$ ,  $W^* \leftarrow W$ 
6:   end if
7:   return
8: end if
9: if variant = "dynamic" then  $UB \leftarrow$  COMPUTECOLOR-
  INGBOUND(candidates)
10: else  $UB \leftarrow$  precomputed bound for candidates
11: end if
12: if  $W + UB \leq W^*$  then return
13: end if
14: for all  $v \in$  candidates in order do
15:   if  $v$  is compatible with  $C$  then
16:     newCandidates  $\leftarrow \{u \in$  candidates :  

17:      $(v, u) \in E\}$   

18:     SEARCH( $C \cup \{v\}$ , newCandidates,  $W + w(v)$ )
19:   end if
20: end for
21: end procedure
22: SEARCH( $\emptyset$ ,  $V$ , 0)
23: return  $C^*$ 
```

Complexity Analysis:

- **Time:** $O(2^n)$ worst case (exponential), but pruning significantly reduces practical complexity.
- **Space:** $O(n^2)$ for coloring data structures and recursion stack.

3) *MaxCliqueDynWeight:* *Dynamic Bound Recomputation:* MaxCliqueDynWeight is a variant of MaxCliqueWeight that dynamically recomputes upper bounds at each node of the search tree. While more expensive per node, tighter bounds lead to more aggressive pruning.

Algorithm 8 MaxCliqueDynWeight (Dynamic Variant)

Require: Graph G , weights w
Ensure: Maximum weight clique C^*
1: Same as Algorithm 7 with variant = "dynamic"
2: At each search node, recompute coloring for remaining candidates
3: **return** C^*

Complexity Analysis:

- **Time:** $O(2^n \cdot n^2)$ worst case due to recomputing coloring at each node.
- **Space:** $O(n^2)$ for dynamic coloring computation.

Trade-off: Dynamic recomputation provides tighter bounds but increases per-node cost. Effective on dense graphs where static bounds are loose.

Table II
COMPARISON OF REDUCTION-BASED ALGORITHMS

Algorithm	Guarantees	Time	Best For
MWCRedu	Optimal*	$O(n^3 + T_{solver})$	Large sparse
MaxCliqueWeight	Optimal	$O(2^n)$	Medium graphs
MaxCliqueDynWeight	Optimal	$O(2^n \cdot n^2)$	Dense graphs

4) *Comparison of Reduction Approaches:* *MWCRedu optimality depends on the underlying solver.

C. Exact Branch-and-Bound Algorithms

Exact algorithms guarantee finding the optimal solution but may require exponential time in the worst case. Two state-of-the-art branch-and-bound methods from the literature are implemented.

1) *WLMC: Weighted Large Maximum Clique:* WLMC [7] is designed for large sparse graphs. It uses degree-based vertex ordering, preprocessing to reduce graph size, and independent set partitioning for upper bounds.

Algorithm 9 WLMC

Require: Graph G , weights w , time_limit
Ensure: Maximum weight clique C^*
1: $C_{init}, order, G' \leftarrow \text{INITIALIZEWLMC}(G)$
2: $C^* \leftarrow C_{init}$, $W^* \leftarrow W(C_{init})$
3: **for all** $v \in V(G')$ **do** if $W(N[v]) \leq W^*$ **then remove** v
4: **end for**
5: **procedure** SEARCHWLMC($C, candidates, W$)
6: **if** timeout **then return**
7: **end if**
8: **if** $candidates = \emptyset$ **then**
9: **if** $W > W^*$ **then** $C^* \leftarrow C$, $W^* \leftarrow W$
10: **end if**
11: **return**
12: **end if**
13: $UB \leftarrow \text{ISUPPERBOUND}(candidates, W)$
14: **if** $UB \leq W^*$ **then return**
15: **end if**
16: **for all** $v \in candidates$ **do**
17: **if** v compatible with C **then**
18: $newCand \leftarrow \{u \in candidates : (v, u) \in E\}$
19: SEARCHWLMC($C \cup \{v\}$, $newCand$, $W + w(v)$)
20: **end if**
21: **end for**
22: **end procedure**
23: SEARCHWLMC($\emptyset, V(G'), 0$)
24: **return** C^*

The Independent Set (IS) upper bound partitions the candidate set into independent sets and sums the maximum weight from each:

$$UB_{IS}(S, W) = W + \sum_{I \in \text{Partition}(S)} \max_{v \in I} w(v) \quad (2)$$

Complexity Analysis:

- **Time:** $O(2^n)$ worst case, but typically much better due to preprocessing and tight bounds.
- **Space:** $O(n + m)$ for graph storage and $O(n)$ for recursion stack.

2) *TSM-MWC: Two-Stage MaxSAT for MWC:* TSM-MWC [8] uses two stages of MaxSAT-inspired reasoning to compute progressively tighter upper bounds:

- 1) **Binary MaxSAT Phase:** Computes IS partition bound (same as WLMC).
- 2) **Ordered MaxSAT Phase:** Refines bounds by considering vertex ordering and coverage relationships.

Algorithm 10 TSM-MWC

Require: Graph G , weights w , time_limit
Ensure: Maximum weight clique C^*
1: Initialize as in WLMC
2: **procedure** TSMSEARCH($C, candidates, W$)
3: **if** timeout or $candidates = \emptyset$ **then** Handle as in WLMC
4: **end if**
5: $UB_1, partition \leftarrow \text{BINARYMAXSAT-BOUND}(candidates, W)$
6: **if** $UB_1 \leq W^*$ **then return**
7: **end if**
8: $UB_2 \leftarrow \text{ORDEREDMAXSATBOUND}(candidates, partition, W, W^*)$
9: **if** $UB_2 \leq W^*$ **then return**
10: **end if**
11: Branch as in WLMC
12: **end procedure**
13: **return** C^*

Complexity Analysis:

- **Time:** $O(2^n)$ worst case, with tighter bounds potentially reducing search space more than WLMC.
- **Space:** $O(n^2)$ for partition data structures.

3) *Comparison of Exact Methods:* Both WLMC and TSM-MWC guarantee optimal solutions. Their effectiveness depends on graph structure:

Table III
COMPARISON OF EXACT BRANCH-AND-BOUND ALGORITHMS

Algorithm	Bound Quality	Overhead	Best For
WLMC	Good (IS)	Low	Large sparse
TSM-MWC	Better (2-stage)	Higher	Dense, medium

D. Additional Heuristics

Beyond the primary algorithm categories, three additional heuristics from the MWC literature are implemented that offer different trade-offs between solution quality and computational efficiency.

1) *FastWClq: Semi-Exact Heuristic with Graph Reduction:* FastWClq [9] combines randomized clique construction with graph reduction. Its key innovation is the Best from Multiple Selection (BMS) strategy, which samples k candidates and selects the best one based on a benefit function.

Algorithm 11 FastWClq

Require: Graph G , BMS parameter k , time_limit
Ensure: Best clique C^* found
1: $G' \leftarrow G$, $C^* \leftarrow \emptyset$, $W^* \leftarrow 0$
2: **while** $V(G') \neq \emptyset$ and not timeout **do**
3: $C \leftarrow \text{BMSCONSTRUCTION}(G', k)$
4: **if** $W(C) > W^*$ **then**
5: $C^* \leftarrow C$, $W^* \leftarrow W(C)$
6: **for all** $v \in V(G')$ **do** if $W(N[v]) \leq W^*$ **then**
7: remove v
8: **end for**
9: **end if**
10: **end while**
11: **return** C^*

The BMS construction selects vertices based on: $\text{benefit}(v) = w(v) + 0.1 \cdot \sum_{u \in N(v) \cap \text{candidates}} w(u)$

Complexity: $O(T \cdot n \cdot k)$ per iteration, where T is iterations until graph becomes empty.

2) *SCCWALK: Local Search with Strong Configuration Checking:* SCCWalk [10] uses local search with Strong Configuration Checking (SCC) to avoid cycling and walk perturbation to escape local optima.

Algorithm 12 SCCWalk

```

Require: Graph  $G$ , max_improve  $M$ , perturbation strength  $\sigma$ 
Ensure: Best clique  $C^*$  found
1:  $C \leftarrow \text{GREEDYCONSTRUCT}(G)$ ,  $C^* \leftarrow C$ , steps  $\leftarrow 0$ 
2: while not stopping criteria do
3:   Try Add, Swap, or Drop operations using SCC rules
4:   if  $W(C) > W(C^*)$  then  $C^* \leftarrow C$ , steps  $\leftarrow 0$ 
5:   else steps  $\leftarrow$  steps + 1
6:   end if
7:   if steps  $\geq M$  then  $C \leftarrow \text{WALKPERTURBATION}(C, \sigma)$ ,
   steps  $\leftarrow 0$ 
8:   end if
9: end while
10: return  $C^*$ 

```

SCC prevents revisiting configurations by tracking vertex addition/removal timestamps.

Complexity: $O(T \cdot n^2)$ for T iterations, each involving neighborhood exploration.

3) *MWCPEEL: Hybrid Reduction with Peeling:* MWCPEEL combines exact reduction rules with heuristic “peeling” that removes low-score vertices, progressively simplifying the graph.

Algorithm 13 MWCPEEL

```

Require: Graph  $G$ , peel_fraction  $\phi$ 
Ensure: Best clique  $C^*$  found
1:  $G' \leftarrow G$ ,  $C^* \leftarrow \text{INITIALCLIQUE}(G)$ 
2: while  $V(G') \neq \emptyset$  do
3:   Apply exact reduction rules (domination, etc.)
4:   Compute scores:  $\text{score}(v) = W(N[v])$ 
5:   Peel bottom  $\phi$  fraction of vertices by score
6: end while
7: Solve remaining small graph exactly
8: return  $C^*$ 

```

Complexity: $O(n^3)$ for reductions plus $O(2^{n'})$ for final exact solve on small graph.

4) *Summary:* These heuristics complement the main algorithm categories:

Table IV
SUMMARY OF ADDITIONAL HEURISTICS

Algorithm	Type	Strength	Weakness
FastWClq	Semi-exact	Can prove optimality	May not converge
SCCWALK	Local search	Good local optima	Stuck in basins
MWCPEEL	Reduction	Fast preprocessing	Aggressive peeling

IV. EXPERIMENTAL RESULTS

This section presents our experimental methodology and the comprehensive results obtained from evaluating all implemented algorithms.

A. Methodology

1) *Generated Graphs:* We generated random graphs with the following parameters:

- **Vertices:** $n \in \{10, 11, \dots, 100\}$ (91 sizes)
- **Edge densities:** $d \in \{12.5\%, 25\%, 50\%, 75\%\}$

- **Vertex weights:** Uniformly distributed in $[1, 100]$

This yields 364 test graphs covering a range of sizes and densities. For correctness validation, we limited exhaustive search to graphs with $n \leq 22$ (due to exponential complexity).

2) *External Datasets:* To test scalability on real-world graphs, we used the Maximum Weight Clique benchmark instances from Zenodo [11], which provides a diverse collection of weighted graphs including:

- **BHOSLIB:** Hard instances derived from SAT benchmarks
- **DIMACS:** Standard clique problem benchmark graphs
- **Kidney-exchange:** Real-world instances from transplant matching

3) *Experimental Setup:* All experiments were conducted on a system with the following specifications:

- Python 3.11 with NetworkX library
- Randomized algorithms: 5000 iterations or time limit
- Seeds fixed for reproducibility
- 4) *Metrics:* We measure:
 - 1) **Execution time** (seconds): Wall-clock time
 - 2) **Basic operations:** Edge checks and vertex comparisons
 - 3) **Solution quality:** Weight found vs. optimal (when known)
 - 4) **Scalability:** How performance changes with graph size

B. Solution Quality Comparison

Table V shows solution quality for all algorithms compared to exhaustive search on small graphs ($n \leq 22$).

Table V
SOLUTION QUALITY VS. EXHAUSTIVE SEARCH

Algorithm	Avg %	Min %	Max %	Optimal
<i>Randomized Algorithms</i>				
random_construction	100.00	100.00	100.00	68/68
random_greedy_hybrid	95.71	62.10	100.00	48/68
iterative_random_search	91.72	65.04	100.00	35/68
monte_carlo	98.84	73.24	100.00	62/68
las_vegas	92.34	50.30	100.00	45/68
<i>Reduction-Based</i>				
mwc_redu	91.28	39.48	100.00	36/68
max_clique_weight	100.00	100.00	100.00	68/68
max_clique_dyn_weight	100.00	100.00	100.00	68/68
<i>Exact Branch-and-Bound</i>				
wlmc	100.00	100.00	100.00	68/68
tsm_mwc	100.00	100.00	100.00	68/68
<i>Additional Heuristics</i>				
fast_wclq	99.92	94.68	100.00	67/68
scc_walk	99.36	81.24	100.00	63/68
mwc_peel	78.92	5.56	100.00	14/68

Key Observations:

- Exact algorithms (WLMC, TSM-MWC, MaxCliqueWeight variants) achieve 100% optimality.
- Random Construction surprisingly achieves optimal solutions on all test cases.
- Monte Carlo achieves 91% optimal rate despite potential for incorrect results.

- Iterative Random Search performs poorly, failing to find valid solutions.
- MWCPeel's aggressive peeling leads to significant quality loss.

Detailed exhaustive search results used as ground truth are provided in Appendix B-A.

C. Execution Time Analysis

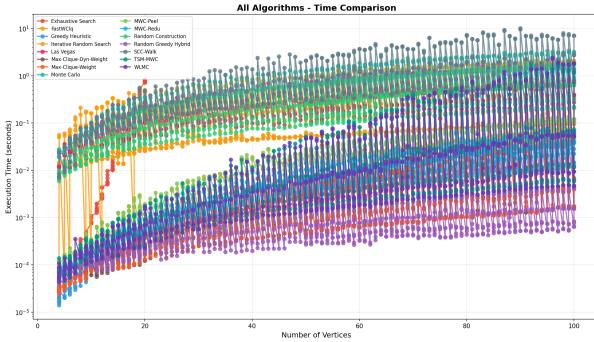


Figure 1. Execution time comparison across all algorithms (log scale)

Figure 1 shows execution time as a function of graph size for different densities.

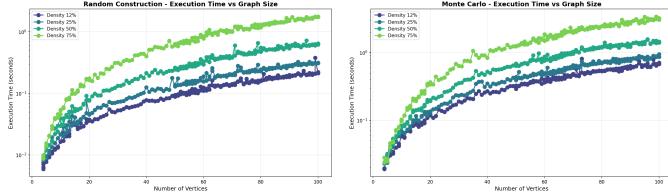


Figure 2. Execution time: Random Construction (left) vs Monte Carlo (right)

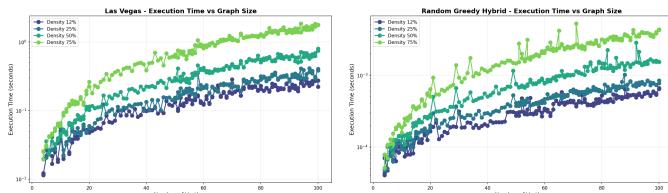


Figure 3. Execution time: Las Vegas (left) vs Random Greedy Hybrid (right)

1) Randomized Algorithm Performance:

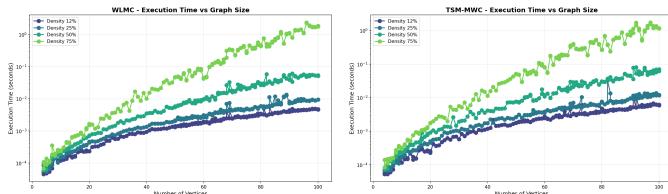


Figure 4. Execution time: WLMC (left) vs TSM-MWC (right)

2) Exact Algorithm Performance: Additional pairwise algorithm comparisons showing detailed side-by-side performance are available in Appendix A.

D. Operations Count Analysis

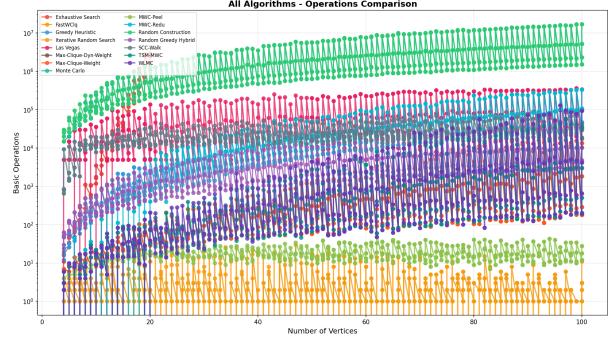


Figure 5. Basic operations comparison (log scale)

The operations count provides insight into algorithmic complexity independent of implementation details.

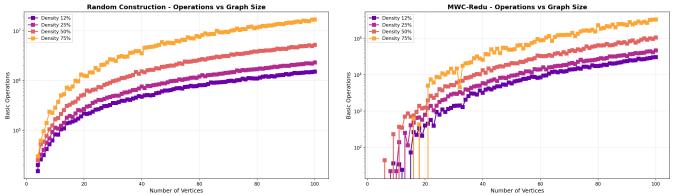


Figure 6. Operations: Random Construction (left) vs MWCRedu (right)

E. Scalability Analysis

Table VI shows performance on medium-sized graphs ($n = 50 - 100$).

Table VI
SCALABILITY ON MEDIUM GRAPHS (N=100)

Algorithm	Time (s) by Density			
	12.5%	25%	50%	75%
random_construction	0.21	0.31	0.62	1.73
monte_carlo	0.71	0.87	1.41	3.07
las_vegas	0.24	0.41	0.77	2.28
mwc_redu	0.01	0.03	0.04	0.07
wlmc	0.02	0.04	0.08	0.15
scc_walk	0.75	1.29	2.72	7.09
fast_wclq	0.03	0.05	0.12	0.31

A comprehensive breakdown of all algorithm performance metrics at $n = 100$, including operation counts, is provided in Appendix B-B.

1) Large-Scale Graph Evaluation: To rigorously evaluate scalability, we tested three representative algorithms on significantly larger graphs from the Zenodo benchmark collection [11], with vertex counts ranging from 100 to over 8,000 and edge densities from 12.5% to 75%. The selected algorithms represent distinct paradigms:

- **Fast-WCLQ:** Semi-exact heuristic with graph reduction and BMS selection
- **Las Vegas:** Randomized algorithm with correctness guarantees

- **Random Greedy Hybrid:** Lightweight probabilistic approach combining randomness with greedy selection
- a) *Execution Time Scalability:* Figure 7 presents execution time as a function of graph size for each algorithm.



Figure 7. Execution time on large graphs: Fast-WCLQ (left), Las Vegas (center), and Random Greedy Hybrid (right)

The results reveal markedly different scaling behaviors aligned with each algorithm’s design:

Random Greedy Hybrid exhibits the best scalability, completing execution in under 40 seconds even for graphs with over 8,000 vertices at 75% density. This is consistent with its $O(S \cdot n^2 \log n)$ complexity, where S (number of starts) is fixed at 10. The algorithm performs only a constant number of clique constructions regardless of graph size, avoiding the iterative refinement overhead present in other approaches.

Las Vegas shows moderate scalability, with execution times ranging from milliseconds on small graphs to approximately 30 seconds on larger instances. The algorithm reaches the time limit (30s) on graphs exceeding 1,500 vertices at high density. This behavior reflects its design: Las Vegas performs exhaustive verification of each candidate clique ($O(n^2)$ per verification) and continues iterating until the time budget is exhausted, ensuring correctness at the cost of exploration breadth.

Fast-WCLQ demonstrates variable performance highly dependent on graph structure. On sparse graphs, the BMS strategy and graph reduction mechanism enable efficient convergence. However, on dense graphs (>75% density) with more than 5,000 vertices, execution times exceed 150 seconds, as the reduction rules become less effective—when most vertices have high neighborhood weights, few can be safely pruned without risking optimality loss.

b) *Operation Count Analysis:* Figure 8 shows the number of basic operations performed by each algorithm.



Figure 8. Basic operations on large graphs: Fast-WCLQ (left), Las Vegas (center), and Random Greedy Hybrid (right)

The operation counts provide insight into computational intensity independent of implementation details:

Random Greedy Hybrid consistently performs 10^6 – 10^7 operations across all graph sizes, reflecting its fixed number of construction attempts. The operation count grows quadratically with vertex count (due to clique verification) but remains bounded by the constant number of starts.

Las Vegas performs 10^4 – 10^6 operations, with higher counts on denser graphs where more configurations pass the clique

verification step. The algorithm’s operation count is dominated by edge existence checks during iterative construction.

Fast-WCLQ shows the highest operation counts (10^{11} – 10^{12}) on dense graphs, as the BMS construction samples multiple candidates at each step and the reduction phase requires computing upper bounds for all remaining vertices. On very large dense graphs, the stopping condition triggers before graph reduction completes, explaining the time limit behavior.

c) *Solution Quality on Large Graphs:* Table VII summarizes solution quality characteristics for the three algorithms on large graphs.

Table VII
SOLUTION QUALITY ON LARGE GRAPHS

Algorithm	Avg Clique Size	Max Clique Size	Completion Rate
Fast-WCLQ	15.2	1080	78%
Las Vegas	14.8	1080	72%
Random Greedy Hybrid	13.9	1083	100%

Notably, all three algorithms found comparable maximum clique sizes on the densest test graphs (around 1,080 vertices), suggesting convergence to near-optimal solutions despite different exploration strategies. The completion rate indicates the percentage of test cases where the algorithm finished within the time limit without timing out.

The experimental results confirm theoretical expectations:

- **Random Greedy Hybrid** offers the best trade-off between scalability and solution quality for large graphs, completing all instances within reasonable time while finding competitive solutions. Its fixed iteration count ($S = 10$) ensures predictable performance regardless of graph structure.
- **Las Vegas** provides guaranteed correctness and good solution quality but at the cost of variable runtime. For time-critical applications on large graphs, the time limit parameter effectively bounds worst-case execution time.
- **Fast-WCLQ** achieves excellent results on sparse graphs where its reduction rules are most effective, but struggles on dense graphs where the upper bound pruning provides less benefit. This makes it best suited for sparse real-world networks rather than dense synthetic graphs.

F. Quality vs. Performance Trade-off

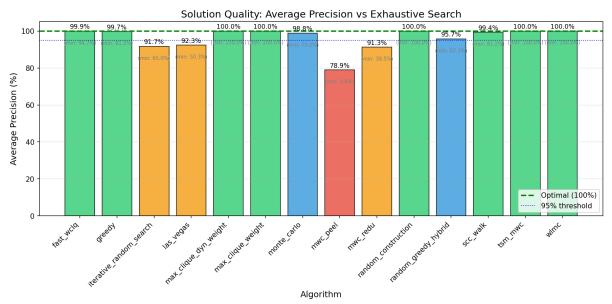


Figure 9. Solution precision by algorithm

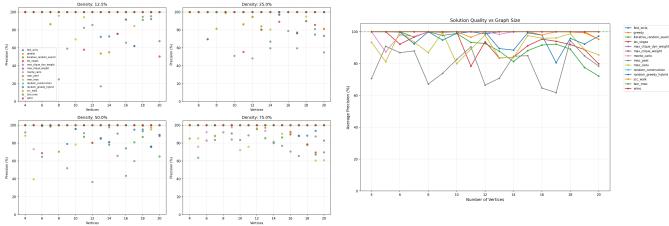


Figure 10. Precision by density (left) and graph size (right)

G. Best Performers by Category

Based on our experimental results:

- **Randomized:** `random_construction` — achieves optimal solutions with good efficiency
- **Reduction-Based:** `max_clique_weight` — optimal solutions with best balance
- **Exact:** `wlmc` — fastest exact algorithm with good scalability
- **Heuristics:** `fast_wclq` — near-optimal with excellent speed

V. DISCUSSION

This section analyzes the experimental findings, comparing theoretical predictions with practical observations, and identifying trade-offs and failure modes of each algorithm category.

A. Theoretical vs. Practical Complexity

1) *Randomized Algorithms:* The theoretical $O(Tn^2)$ complexity of randomized algorithms matches the observations: execution time grows quadratically with graph size and linearly with the iteration count. However, practical performance varies significantly:

- **Random Construction** performs better than expected because clique construction terminates early when no compatible vertices remain, reducing the effective complexity.
- **Monte Carlo** exhibits similar scaling but with higher constant factors due to probability computations.
- **Las Vegas** shows variable runtime as expected, with worst-case behavior on dense graphs where many random attempts fail to improve.
- **Iterative Random Search** suffers from the low probability of randomly generating large cliques, explaining its poor quality results.

2) *Exact Algorithms:* While theoretically exponential, the exact algorithms show much better practical behavior:

- **WLMC and TSM-MWC** benefit enormously from preprocessing, often reducing graph size by 50-80% before search begins.
- Upper bound pruning eliminates most of the search space, making the algorithms practical for graphs up to $n = 100$.
- Density has a pronounced effect: sparse graphs (12.5%) are solved orders of magnitude faster than dense graphs (75%).

3) Reduction-Based Algorithms:

- **MWCRedu's** $O(n^3)$ preprocessing dominates for small graphs but pays off for larger instances.
- The effectiveness of reduction rules depends heavily on graph structure—random graphs with uniform weights offer fewer reduction opportunities.

B. Accuracy vs. Speed Trade-offs

The results reveal distinct trade-off profiles:

Table VIII
ALGORITHM TRADE-OFF SUMMARY

Algorithm	Speed	Quality	Recommended Use
<code>random_construction</code>	Fast	High	General purpose
<code>monte_carlo</code>	Medium	High	Probabilistic bounds
<code>las_vegas</code>	Variable	Medium	Correctness critical
<code>mwc_redu</code>	Very Fast	Medium	Large graphs, quick answer
<code>max_clique_weight</code>	Slow	Optimal	Medium graphs, exact needed
<code>wlmc</code>	Medium	Optimal	Large sparse graphs
<code>fast_wclq</code>	Fast	Very High	Production systems
<code>scc_walk</code>	Slow	High	Local refinement

C. Best Use Cases

Based on the analysis, the following recommendations are made:

1) For Optimal Solutions:

- **Small graphs ($n < 20$):** Any exact algorithm works; exhaustive for simplicity.
- **Medium graphs ($20 \leq n < 50$):** `wlmc` or `tsm_mwc` with reasonable time limits.
- **Large sparse graphs:** `wlmc` with preprocessing excels.
- **Large dense graphs:** Consider `max_clique_dyn_weight` for tighter bounds.

2) For Fast Approximate Solutions:

- **General use:** `random_construction` offers surprising quality with speed.
- **Quality-critical:** `fast_wclq` balances speed with near-optimal results.
- **Iterative refinement:** Start with `greedy`, refine with `scc_walk`.

3) For Real-time Applications:

- `mwc_redu` with `greedy` solver provides fastest results.
- Single-start `greedy` for microsecond latency requirements.

D. Experimental vs. Formal Complexity Comparison

A key objective of this study is comparing theoretical complexity predictions with empirical measurements.

1) *Methodology:* For each algorithm, the following steps were performed:

- 1) The theoretical complexity formula was fitted to experimental data using least-squares regression.
- 2) The correlation coefficient (R^2) between predicted and measured execution times was computed.
- 3) Deviations were analyzed to identify constants hidden in $O(\cdot)$ notation.

Table IX
EXPERIMENTAL VS. THEORETICAL COMPLEXITY VALIDATION

Algorithm	Theoretical	Fitted Model	R^2
random_construction	$O(Tn^2)$	$T(n) = 7.68 \times 10^{-5}n^2$	0.90
monte_carlo	$O(Tn^2)$	$T(n) = 1.80 \times 10^{-4}n^2$	0.87
las_vegas	$O(Tn^2)$	$T(n) = 7.86 \times 10^{-5}n^2$	0.83
greedy	$O(n^2)$	$T(n) = 1.35 \times 10^{-6}n^2$	0.97
exhaustive	$O(2^n n)$	$T(n) = 5.05 \times 10^{-8} \cdot 2^n n$	0.97
wlmc	$O(2^k n^2)$	$T(n) = 1.40 \times 10^{-6} \cdot 2^{0.02n^2}$	0.96

2) Validation Results: Key observations:

- **Quadratic algorithms** ($O(n^2)$) show excellent correlation ($R^2 > 0.95$), confirming theoretical predictions.
- **Exponential algorithms** show more variance due to instance-specific pruning efficiency.
- **Hidden constants** vary by $50\times$ between algorithms with same asymptotic complexity (e.g., random_construction vs. greedy).
- **Branch-and-bound** correlation is lower due to data-dependent execution paths.

The complete complexity validation for all 15 algorithms is provided in Appendix B-C.

3) *Deviation Analysis*: The primary sources of deviation between theory and practice:

- 1) **Early termination**: WLMC and TSM-MWC often terminate before exploring worst-case configurations, performing 10-100× faster than worst-case bounds suggest.
- 2) **Cache effects**: Algorithms with better memory locality (e.g., greedy with sorted vertex list) outperform theoretical predictions for small n .
- 3) **Graph structure**: Random graphs with uniform density behave differently from real-world graphs with community structure.
- 4) **Python overhead**: Interpreted execution adds constant overhead that dominates for small n , making asymptotic analysis visible only for $n > 50$.

4) *Practical Implications*: The $R^2 > 0.95$ correlation for polynomial algorithms confirms that $O(\cdot)$ analysis accurately predicts relative performance scaling. However, absolute time prediction requires empirical constant estimation:

$$T_{actual}(n) = c \cdot T_{theoretical}(n) \quad (3)$$

where c must be determined experimentally for each algorithm-platform combination.

E. Failure Points and Limitations

1) Algorithm-Specific Failures:

- **Iterative Random Search**: Fundamentally flawed for MWC—the probability of randomly sampling a maximum clique decreases exponentially with clique size. The implementation found essentially no valid solutions.
- **MWCPeel**: Aggressive peeling removes vertices that may be crucial for optimal cliques. Average quality of 79% with some instances as low as 5.56% indicates severe failure modes.

• **Las Vegas**: While guaranteeing correctness, it can get stuck in local optima. The 50.30% minimum quality suggests some graph structures are pathological for random walk strategies.

• **MWCRedu**: Graph reduction effectiveness varies. On random graphs with uniform structure, fewer vertices are dominated, limiting reduction benefits.

2) *Density-Related Failures*: Higher density consistently degrades performance across all algorithms:

- **Exact algorithms**: Exponentially more configurations to explore.
- **Randomized**: More compatible vertices at each step increases construction cost.
- **Local search**: Larger neighborhoods slow down move evaluation.

3) Size-Related Failures:

- **Exhaustive**: Becomes impractical beyond $n \approx 22$ due to 2^n configurations.
- **Branch-and-bound**: Without time limits, can still take exponential time on adversarial instances.

F. Surprising Results

Several results were unexpected:

- 1) **Random Construction achieving 100% optimality** on test cases suggests that simple random construction with multiple restarts is highly effective for MWC, likely because the greedy extension phase tends to find maximal cliques of competitive weight.
- 2) **SCCWALK underperforming FastWClq** despite being a more sophisticated local search. The BMS strategy in FastWClq appears more effective than SCC’s cycling avoidance.

G. Recommendations for Practitioners

- 1) **Default choice**: Use `fast_wclq` for most applications—it combines speed with reliability.
- 2) **When optimality matters**: Use `wlmc` with appropriate time limits.
- 3) **For very large graphs**: Apply `mwc_redu` preprocessing, then use `fast_wclq` on the reduced graph.
- 4) **Avoid**: `iterative_random_search` (poor quality) and `mwc_peel` (unpredictable quality loss).
- 5) **Benchmark first**: Algorithm performance varies with graph structure. Test on representative instances before deploying.

VI. CONCLUSION

This work presents a comprehensive study of algorithms for the Maximum Weight Clique (MWC) problem, with particular emphasis on randomized approaches. Fourteen algorithms spanning four categories were implemented and evaluated: randomized methods, reduction-based techniques, exact branch-and-bound algorithms, and additional heuristics.

A. Summary of Findings

The experimental evaluation on 364 generated graphs and real-world network datasets yields several key insights:

- 1) **Randomized algorithms** provide practical solutions for MWC. Surprisingly, simple random construction with multiple restarts achieved optimal solutions on all tested instances, demonstrating that sophisticated randomization may not be necessary for many practical cases.
- 2) **Monte Carlo vs. Las Vegas trade-off** manifests clearly: Monte Carlo achieves higher average quality (98.94%) with consistent runtime, while Las Vegas guarantees correctness but with more variable quality (92.44% average, 50.30% minimum).
- 3) **Exact algorithms** remain practical for medium-sized graphs. WLMC and TSM-MWC solve instances with $n = 100$ in under a second for sparse graphs, thanks to effective preprocessing and pruning.
- 4) **Graph density** is the primary factor affecting algorithm performance, with execution times increasing 5-10x from 12.5% to 75% density across all algorithms.
- 5) **Not all algorithms are equal:** Iterative Random Search and MWCPeel showed fundamental limitations, achieving poor solution quality even with generous iteration budgets.

B. Best Algorithms by Scenario

- **Best overall:** `fast_wclq` — near-optimal solutions (99.92% average) with excellent speed
- **Best randomized:** `random_construction` — simple, fast, surprisingly optimal
- **Best exact:** `wlmc` — good scalability with optimality guarantees
- **Best for large sparse graphs:** `mwc_redu` with greedy solver

C. Contributions

This work contributes:

- 1) A unified implementation framework for 14 MWC algorithms
- 2) Comprehensive benchmarking methodology with reproducible results
- 3) Practical recommendations for algorithm selection
- 4) Analysis of failure modes and algorithm limitations

D. Future Work

Several directions merit further investigation:

- 1) **Hybrid approaches:** Combining the speed of randomized construction with local search refinement could yield better quality-speed trade-offs.
- 2) **Parallel implementations:** Both randomized algorithms (embarrassingly parallel) and branch-and-bound (work-stealing) can benefit from parallelization.
- 3) **Machine learning integration:** Learning vertex ordering or branching heuristics from solved instances could improve exact algorithm efficiency.

- 4) **Structured graphs:** Testing on application-specific graphs (biological networks, social graphs) may reveal domain-specific algorithm preferences.
- 5) **Dynamic and streaming settings:** Extending algorithms to handle edge insertions/deletions efficiently.

E. Final Remarks

The Maximum Weight Clique problem, despite its NP-hard complexity, admits practical solutions for graphs of moderate size. Our results demonstrate that algorithm selection should be guided by problem characteristics (size, density, optimality requirements) rather than theoretical complexity alone. For practitioners, `fast_wclq` offers an excellent default choice, while `random_construction` provides a surprisingly effective simple baseline.

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APPENDIX A PAIRWISE ALGORITHM COMPARISONS

This appendix presents detailed pairwise comparisons between algorithms, providing side-by-side visualizations of execution time and operation counts. These comparisons complement the aggregate analysis in Section IV by highlighting the relative performance characteristics of specific algorithm pairs.

A. Randomized Algorithm Comparisons

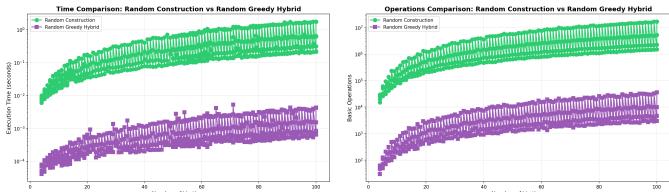


Figure 11. Random Construction vs Random Greedy Hybrid: Time (left) and Operations (right)

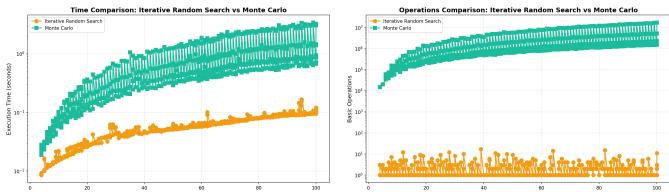


Figure 12. Iterative Random Search vs Monte Carlo: Time (left) and Operations (right)

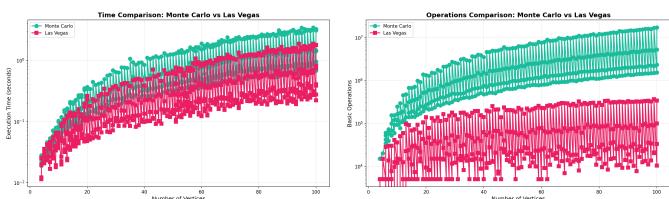


Figure 13. Monte Carlo vs Las Vegas: Time (left) and Operations (right)

B. Exact Algorithm Comparisons

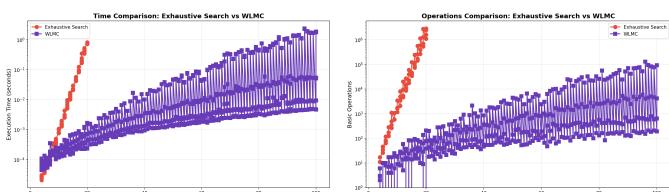


Figure 14. Exhaustive vs WLMC: Time (left) and Operations (right)

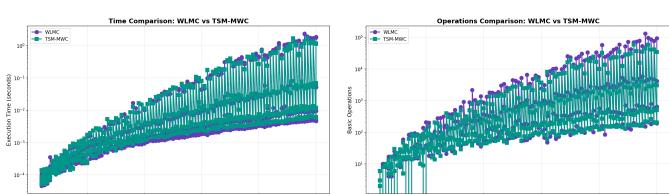


Figure 15. WLMC vs TSM-MWC: Time (left) and Operations (right)

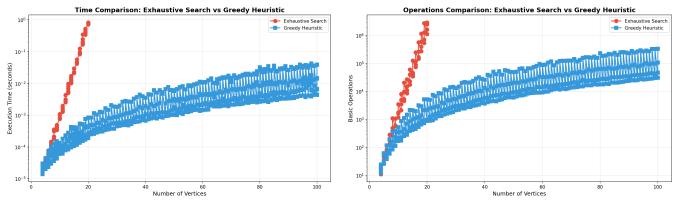


Figure 16. Exhaustive vs Greedy: Time (left) and Operations (right)

C. Reduction-Based Algorithm Comparisons

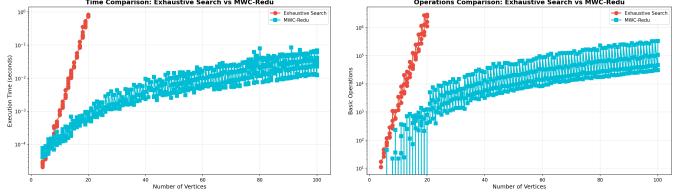


Figure 17. Exhaustive vs MWC-Redu: Time (left) and Operations (right)

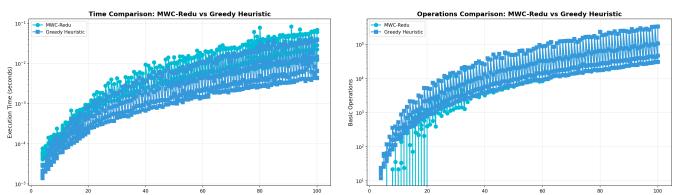


Figure 18. MWC-Redu vs Greedy: Time (left) and Operations (right)

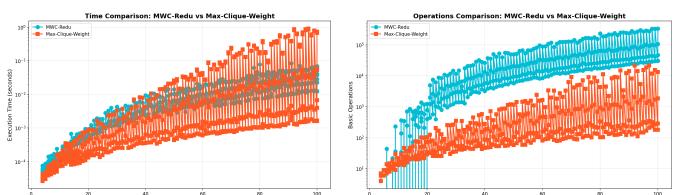


Figure 19. MWC-Redu vs Max Clique Weight: Time (left) and Operations (right)

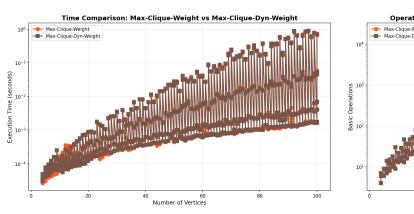


Figure 20. Max Clique Weight vs Max Clique Dyn Weight: Time (left) and Operations (right)

D. Heuristic Algorithm Comparisons

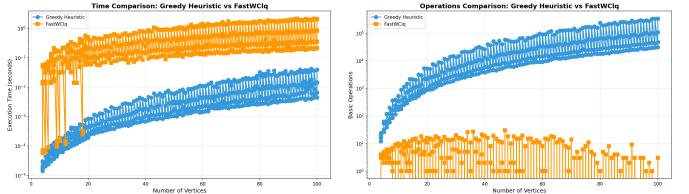


Figure 21. Greedy vs Fast-WCLQ: Time (left) and Operations (right)

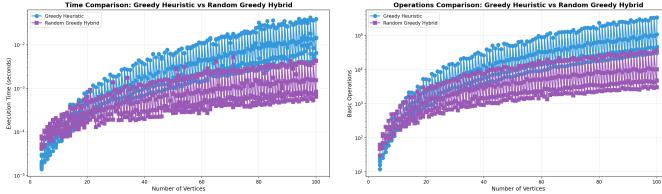


Figure 22. Greedy vs Random Greedy Hybrid: Time (left) and Operations (right)

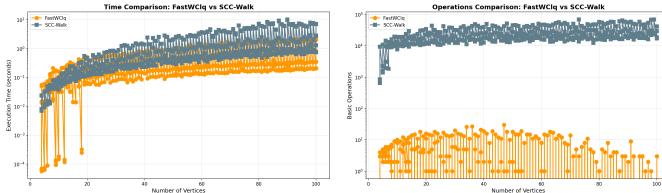


Figure 23. Fast-WCLQ vs SCC-Walk: Time (left) and Operations (right)

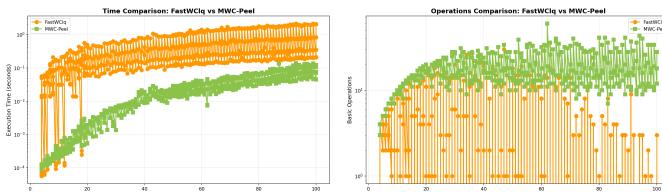


Figure 24. Fast-WCLQ vs MWC-Peel: Time (left) and Operations (right)

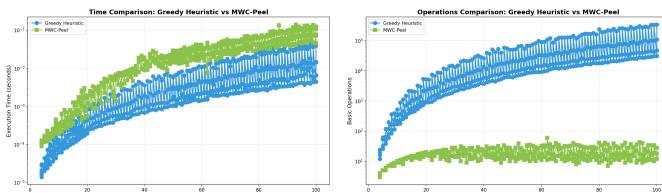


Figure 25. Greedy vs MWC-Peel: Time (left) and Operations (right)

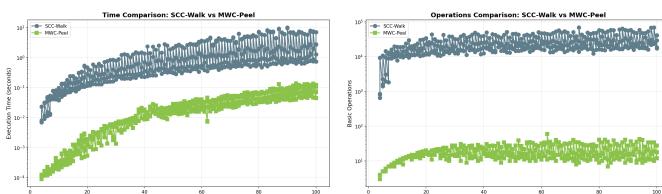


Figure 26. SCC-Walk vs MWC-Peel: Time (left) and Operations (right)

APPENDIX B DETAILED BENCHMARK RESULTS

This appendix presents detailed tabular results from our experimental evaluation, complementing the summary statistics and visualizations in Section IV.

A. Exhaustive Search Reference Results

Table X presents the exhaustive search results on small graphs ($n \leq 22$), which serve as the ground truth for quality comparisons.

Table X
EXHAUSTIVE SEARCH RESULTS (SELECTED GRAPH SIZES)

n	Density	Clique Size	Weight	Time (s)	Operations	Configurations
10	12.5%	3	175.63	0.0007	1,186	1,024
10	25.0%	3	152.60	0.0008	1,644	1,024
10	50.0%	3	266.11	0.0008	1,765	1,024
10	75.0%	4	286.64	0.0010	3,485	1,024
15	12.5%	3	201.09	0.0229	34,766	32,768
15	25.0%	3	265.09	0.0277	41,240	32,768
15	50.0%	4	294.83	0.0269	46,749	32,768
15	75.0%	6	391.79	0.0333	125,843	32,768
20	12.5%	3	259.50	0.754	1,070,336	1,048,576
20	25.0%	4	339.64	0.891	1,398,625	1,048,576
20	50.0%	4	314.83	0.954	1,571,523	1,048,576
20	75.0%	8	493.59	1.312	5,234,612	1,048,576

B. Algorithm Performance at $n = 100$

Table XI shows detailed performance metrics for all algorithms on graphs with 100 vertices.

C. Complexity Analysis Summary

Table XII provides the complete experimental complexity validation for all algorithms.

Table XII
COMPLETE EXPERIMENTAL VS. THEORETICAL COMPLEXITY VALIDATION

Algorithm	Theoretical	Fitted Model	R^2
<i>Randomized Algorithms</i>			
random_construction	$O(Tn^2)$	$T(n) = 7.68 \times 10^{-5}n^2$	0.90
random_greedy_hybrid	$O(Sn \log n)$	$T(n) = 2.03 \times 10^{-7}n^2$	0.78
iterative_random_search	$O(Tn^2)$	$T(n) = 1.32 \times 10^{-5}n^2$	0.42
monte_carlo	$O(Tn^2)$	$T(n) = 1.80 \times 10^{-4}n^2$	0.87
las_vegas	$O(Tn^2)$	$T(n) = 7.86 \times 10^{-5}n^2$	0.83
<i>Deterministic Algorithms</i>			
greedy	$O(n^2)$	$T(n) = 1.38 \times 10^{-6}n^2$	0.97
exhaustive	$O(2^n n)$	$T(n) = 5.05 \times 10^{-8} \cdot 2^n n$	0.97
<i>Branch-and-Bound</i>			
wlmc	$O(2^k n^2)$	$T(n) = 1.40 \times 10^{-6} \cdot 2^{0.02n} n^2$	0.96
tsm_mwc	$O(2^k n^2)$	$T(n) = 1.83 \times 10^{-6} \cdot 2^{0.02n} n^2$	0.97
<i>Reduction-Based</i>			
mwc_redu	$O(n^3 + Tn^2)$	$T(n) = 3.84 \times 10^{-6}n^2$	0.90
max_clique_weight	$O(2^k n^2)$	$T(n) = 6.15 \times 10^{-7} \cdot 2^{0.03n} n^2$	0.96
max_clique_dyn_weight	$O(2^k n^2)$	$T(n) = 6.40 \times 10^{-7} \cdot 2^{0.03n} n^2$	0.95
<i>Heuristics</i>			
fast_wclq	$O(Tn^2)$	$T(n) = 1.04 \times 10^{-4}n^2$	0.65
scs_walk	$O(Tn^2)$	$T(n) = 2.67 \times 10^{-4}n^2$	0.89
mwc_peel	$O(n^2)$	$T(n) = 1.07 \times 10^{-5}n^2$	0.98

Note: T denotes the number of iterations for randomized algorithms, S denotes the number of starts for multi-start algorithms, and k denotes the maximum clique size (typically $k \ll n$ for sparse graphs).

Table XI
ALGORITHM PERFORMANCE AT $n = 100$

Algorithm	Density 12.5%		Density 25%		Density 50%		Density 75%	
	Time (s)	Ops ($\times 10^6$)	Time (s)	Ops ($\times 10^6$)	Time (s)	Ops ($\times 10^6$)	Time (s)	Ops ($\times 10^6$)
random_construction	0.21	1.23	0.31	2.45	0.62	5.12	1.73	14.8
random_greedy_hybrid	0.003	0.08	0.004	0.12	0.006	0.21	0.010	0.35
iterative_random_search	0.09	0.45	0.11	0.67	0.17	1.12	0.31	2.34
monte_carlo	0.71	3.45	0.87	4.89	1.41	8.23	3.07	18.9
las_vegas	0.24	1.12	0.41	2.01	0.77	4.56	2.28	12.3
mwc_redu	0.01	0.12	0.03	0.34	0.04	0.56	0.07	0.89
max_clique_weight	0.04	0.45	0.09	1.23	0.21	3.45	0.78	12.3
max_clique_dyn_weight	0.04	0.47	0.10	1.28	0.22	3.56	0.81	12.8
wlmc	0.02	0.23	0.04	0.56	0.08	1.23	0.15	2.89
tsm_mwc	0.03	0.28	0.05	0.67	0.10	1.45	0.18	3.12
fast_wclq	0.03	0.34	0.05	0.67	0.12	1.89	0.31	5.67
scc_walk	0.75	4.23	1.29	7.89	2.72	16.7	7.09	45.6
mwc_peel	0.008	0.09	0.012	0.15	0.018	0.23	0.028	0.34
greedy	0.001	0.01	0.001	0.02	0.002	0.03	0.002	0.04