# MEK 4250 Elementmethod Mandatory Assignment

Andreas Slyngstad

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# 1 Exercise 1

In these set of exercises we will study the Stokes problem defined as

$$-\Delta u + \nabla p = f \text{ in } \Omega$$
$$\nabla \cdot v = 0 \text{ in } \partial \Omega$$
$$u = g \text{ in } \partial \Omega_N$$
$$\frac{\partial u}{\partial x} - pn = h \text{ in } \partial \Omega_N$$

First off we will define the weak formulation for the stokes problem. Let  $\mathbf{u} \in H^1_{D,g}$  and  $p \in L^2$ . Then the stokes problem can be defined as

$$a(u,v)+b(p,v)=f(v) \ v\in H^1_{D,0}$$
 
$$b(q,u)=0 \ q\in L^2$$

Where a and b defines the bilinear form, and f defines the linear form as

$$a(u,v) = \int \nabla u : \nabla v \, dx$$
$$b(p,v) = \int p \nabla \cdot v \, dx$$
$$f(v) = \int fv \, dx + \int_{\Omega_N} hv \, ds$$

Further we will define to properties which will be usefull for solving the exercises Cauchy-Schwarts inequality

Let V be a inner product space, then

$$|\langle u, v \rangle| \le ||u|| \cdot ||w|| \ \forall \ v, q \in V$$

Poincare's Inequality Let  $v \in H_0^1(\Omega)$ 

$$||v||_{L^2(\Omega)} \le C|v|_{H^1}(\Omega)$$

### Exercise 7.1

In this section we are to prove the conditions (7.14-7.16) from the course lecturenotes. Starting off with the first **Condition 7.14** 

$$a(u_h, v_h) \le C_1 ||u_n||_{V_n} ||v_n||_{V_n} \quad \forall u_n, v_n \in V_n$$

As for in all of these conditions we will assume that  $V_h \in H_0^1$ , and for later conditions that  $Q_h \in L^2$ . First off we write out the term  $a(u_h, v_h)$ , and we observe we can use the Cauchy-Schwarts inequality since V is an inner product space.

$$a(u_h, v_h) = \int_{\Omega} \nabla u_h : \nabla v_h \, dx = \langle \nabla u_h, \nabla v_h \rangle$$
$$\langle \nabla u_h, \nabla v_h \rangle \leq |\langle \nabla u_h, \nabla v_h \rangle|_0 \leq ||\nabla u_h|| \cdot ||\nabla v_h||$$

Now since we have defined that  $u_h, v_h \in V_h \in H_0^1$  we can use the Poincare inequality. First we observe that

$$||\nabla u_h||_{L^2}^2 \le ||u_h||_{H^1}^2 = ||u_h||_{L^2}^2 + ||\nabla u_h||_{L^2}^2 \le C_1|u_h|_{H_1}^2 + ||\nabla u_h||_{L^2}^2 = C_1||\nabla u_h||_{L^2}^2 + ||\nabla u_h||_{L^2}^2$$

$$(C_1 + 1)||\nabla u_h||_{L^2}^2 \le D||u_h||_{H^1}^2$$

#### Condition 7.14

$$b(u_h, q_h) \le C_2 ||u_h||_{V_h} ||q_h||_{Q_h} \ V_h \in H_0^1, \ Q_h \in L^2,$$

By direct insertion we get

$$b(u_h, q_h) = \int p \nabla \cdot v \, dx = \langle p, \nabla \cdot u \rangle \le |\langle p, \nabla \cdot u \rangle|_0$$

Using the Cauchy-Schwarts inequality we can show that

$$|\langle q, \nabla \cdot u \rangle| < ||q||_0 \cdot ||\nabla \cdot u||_0$$

Hence, it holds to show that

$$||q||_0 \cdot ||\nabla \cdot u||_0 \le C_2 ||u_h||_1 ||q_h||_0$$
  
 $||\nabla \cdot u||_0 \le C_2 ||u_h||_1$ 

We choose square the left side of the inequality and expand the norm, in hope of finding a term to determine the upper bound of b. Applying the poincare inequality on line 2, we can determine that the bound must be determined by some constant  $C_2$ 

$$||\nabla \cdot u||_0^2 \le ||u||_1^2 = ||u||_0^2 + ||\nabla u||_0^2$$

$$||u||_0^2 + ||\nabla u||_0^2 \le C_2^2 |u|_1 + ||\nabla u||_0^2 = (C_2^2 + 1)||\nabla u||_0^2 = C_2^2 ||\nabla u||_0^2$$

Hence, to show the implied boundedness of b, it holds to show  $||\nabla \cdot u||_0^2 \le (C_2^2 + 1)||\nabla u||_0^2$  For simplicity we write out the terms for the  $R^2$  case, but the same proof can be showed for the general case  $R^n$ .

$$||\nabla \cdot u||_0^2 = \int \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial y^2}\right)^2 dx$$
$$||\nabla u||_0^2 = \int \left(\frac{\partial^2 u}{\partial x^2}\right)^2 + \left(\frac{\partial^2 u}{\partial y^2}\right)^2 + \left(\frac{\partial^2 v}{\partial x^2}\right)^2 + \left(\frac{\partial^2 v}{\partial y^2}\right)^2 dx$$

Remembering that since we are in a normed vector space V, the triangle inequality holds.

$$||x + y|| \le ||x|| + ||y|| \ \forall x, y \in V$$

Rearrangeing the terms we observe that

$$||\nabla \cdot u||_0^2 = \int \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial y^2}\right)^2 dx$$

$$||\nabla u||_0^2 = \int \left(\frac{\partial^2 u}{\partial x^2}\right)^2 + \left(\frac{\partial^2 v}{\partial y^2}\right)^2 dx + \int \left(\frac{\partial^2 v}{\partial x^2}\right)^2 + \left(\frac{\partial^2 u}{\partial y^2}\right)^2 dx$$

$$\sqrt{\int \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial y^2}\right)^2 dx} \le \sqrt{\int \left(\frac{\partial^2 u}{\partial x^2}\right)^2} + \sqrt{\left(\frac{\partial^2 v}{\partial y^2}\right)^2 dx}$$

Hence  $||\nabla \cdot u||_0^2 \le C_2^2 ||\nabla u||_0^2$ , and the inequality holds. Condition 7.16, Coersivity of a

$$a(u_h, u_h) \ge C_3 ||u_h||_{V_h}^2 \quad \forall u_h \in V_h$$

Expanding the  $H^1$  norm of  $u_h$ , and applying the Cauchy-Schwarts inequality we find the relations

$$||u_h||_1^2 = ||u_h||_0^2 + ||\nabla u_h||_0^2 \le C|u_h|_1^2 + ||\nabla u_h||_0^2$$
$$= C||\nabla u_h||_0^2 + ||\nabla u_h||_0^2 = (C+1)||\nabla u_h||_0^2 = C_3||\nabla u_h||_0^2$$

Dividing the constant on both sides of the inequality and let  $C_3 = 1/C_3$  we get our final result which proofs the coersivity of a

$$|C_3||u_h||_1^2 \le ||\nabla u_h||_0^2 = \int \nabla u_h : \nabla u_h \, dx = a(u_h, u_h)$$

#### 1.1 Exercise 7.6

Looking on the poiseuille flow, we are to investigate if the anticipated convergence rates applies for the problem

$$-\Delta u - \nabla p = f \text{ in } \Omega$$
$$\nabla \cdot v = 0 \text{ in } \partial \Omega$$

We will make use of the "manufactured solution" approach defining the analytical solution in  $\Omega$  and finding the appropriate soruce function as

$$u = (\sin(\pi y), \cos(\pi x)); \quad p = \sin(2\pi x)$$
$$f = (\pi^2 \sin(\pi y) - 2\pi \cos(2\pi x), \pi^2 \cos(\pi x))$$

We will this exercise examinate the error estimate

$$||u - u_h||_1 + ||p - p_h||_0 \le Ch^k ||u||_{k+1} + Dh^{l+1} ||p||_l + 1$$

Where k, l denotes the polynomial degree of the velocity and pressure. The error estimate will be examined using  $(P_4 - P_3)$ ,  $(P_4 - P_2)$ ,  $(P_3 - P_2)$  and  $(P_3 - P_1)$  elements for velocity and pressure accordingly. The problem will be solved on a UnitSquareMesh(N, N), for N = [8, 16, 32, 64]. Order of convergence is calculated for each choice of elements, between to neighbouring N values defined as

$$r = \frac{log\left(\frac{E[i+1]}{E[i]}\right)}{log\left(\frac{(h[i+1]}{h[i]}\right)}$$

Where E is a list of errornorms and h is a list of the facetlength in the mesh defined as  $\frac{1}{N}$ 

Tabell 1: Convergence rate velocity,  $E = ||u - u_h||_1$ 

N	Conv 4 to 8	Conv 8 to 16	Conv 16 to 32	Conv 32 to 64
4-3	4.53315	4.2951	4.11514	4.03954
4-2	2.6871	2.88045	2.96138	2.98766
3-2	2.57912	2.84778	2.9518	2.98466
3-1	2.17924	2.08939	2.04646	2.02452

Tabell 2: Convergence rate velocity,  $E = ||p - p_h||_0$ 

N	Conv 4 to 8	Conv 8 to 16	Conv 16 to 32	Conv 32 to 64
4-3	4.22147	4.08419	4.02915	4.01063
4-2	2.71627	2.89978	2.97342	2.99382
3-2	2.71694	2.90114	2.97394	2.99397
3-1	2.35349	2.19402	2.09554	2.04362

To describe these results we have to take a closer look on the error estimate. Let us choose the dataset from the  $(P_4 - P_3)$  computation. For k = 4 and p = 3 we get.

$$||u - u_h||_1 + ||p - p_h||_0 \le Ch^4||u||_5 + Dh^4||p||_4$$

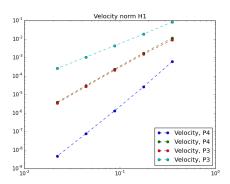
Observing that C,D,  $||u||_{5}$  and  $||p||_{4}$  are some constants and will not effect the trend of the error estimate, we see that the error is limited to  $h^{4}$ , both for the velocity and pressure norm. From our result this seems reasonable as we can see the order of convergence approach 4.

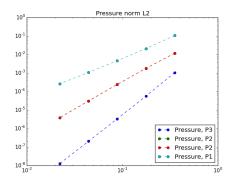
What about if we choose some elements which differ in degree by 2? Let's choose the  $(P_4 - P_2$  computation and see what is going on. Our error estimate then yields

$$||u - u_h||_1 + ||p - p_h||_0 \le Ch^4 ||u||_5 + Dh^3 ||p||_3$$

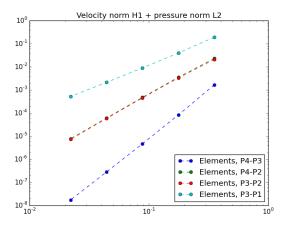
Now as the velocity norm on the right side of the inequality is dominated by the h term, we obsere that this term will go faster to zero than the pressure norm. Hence our calculations should be dominated by the pressure norm. From this logic we would expect the order of convergence to be limited by 3. As we can see from the numerical results, this seems legit as we can see that the rate of convergence approaches 3 as the mesh gets finer.

## loglogplot





loglogplot



#### 1.2 Exercise 7.7

In this exercise we where to calculate the order of convergence for the shear stress in the same domain presented en exercise 7.6.