

tmon-p1

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1 Montecarlo Techniques - Practice 1

Andrés Herencia López-Menchero

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1.1 Old car simulation process

1.1.1 Implement the simulation model of the old car problem in R or python.

```
[1]: import numpy as np
import random

### Implement the simulation model of the old car problem in R or python.

def dtmc(N = 10**4, transitionMatrix = [[1, 0, 0, 0],
                                         [0.05, 0.50, 0.20, 0.25],
                                         [0.10, 0.75, 0, 0.15],
                                         [0, 0, 0, 1]],
         initialState = 1, finalState = 0):

    """
    Simulate a Discrete-Time Markov Chain (DTMC).

    Parameters:
    - N (int): The number of steps to simulate the Markov Chain. Default is 1000.
    - transitionMatrix (list of lists): The transition matrix representing the DTMC. Default is a 4x4 matrix.
    - initialState (int): The initial state from which the simulation starts. Default is state 1.
    - finalState (int): The absorption state, if any, at which the simulation should stop. Default is state 0.

    Returns:
    - t: A list which contains the number of steps from the initialState to the finalState in each iteration.
```

```

- p: A list which indicates whether the iteration has reach to the
↪finalState (1) or not (0).
- states: A list that saves all the states it has gone through since the
↪initial state for each iteration.
"""

# list where we will save our states
states = [initialState]
np.random.seed(123)
p = np.zeros(N) # final state reached.
t = np.full(N,np.nan) # simulation time.
states = [[] for _ in range(N)] # states.

# check if we have an absorption state
absorption_state = []
for tm in range(0,len(transitionMatrix)):
    for m in transitionMatrix[tm]:
        if (m == 1)&(transitionMatrix[tm].index(m) == tm):
            absorption_state.append(tm)

# simulation
for n in range(N):
    i = initialState
    states[n].append(i)
    while (i not in absorption_state):
        j = -1; # columns of our transition matrix (this is the 'next
↪state' column)
        pj = 0; # transition probability from state 'i' to state 'j'.
        threshold = np.random.uniform(0, 1)
        while (pj < threshold):
            j += 1
            pj = pj + transitionMatrix[i][j]
        i = j
        states[n].append(i)
        if i == finalState:
            t[n] = len(states[n])-1
            p[n] += 1
    return(t,p,states)

```

[2]: help(dtmc)

Help on function dtmc in module __main__:

```

dtmc(N=10000, transitionMatrix=[[1, 0, 0, 0], [0.05, 0.5, 0.2, 0.25], [0.1,
0.75, 0, 0.15], [0, 0, 0, 1]], initialState=1, finalState=0)
    Simulate a Discrete-Time Markov Chain (DTMC).

```

Parameters:

- N (int): The number of steps to simulate the Markov Chain. Default is 1000.
- transitionMatrix (list of lists): The transition matrix representing the DTMC. Default is a 4x4 matrix.
- initialState (int): The initial state from which the simulation starts. Default is state 1.
- finalState (int): The absorption state, if any, at which the simulation should stop. Default is state 0.

Returns:

- t: A list which contains the number of steps from the initialState to the finalState in each iteration.
- p: A list which indicates whether the iteration has reach to the finalState (1) or not (0).
- states: A list that saves all the states it has gone through since the initial state for each iteration.

1.1.2 Example of use and some metrics

```
[3]: N = 10**5
initialState = 1
finalState = 0
transitionMatrix = [[1, 0, 0, 0],
                    [0.05, 0.50, 0.20, 0.25],
                    [0.10, 0.75, 0, 0.15],
                    [0, 0, 0, 1]]

[t,p,s] = dtmc(N=N,transitionMatrix=transitionMatrix,initialState=initialState,finalState=finalState)
print('The number of steps consumed to reach to the final state in each_
iteration is '+str(t))
print('The times that our function has reached to the final state_
is',str(sum(p)), 'in',N,'simulations')
print('The history of states in',N,'simulations is',str(s[0:5]))
```

The number of steps consumed to reach to the final state in each iteration is
[nan 24. nan ... nan nan nan]

The times that our function has reached to the final state is 19887.0 in 100000 simulations

The history of states in 100000 simulations is [[1, 2, 1, 1, 2, 1, 1, 3], [1, 2, 1, 1, 1, 2, 1, 1, 1, 2, 1, 2, 1, 2, 1, 1, 1, 1, 2, 0], [1, 1, 1, 1, 1, 1, 1, 3], [1, 3], [1, 1, 2, 1, 1, 1, 3]]

1.1.3 Approximate the absorption time from Operativo to Siniestrado through simulation (years).

```
[4]: np.nanmean(dtmc(N=N, initialState = 1, finalState = 0)[0])
```

```
[4]: 3.571227435007794
```

1.1.4 Approximate through simulation the probability of absorption from Averiado to Vendido (%).

```
[5]: round(sum(dtmc(N=N, initialState = 2, finalState = 3)[1])*100/N,4)
```

```
[5]: 75.168
```