

CV

Programming Language: Java

Project #9

Hough Transform

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Due Date:

Soft copy: 4/12/2020

Hard copy: 4/12/2020

\*\*\*\*\*Main\*\*\*\*\*

```
Step 0:      inFile ← open input file from args
            outFile1, outFile2 ← open from args
            numRows, numCols, minVal, maxVal ← read from inFile
            HoughAngle ← 180
            HoughDist ← 2 * (the diagonal of the input image)
            imgAry ← dynamically allocate
            HoughAry ← dynamically allocate HoughAry, size of
                        HoughDist by HoughAngle and initialize to zero
```

```
Step 1: loadImage(imgAry, inFile)
```

```
Step 2: buildHoughSpace (imageAry)
```

```
Step 3: prettyPrint(HoughAry, outFile1)
```

```
Step 4: determineMinMax (HoughAry)
```

```
Step 5: write HoughDist, HoughAngle, HoughMinVal, HoughMaxVal to outFile2
        // as the header of Hough image
```

```
step 6: ary2File (HoughAry, outFile2) // output HoughAry to outFile2
```

```
Step 7: close all files
```

**Source code:**

```
import java.util.*;
import java.io.*;
import java.lang.Math;

public class Main{
    public static void main(String args[]){
        ImageProcessing image = new ImageProcessing();
        HoughTransform hough = new HoughTransform();

        Scanner inFile = null;
        PrintWriter outFile1 = null;
        PrintWriter outFile2 = null;

        // 0
        try {
            inFile = new Scanner(new File(args[0]));
        } catch (FileNotFoundException err) {
            System.out.println("Error in opening input file from CLI: " + err);
        }

        try {
            outFile1 = new PrintWriter(args[1]);
            outFile2 = new PrintWriter(args[2]);
        } catch (FileNotFoundException err) {
            System.out.println("Error in opening output files from CLI: " + err);
        }

        image.numRows = inFile.nextInt();
        image.numCols = inFile.nextInt();
        image.minVal = inFile.nextInt();
        image.maxVal = inFile.nextInt();

        // dynamically allocating imgAry
        image.imgAry = new int[image.numRows][image.numCols];

        // HOUGH STUFF
        //  $a^2 + b^2 = c^2$ 
        int diagonal = (int) Math.sqrt( Math.pow(image.numRows, 2) + Math.pow(image.numCols, 2)
);

        hough.HoughAngle = 180;
        hough.HoughDist = 2 * diagonal;
        hough.HoughAry = new int[hough.HoughDist][hough.HoughAngle];

        // 1
        image.loadImage(inFile);

        // 2
        hough.buildHoughSpace(image);

        // 3
        hough.prettyPrint(outFile1);

        // 4
        hough.determineMinMax();

        // 5
        outFile2.println(hough.HoughDist + " " + hough.HoughAngle + " " + hough.HoughMinVal + " "
+ hough.HoughMaxVal);

        // 6
        hough.ary2File(outFile2);

        // 7
        // Closing files
        inFile.close();
        outFile1.close();
        outFile2.close();
    }
}
```

```

}

public class ImageProcessing {
    int numRows;
    int numCols;
    int minVal;
    int maxVal;

    int[][] imgAry;

    ImageProcessing(){
        numRows = 0;
        numCols = 0;
        minVal = 0;
        maxVal = 0;
    }

    void loadImage(Scanner inFile){
        for(int i = 0; i < numRows; i++){
            for(int j = 0; j < numCols; j++){
                imgAry[i][j] = inFile.nextInt();
            }
        }
    }

}

public class xyCoord{
    int x;
    int y;
}

public class HoughTransform {

    xyCoord point = new xyCoord();
    int angleInDegree;
    double angleInRadians;

    int HoughDist;
    int HoughAngle = 180;
    int HoughMinVal;
    int HoughMaxVal;
    int[][] HoughAry;

    // Functions

    void buildHoughSpace(ImageProcessing image){
        for(int r = 0; r < image.numRows; r++){
            for(int c = 0; c < image.numCols; c++){

                if(image.imgAry[r][c] > 0){
                    point.x = c;
                    point.y = r;

                    angleInDegree = 0;

                    while(angleInDegree <= 179){

```

```

        angleInRadians = angleInDegree/180.00 * Math.PI;
        double dist = computeDistance(point, angleInRadians);
        int distInt = (int) dist;
        HoughAry[distInt][angleInDegree]++;
        angleInDegree++;
    }
}

double computeDistance(xyCoord point, double angleInRadians){
    double a = angleInRadians;
    double x = point.x ;
    double y = point.y ;

    double c = Math.atan(y/x);
    double t = a - c - (Math.PI/2);

    double distance = ( Math.sqrt(Math.pow(x, 2)+Math.pow(y, 2)) ) * Math.cos(t) +
(HoughDist/2);

    // System.out.println(distance);

    return distance;
}

void determineMinMax() {
    int max = 0;

    for(int i = 0; i < HoughDist; i++){
        for(int j = 0; j < HoughAngle; j++){
            if(HoughAry[i][j] > max){ max = HoughAry[i][j];}
        }
    }

    HoughMaxVal = max;
    int min = max;

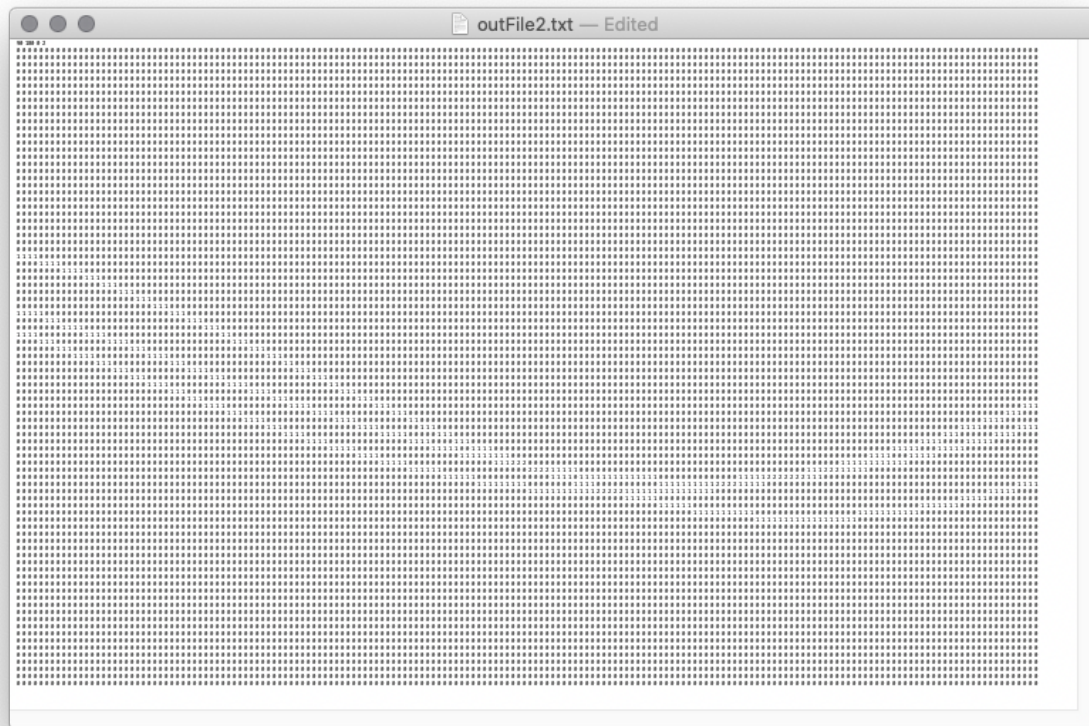
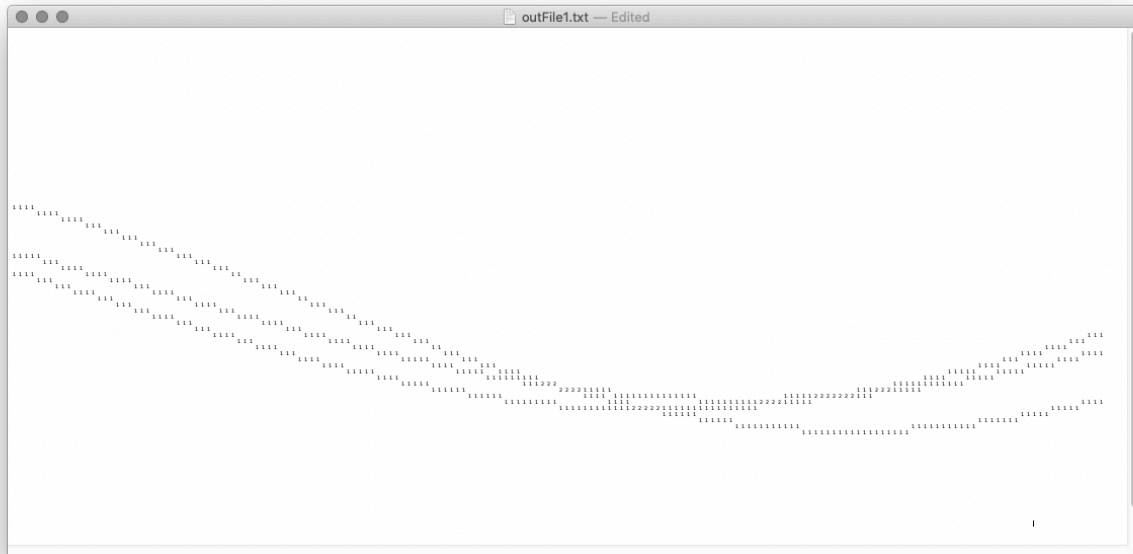
    for(int i = 0; i < HoughDist; i++){
        for(int j = 0; j < HoughAngle; j++){
            if(HoughAry[i][j] < min){ min = HoughAry[i][j];}
        }
    }
    HoughMinVal = min;
}

void prettyPrint(PrintWriter outFile){
    for(int i = 0; i < HoughDist; i++){
        for(int j = 0; j < HoughAngle; j++){
            if(HoughAry[i][j] > 0) {outFile.print(HoughAry[i][j] + " ");}
            else {outFile.print(" ");}
        }
        outFile.println();
    }
}

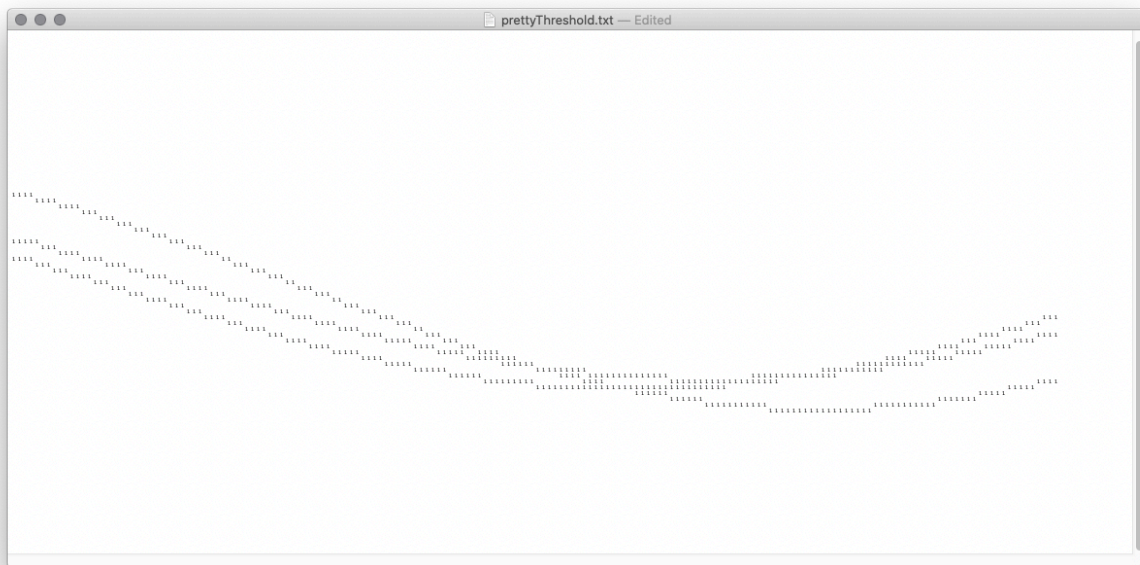
void ary2File(PrintWriter outFile){
    for(int i = 0; i < HoughDist; i++){
        for(int j = 0; j < HoughAngle; j++){
            if(HoughAry[i][j] > 0) {outFile.print(HoughAry[i][j] + " ");}
            else {outFile.print("0 ");}
        }
        outFile.println();
    }
}
}

```

## Outputs for 2pts



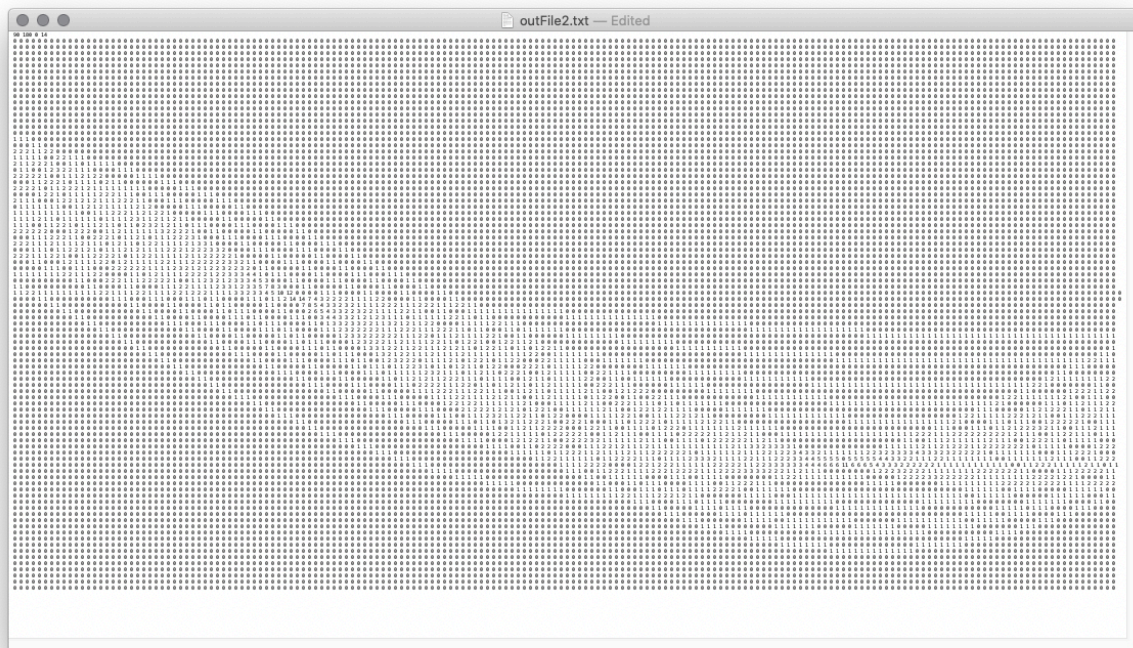
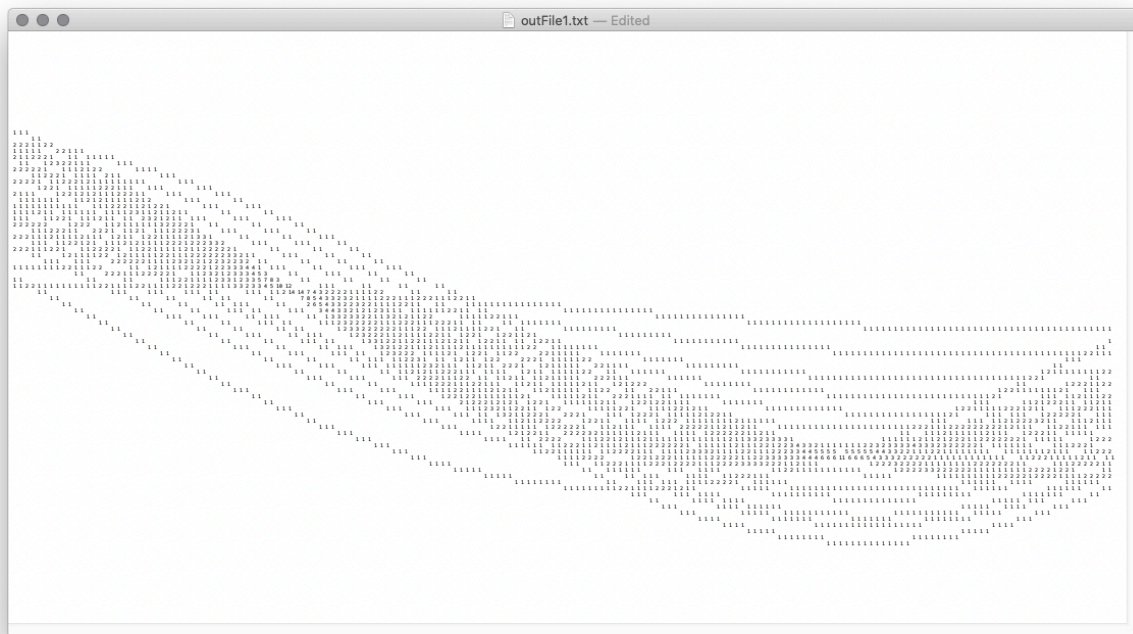
```
histogram.txt
90 180 0 2
0 (15686):+++++
1 (488):+++++
2 (26):+++++
```



END OF 2pt OUTPUTS



## Outputs for 2lines



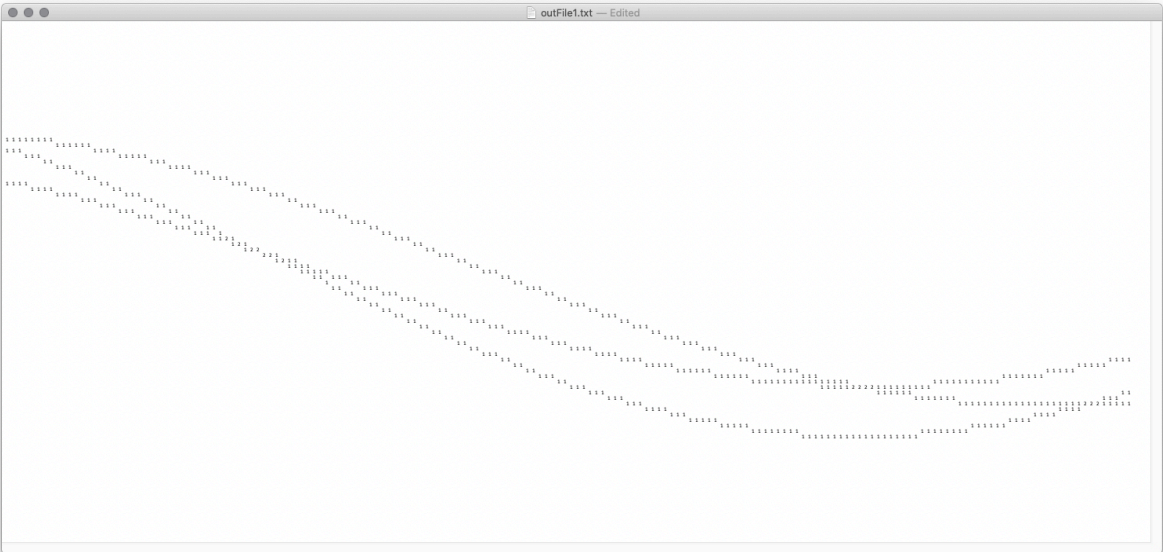
```
90 180 0 14
0 (13014):+++++
1 (2343):+++++
2 (690):+++++
3 (102):+++++
4 (19):+++++
5 (15):+++++
6 (7):+++++
7 (3):+++
8 (2):++
9 (0):
10 (1):+
11 (1):+
12 (1):+
13 (0):
14 (2):++
```

```
prettyThreshold.txt — Edited
```

END OF 2lines OUTPUTS



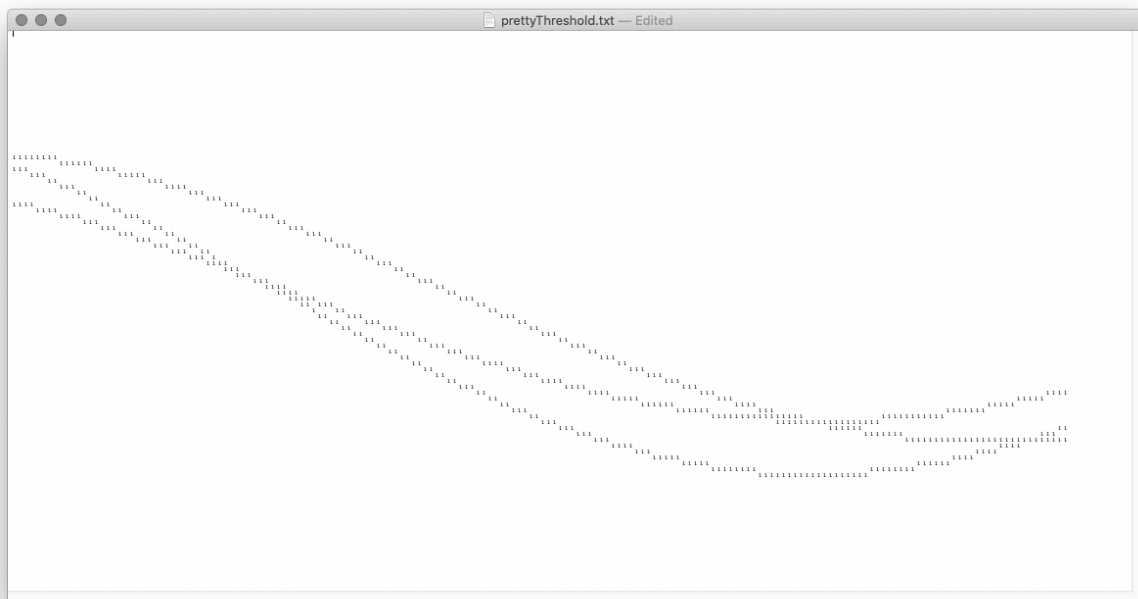
Outputs for 3pts



```

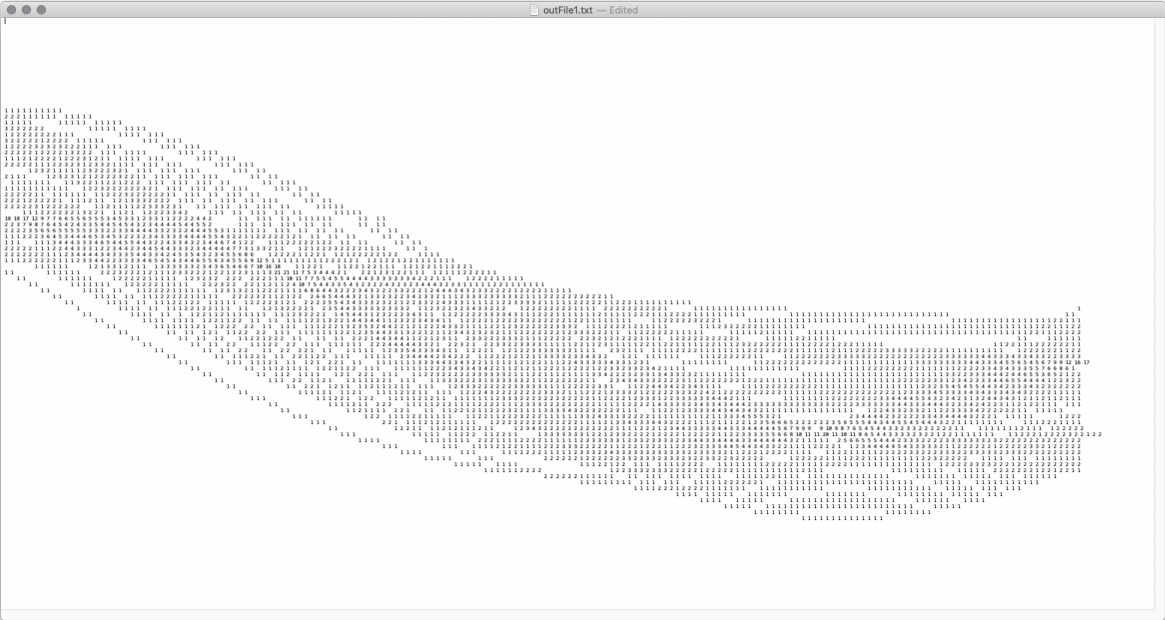
p0 180 0 2
0 (15674):+++++
1 (512):+++++
2 (14):+++++

```



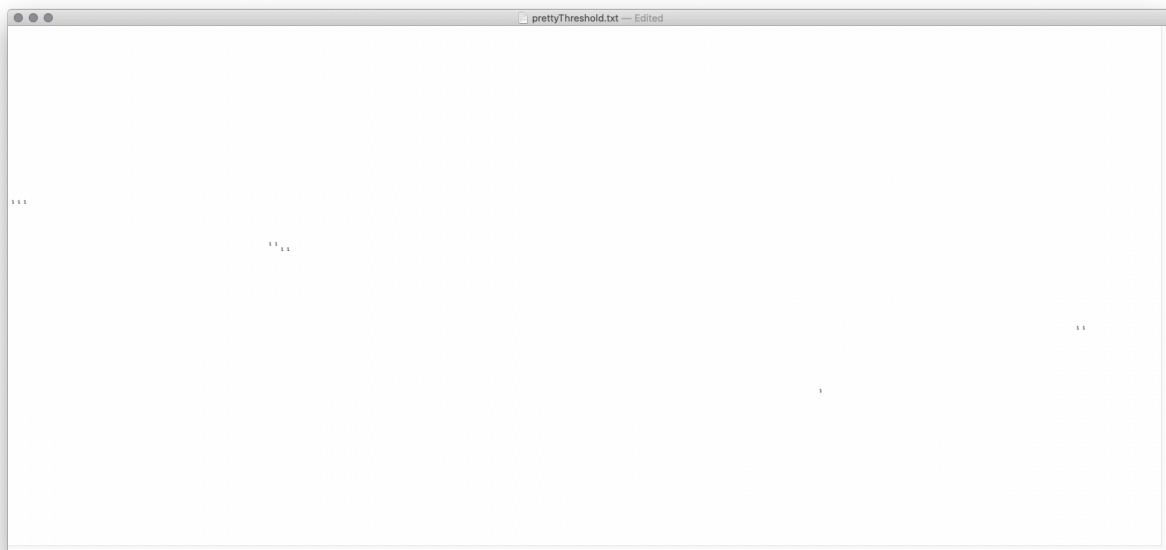
END OF 3pts OUTPUTS

Outputs for 3lines





```
90 180 0 21
0 (11071):+++++
1 (2417):+++++
2 (1528):+++++
3 (684):+++++
4 (299):+++++
5 (101):+++++
6 (42):+++++
7 (16):+++++
8 (7):+++++
9 (10):+++++
10 (6):+++++
11 (6):+++++
12 (3):+++
13 (0):
14 (0):
15 (0):
16 (2):++
17 (2):++
18 (3):+++
19 (0):
20 (1):+
21 (2):++
```



END OF 3lines OUTPUTS