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# **io\_anim\_mvnx**

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## IO\_ANIM\_MVNX PACKAGE

### 1.1 Submodules

### 1.2 io\_anim\_mvnx.mvnx module

This module contains functionality concerning the adaption of the XSENS MVN-XML format into our Python setup.

**The official explanation can be found in section 14.4 of this document::** <https://usermanual.wiki/Document/MVNUserManual.1147412416.pdf>

A copy is stored in this repository.

The following section introduces more informally the contents of the imported MVN file and the way they can be accessed from Python:

```
# MVNX schemata can be found in this package or in
# https://www.xsens.com/mvn/mvnx/schema.xsd
mvn_path = "XXX"
mmvn = Mvnx(mvn_path)

# These elements contain some small metadata:
mmvn.mvnx.attrib
mmvn.mvnx.comment.attrib
mmvn.mvnx.securityCode.attrib["code"]
mmvn.mvnx.subject.attrib

# subject.segments contain 3D pos_b labels:
for ch in mmvn.mvnx.subject.segments.iterchildren():
    ch.attrib, [p.attrib for p in ch.points.iterchildren()]

# Segments can look as follows: ``['Pelvis', 'L5', 'L3', 'T12', 'T8', 'Neck',
'Head', 'RightShoulder', 'RightUpperArm', 'RightForeArm', 'RightHand',
'LeftShoulder', 'LeftUpperArm', 'LeftForeArm', 'LeftHand', 'RightUpperLeg',
'RightLowerLeg', 'RightFoot', 'RightToe', 'LeftUpperLeg', 'LeftLowerLeg',
'LeftFoot', 'LeftToe']``

# sensors is basically a list of names
for s in mmvn.mvnx.subject.sensors.iterchildren():
    s.attrib

# Joints is a list that connects segment points:
for j in mmvn.mvnx.subject.joints.iterchildren():
    j.attrib["label"], j.getchildren()
```

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```

# miscellaneous:
for j in mmvn.mvnx.subject.ergonomicJointAngles.iterchildren():
    j.attrib, j.getchildren()

for f in mmvn.mvnx.subject.footContactDefinition.iterchildren():
    f.attrib, f.getchildren()

# The bulk of the data is in the frames.
frames_metadata, config_frames, normal_frames = mmvn.extract_frame_info()

# Metadata looks like this:
{'segmentCount': '23', 'sensorCount': '17', 'jointCount': '22'}

# config frames have the following fields:
['orientation', 'position', 'time', 'tc', 'ms', 'type']

# normal frames have the following fields:
['orientation', 'position', 'velocity', 'acceleration',
 'angularVelocity', 'angularAcceleration', 'footContacts',
 'sensorFreeAcceleration', 'sensorMagneticField', 'sensorOrientation',
 'jointAngle', 'jointAngleXZY', 'jointAngleErgo', 'centerOfMass', 'time',
 'index', 'tc', 'ms', 'type']

```

The following fields contain metadata about the frame:

**time** ms since start (integer). It is close to `int(1000.0 * index / samplerate)`, being equal most of the times and at most 1 milisecond away. It is neither truncated nor rounded, maybe it is given by the hardware.

**index** starts with 0, +1 each normal frame

**tc** string like '02:23:28:164'

**ms** unix timestamp like 1515983008686 (used to compute time)

**type** one of "identity", "tpose", "tpose-isb", "normal"

# The following fields are float vectors of the following dimensionality:

**orientation** `segmentCount*4 = 92` Quaternion vector

**position, velocity, acceleration, angularVelocity, angularAcceleration** `segmentCount*3 = 69`  
3D vectors in (x, y, z) format

**footContacts** 4 4D boolean vector

**sensorFreeAcceleration, sensorMagneticField** `sensorCount*3 = 51`

**sensorOrientation** `sensorCount*4 = 68`

**jointAngle, jointAngleXZY** `jointCount*3 = 66`

**jointAngleErgo** 12

**centerOfMass** 3

The units are SI for position, velocity and acceleration. Angular magnitudes are in radians except the `jointAngle`. . . ones that are in degrees. All 3D vectors are in (x, y, z) format, but the `jointAngle`. . . ones differ in the Euler-rotation order by which they are computed (ZXY, standard or XZY, for shoulders usually).

```

class io_anim_mvnx.mvnx.Mvnx(mvnx_path, mvnx_schema_path=None)
    Bases: object

```

This class imports and adapts an XML file (expected to be in MVNX format) to a Python-friendly representation. See this module's docstring for usage examples and more information.

**export** (*filepath*, *pretty\_print=True*, *extra\_comment=""*)

Saves the current mvnx attribute to the given file path as XML and adds the `self.mvnx.attrib["pythonComment"]` attribute with a timestamp.

**extract\_frame\_info** ()

**Returns** The tuple (`frames_metadata`, `config_frames`, `normal_frames`)

**static extract\_frames** (*mvnx*)

The bulk of the MVNX file is the `mvnx->subject->frames` section. This function parses it and returns its information in a python-friendly format.

**Parameters** *mvnx* – An XML tree, expected to be in MVNX format

**Returns** a tuple (`frames_metadata`, `config_frames`, `normal_frames`) where the metadata is a dict in the form `{'segmentCount': '23', 'sensorCount': '17', 'jointCount': '22'}`, the config frames are the first 3 frame entries (expected to contain special config info) and the normal\_frames are all frames starting from the 4th. Both frame outputs are relational collections of dictionaries that can be formatted into tabular form.

**extract\_joints** ()

**Returns** A tuple (X, Y). The element X is a list of the joint names ordered as they appear in the MVNX file. The element Y is a list in the original MVNX ordering, in the form `[((seg_ori, point_ori), (seg_dest, point_dest)), ...]`, where each element contains 4 strings summarizing the origin->destiny of a connection.

**extract\_segments** ()

**Returns** A list of the segment names in `self.mvnx.subject.segments` ordered by id (starting at 1 and incrementing +1).

## 1.3 io\_anim\_mvnx.mvnx\_import module

This module contains the required functionality to import an MVNX file as a moving set of bones into Blender. It allows for different options regarding their connectivity, scale...

`io_anim_mvnx.mvnx_import.global_to_inherited_quats` (*quaternions*, *joints*, *name\_to\_idx\_map*)

**Parameters**

- **quaternions** (*list*) – [q1, q2, ...]
- **joints** – A list of segment connections in the form [(parent\_name, child\_name), ...]
- **name\_to\_idx\_map** (*dict*) – A dict in the form {seg\_name: idx, ...} where The quaternion for the segment seg\_name can be found in `quaternions[idx]`.

Given the list of MVNX quaternions and their tree relations, return a list with same shape, but each quaternion is expressed relative to its parent. For that, it suffices the following calculation:

```
q_child_relative = q_parent_glob.conjugated() * q_child_glob
```

**Warning:** This function assumes that the joints are given topologically sorted, i.e. that all parents prior to the current connection have been already visited when iterating the joint list from left to right (starting with the roots, and going down the leafs in order).

```
io_anim_mvnx.mvnx_import.load_mvnx_into_blender(context,          filepath,
                                                mvnx_schema_path=None,      con-
                                                nectivity='CONNECTED',
                                                scale=1.0, report=<built-in func-
                                                tion print>, frame_start=0.0,
                                                inherit_rotations=True,
                                                add_identity_pose=True,
                                                add_t_pose=True)

io_anim_mvnx.mvnx_import.set_bone_head_and_tail(bone,      segment_points,  joints,
                                                root_points=['pHipOrigin'],
                                                leaf_points=['pTopOfHead', 'pRight-
                                                TopOfHand', 'pLeftTopOfHand',
                                                'pRightToe', 'pLeftToe'], scale=1.0)
```

### Parameters

- **bone** – an EditBone
- **segment\_points** – A dict of dicts that allows to find an offset given a joint connector. Expected: {seg\_name: {p\_name: 3d\_vector, ...}, ... }.
- **joints** – A list in the original MVNX ordering, in the form [((seg\_ori, point\_ori), (seg\_dest, point\_dest)), ...], where each element contains 4 strings summarizing the origin->destiny of a connection.
- **root\_points** (*list*) – If a given bone/segment is root (has no parent), the first match in this list will be taken as bone.head.
- **leaf\_points** (*list*) – If a given bone/segment is a leaf (has no children), the first match in this list will be taken as bone.tail.
- **scale** (*float*) – A positive float by which head and tail vectors will be multiplied.

For a given bone, this function reads the information of its parent and, given some MVNX data and assumptions, calculates its head and tail positions.

### Warning:

#### This function assumes the following:

1. If the bone has a parent, it can be found under bone.parent.
2. The head and tail of the parent have been already properly set.
3. If this bone is a root, its segment will have a point with a label in root\_points.
4. If this bone is a leaf, its segment will have a point with a label in leaf\_points.
5. For a given bone, there aren't any possible collisions between the different root or head\_points, i.e., the first match in the list will always be a good match (this happens e.g. if each leaf has a uniquely named leaf\_point, which is usually the case).

## 1.4 io\_anim\_mvnx.operators module

This module contains subclasses from `bpy.types.Operator` defining user-callable functors. Operators can also be embedded in Panels and other UI elements.

```
class io_anim_mvnx.operators.ImportMVNX
    Bases: bpy.types.Operator, bpy_extras.io_utils.ImportHelper

    Load an MVNX motion capture file. This Operator is heavily inspired in the officially supported ImportBVH.

    bl_idname = 'import_anim_mvnx'

    bl_label = 'Import MVNX'

    bl_options = {'REGISTER', 'UNDO'}

    bl_rna = <bpy_struct, Struct("IMPORT_ANIM_OT_mvnx")>

    execute(context)
        Passes the properties captured by the UI to the load_mvnx_into_blender function. :returns:
        {"FINISHED"} if everything went OK.
```

## 1.5 io\_anim\_mvnx.utils module

Utilities for interaction with Blender

```
class io_anim_mvnx.utils.ArgumentParserForBlender(prog=None, usage=None, descrip-
                                                    tion=None, epilog=None, par-
                                                    ents=[], formatter_class=<class
                                                    'argparse.HelpFormatter'>,
                                                    prefix_chars='-', from-
                                                    file_prefix_chars=None,
                                                    argument_default=None,
                                                    conflict_handler='error',
                                                    add_help=True, al-
                                                    low_abbrev=True)
```

Bases: `argparse.ArgumentParser`

This class is identical to its superclass, except for the `parse_args` method (see docstring). It resolves the ambiguity generated when calling Blender from the CLI with a python script, and both Blender and the script have arguments. E.g., the following call will make Blender crash because it will try to process the script's `-a` and `-b` flags:

```
blender --python my_script.py -a 1 -b 2
```

To bypass this issue this class uses the fact that Blender will ignore all arguments given after a double-dash ('--'). The approach is that all arguments before '--' go to Blender, arguments after go to the script. The following CLI calls work fine:

```
blender --python my_script.py -- -a 1 -b 2
blender --python my_script.py --
```

**get\_argv\_after\_doubledash** (argv)

**Parameters** `argv` (`list<str>`) – Expected to be `sys.argv` (or alike).

**Returns** The argv sublist after the first '--' element (if present, otherwise returns an empty list).

**Return type** list of str

---

**Note:** Works with any *ordered* collection of strings (e.g. list, tuple).

---

#### **parse\_args()**

This method is expected to behave identically as in the superclass, except that the `sys.argv` list will be pre-processed using `get_argv_after_doubledash` before. See the docstring of the class for usage examples and details.

---

**Note:** By default, `argparse.ArgumentParser` will call `sys.exit()` when encountering an error. Blender will react to that shutting down, making it look like a crash. Make sure the arguments are correct!

---

#### **class io\_anim\_mvnX.utils.ImportFilesCollection**

Bases: `bpy.types.PropertyGroup`

This property group allows to load multiple files from the UI file browser menu, by selecting them with shift pressed. Source and usage example:

```
https://www.blender.org/forum/viewtopic.php?t=26470
```

```
bl_rna = <bpy_struct, Struct("ImportFilesCollection")>
```

#### **class io\_anim\_mvnX.utils.KeymapManager**

Bases: list

This class implements functionality for registering/deregistering keymaps into Blender. It also behaves like a regular list, holding the keymaps currently registered. To inspect the registered keymaps simply iterate the instance.

**KEYMAP\_NAME** = 'Object Mode'

**KEYMAP\_REGION\_TYPE** = 'WINDOW'

**KEYMAP\_SPACE\_TYPE** = 'EMPTY'

**register**(*context*, *key*, *stroke\_mode*, *op\_name*, *ctrl=True*, *shift=True*, *alt=False*)

Adds a new keymap to this collection, and to the config in `context.window_manager.keyconfigs.addon`. See the API for details:

<https://docs.blender.org/api/blender2.8/bpy.types.KeyMap.html>

<https://docs.blender.org/api/blender2.8/bpy.types.KeyMapItem.html>

[https://docs.blender.org/manual/de/dev/advanced/keymap\\_editing.html](https://docs.blender.org/manual/de/dev/advanced/keymap_editing.html)

Usage example:

```
kmm = KeymapManager()
kmm.register(bpy.context, "D", "PRESS", MyOperator.bl_idname)
```

#### **Parameters**

- **context** (*bpy.types.Context*) – The Blender context to work in.
- **key** (*str*) – See `bpy.types.KeyMapItem.key_modifier`
- **stroke\_mode** (*str*) – See `bpy.types.KeyMapItem.value`



- **op\_name** (*str*) – Name of a valid operation in `bpy.ops` (usually the `bl_idname`)
- **ctrl, shift, alt** (*booleans*) – Modifiers of the key

**Returns** None

**unregister()**

Removes every mapped item from every keymap in this collection, and then empties the collection.

**class** `io_anim_mvnx.utils.OperatorToMenuManager`

Bases: `list`

This class implements functionality for adding/removing operators into Blender UI menus. It also behaves like a regular list, holding the currently registered items. Usage example:

```
omm = OperatorToMenuManager()
# In register():
omm.register(MyOperator, bpy.types.VIEW3D_MT_object)
# ... in unregister():
omm.unregister
```

**register** (*op\_class, menu\_class*)

**Parameters**

- **op\_class** (*bpy.types.Operator*) – (Sub)class handle with desired functionality.
- **menu\_class** (*bpy.types.{Header, Panel, ...}*) – Class handle for the Blender GUI where the functionality can be triggered.

---

**Note:** `op_class` must define the `bl_idname` and `bl_label` fields.

---

**unregister()**

Removes every mapped operator from every menu class in this collection, then empties the collection.

`io_anim_mvnx.utils.is_number(s)`

**Returns** True iff `s` is a number.

`io_anim_mvnx.utils.make_timestamp(timezone='Europe/Berlin')`

Output example: day, month, year, hour, min, sec, miliseconds: `10_Feb_2018_20:10:16.151`

`io_anim_mvnx.utils.resolve_path(*path_elements)`

A convenience path wrapper to find elements in this package. Retrieves the absolute path, given the OS-agnostic path relative to the package root path (by basically joining the path elements via `os.path.join`). E.g., the following call retrieves the absolute path for `<PACKAGE_ROOT>/a/b/test.txt`:

```
resolve_path("a", "b", "test.txt")
```

**Params strings** `path_elements` From left to right, the path nodes, the last one being the filename.

**Return type** `str`

`io_anim_mvnx.utils.rot_euler_degrees(rot_x, rot_y, rot_z, order='XYZ')`

**Parameters** `rot` (*float*) – Rotation angle in degrees.

**Returns** An Euler rotation object with the given rotations (converted to radians) and rotation order.

`io_anim_mvnx.utils.str_to_vec(s)`

Converts a string like `'1.23, 2.34 ...'` into a list like `[1.23, 2.34, ...]`

## 1.6 Module contents

This add-on allows you to import motion capture data in MVNX format into Blender.

After activating it, it features an operator that can be found in [File > Import/Export]. Clicking on it will open a file navigator with a set of options to customize how the MVNX will be imported into a Blender armature.

Position the mouse over the different options or read the corresponding docstrings to get more info about what do they do.

To install this add-on, make sure Blender's Python is able to find it under `addon_utils.paths()`, and that the Blender version matches to make it installable. Alternatively, run this init file as a script from Blender.

```
io_anim_mvnx.register()
```

Main register function, called on startup by Blender

```
io_anim_mvnx.unregister()
```

Main unregister function, called on shutdown by Blender

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