Markov Decision Process Report

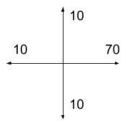
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Problem #2

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(a) Given the next value function for a MDP (equation 1): consider the figure 1 and calculate the value function for every reward state, as well as the best policy.

$$V_{i+1}(s) = \max_{a} \left\{ \sum_{s'} P_a(S, S') \left(R_a(S, S') + \gamma V_i(S') \right) \right\}$$
 (1)



S0	S1	S2	S3
S4		S5	W:+3
S6		S7	L:-1
S8	S9	S10	S11

Figure 1: MDP exercise

Solution: In order to get the function value for the MDP. We proceed to define the transitions matrix for every state S_i to the next state S_{i+n} . for every action a_i taken (up, right, down, left).

The probabilities and rewards matrices according to the actions are defined as:

	$\lceil S0 \rceil$	S1	S2	S3	S4	S5	S6	S7	S8	S9	S10	S11	W	L	7
	0	0.5	0	0	0.5	0	0	0	0	0	0	0	0	0	S0
	0.5	0	0.5	0	0	0	0	0	0	0	0	0	0	0	S1
	0	0.33	0	0.33	0	0.33	0	0	0	0	0	0	0	0	S2
	0	0	0.5	0	0	0	0	0	0	0	0	0	0.5	0	S3
	0.7	0	0	0	0	0	0.3	0	0	0	0	0	0	0	S4
	0	0	0.15	0	0	0.7	0	0.15	0	0	0	0	0.15	0	S5
$P_{up} =$	0	0	0	0	0.7	0	0	0	0.3	0	0	0	0	0	S6
·	0	0	0	0	0	0.7	0	0	0	0	0.15	0	0	0.15	S7
	0	0	0	0	0	0	0.7	0	0	0.3	0	0	0	0	S8
	0	0	0	0	0	0	0	0	0.5	0	0.5	0	0	0	S9
	0	0	0	0	0	0	0	0.7	0	0.15	0	0.15	0	0	S10
	0	0	0	0	0	0	0	0	0	0	0.3	0	0	0.7	S11
	0	0	0	0	0	0	0	0	0	0	0	0	1	0	W
	0	0	0	0	0	0	0	0	0	0	0	0	0	1	L

Figure 2: Probability matrix for action taken up

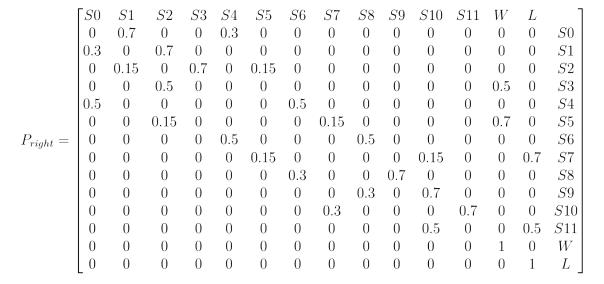


Figure 3: Probability matrix for action taken right

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S0
                S1
                      S2
                            S3
                                  S4
                                        S5
                                             S6
                                                  S7
                                                       S8
                                                            S9
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P_{down} =
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```

Figure 4: Probability matrix for action taken down

Figure 5: Probability matrix for action taken left

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                     S3
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                                      S7
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                                                         S11
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R_{up} =
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Figure 6: Reward matrix for action taken up

	S0	S1	S2	S3	S4	S5	S6	S7	S8	S9	S10	S11	W	L	
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	S0
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	S1
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	S2
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	S3
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	S4
$R_{right} =$	0	0	0	0	0	0	0	0	0	0	0	0	3	0	S5
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	S6
	0	0	0	0	0	0	0	0	0	0	0	0	0	-1	S7
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	S8
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	S9
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	S10
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	S11
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	W
	0	0	0	0	0	0	0	0	0	0	0	0	0	0	L

Figure 7: Reward matrix for action taken right

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S1
                    S2
                        S3
                            S4
                                 S5
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Figure 8: Reward matrix for action taken down

Figure 9: Reward matrix for action taken left

Value functions: From the above matrices, we can focus only in the probability where we have a reward value (Reward matrices). Starting from the S_0 to S_n , we find that the first reward value is located from the probability (P=0.5) of state S_3 to state W is the action R_{down} with a reward value of 3. As stated in the value function formula(1), we get the following value function:

$$a_{down} = (0.5)(3 + 0.1(0)) = 2.4$$
 (2)

$$V_{S_3} = \max_{a} \left\{ \sum_{s'} P_a(S, S') \left(R_a(S, S') + \gamma V_i(S') \right) \right\} = 1.5$$
 (3)

The second reward value is located from the probability (P=0.7) of state S_5 to state W is the action R_{right} with a reward value of 3:

$$a_{right} = (0.7)(3 + 0.1(0)) = 2.1$$
 (4)

$$V_{S_3} = \max_{a} \left\{ \sum_{s'} P_a(S, S') \left(R_a(S, S') + \gamma V_i(S') \right) \right\} = 2.1$$
 (5)

For the next value functions we get a negative value, according to the MDP, we avoid negative rewards so we do not take in mind. The third reward value is located from the probability (P=0.73) of state S_7 to state L is the action R_{right} with a reward value of -1:

$$a_{right} = (0.7)(-1 + 0.1(0)) = -0.7$$
 (6)

Since we only take the maximum value for the function, then:

$$V_{S_7} = \max_{a} \left\{ \sum_{s'} P_a(S, S') \left(R_a(S, S') + \gamma V_i(S') \right) \right\} = 0$$
 (7)

The fourth reward value is located from the probability (P=0.7) of state S_{11} to state L is the action R_{up} with a reward value of -1:

$$a_{up} = (0.7)(-1 + 0.1(0)) = -0.7$$
 (8)

then:

$$V_{S_{11}} = \max_{a} \left\{ \sum_{s'} P_a(S, S') \left(R_a(S, S') + \gamma V_i(S') \right) \right\} = 0$$
 (9)

Policy: The policy from the proposed problem is visualized in the next sequence:

$$policy_{(S0:S9)} = \begin{bmatrix} S0 & S1 & S2 & S3 & S4 & S5 & S6 & S7 & S8 & S9 \\ 1 & 1 & 1 & 2 & 0 & 1 & 0 & 2 & 0 & 3 \\ right & right & right & down & up & right & up & down & up & left \end{bmatrix}$$
(10)

$$policy_{(S_10:S_11)} = \begin{bmatrix} S10 & S11 \\ 3 & 3 \\ left & left \end{bmatrix}$$

$$(11)$$

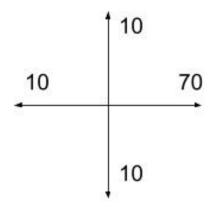




Figure 10: Environment