

Von Karman Viscous Pump

Andreas Slyngstad

18. april 2016

Abstract

Consider a tube filled with a newtonian viscous fluid initially at rest. Upon applying a pressure-gradient, a pressuredriven flow will occur known as Hagen–Poiseuille flow. Limiting ourselves to steady state case, we will derive an analytical solution for this problem. Our goal is to validate the Oasis software, a high-performance Navier-Stokes solver based on the opensoure Fenics software. The solver is based on the finite element method and implemented in python.

Navier-Stokes Equation

Let the velocity vector components be defined as $\mathbf{v} = (v_r, v_\theta, v_z)$ The balance of momentum within the fluid introduces the famous Navier-Stokes equations. By assuming that fluid fluid is incompressible, we get the Navier-Stokes eqations as

$$\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} = -\frac{\nabla p}{\rho} + \frac{\mu}{\rho} \nabla^2 \mathbf{v} \quad (1)$$

$$\nabla \cdot \mathbf{v} = 0 \quad (2)$$

Limiting ourselves to the steady-state case of a fully developed fluid, following component equations.

$$r : \quad v_r \frac{\partial v_r}{\partial r} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial r} + \frac{\mu}{\rho} \left(\frac{\partial^2 v_r}{\partial r^2} + \frac{1}{r} \frac{\partial v_r}{\partial r} + \frac{\partial^2 v_r}{\partial z^2} - \frac{v_r}{r^2} \right) \quad (3)$$

$$\theta : \quad v_r \frac{\partial v_\theta}{\partial r} + v_z \frac{\partial v_\theta}{\partial z} + \frac{1}{r} v_\theta v_r = \frac{\mu}{\rho} \left(\frac{\partial^2 v_\theta}{\partial r^2} + \frac{1}{r} \frac{\partial v_\theta}{\partial r} + \frac{\partial^2 v_\theta}{\partial z^2} - \frac{v_\theta}{r^2} \right) \quad (4)$$

$$z : \quad v_r \frac{\partial v_z}{\partial r} + \frac{\partial v_z}{\partial z} = \frac{1}{\rho} \frac{\partial p}{\partial z} + \frac{\mu}{\rho} \left(\frac{\partial^2 v_z}{\partial r^2} + \frac{1}{r} \frac{\partial v_z}{\partial r} + \frac{\partial^2 v_z}{\partial z^2} \right) \quad (5)$$

nevn senere hva som kan fjernes i teori

On Laminar flow

The following calculations is based on a flow regime said to be laminar. This kind of flow is recognized by smoothed streamlines, to the opposite of turbulent flow characterized by fluctuations in the velocity profile. These flow regimes are bound by the dimensionless Reynolds number discovered Osborne Reynolds as the relation between inertial and viscous forces.

$$Re = \frac{\rho U D}{\mu} = \frac{U D}{\nu} \quad (6)$$

Where ν denotes the kinematic viscosity, while U and D is some characteristic velocity and lenght. In our case U will be average velocity and U and D is the diameter of the pipe. We define the

Reynolds number at which the flow becomes fully turbulent as the critical Reynolds number. For flow inside a pipe, the most common accepted value for the critical Reynolds number is

$$\text{Re} = 2300.$$

We will further simplify the Navier-Stokes equations by specifying certain conditions for the fluid flow. We will for simplicity look at a constructed test case for a straight tube with constant diameter, with a fully developed laminar flow. From this we can conclude that we have a fluid flow with the property of constant axial velocity, and no radial or angular velocity. Further we will assume that the fluid is driven by a pressure gradient parallel to the axial direction. For the boundaries we will assume noslip condition at the circumference of the tube, and dirichlet boundary conditions for the pressure at the inflow and outflow regions. For the velocity we use do-nothing"conditions at the inflow and outflow of the domain.

Let Ω be our computational domain, and let $\partial\Omega$ denote the boundaries of the domain. Our conditions then can be defined as

$$\text{In } \Omega \quad (7)$$

$$(8)$$

$$\frac{\partial v}{\partial t} = 0 \quad (9)$$

$$v \cdot \nabla v = 0 \quad (10)$$

$$v_r = v_\theta = 0 \quad (11)$$

$$(12)$$

$$\text{In } \partial\Omega \quad (13)$$

$$(14)$$

$$v = 0 \in \Gamma_N \quad (15)$$

$$P = \text{ASJEKK GOD NOTASJON} \quad (16)$$

TEGning Problem

Now lets imagine extracting a ring-shaped control volume from the fluid flow and assess the forces acting on this volume. Let this control volume have thickness dr and width dx . SETT INN BILDE Due to the balance of momentum the following forces must balance each other. As observed the only acting forces are the pressure and viscous forces, denoted as p and τ

$$2\pi r P_x dr - 2\pi r P_{x+\delta x} dr + 2\pi r dx \tau_r - 2\pi r dx \tau_{r+\delta r} = 0 \quad * \left(\frac{1}{2\pi r dx} \right) \quad (17)$$

$$r \frac{P_{x+\delta x} - P_x}{dx} + \frac{r(\tau_{r+\delta r} - \tau_r)}{dr} = 0 \quad (18)$$

In the limit $dr, dx \rightarrow 0$, we get the following equation

$$r \frac{dP}{dx} + \frac{d(r\tau)}{dr} = 0 \quad (19)$$

Now by replacing τ with $-\mu \frac{du}{dx}$ where the constant μ denotes the dynamic viscosity. Now, this means that choice of x or r , the relation (10) must be fulfilled. Hence we must conclude that $\frac{dP}{dx}$ must be some constant. This constant can be derived by changing our control volume with a slice at any point in the tube. Using the same relations it can be shown that

$$\frac{dP}{dx} = \frac{-2\tau_W}{R} \quad (20)$$

Where τ_W denotes the wall shear stress.

We now solve the second order differential equation(10), using double integration

$$u(r) = \frac{1}{4\mu} \frac{dP}{dx} + C_1 \ln(r) + C_2 \quad (21)$$

To remove the non-physical consequence of $\lim_{r \rightarrow 0} \ln r \rightarrow \infty$ for the velocity update, we choose $C1 = 0$. By using our second condition $u(R) = 0$ where R denotes the tube of the radius, the final analytical result yields

$$u(r) = -\frac{1}{4\mu} \frac{dP}{dx} (R^2 - r^2) \quad (22)$$

For scaling of the numerical experiments the

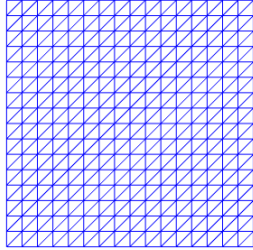
Setting up the problem

Using Oasis, we can choose between two sets of solver methods, coupled and fracstep. **Coupled** is a steady-state solver, while fracstep is a fractional step solver for solving the Navier-Stokes equations which we will use. Further specification of the schemes of solver can be specified for the fracstep module, but for our case we will choose the IPCN ABCN method which stands for Incremental Pressure Correction Scheme, using second order Crank-Nicolson in time and Adams-Bashforth projection to calculate the convecting velocity. KILDE TIL DETTE??

For validation, we will construct a 2D and 3D case for the poiseuille flow and compare the numerical calculations against our analytical results. Both the coupled and fracstep modules will be implemented. For the computation we have to construct a mesh to do our calculations upon. In these problems we will use Gmsh, a free 3D finite element grid generator for the 3D case, and FEniCS own mesh module for the 2D case.

KILDE: Mikael sin side

Implementing 2D pipe



Computational domain $\Omega = [0, 1]^2$
 Inflow Condition $P_{in} = 1$
 Outflow Condition $P_{out} = 0$
 $\nu = 1/8$

For the coupled solver, our goal is to approximate the fully analytical steady-state flow in 2D. In the case for the fracstep solver, we will try to imitate the calculations from (Logg, 2012), where the numerical calculations are compared to the analytical axial velocity $v(1, 0.5)$ at time $T = 0.5$ shown as.

$$u_x(1, 0.5, t) = 1 - \sum_{N=1,3,..}^{\infty} \frac{32}{\pi^3 n^3} e^{-\frac{\pi^2 n^2}{8}} (-1)^{\frac{(n-1)}{2}}$$

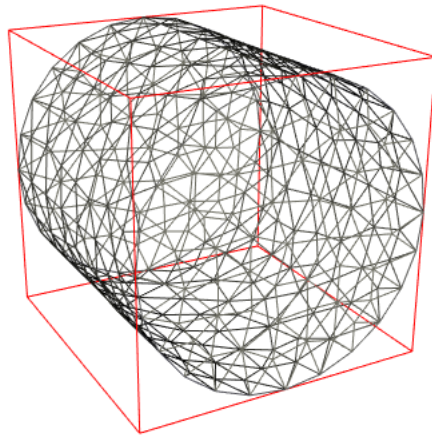
$$u_x(1, 0.5, 0.5) \approx 0.44321183655681595$$

Implementing 3D pipe

Computational domain $\Omega = [0, 1]^2$

Inflow Condition $P_{in} = 1$

Outflow Condition $P_{out} = 0$



Figur 1: A gull

For the 3D case aswell, we have the analytical solution for the fully steady-state flow. Here we will for both coupled and fracstep measure the error for the steady-state case.

Results

Implementing 2D pipe