

Designing Incentives for Multitasking Agents: Evidence from Payments to English Physicians

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Incentive Design in Principal-Agent Problems

- ▶ Central to theory and applications
 - ▶ (e.g. healthcare, education, org econ)
- ▶ Often actions and outcomes are high-dimensional
 - ▶ doctor chooses tests, prescriptions → clinical outcomes
 - ▶ teacher chooses topics and methods → test scores, human capital, etc
 - ▶ salesperson chooses advertising, discounts → sales, renewals, rating
- ▶ Often there is multitasking : higher effort in one outcome influences the cost of other outcomes [[Holmstrom and Milgrom, 1991](#)]

Empirical models of multitasking

- ▶ Counterfactuals require estimates of
 - ▶ distribution of types
 - ▶ technology: interaction between outcomes
- ▶ Each “task” potential interacts with all other tasks
 - ▶ → dimensionality and variation needed for identification grow quickly
- ▶ Most applied work focuses on testing

This Paper

- ▶ Empirically tractable model of multitasking
- ▶ Sufficient conditions for identification
- ▶ Application to Quality of Outcomes Framework in England (2009-2019)
 - ▶ possibly world's largest P4P scheme in primary care
- ▶ Strong evidence of
 - ▶ physicians responding to incentives
 - ▶ interactions between indicators
- ▶ Practice location is exogenous shifter of patient composition
- ▶ Estimate model & counterfactual design of incentives

Literature

- ▶ Empirical models of multitasking: Slade [1996], Buser and Peter [2012], Hong, Hossain, List, and Tanaka [2018], Goes, Ilk, Lin, and Zhao [2018], Manthei and Sliwka [2019], Rodríguez-Lesmes and Vera-Hernández [2021], Kim, Sudhir, and Uetake [2022], Dinerstein and Oppen [2022]
 - ▶ We go beyond testing
 - ▶ We can consider counterfactual design
- ▶ Pay-for-performance in healthcare: Gaynor et al. [2004], Dumont et al. [2008], Mullen et al. [2010], Choné and Ma [2011], Clemens and Gottlieb [2014], Li et al. [2014], Einav et al. [2018], Gupta [2021], Rodríguez-Lesmes and Vera-Hernández [2021], Einav et al. [2022], Gaynor et al. [2023], Dunn et al. [2024], Shi [2024], and many more
 - ▶ We incorporate multitasking
 - ▶ We focus on primary care in non-US context

Roadmap

- 1 Setting and Data
- 2 Model
- 3 Demand
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GP practices (GPPs)

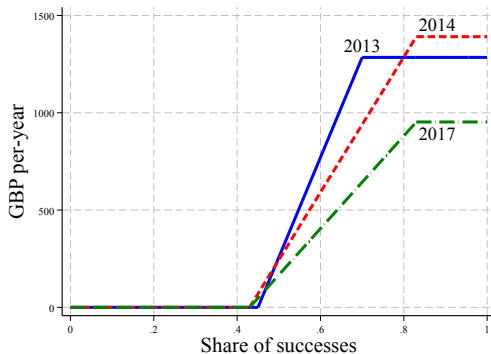
- ▶ GPPs provide primary care: prescriptions, minor interventions, referral to secondary care
- ▶ Approximately 8000 GPPs in England
- ▶ Each GPP has about 10 doctors (but we study GPPs)
- ▶ Zero prices to patients
- ▶ Revenue:
 - ▶ $\approx 75\%$ capitation (# of individuals registered, mild risk adjustment)
 - ▶ $\approx 25\%$ financial incentives, mainly from QOF

- ▶ Gives GPPs yearly financial incentives to perform certain tasks (“indicators”):
 - ▶ “The percentage of patients aged 75 or over with a fragility fracture on or after 1 April 2012, who are currently treated with an appropriate bone-sparing agent”
 - ▶ “The percentage of patients on the chronic kidney disease (CKD) register in whom the last blood pressure reading, measured in the previous 15 months, is 140/85 or less.”
- ▶ Started 2004, changes over time in
 - ▶ intensity of incentives
 - ▶ which tasks are incentivized
- ▶ Voluntary participation (95.1% in 2019)
- ▶ Total payments \approx £1B
- ▶ Electronic record-keeping \rightarrow minimal errors / cheating
- ▶ We focus on 40 indicators that are “truly clinical”

QOF payments

- ▶ Indicator j has n_j relevant patients
- ▶ If task is successful for k_j patients, achievement is $k_j/n_j = y_j \in [0,1]$
- ▶ Revenue per patient for indicator j is $\rho_{jt}(y_{ijt})$: piece-wise linear with slope α_{jt} and thresholds $\underline{y}_{jt}, \overline{y}_{jt}$:

DM11: % diabetes patients in whom the last glycohaemoglobin IFCC-HbA1c is 64 mmol/mol or less



Data

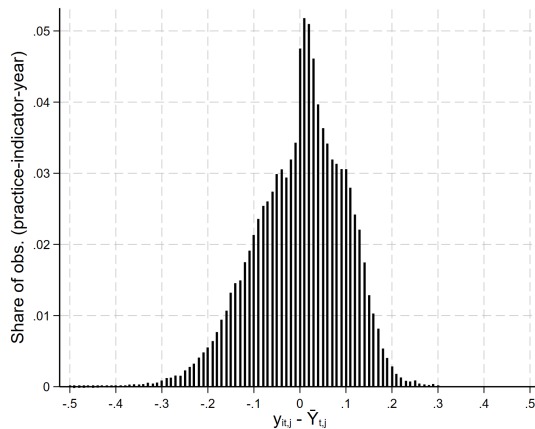
- ▶ GPP i , indicator j , year t
- ▶ Achievement y_{ijt}
- ▶ GPP covariates x_{it} (number of physicians, average age, etc)
- ▶ Nr of relevant patients n_{ijt}
- ▶ Thresholds $\overline{y_{jt}}, \underline{y_{jt}}$
- ▶ Incentives α_{jt}
- ▶ Everything in 2020 £

Summary Stats

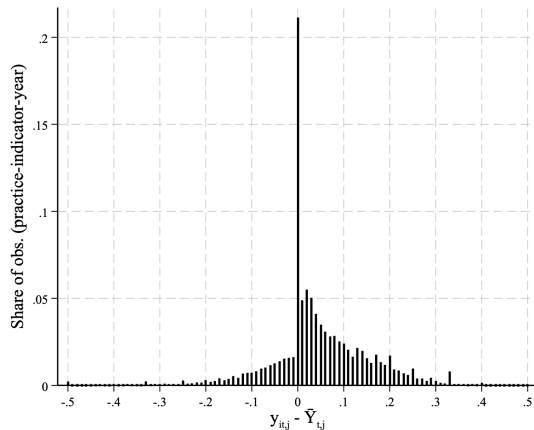
		Mean	Std. Dev.	P-10	Median	P-90	Obs.
Panel B: Indicator-practice-year							
Share of successes	$y_{it,j}$	0.878	0.121	0.722	0.906	1	2389540
Number of patients	$n_{it,j}$	177	264	4	87	445	2389540
Revenues per patient	$\rho_j(y_{it,j})$	11.16	12.64	2.32	7.23	27.99	2389540

Practices respond to incentives

DM11: % diabetes patients in whom the last glycohaemoglobin IFCC-HbA1c is 64 mmol/mol or less



For all indicators, distribution of $y_{ijt} - \bar{y}_{jt}$



- ▶ Bunching suggests strong response to financial incentives
- ▶ $y_{ijt} > \bar{y}_{jt}$ suggests GPPs also have non-financial incentives.

Achievement responds to incentives

- Column (4) uses variation in incentives within GPP-indicator over time

Panel B: Share of successes – $y_{it,j} = \delta^1 \bar{Y}_{t,j} + \delta^2 \alpha_{t,j} + \zeta^1 x_i + \zeta^2 \hat{\xi}_i + \epsilon_{it,j}$					
$\bar{Y}_{t,j}$	0.281 (0.001)	0.276 (0.001)	0.241 (0.001)	0.279 (0.001)	0.289 (0.001)
$\bar{Y}_{t,j} \times \text{Large practice}$				0.076 (0.002)	0.004 (0.000)
$\alpha_{t,j}$	0.087 (0.005)	0.082 (0.005)	0.031 (0.007)	0.094 (0.005)	0.170 (0.006)
$\alpha_{t,j} \times \text{Large practice}$				0.115 (0.009)	–0.135 (0.004)
Practice-level average residual $\hat{\xi}_i$ from practice-choice model					0.129 (0.005)
FE	Ind.	Ind., Practice	Ind. \times Practice	Ind. \times Practice	Ind.
Controls	N	N	N	N	Y
R-squared	0.412	0.476	0.656	0.656	0.431
Observations	2353922	2353922	2332413	2332413	2060431

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2 tasks

- ▶ Single GPP, 2 tasks ($j = 1, 2$)
- ▶ Number of patients n_j
- ▶ A clinic chooses outcomes $y_j \in [0, 1]$
 - ▶ large number of patients \rightarrow negligible noise
- ▶ Payer chooses revenue functions $\rho_j(\cdot)$
- ▶ GPP utility:

$$U(y) = n_1 \rho_1(y_1) + n_2 \rho_2(y_2) + n_1 \theta_1 y_1 + n_2 \theta_2 y_2 \\ - n_1 \lambda_1 y_1^2 - n_2 \lambda_2 y_2^2 - (n_1 + n_2) \lambda_{12} y_1 y_2$$

- ▶ Revenue, Altruism, Costs, Complementarities
 - ▶ (Altruism is short-hand for all non-financial incentives)
- ▶ If $\lambda_{12} > 0$, tasks are “substitutes”
- ▶ If $\lambda_{12} < 0$, tasks are “complements”

Many tasks

$$U(y) = \sum_j n_j (\rho_j(y_j) + \theta_j y_j) - y^T \Lambda y$$

$$\Lambda = \begin{bmatrix} n_1 \lambda_1 & n_2 \lambda_{12} & \cdots & n_J \lambda_{1J} \\ n_1 \lambda_{12} & n_2 \lambda_2 & & \\ \vdots & & \ddots & \\ n_1 \lambda_{1J} & n_2 \lambda_{2J} & & n_J \lambda_J \end{bmatrix}$$

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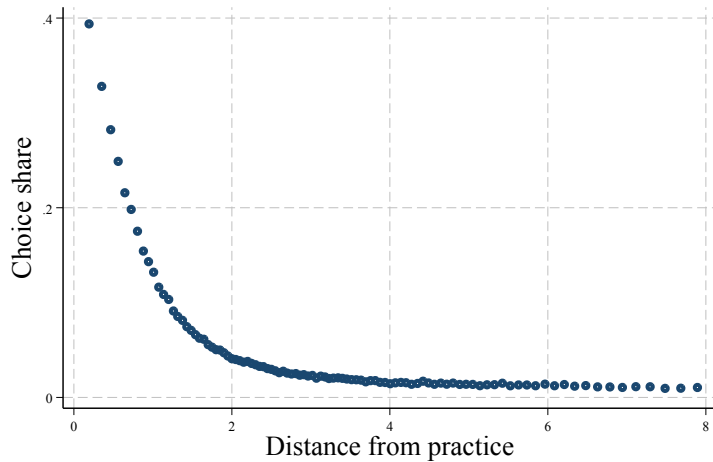
Demand

- ▶ Patients might select into “high-quality” practices
 - ▶ must consider demand
- ▶ We use exogenous variation in patient-practice location z_{it} to identify choice-relevant unobservable quality
- ▶ Simple logit: share of patients from location ℓ choosing practice i in year t is

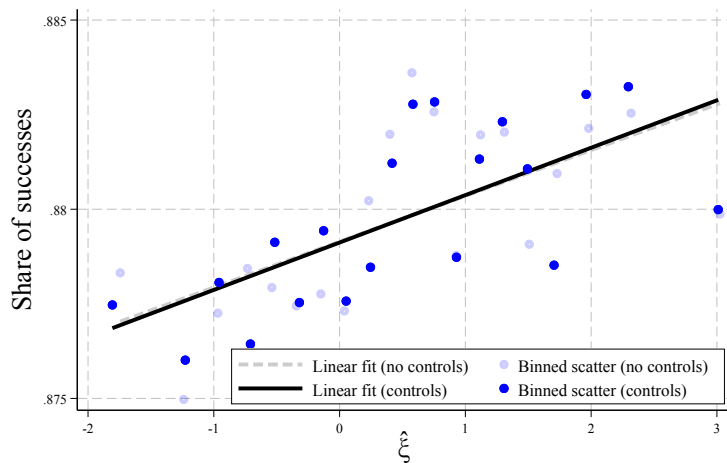
$$s_{it}^{\ell} = \frac{\exp \{ \gamma z_i^{\ell} + \eta x_i + \xi_{it}^{\ell} \}}{1 + \sum_{d: z_d^{\ell} \leq 5} \exp \{ \gamma z_d^{\ell} + \eta x_d + \xi_{dt}^{\ell} \}} \quad , z_i^{\ell} \leq 5 \text{ kilometers.}$$

- ▶ Aggregate $\hat{\xi}_i = \mathbb{E}_{\ell,t}[\xi_{it}^{\ell}]$
- ▶ **Assumption:** n_{ijt} iid conditional on $x_i, \hat{\xi}_i$
- ▶ Currently working on adding health conditions by location
 - ▶ we will approximate market size for GPP i condition j : total number of patients with that condition in all GPPs within 10Km of i
 - ▶ allows patients with condition j to choose GPP i because it is high-quality for condition j (but possibly low-quality for $k \neq j$)

Distance shifts demand



Demand residual is correlated with achievement



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Identification

- ▶ Goal: identify technology Λ separately from type distribution $f(\theta)$
- ▶ Data: demand n_{it} , achievement y_{it} , characteristics x_{it}, z_{it} , incentives $\rho_{jt}(\cdot)$
- ▶ We prove that the model is identified if:
 - ▶ **Assumption (LQU):** Utility $U(y)$ follows the Linear-Quadratic specification
 - ▶ **Assumption (exogeneity):** Instrument z_{it} such that demand is $n_{it} = \sigma(x_{it}, z_{it}, \xi_{it})$
 - ▶ n_{it} and θ_{it} independent conditional on (x_{it}, ξ_{it})
 - ▶ **Assumption (independence):** $f(\theta_{it}|x_{it}, \xi_{it}) = \prod_j f_j(\theta_{it,j}|x_{it}, \xi_{it})$
 - ▶ not actually needed. currently working on relaxing.
 - ▶ **Assumption (variation):** Rich variation in incentives (α_{jt}) and task assignments (z_{it}) to distinguish any function of y_{it}
 - ▶ Intuition: Change incentives for blood sugar control. Compare GPP A with many diabetics to GPP B with few. If A's cholesterol outcomes improve more than B's \rightarrow cholesterol & blood sugar are complements

Estimation

- ▶ Assume y_{ijt} in the data is the optimal effort choice made by the GPPs (up to integers)
- ▶ Let $\tilde{x}_i = (x_i, \hat{\xi}_i)$ be GPP covariates
 - ▶ includes demand residuals
- ▶ Assume that, for each ijt ,

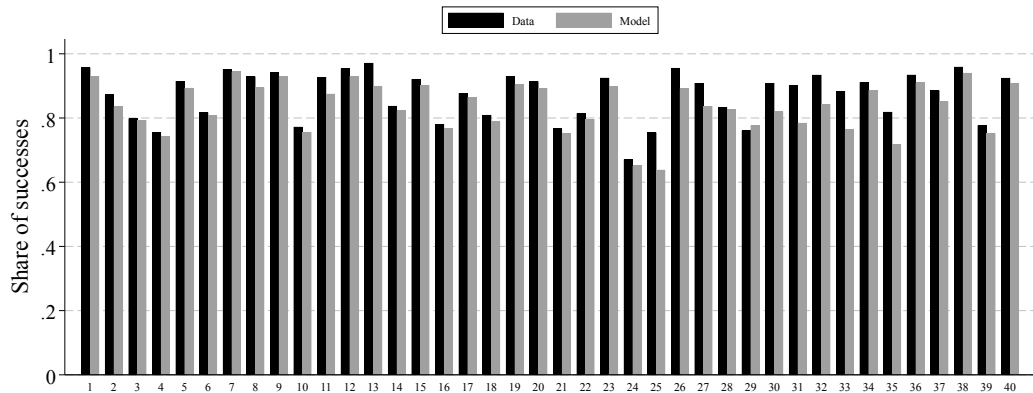
$$\theta_{ijt} \sim \mathcal{N}(\mu_j \tilde{x}_i, \sigma_j) \qquad (n_{it} \mid \tilde{x}_i) \perp (\theta_{it} \mid \tilde{x}_i)$$

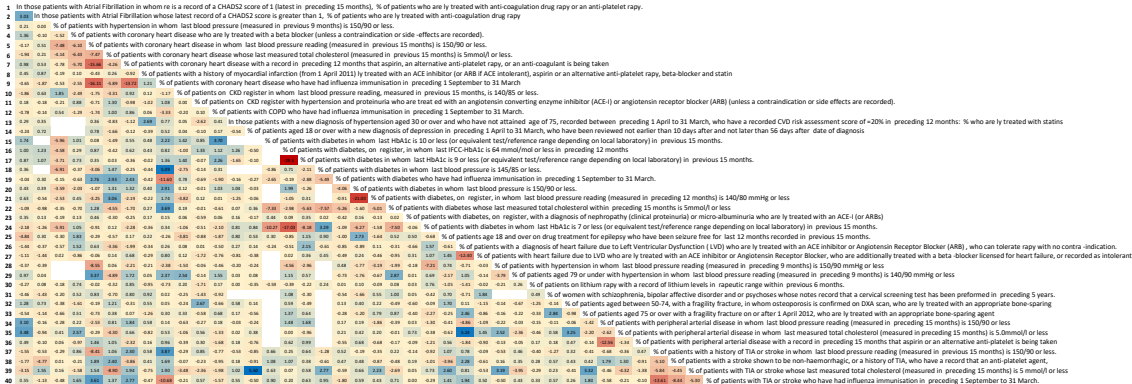
- ▶ Given LQU, $\frac{\partial U_{it}}{\partial y_{ijt}}$ is linear in θ_{ijt}
 - ▶ Can derive (discrete-continuous) distribution of θ_{ijt} analytically: [▶ Details](#)
- ▶ Estimate Λ and $\{\sigma_j, \mu_j\}_j$ by MLE
 - ▶ 1060 parameters

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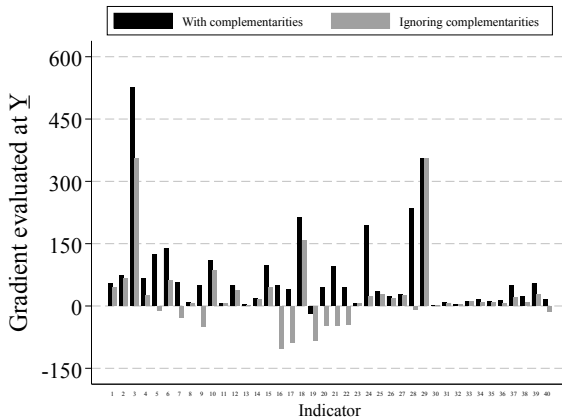
Goodness of Fit





Relevance of Multitasking

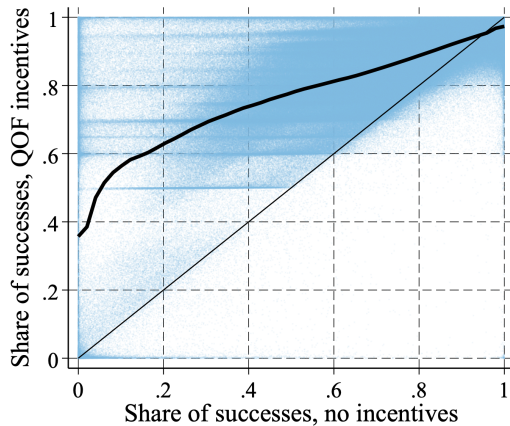
- ▶ Given estimates, for each indicator j , calculate $\mathbb{E}_{it}[\partial U_{it}/\partial y_{it,j}]$, evaluated at \underline{y}_{tj} (beginning of incentives)
 - ▶ then repeat this using $\lambda[j, k] = 0$ if $j \neq k$



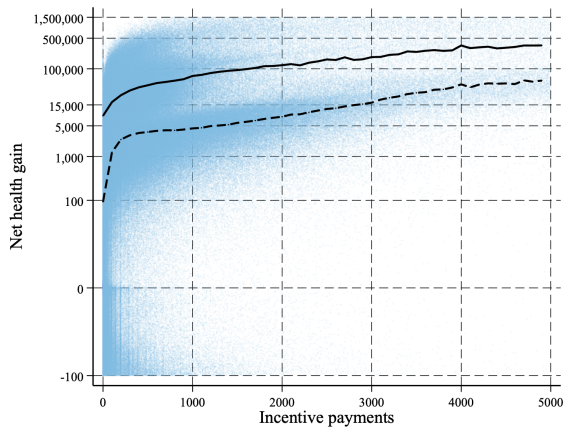
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Shutting Down QOF: achievement

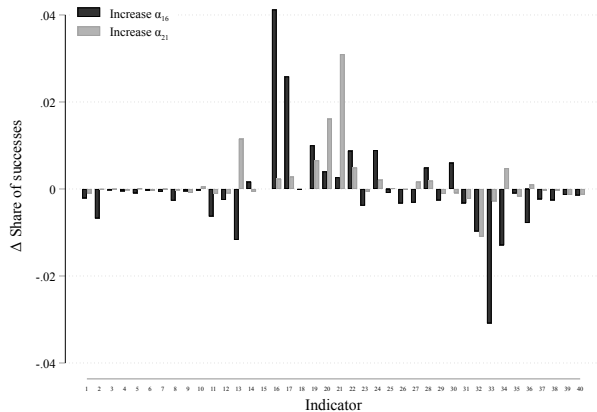


Shutting Down QOF: health gains (in £)



Increasing incentives for one indicator

- ▶ Increase incentives for indicator 16 & 21 (by £40)
- ▶ Large impact on other indicators



Empirical incentive design

- ▶ b_j are health benefits net of medicals costs for indicator j , in £, from NICE guidelines
 - ▶ so far only 20/40 indicators
- ▶ Set \underline{y}_j fixed and $\overline{y}_j = 1$ for each years
- ▶ Choose α_j to maximize the payer's objective

$$W = \sum_{i,j,t} n_{ijt} \int (y_{ijt} b_j - \rho_{jt}(y_{ijt} | \alpha_{jt})) f(\theta_{ijt} | \tilde{x}_i) d\theta_{ijt}$$

where y_{ijt} is chosen by GPPs to maximize utility

- ▶ Requires, for each α , solving the problem for all GPPs
- ▶ For tractability, we use k-means to cluster GPPs in terms of x_i, ξ_i, n_{ijt}
 - ▶ For every group $g = 1, \dots, 20$ obtain weight π_g and average values x_g, ξ_g, n_{gjt}
 - ▶ Approximate W using these groups. At the solution, compute outcomes for all GPPs

NHS should incentivize QOF more

	No QOF Δ from QOF	QOF	Optimized QOF Δ from QOF
Practice payoffs	-348 -11%	3,240	164 5%
QOF payments	-361 -100%	361	221 61%
Medical costs	-1,449 -3%	43,465	731 2%
Health benefits	-5,574 -4%	131,900	3,915 3%
Welfare	-4,113 -5%	91,314	3,128 3%

Notes: All monetary values are in GBP millions. Welfare is computed as the Practice payoffs + Health benefits - QOF payments - Medical costs

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Next Steps

- ▶ Include co-morbidities in demand
- ▶ Integrate “missing indicators” into the estimation

Conclusion

- ▶ Empirically tractable principal-agent model with multitasking
- ▶ Sufficient conditions for identification
 - ▶ relying on variation in exposure to different tasks
- ▶ Apply model to QOF program in England
- ▶ Ample evidence of response to incentives and multitasking
- ▶ Model allows counterfactuals:
 - ▶ Program generates large welfare gains
 - ▶ Scope for optimization of incentives accounting for multitasking

Thank you

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Additional slides:

$U'(y)$ Linear in ε

- ▶ Given LQU, $\frac{\partial U_{it}}{\partial y_{ijt}}$ is linear in θ_{ijt}
- ▶ For instance, in the 2D case:

$$\frac{\partial U}{\partial y_1} = n_1 \rho'_1(y_1) + n_1 \theta_1 - 2n_1 \lambda_1 y_1 - (n_1 + n_2) \lambda_{12} y_2$$

- ▶ If $y_1 = 1$, and knowing $\rho'_1(1) = 0$, then

$$\frac{\partial U}{\partial y_1} \big|_{y_1=1} \geq 0 \Leftrightarrow \theta_1 \geq 2\lambda_1 + \frac{n_1 + n_2}{n_1} \lambda_{12} y_2$$

- ▶ If $y_1 \in (\overline{y_1}, 1)$, the FOC holds, so

$$\frac{\partial U}{\partial y_1} = 0 \Leftrightarrow \theta_1 = 2\lambda_1 y_1 + \frac{n_1 + n_2}{n_1} \lambda_{12} y_2 - \rho'_1(y_1)$$

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