# cnn v12

### November 4, 2022

```
[]: %env LD_LIBRARY_PATH=$LD_LIBRARY_PATH:$CONDA_PREFIX/lib/
     #%env TF_GPU_ALLOCATOR=cuda_malloc_async
    env: LD_LIBRARY_PATH=$LD_LIBRARY_PATH:$CONDA_PREFIX/lib/
[]: import os
     print(os.environ["LD_LIBRARY_PATH"])
    $LD LIBRARY PATH: $CONDA PREFIX/lib/
[]: import tensorflow as tf
     import numpy as np
     import pandas as pd
     import os
     import matplotlib.pyplot as plt
     from tensorflow.keras import Sequential, models, Input
     from tensorflow.keras.layers import Dense, Flatten, Conv2D, MaxPooling2D,
     →Dropout, LeakyReLU, AveragePooling2D, GlobalAveragePooling2D, __
     →BatchNormalization, TimeDistributed, LSTM, SpatialDropout2D
     from tensorflow.keras.optimizers import SGD, Adam
    2022-11-03 22:13:21.588312: I tensorflow/core/platform/cpu_feature_guard.cc:193]
    This TensorFlow binary is optimized with oneAPI Deep Neural Network Library
    (oneDNN) to use the following CPU instructions in performance-critical
    operations: AVX2 FMA
    To enable them in other operations, rebuild TensorFlow with the appropriate
    compiler flags.
    2022-11-03 22:13:22.142775: E tensorflow/stream_executor/cuda/cuda_blas.cc:2981]
    Unable to register cuBLAS factory: Attempting to register factory for plugin
    cuBLAS when one has already been registered
    2022-11-03 22:13:23.284245: W
    tensorflow/stream_executor/platform/default/dso_loader.cc:64] Could not load
    dynamic library 'libnvinfer.so.7'; dlerror: libnvinfer.so.7: cannot open shared
    object file: No such file or directory; LD_LIBRARY_PATH:
    :/home/nkspartan/miniconda3/envs/tf-gpu/lib/:/home/nkspartan/miniconda3/envs/tf-
    gpu/lib/
    2022-11-03 22:13:23.284487: W
```

tensorflow/stream\_executor/platform/default/dso\_loader.cc:64] Could not load dynamic library 'libnvinfer\_plugin.so.7'; dlerror: libnvinfer\_plugin.so.7: cannot open shared object file: No such file or directory; LD\_LIBRARY\_PATH: :/home/nkspartan/miniconda3/envs/tf-gpu/lib/:/home/nkspartan/miniconda3/envs/tf-gpu/lib/

2022-11-03 22:13:23.284497: W

tensorflow/compiler/tf2tensorrt/utils/py\_utils.cc:38] TF-TRT Warning: Cannot dlopen some TensorRT libraries. If you would like to use Nvidia GPU with TensorRT, please make sure the missing libraries mentioned above are installed properly.

```
[]: from tensorflow.python.client import device_lib

print('Default GPU Device: {}'.format(tf.test.gpu_device_name()))
```

Default GPU Device: /device:GPU:0

2022-11-03 22:13:24.971054: I tensorflow/core/platform/cpu\_feature\_guard.cc:193] This TensorFlow binary is optimized with oneAPI Deep Neural Network Library (oneDNN) to use the following CPU instructions in performance-critical operations: AVX2 FMA

To enable them in other operations, rebuild TensorFlow with the appropriate compiler flags.

2022-11-03 22:13:25.006076: I

tensorflow/stream\_executor/cuda/cuda\_gpu\_executor.cc:980] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero

2022-11-03 22:13:25.050066: I

tensorflow/stream\_executor/cuda/cuda\_gpu\_executor.cc:980] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero

2022-11-03 22:13:25.050275: I

tensorflow/stream\_executor/cuda/cuda\_gpu\_executor.cc:980] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero

2022-11-03 22:13:25.934775: I

tensorflow/stream\_executor/cuda/cuda\_gpu\_executor.cc:980] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero

2022-11-03 22:13:25.935857: I

tensorflow/stream\_executor/cuda/cuda\_gpu\_executor.cc:980] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero

2022-11-03 22:13:25.936081: I

tensorflow/stream\_executor/cuda/cuda\_gpu\_executor.cc:980] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero

2022-11-03 22:13:25.936259: I

```
tensorflow/core/common_runtime/gpu/gpu_device.cc:1616] Created device
/device:GPU:0 with 4008 MB memory: -> device: 0, name: NVIDIA GeForce RTX 2060,
pci bus id: 0000:08:00.0, compute capability: 7.5
```

```
physical_devices = tf.config.list_physical_devices('GPU')
tf.config.experimental.set_memory_growth(physical_devices[0], True)
```

2022-11-03 22:13:25.991236: I

tensorflow/stream\_executor/cuda/cuda\_gpu\_executor.cc:980] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero

2022-11-03 22:13:25.992002: I

tensorflow/stream\_executor/cuda/cuda\_gpu\_executor.cc:980] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero

2022-11-03 22:13:25.992181: I

tensorflow/stream\_executor/cuda/cuda\_gpu\_executor.cc:980] successful NUMA node read from SysFS had negative value (-1), but there must be at least one NUMA node, so returning NUMA node zero

## 0.1 Read the csv dataset to get the values for stage and discharge of the images

	aı	dinead()											
[]:		Unnamed:	0	Se	ensorTime	Э		Capt	tureTime	\			
	0		0	2012-06-09	13:15:00	) 20	012-0	6-09T1	13:09:07				
	1		1	2012-06-09	13:15:00	) 20	012-0	6-09T1	13:10:29				
	2		2	2012-06-09	13:45:00	) 20	012-0	6-09T1	13:44:01				
	3		3	2012-06-09	14:45:00	) 20	012-0	6-09T1	14:44:30				
	4		4	2012-06-09	15:45:00	) 20	012-0	6-09T1	15:44:59				
					F	File	name	Agency	y SiteNu	mber	TimeZone	Stage	\
	0	StateLine	eWe:	ir_20120609_	_Farrell_	_001	.jpg	USGS	5 667	4500	MDT	2.99	
	1	StateLine	eWe:	ir_20120609_	_Farrell_	_002	.jpg	USGS	5 667	4500	MDT	2.99	
	2	StateLine	eWe:	ir_20120609_	_Farrell_	_003	.jpg	USGS	5 667	4500	MDT	2.96	
	3	StateLine	eWe:	ir_20120609_	_Farrell_	_004	.jpg	USGS	S 667	4500	MDT	2.94	
	4	StateLine	eWe:	ir_20120609_	_Farrell_	_005	.jpg	USGS	5 667	4500	MDT	2.94	
		Discharge	9	CalcTi	imestamp	•••	Weir	Pt2X	WeirPt2Y	WwF	RawLineMin	\	
	0	916.0	) :	2020-03-11T1	16:58:28	•••		-1	-1		0.0		
	1	916.0	) :	2020-03-11T1	16:58:33	•••		-1	-1		0.0		
	2	873.0	) :	2020-03-11T1	16:58:40	•••		-1	-1		0.0		
	3	846.0	) :	2020-03-11T1	16:58:47	•••		-1	-1		0.0		
	4	846.0	) :	2020-03-11T1	16:58:55	•••		-1	-1		0.0		

```
WwRawLineMax WwRawLineMean WwRawLineSigma WwCurveLineMin \
     0
                 0.0
                                0.0
                                                0.0
                                                                0.0
                 0.0
                                0.0
                                                0.0
                                                                 0.0
     1
     2
                 0.0
                                0.0
                                                                 0.0
                                                0.0
     3
                 0.0
                                0.0
                                                0.0
                                                                 0.0
                 0.0
                                0.0
                                                0.0
                                                                 0.0
       WwCurveLineMax WwCurveLineMean WwCurveLineSigma
                                    0.0
     0
                   0.0
                                                      0.0
     1
                   0.0
                                    0.0
                                                      0.0
     2
                   0.0
                                    0.0
                                                      0.0
     3
                   0.0
                                    0.0
                                                      0.0
                   0.0
                                    0.0
                                                      0.0
     [5 rows x 60 columns]
[]: df = df[["Filename", "Stage", "Discharge", 'SensorTime']]
[]: df['SensorTime'] = pd.to_datetime(df['SensorTime'])
     df['Year'] = df['SensorTime'].dt.year
     df.head()
[]:
                                      Filename
                                                Stage
                                                       Discharge \
                                                 2.99
                                                           916.0
     O StateLineWeir_20120609_Farrell_001.jpg
     1 StateLineWeir_20120609_Farrell_002.jpg
                                                 2.99
                                                           916.0
     2 StateLineWeir 20120609 Farrell 003.jpg
                                                 2.96
                                                           873.0
     3 StateLineWeir_20120609_Farrell_004.jpg
                                                 2.94
                                                           846.0
     4 StateLineWeir_20120609_Farrell_005.jpg
                                                 2.94
                                                           846.0
                SensorTime Year
     0 2012-06-09 13:15:00 2012
     1 2012-06-09 13:15:00 2012
     2 2012-06-09 13:45:00 2012
     3 2012-06-09 14:45:00
                            2012
     4 2012-06-09 15:45:00 2012
[]: df = df.sort_values(by="SensorTime", ascending=True)
     df.head()
[]:
                                      Filename
                                                Stage
                                                       Discharge \
     O StateLineWeir_20120609_Farrell_001.jpg
                                                 2.99
                                                           916.0
     1 StateLineWeir_20120609_Farrell_002.jpg
                                                 2.99
                                                           916.0
     2 StateLineWeir_20120609_Farrell_003.jpg
                                                 2.96
                                                           873.0
     3 StateLineWeir_20120609_Farrell_004.jpg
                                                 2.94
                                                           846.0
     4 StateLineWeir_20120609_Farrell_005.jpg
                                                 2.94
                                                           846.0
```

SensorTime Year

```
0 2012-06-09 13:15:00 2012
1 2012-06-09 13:15:00 2012
2 2012-06-09 13:45:00 2012
3 2012-06-09 14:45:00 2012
4 2012-06-09 15:45:00 2012
```

## 0.1.1 Remove outliers

```
[ ]: df = df[df.Stage > 0]
df = df[df.Discharge > 0]
```

We consider values equal to 0 as outliers because from the photos it doesn't seem that it would be possible that at this time we would have a value of 0 for stage or discharge

```
[]: df.shape
```

[]: (40148, 5)

#### 0.1.2 Scale the data

```
[]: from sklearn.preprocessing import StandardScaler from joblib import load

scaler = StandardScaler()
#scaler = load('std_scaler.joblib') # scaler with all the 42059 observations
```

Scale the data based only on the training dataset (in this case the training dataset is from 2012 to 2016)

```
[]: data_to_scale_fit = df[(df["Year"] >= 2012) & (df["Year"] <= 2016)][["Stage", 

→"Discharge"]]
data_to_scale_fit
```

```
[]:
            Stage
                    Discharge
     0
             2.99
                        916.0
     1
             2.99
                        916.0
     2
             2.96
                        873.0
     3
             2.94
                        846.0
             2.94
                        846.0
     4
     21416
             2.38
                        279.0
     21417
             2.38
                        279.0
     21418
             2.38
                        279.0
     21419
             2.38
                        279.0
     21420
             2.38
                        279.0
```

[20304 rows x 2 columns]

```
[]: scaler.fit(data_to_scale_fit)
[]: StandardScaler()
[]: df[["Stage", "Discharge"]] = scaler.transform(df[["Stage", "Discharge"]])
[]:
                                          Filename
                                                       Stage Discharge \
    0
           StateLineWeir_20120609_Farrell_001.jpg 0.077964
                                                             -0.136077
           StateLineWeir_20120609_Farrell_002.jpg
    1
                                                   0.077964
                                                             -0.136077
    2
           StateLineWeir_20120609_Farrell_003.jpg 0.045759
                                                             -0.165451
    3
           StateLineWeir_20120609_Farrell_004.jpg
                                                   0.024290
                                                             -0.183894
    4
           StateLineWeir_20120609_Farrell_005.jpg
                                                   0.024290
                                                             -0.183894
           StateLineWeir_20191011_Farrell_409.jpg -0.405103
    42054
                                                             -0.465332
    42055
           StateLineWeir_20191011_Farrell_410.jpg -0.405103
                                                             -0.465332
    42056
           StateLineWeir_20191011_Farrell_411.jpg -0.405103
                                                             -0.465332
    42057
           StateLineWeir_20191011_Farrell_412.jpg -0.405103
                                                             -0.465332
    42058
           StateLineWeir_20191011_Farrell_413.jpg -0.405103
                                                             -0.465332
                    SensorTime Year
    0
           2012-06-09 13:15:00 2012
    1
          2012-06-09 13:15:00 2012
           2012-06-09 13:45:00 2012
    3
          2012-06-09 14:45:00 2012
    4
           2012-06-09 15:45:00 2012
    42054 2019-10-11 09:00:00
                               2019
    42055 2019-10-11 10:00:00
                               2019
    42056 2019-10-11 11:00:00
                               2019
    42057 2019-10-11 12:00:00
                               2019
    42058 2019-10-11 12:45:00 2019
    [40148 rows x 5 columns]
[]: from joblib import dump
     #dump(scaler, 'std_scaler_train_value_0_outliers.joblib')
         Create the dataset pipeline
[]: IMG_SIZE = 224
     \#IMG\ SIZE\ =\ 512
    BATCH_SIZE = 32
    FRAMES = 10
[]: from dataset_transformer import make_dataset
```

```
[ ]: path = "../../dataset/images_tmp_draw"
     with tf.device("/gpu:0"):
         train_ds, train_size, val_ds, val_size, test_ds, test_size =__
      →make_dataset(path, BATCH_SIZE, IMG_SIZE, FRAMES, df, 10, True, "cnn")
    2022-11-03 22:13:27.304760: I
    tensorflow/stream_executor/cuda/cuda_gpu_executor.cc:980] successful NUMA node
    read from SysFS had negative value (-1), but there must be at least one NUMA
    node, so returning NUMA node zero
    2022-11-03 22:13:27.304964: I
    tensorflow/stream_executor/cuda/cuda_gpu_executor.cc:980] successful NUMA node
    read from SysFS had negative value (-1), but there must be at least one NUMA
    node, so returning NUMA node zero
    2022-11-03 22:13:27.305105: I
    tensorflow/stream_executor/cuda/cuda_gpu_executor.cc:980] successful NUMA node
    read from SysFS had negative value (-1), but there must be at least one NUMA
    node, so returning NUMA node zero
    2022-11-03 22:13:27.305466: I
    tensorflow/stream_executor/cuda/cuda_gpu_executor.cc:980] successful NUMA node
    read from SysFS had negative value (-1), but there must be at least one NUMA
    node, so returning NUMA node zero
    2022-11-03 22:13:27.305620: I
    tensorflow/stream_executor/cuda/cuda_gpu_executor.cc:980] successful NUMA node
    read from SysFS had negative value (-1), but there must be at least one NUMA
    node, so returning NUMA node zero
    2022-11-03 22:13:27.305737: I
    tensorflow/core/common_runtime/gpu/gpu_device.cc:1616] Created device
    /job:localhost/replica:0/task:0/device:GPU:0 with 4008 MB memory: -> device: 0,
    name: NVIDIA GeForce RTX 2060, pci bus id: 0000:08:00.0, compute capability: 7.5
    20304
    7117
    12727
[]: input_shape = 0
     output_shape = 0
     for image, stage_discharge in train_ds.take(1):
         print(image.numpy().shape)
         print(stage_discharge.numpy().shape)
         input_shape = image.numpy().shape[1:]
         output_shape = stage_discharge.numpy().shape[1:]
    (32, 224, 224, 3)
```

(32, 2)

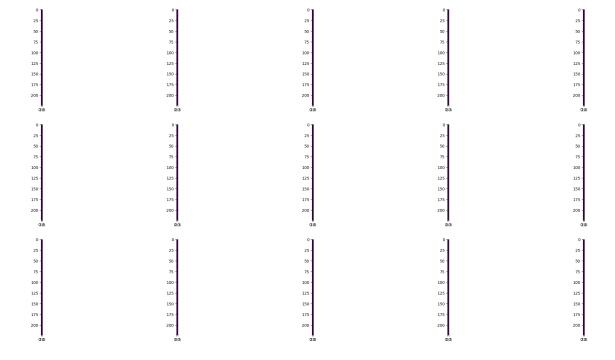
```
[]: print(input_shape) print(output_shape) (224, 224, 3)
```

(224, 224, 3, (2,)

# 0.3 Check images

```
fig, ax = plt.subplots(nrows=3, ncols=5, figsize=(30, 15))

for image, stage_discharge in test_ds.take(1):
    images = image[:15]
    for img, ax in zip(images, ax.flatten()):
        img = img.numpy()[0]
        #img = img.numpy()
        img = img / 2 + 0.5  # unnormalize
        ax.imshow(img)
```



#### 0.4 Create model

```
[]: def create_model(input_shape, output_shape, option="normal"):
         model = Sequential()
         if option == "transfer":
             base_model = tf.keras.applications.ResNet50V2(include_top=False,
                                                      weights='imagenet',
                                                      input_shape=input_shape)
             for layer in base_model.layers:
                 layer.trainable = False
             base_model._name = 'base_model_ResNet50'
             model.add(base_model)
             model.add(Dropout(0.3))
             model.add(GlobalAveragePooling2D())
             model.add(Dense(1024, activation='elu'))
             model.add(Dropout(0.3))
             model.add(Dense(512, activation='elu'))
             model.add(Dropout(0.3))
             model.add(Dense(256, activation='elu'))
             model.add(Dense(128, activation='elu'))
         elif option == "normal":
             model.add(Input(shape=input_shape))
             """model.add(Conv2D(16, kernel\_size=(3, 3), activation="elu", 
      →padding='same', kernel_initializer='he_uniform'))
             model.add(MaxPooling2D(pool size=(2, 2), strides=(2, 2)))
             model.add(BatchNormalization())
             model.add(Conv2D(32, kernel\_size=(3, 3), activation="elu", 
      →padding='same', kernel_initializer='he_uniform'))
             model.add(MaxPooling2D(pool_size=(2, 2), strides=(2, 2)))
             model.add(BatchNormalization())
             model.add(Conv2D(32, kernel_size=(3, 3), activation="elu", _
      →padding='same', kernel_initializer='he_uniform'))
             model.add(Conv2D(32, kernel size=(3, 3), activation="elu", ...
      →padding='same', kernel_initializer='he_uniform'))
             model.add(MaxPooling2D(pool_size=(2, 2), strides=(2, 2)))
             model.add(BatchNormalization())
             model.add(Conv2D(64, kernel\_size=(4, 4), activation="elu", 
      →padding='same', kernel initializer='he uniform'))
```

```
model.add(Conv2D(64, kernel\_size=(4, 4), activation="elu", 
→padding='same', kernel_initializer='he_uniform'))
       model.add(MaxPooling2D(pool_size=(2, 2), strides=(2, 2)))
       model.add(BatchNormalization())
       model.add(Conv2D(64, kernel size=(4, 4), activation="elu",,,
→padding='same', kernel_initializer='he_uniform'))
       model.add(Conv2D(64, kernel_size=(4, 4), activation="elu", __
→padding='same', kernel_initializer='he_uniform'))
       model.add(MaxPooling2D(pool_size=(2, 2), strides=(2, 2)))
       model.add(BatchNormalization())
       model.add(Conv2D(64, kernel_size=(3, 3), activation="elu", _
→padding='same', kernel_initializer='he_uniform'))
       model.add(Conv2D(64, kernel\_size=(3, 3), activation="elu", 
→padding='same', kernel_initializer='he_uniform'))
       model.add(MaxPooling2D(pool_size=(2, 2), strides=(2, 2)))
       model.add(BatchNormalization())
       model.add(GlobalAveragePooling2D())
       model.add(Dense(512, activation='elu'))
       model.add(Dropout(0.3))
       model.add(Dense(512, activation='elu'))
       model.add(Dropout(0.3))
       model.add(Dense(256, activation='elu'))
       model.add(Dense(64, activation='elu'))"""
       model.add(Conv2D(32, kernel_size=(4, 4), strides=(2, 2), u
→padding='same', activation="elu"))
       model.add(MaxPooling2D(pool_size=(2, 2)))
       model.add(Conv2D(32, kernel_size=(4, 4), strides=(2, 2), __
→activation="elu", padding='same'))
       model.add(MaxPooling2D(pool_size=(2, 2)))
       model.add(Conv2D(64, kernel_size=(3, 3), activation="elu", __
→padding='same'))
       #model.add(AveragePooling2D(pool_size=(2, 2)))
       model.add(Conv2D(64, kernel_size=(3, 3), activation='elu'))
       model.add(Conv2D(64, kernel_size=(2, 2), activation='elu'))
       model.add(MaxPooling2D(pool_size=(2, 2)))
       model.add(Conv2D(64, kernel_size=(3, 3), activation='elu'))
```

```
model.add(Conv2D(64, kernel_size=(2, 2), activation='elu'))
      model.add(MaxPooling2D(pool_size=(2, 2)))
      model.add(Flatten())
      model.add(Dense(256, activation='tanh'))
      model.add(Dropout(0.3))
      model.add(Dense(128, activation='tanh'))
      model.add(Dense(64, activation='tanh'))
      model.add(Dense(32, activation='tanh'))
   elif option == "cnn/lstm":
      base_model = tf.keras.applications.ResNet50V2(include_top=False,
                                                    weights='imagenet',
                                                    input_shape=(224, 224, 3))
      base_model.trainable = False
      base_model._name = 'base_model_ResNet50'
      model.add(Input(shape=input_shape))
      model.add(TimeDistributed(base_model))
      model.add(TimeDistributed(Dropout(0.3)))
      model.add(TimeDistributed(GlobalAveragePooling2D()))
       """model.add(Input(shape=input_shape))
      →2), padding='same', activation='elu')))
       model.add(TimeDistributed(MaxPooling2D(pool_size=(3, 3))))
       model.add(TimeDistributed(Conv2D(32, kernel size=(4, 4), strides=(2, 1)))
\hookrightarrow2), activation='elu', padding='same')))
       model.add(TimeDistributed(MaxPooling2D(pool_size=(2, 2))))
       model.add(TimeDistributed(Conv2D(32, kernel_size=(3, 3), __
→activation='elu', padding='same')))
       model.add(TimeDistributed(MaxPooling2D(pool_size=(2, 2))))
      model.add(TimeDistributed(Conv2D(32, kernel_size=(3, 3), __
\rightarrow activation='elu', padding='same')))
       model.add(TimeDistributed(MaxPooling2D(pool_size=(2, 2))))
      model.add(TimeDistributed(Flatten()))"""
      model.add(LSTM(10, return_sequences=True))
      model.add(LSTM(15))
      model.add(Dense(512, activation='elu'))
      model.add(Dense(256, activation='elu'))
```

```
model.add(Dense(128, activation='elu'))
model.add(Dense(128, activation='elu'))

model.add(Dense(output_shape, activation='linear')) # linear regression
→output layer

return model
```

```
[]: model = create_model(input_shape, output_shape[0], "transfer")
```

# []: model.summary()

Model: "sequential\_3"

Layer (type)		Param #
base_model_ResNet50 (Functional)		23564800
dropout_6 (Dropout)	(None, 7, 7, 2048)	0
<pre>global_average_pooling2d_2 (GlobalAveragePooling2D)</pre>	(None, 2048)	0
dense_10 (Dense)	(None, 1024)	2098176
dropout_7 (Dropout)	(None, 1024)	0
dense_11 (Dense)	(None, 512)	524800
dropout_8 (Dropout)	(None, 512)	0
dense_12 (Dense)	(None, 256)	131328
dense_13 (Dense)	(None, 128)	32896
dense_14 (Dense)	(None, 2)	258

\_\_\_\_\_

Total params: 26,352,258
Trainable params: 2,787,458
Non-trainable params: 23,564,800

-----

```
[]: def compile_model(loss_func, optimizer, metrics=["accuracy"]):
    model.compile(loss=loss_func, optimizer=optimizer, metrics=metrics)
```

```
[]: sgd = SGD(learning_rate=0.01, decay=1e-3, momentum=0.9, nesterov=True)
    #adam = Adam(learning_rate=1e-3, decay=1e-3 / 200)
    adam = Adam(learning_rate=1e-3, decay=1e-3 / 200)
    compile_model('mse', adam, [
                 'mse', tf.keras.metrics.RootMeanSquaredError(name='rmse'), 'mae',
     []: def fit model(training_values, validation_values=None, epochs=10, steps=32,__
     →val_steps=32, callbacks=[]):
        return model.fit(training_values, validation_data=validation_values, u
     →epochs=epochs, steps_per_epoch=steps, validation_steps=val_steps, u
     []: import datetime
    date_actual = datetime.datetime.now().strftime("%Y%m%d-%H%M%S")
    log_dir = "logs/fit/" + date_actual
    tensorboard_callback = tf.keras.callbacks.TensorBoard(log_dir=log_dir,_
     →histogram_freq=1)
    es_callback = tf.keras.callbacks.EarlyStopping(monitor='val_loss', mode='min',_
     →verbose=1, patience=8)
    checkpoint_callback = tf.keras.callbacks.
     →ModelCheckpoint(filepath=f"model_weights/{date_actual}_cnn_best_weights.
     ⇔hdf5",
                                monitor='val_loss',
                                verbose=1,
                                save_best_only=True)
[]: | # batch_size = 0 because we already have batch size in tf dataset
    with tf.device("/gpu:0"):
        model_h = fit_model(train_ds, val_ds, epochs=60, steps=np.ceil(train_size / ___
     →BATCH SIZE), val steps=np.ceil(val size / BATCH SIZE),
     →callbacks=[tensorboard_callback, checkpoint_callback, es_callback])
   Epoch 1/60
   - rmse: 0.4842 - mae: 0.2784 - mape: 140.3885
   Epoch 1: val loss improved from inf to 0.08667, saving model to
   model_weights/20221103-230002_cnn_best_weights.hdf5
   635/635 [============= ] - 80s 122ms/step - loss: 0.2343 - mse:
   0.2343 - rmse: 0.4841 - mae: 0.2784 - mape: 140.3092 - val_loss: 0.0867 -
   val mse: 0.0867 - val rmse: 0.2944 - val mae: 0.2105 - val mape: 65.5157
   Epoch 2/60
```

```
- rmse: 0.2046 - mae: 0.1448 - mape: 78.3303
Epoch 2: val_loss improved from 0.08667 to 0.07906, saving model to
model_weights/20221103-230002_cnn_best_weights.hdf5
0.0419 - rmse: 0.2046 - mae: 0.1448 - mape: 78.2950 - val loss: 0.0791 -
val_mse: 0.0791 - val_rmse: 0.2812 - val_mae: 0.1927 - val_mape: 64.4429
- rmse: 0.1748 - mae: 0.1226 - mape: 70.2164
Epoch 3: val_loss improved from 0.07906 to 0.07415, saving model to
model weights/20221103-230002_cnn_best_weights.hdf5
0.0305 - rmse: 0.1747 - mae: 0.1225 - mape: 70.1723 - val_loss: 0.0742 -
val mse: 0.0742 - val rmse: 0.2723 - val mae: 0.1817 - val mape: 60.1087
- rmse: 0.1642 - mae: 0.1144 - mape: 63.5036
Epoch 4: val_loss improved from 0.07415 to 0.06344, saving model to
model_weights/20221103-230002_cnn_best_weights.hdf5
635/635 [============ ] - 76s 119ms/step - loss: 0.0269 - mse:
0.0269 - rmse: 0.1641 - mae: 0.1144 - mape: 63.4689 - val_loss: 0.0634 -
val_mse: 0.0634 - val_rmse: 0.2519 - val_mae: 0.1574 - val_mape: 49.7525
Epoch 5/60
- rmse: 0.1496 - mae: 0.1036 - mape: 57.7936
Epoch 5: val_loss did not improve from 0.06344
635/635 [============= ] - 75s 118ms/step - loss: 0.0224 - mse:
0.0224 - rmse: 0.1496 - mae: 0.1036 - mape: 57.7635 - val_loss: 0.0652 -
val_mse: 0.0652 - val_rmse: 0.2553 - val_mae: 0.1577 - val_mape: 49.2678
Epoch 6/60
- rmse: 0.1479 - mae: 0.1024 - mape: 59.2665
Epoch 6: val_loss did not improve from 0.06344
0.0219 - rmse: 0.1479 - mae: 0.1024 - mape: 59.2348 - val loss: 0.0666 -
val_mse: 0.0666 - val_rmse: 0.2582 - val_mae: 0.1632 - val_mape: 50.4255
Epoch 7/60
- rmse: 0.1387 - mae: 0.0957 - mape: 55.0968
Epoch 7: val_loss did not improve from 0.06344
0.0192 - rmse: 0.1387 - mae: 0.0957 - mape: 55.0644 - val_loss: 0.0690 -
val_mse: 0.0690 - val_rmse: 0.2627 - val_mae: 0.1642 - val_mape: 59.2706
Epoch 8/60
- rmse: 0.1572 - mae: 0.1047 - mape: 58.8439
Epoch 8: val_loss did not improve from 0.06344
635/635 [============= ] - 75s 119ms/step - loss: 0.0247 - mse:
```

```
0.0247 - rmse: 0.1571 - mae: 0.1047 - mape: 58.8113 - val_loss: 0.0781 -
val_mse: 0.0781 - val_rmse: 0.2794 - val_mae: 0.1724 - val_mape: 55.7035
Epoch 9/60
- rmse: 0.1568 - mae: 0.1041 - mape: 59.2239
Epoch 9: val_loss did not improve from 0.06344
0.0246 - rmse: 0.1568 - mae: 0.1041 - mape: 59.1929 - val_loss: 0.0802 -
val_mse: 0.0802 - val_rmse: 0.2831 - val_mae: 0.1682 - val_mape: 48.9895
Epoch 10/60
- rmse: 0.1302 - mae: 0.0882 - mape: 51.5287
Epoch 10: val loss improved from 0.06344 to 0.06236, saving model to
model weights/20221103-230002 cnn best weights.hdf5
0.0170 - rmse: 0.1302 - mae: 0.0881 - mape: 51.4980 - val_loss: 0.0624 -
val_mse: 0.0624 - val_rmse: 0.2497 - val_mae: 0.1509 - val_mape: 58.8778
Epoch 11/60
- rmse: 0.1205 - mae: 0.0821 - mape: 50.1194
Epoch 11: val loss improved from 0.06236 to 0.05849, saving model to
model weights/20221103-230002 cnn best weights.hdf5
0.0145 - rmse: 0.1205 - mae: 0.0821 - mape: 50.0889 - val_loss: 0.0585 -
val_mse: 0.0585 - val_rmse: 0.2419 - val_mae: 0.1437 - val_mape: 44.7324
Epoch 12/60
- rmse: 0.1211 - mae: 0.0813 - mape: 47.9710
Epoch 12: val_loss did not improve from 0.05849
0.0147 - rmse: 0.1211 - mae: 0.0813 - mape: 47.9434 - val_loss: 0.1153 -
val_mse: 0.1153 - val_rmse: 0.3395 - val_mae: 0.2035 - val_mape: 49.4566
Epoch 13/60
- rmse: 0.1203 - mae: 0.0804 - mape: 48.8194
Epoch 13: val loss did not improve from 0.05849
0.0145 - rmse: 0.1202 - mae: 0.0804 - mape: 48.7864 - val_loss: 0.0618 -
val_mse: 0.0618 - val_rmse: 0.2487 - val_mae: 0.1561 - val_mape: 63.2799
Epoch 14/60
- rmse: 0.1137 - mae: 0.0762 - mape: 43.7422
Epoch 14: val_loss did not improve from 0.05849
0.0129 - rmse: 0.1137 - mae: 0.0762 - mape: 43.7214 - val_loss: 0.0601 -
val_mse: 0.0601 - val_rmse: 0.2451 - val_mae: 0.1567 - val_mape: 58.1463
Epoch 15/60
```

```
- rmse: 0.1088 - mae: 0.0739 - mape: 43.2454
   Epoch 15: val_loss did not improve from 0.05849
   0.0118 - rmse: 0.1088 - mae: 0.0739 - mape: 43.2178 - val_loss: 0.0681 -
   val_mse: 0.0681 - val_rmse: 0.2610 - val_mae: 0.1638 - val_mape: 59.8237
   Epoch 16/60
   - rmse: 0.1445 - mae: 0.0915 - mape: 52.1147
   Epoch 16: val loss did not improve from 0.05849
   635/635 [============== ] - 72s 113ms/step - loss: 0.0209 - mse:
   0.0209 - rmse: 0.1445 - mae: 0.0915 - mape: 52.0831 - val_loss: 0.0629 -
   val mse: 0.0629 - val rmse: 0.2509 - val mae: 0.1527 - val mape: 51.7619
   Epoch 17/60
   - rmse: 0.1091 - mae: 0.0733 - mape: 43.4485
   Epoch 17: val_loss did not improve from 0.05849
   0.0119 - rmse: 0.1090 - mae: 0.0733 - mape: 43.4247 - val_loss: 0.0628 -
   val_mse: 0.0628 - val_rmse: 0.2505 - val_mae: 0.1556 - val_mape: 52.8115
   Epoch 18/60
   - rmse: 0.1158 - mae: 0.0766 - mape: 43.6014
   Epoch 18: val_loss did not improve from 0.05849
   635/635 [============= ] - 72s 113ms/step - loss: 0.0134 - mse:
   0.0134 - rmse: 0.1160 - mae: 0.0767 - mape: 43.5898 - val_loss: 0.0890 -
   val mse: 0.0890 - val rmse: 0.2984 - val mae: 0.1766 - val mape: 57.7655
   Epoch 19/60
   - rmse: 0.1460 - mae: 0.0934 - mape: 55.5282
   Epoch 19: val_loss did not improve from 0.05849
   0.0213 - rmse: 0.1460 - mae: 0.0934 - mape: 55.4964 - val_loss: 0.0698 -
   val_mse: 0.0698 - val_rmse: 0.2643 - val_mae: 0.1614 - val_mape: 55.8318
   Epoch 19: early stopping
   0.5 Evaluate model
[]: print(date_actual)
   20221103-230002
[]: best_model = models.load_model(f'model_weights/{date_actual}_cnn_best_weights.
    →hdf5')
   #best model = models.load model(f'best models weights/cnn best weights v9.hdf5')
[]: def evaluate_model(model, test_values, steps):
     score = model.evaluate(test_values, steps=steps)
```

```
return score
[]: test_loss, test_mse, test_rmse, test_mae, test_mape =_
     →evaluate model(best model, test ds, steps=np.ceil(test size / BATCH SIZE))
    0.0540 - rmse: 0.2324 - mae: 0.1440 - mape: 68.1599
[]: #predictions = best_model.predict(test_ds, steps=np.ceil(test_size /u
     →BATCH SIZE))
[]: for image, stage_discharge in test_ds.take(1):
            predictions = best_model.predict(x=image)
            stage_discharge_test_values = stage_discharge.numpy()
            predictions_values = predictions
            diff = predictions_values.flatten() - stage_discharge_test_values.
     →flatten()
            percentDiff = (diff / stage_discharge_test_values.flatten()) * 100
            absPercentDiff = np.abs(percentDiff)
            # compute the mean and standard deviation of the absolute percentage
            # difference
            mean = np.mean(absPercentDiff)
            std = np.std(absPercentDiff)
            # finally, show some statistics on our model
            print(mean)
            print(std)
            stage_discharge_test_values = stage_discharge[:10]
            stage_discharge_test_values = stage_discharge_test_values.numpy().
     \rightarrowreshape(10, 2)
            predictions_values = predictions[:10]
            for i in range(len(stage_discharge_test_values)):
                   print(f"pred stage: {scaler.
     →inverse_transform(predictions_values)[i][0]}, actual stage: {scaler.
     →inverse_transform(stage_discharge_test_values)[i][0]}")
                   print(f"pred discharge: {scaler.
     →inverse_transform(predictions_values)[i][1]}, actual discharge: {scaler.
     →inverse_transform(stage_discharge_test_values)[i][1]}")
    1/1 [======= ] - Os 495ms/step
    79.2600525051517
    218.17216149864743
    pred stage: 2.4097249507904053, actual stage: 2.31
    pred discharge: 284.9043884277344, actual discharge: 210.000000000001
```

```
pred stage: 2.463397979736328, actual stage: 2.41
pred discharge: 332.1559753417969, actual discharge: 210.000000000001
pred stage: 3.3087246417999268, actual stage: 2.67
pred discharge: 1338.3272705078125, actual discharge: 210.0000000000001
pred stage: 2.3510382175445557, actual stage: 2.43
pred discharge: 257.7505187988281, actual discharge: 210.0000000000001
pred stage: 2.4264814853668213, actual stage: 2.42
pred discharge: 329.0776672363281, actual discharge: 210.000000000001
pred stage: 2.7900302410125732, actual stage: 2.71
pred discharge: 804.0298461914062, actual discharge: 210.000000000001
pred stage: 2.40978741645813, actual stage: 2.71
pred discharge: 290.5561828613281, actual discharge: 210.0000000000001
pred stage: 2.2910003662109375, actual stage: 2.76
pred discharge: 218.1156768798828, actual discharge: 210.0000000000001
pred stage: 2.5312607288360596, actual stage: 2.89
pred discharge: 354.0725402832031, actual discharge: 210.0000000000001
pred stage: 2.907449245452881, actual stage: 2.82
pred discharge: 1025.2611083984375, actual discharge: 210.0000000000001
```

#### 0.5.1 Residual analysis

```
[]: y_predictions = np.empty(shape=(1, 2)).astype('float32')
y_real = np.empty(shape=(1, 2)).astype('float32')

for image, stage_discharge in test_ds.take(100):
    y_predictions = np.concatenate((y_predictions, best_model.predict(x=image)))
    y_real = np.concatenate((y_real, stage_discharge.numpy()))
```

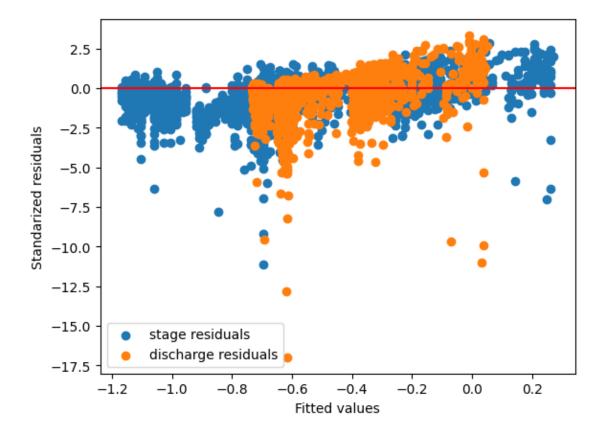
```
1/1 [=======] - Os 22ms/step
1/1 [======] - Os 23ms/step
1/1 [=======] - Os 22ms/step
1/1 [======= ] - 0s 22ms/step
1/1 [=======] - Os 21ms/step
1/1 [======= ] - Os 21ms/step
1/1 [======] - 0s 22ms/step
1/1 [======= ] - 0s 22ms/step
1/1 [=======] - Os 22ms/step
1/1 [======= ] - 0s 22ms/step
1/1 [=======] - Os 22ms/step
1/1 [======= ] - Os 22ms/step
1/1 [======] - Os 22ms/step
1/1 [=======] - Os 21ms/step
1/1 [======] - 0s 21ms/step
1/1 [=======] - Os 21ms/step
1/1 [======= ] - 0s 21ms/step
1/1 [=======] - Os 22ms/step
1/1 [======= ] - 0s 22ms/step
1/1 [======= ] - 0s 22ms/step
```

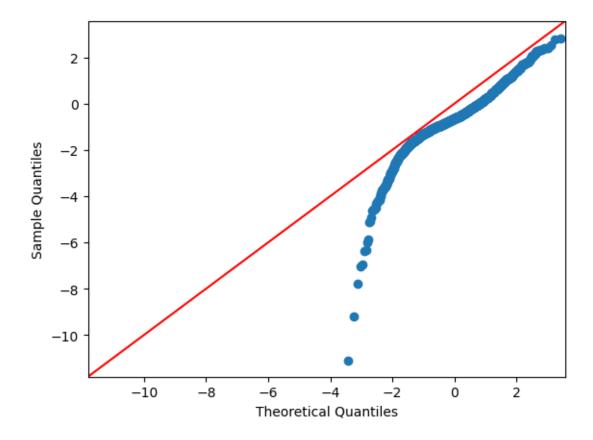
```
1/1 [======= ] - Os 21ms/step
1/1 [======= ] - 0s 25ms/step
1/1 [=======] - Os 22ms/step
1/1 [======== ] - Os 21ms/step
1/1 [=======] - 0s 22ms/step
1/1 [=======] - 0s 21ms/step
1/1 [=======] - 0s 21ms/step
1/1 [======] - Os 21ms/step
1/1 [======= ] - Os 22ms/step
1/1 [======= ] - Os 21ms/step
1/1 [=======] - Os 22ms/step
1/1 [=======] - Os 21ms/step
1/1 [======] - Os 21ms/step
1/1 [=======] - Os 22ms/step
1/1 [======] - Os 21ms/step
1/1 [=======] - 0s 25ms/step
1/1 [======] - Os 21ms/step
1/1 [=======] - 0s 25ms/step
1/1 [=======] - 0s 21ms/step
1/1 [=======] - 0s 21ms/step
1/1 [======= ] - Os 22ms/step
1/1 [======] - Os 21ms/step
1/1 [======= ] - Os 22ms/step
1/1 [======] - 0s 22ms/step
1/1 [======] - Os 21ms/step
1/1 [=======] - Os 21ms/step
1/1 [=======] - Os 21ms/step
1/1 [=======] - 0s 23ms/step
1/1 [======== ] - 0s 22ms/step
1/1 [=======] - Os 21ms/step
1/1 [======] - Os 21ms/step
1/1 [=======] - Os 21ms/step
1/1 [======] - 0s 21ms/step
1/1 [=======] - 0s 25ms/step
1/1 [=======] - 0s 22ms/step
1/1 [=======] - 0s 21ms/step
1/1 [======= ] - Os 22ms/step
1/1 [======] - Os 22ms/step
1/1 [======= ] - Os 22ms/step
1/1 [=======] - 0s 21ms/step
1/1 [======= ] - Os 21ms/step
1/1 [=======] - Os 21ms/step
1/1 [======] - Os 21ms/step
1/1 [=======] - Os 21ms/step
1/1 [======] - Os 21ms/step
1/1 [=======] - 0s 23ms/step
1/1 [======] - 0s 20ms/step
1/1 [======] - Os 21ms/step
```

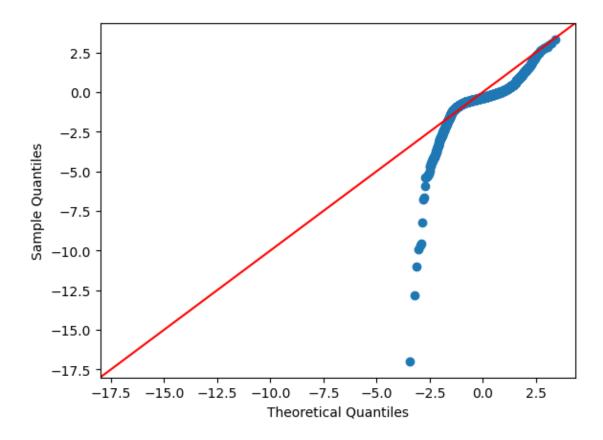
```
1/1 [=======] - Os 22ms/step
  1/1 [======] - 0s 22ms/step
  1/1 [======= ] - Os 21ms/step
  1/1 [=======] - 0s 20ms/step
  1/1 [======= ] - Os 21ms/step
  1/1 [=======] - 0s 21ms/step
  1/1 [=======] - Os 21ms/step
  1/1 [======] - Os 21ms/step
  1/1 [======= ] - Os 21ms/step
  1/1 [=======] - Os 22ms/step
  1/1 [=======] - Os 21ms/step
  1/1 [=======] - Os 21ms/step
  1/1 [======== ] - 0s 21ms/step
  1/1 [=======] - Os 21ms/step
  1/1 [=======] - 0s 21ms/step
  1/1 [=======] - 0s 21ms/step
  1/1 [======= ] - Os 21ms/step
  1/1 [======] - Os 21ms/step
  1/1 [=======] - Os 21ms/step
  1/1 [======] - Os 21ms/step
  1/1 [======] - Os 21ms/step
  1/1 [=======] - 0s 21ms/step
  1/1 [======== ] - 0s 21ms/step
  1/1 [=======] - 0s 21ms/step
  1/1 [======== ] - 0s 21ms/step
  1/1 [=======] - Os 22ms/step
  1/1 [======] - Os 21ms/step
  1/1 [=======] - Os 21ms/step
[]: residuals = y_real - y_predictions
   residuals_std = residuals/residuals.std()
   y_real_stage = np.array([i[0] for i in y_real])
   residual_stage = np.array([i[0] for i in residuals])
   y_real_discharge = np.array([i[1] for i in y_real])
   residual_discharge = np.array([i[1] for i in residuals])
   print(residual_stage.std())
   plt.scatter(y_real_stage, residual_stage / residual_stage.std(), label="stage_
   →residuals")
```

1/1 [======= ] - 0s 21ms/step

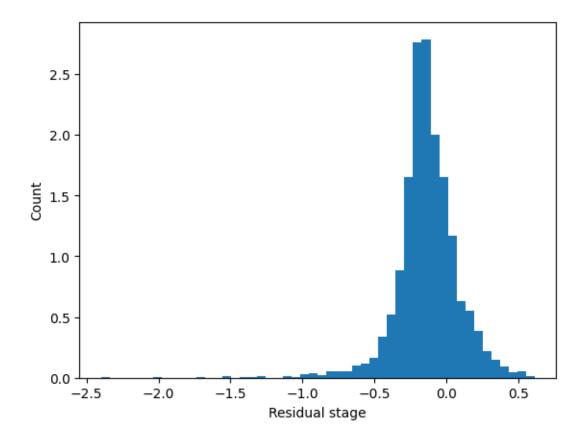
## 0.21593582108796294



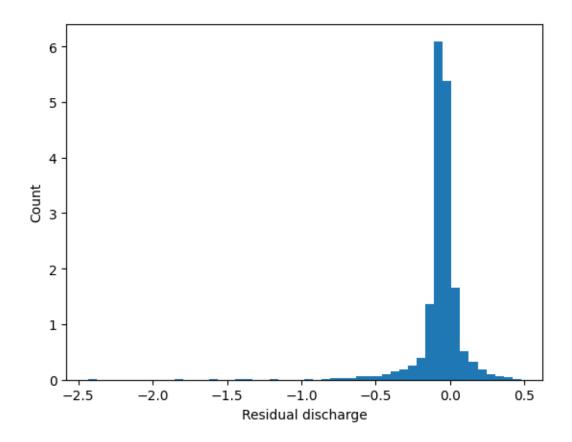




```
[]: plt.hist(residual_stage, density=True, bins = 50)
plt.ylabel('Count')
plt.xlabel('Residual stage');
plt.show()
```



```
[]: plt.hist(residual_discharge, density=True, bins = 50)
   plt.ylabel('Count')
   plt.xlabel('Residual discharge');
   plt.show()
```



```
[]: stat, pval = normal_ad(residual_stage)
print("p-value:", pval)

if pval<0.05:
    print("Hay evidencia de que los residuos no provienen de una distribución
    →normal.")
else:
    print("No hay evidencia para rechazar la hipótesis de que los residuos
    →vienen de una distribución normal.")
```

p-value: 0.0 Hay evidencia de que los residuos no provienen de una distribución normal.

```
[]: stat, pval = normal_ad(residual_discharge)
print("p-value:", pval)

if pval < 0.05:
    print("Hay evidencia de que los residuos no provienen de una distribución
    →normal.")
else:
```

```
print("No hay evidencia para rechazar la hipótesis de que los residuos_{\sqcup} _{\hookrightarrow}vienen de una distribución normal.")
```

p-value: 0.0

Hay evidencia de que los residuos no provienen de una distribución normal.

# 0.6 Visualize layers

```
ValueError
                                           Traceback (most recent call last)
Cell In [95], line 3
      1 layer_outputs = [layer.output for layer in best_model.layers[:12]]
      2 # Extracts the outputs of the top 12 layers
----> 3 activation_model = models.Model(inputs=best_model.input,_
→outputs=layer_outputs)
File ~/miniconda3/envs/tf-gpu/lib/python3.10/site-packages/tensorflow/python/
→trackable/base.py:205, in no automatic dependency tracking.<locals>.
→ method_wrapper(self, *args, **kwargs)
    203 self._self_setattr_tracking = False # pylint: disable=protected-access
    204 try:
          result = method(self, *args, **kwargs)
--> 205
    206 finally:
          self._self_setattr_tracking = previous_value # pylint:__
\hookrightarrow disable=protected-access
File ~/miniconda3/envs/tf-gpu/lib/python3.10/site-packages/keras/engine/
 →functional.py:165, in Functional.__init__(self, inputs, outputs, name,__
 →trainable, **kwargs)
    156
            if not all(
    157
    158
                    functional_utils.is_input_keras_tensor(t)
    159
                    for t in tf.nest.flatten(inputs)
    160
                ]
            ):
    161
                inputs, outputs = functional_utils.clone_graph_nodes(
    162
    163
                    inputs, outputs
    164
--> 165 self._init_graph_network(inputs, outputs)
File ~/miniconda3/envs/tf-gpu/lib/python3.10/site-packages/tensorflow/python/
 →trackable/base.py:205, in no automatic dependency tracking. <locals>.
→_method_wrapper(self, *args, **kwargs)
```

```
203 self._self_setattr_tracking = False # pylint: disable=protected-access
    204 try:
          result = method(self, *args, **kwargs)
--> 205
    206 finally:
    207
          self. self setattr tracking = previous value # pylint:
 →disable=protected-access
File ~/miniconda3/envs/tf-gpu/lib/python3.10/site-packages/keras/engine/
 →functional.py:264, in Functional. init graph network(self, inputs, outputs)
             self._input_coordinates.append((layer, node_index, tensor_index))
    263 # Keep track of the network's nodes and layers.
--> 264 nodes, nodes_by_depth, layers, _ = _map_graph_network(
             self.inputs, self.outputs
    266 )
    267 self._network_nodes = nodes
    268 self._nodes_by_depth = nodes_by_depth
File ~/miniconda3/envs/tf-gpu/lib/python3.10/site-packages/keras/engine/

→functional.py:1128, in _map_graph_network(inputs, outputs)

   1126 for x in tf.nest.flatten(node.keras inputs):
             if id(x) not in computable tensors:
-> 1128
                 raise ValueError(
                     f"Graph disconnected: cannot obtain value for "
   1129
                     f'tensor {x} at layer "{layer.name}". '
   1130
   1131
                     "The following previous layers were accessed "
                     f"without issue: {layers_with_complete_input}"
   1132
   1133
                 )
   1134 for x in tf.nest.flatten(node.outputs):
   1135
             computable_tensors.add(id(x))
ValueError: Graph disconnected: cannot obtain value for tensor
→KerasTensor(type_spec=TensorSpec(shape=(None, 224, 224, 3), dtype=tf.float32,
→name='input_4'), name='input_4', description="created by layer 'input_4'") at →layer "conv1_pad". The following previous layers were accessed without issue:
 \hookrightarrow []
```

```
[]: activations = activation_model.predict(test_ds.take(1))
```

```
Running cells with 'Python 3.9.13 ('tf-metal')' requires ipykernel package.

Run the following command to install 'ipykernel' into the Python environment.

Command: 'conda install -n tf-metal ipykernel --update-deps --force-reinstall'
```

```
[]: import matplotlib.pyplot as plt
     layer_names = []
     for layer in best_model.layers[:12]:
         layer_names.append(layer.name) # Names of the layers, so you can have them_
      →as part of your plot
     images_per_row = 16
     for layer_name, layer_activation in zip(layer_names, activations): # Displays_
      \hookrightarrow the feature maps
         n_features = layer_activation.shape[-1] # Number of features in the feature_
         size = layer_activation.shape[1] #The feature map has shape (1, size, size, __
      \rightarrow n_{\text{features}}).
         n_cols = n_features // images_per_row # Tiles the activation channels in_
      \rightarrow this matrix
         display_grid = np.zeros((size * n_cols, images_per_row * size))
         print(layer_name)
         if "flatten" in layer_name or "dense" in layer_name: break
         for col in range(n_cols): # Tiles each filter into a big horizontal grid
             for row in range(images_per_row):
                 channel_image = layer_activation[0,
                                                    :,:,
                                                    col * images_per_row + row]
                 channel_image -= channel_image.mean() # Post-processes the feature_
      → to make it visually palatable
                 channel_image /= channel_image.std()
                 channel_image *= 64
                 channel_image += 128
                 channel_image = np.clip(channel_image, 0, 255).astype('uint8')
                 display_grid[col * size : (col + 1) * size, # Displays the grid
                               row * size : (row + 1) * size] = channel_image
         scale = 1. / size
         plt.figure(figsize=(scale * display_grid.shape[1],
                              scale * display_grid.shape[0]))
         plt.title(layer name)
         plt.grid(False)
         plt.imshow(display_grid, aspect='auto', cmap='viridis')
```

```
Running cells with 'Python 3.9.13 ('tf-metal')' requires ipykernel package.

Run the following command to install 'ipykernel' into the Python environment.
```

Command: 'conda install -n tf-metal ipykernel --update-deps --force-reinstall'