

PX920 Workshop:
**Implementation of Periodic Boundary Conditions
(PBCs)**

Łukasz Figiel

WMG, University of Warwick

PBCs via Multiple Point Constraints

Consider a periodic cell (RVE) bounded by the boundaries Γ_1 is coupled with Γ_2 , while Γ_3 is coupled with Γ_4 .

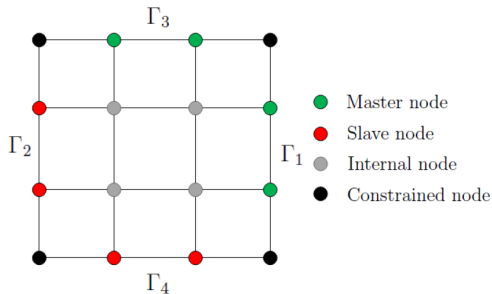


Figure: RVE with matching meshes on the opposite sides.

The nodes within the RVE are divided into **master** (m), **slave** (s), **internal** (*free*) and **corner** (*constrained*) nodes.

Multiple Point Constraints (MPCs) is a common way of enforcing nodal constraints, and applying periodic boundary conditions. The *slave* DOFs are related to the *master* DOFs through constraint equations, and the original system of equations is modified, so the slave nodes are eliminated.

The constraint equations can be written as

$$\begin{bmatrix} \mathbf{G}_m & \mathbf{G}_s \end{bmatrix} \begin{bmatrix} \mathbf{d}_m \\ \mathbf{d}_s \end{bmatrix} = \mathbf{0} \quad (1)$$

where \mathbf{d}_m and \mathbf{d}_s are the vectors containing master and slave DOFs, while \mathbf{G}_m and \mathbf{G}_s are matrices containing constants (typically 1 or -1 as coefficients in front of master and slave DOFs).

Solving for the slave DOFs

$$\mathbf{d}_s = -\mathbf{G}_s^{-1} \mathbf{G}_m \mathbf{d}_m \quad (2)$$

which gives the complete expression of DOFs in terms of master DOFs, and \mathbf{G}_m and \mathbf{G}_s are matrices

$$\begin{bmatrix} \mathbf{d}_m \\ \mathbf{d}_s \end{bmatrix} = \begin{bmatrix} \mathbf{I} \\ -\mathbf{G}_s^{-1} \mathbf{G}_m \end{bmatrix} \mathbf{d}_m \implies \mathbf{d} = \mathbf{T} \mathbf{d}_m \quad (3)$$

where \mathbf{d} is the vector of global DOF, \mathbf{T} is the transformation matrix, and \mathbf{I} is the identity matrix.

The global system of FE equations is given by

$$\mathbf{K}\mathbf{d} = \mathbf{r} \quad (4)$$

Substitution of \mathbf{d} from the second term in (3) into (4), and further pre-multiplication by \mathbf{T}^T yields

$$\mathbf{T}^T \mathbf{K} \mathbf{T} \mathbf{d}_m = \mathbf{T}^T \mathbf{r} \implies \mathbf{K}_m \mathbf{d}_m = \mathbf{r}_m \quad (5)$$

Solution of (5) for \mathbf{d}_m can be used to calculate the total nodal displacement vector \mathbf{d} in (3).

Constraint equations with linearly dependent DOFs

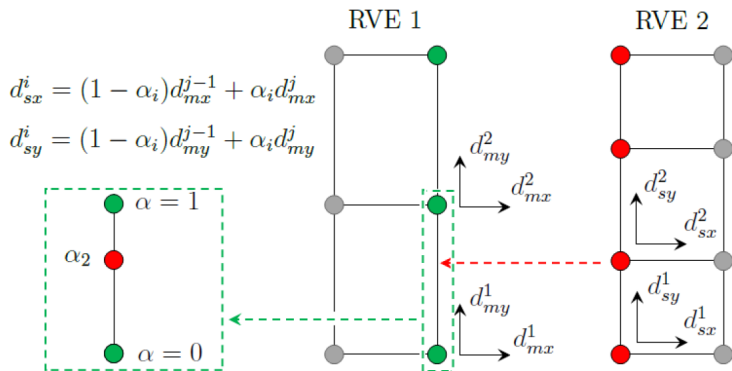


Figure: The slave DOF is linearly related to the two adjacent master DOFs.

MPCs for non-matching grids

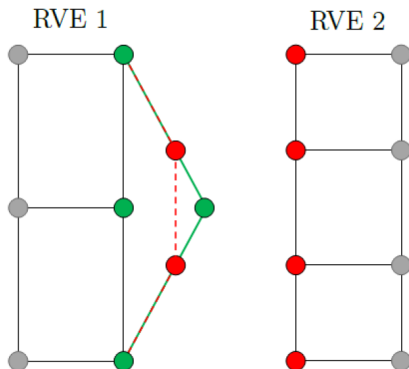


Figure: RVE deformation for non-matching grids.

Transformation matrix T - pseudo-code (Part 1)

The T-matrix

- id1 = node numbers for boundary 1
- id3 = node numbers for boundary 3
- ids2 = slave node numbers for boundary 2 (excluding corner nodes)
- ids4 = slave node numbers for boundary 4 (excluding corner nodes)
- idm = master node numbers (excluding corner nodes, including internal nodes)
- slavedofs = slave DOFs
- masterdofs = master DOFs

G = zeros(2*number of slave nodes , 2*number of RVE nodes)

FOR i = 1 **TO** i = number of boundary 4 slave nodes **DO**

 G(2*i-1 , 2*ids4(i)-1) = -1

 G(2*i , 2*ids4(i)) = -1

- Call mpc_alpha.m to get **alpha** and **masternode** = the upper masternode where alpha is equal 1

 G(2*i-1 , 2*id3(masternode)-1) = alpha

 G(2*i-1 , 2*id3(masternode-1)-1) = 1 - alpha

 G(2*i , 2*id3(masternode)) = alpha

 G(2*i , 2*id3(masternode-1)) = 1 - alpha

END DO

Transformation matrix T - pseudo-code (Part 2)

c = number of boundary 4 slave nodes

FOR i = 1 **TO** i = number of boundary 2 slave nodes **DO**

$G(2*(i + c)-1, 2*ids2(i)-1) = -1$

$G(2*(i + c), 2*ids2(i)) = -1$

- Call mpc_alpha.m to get **alpha** and **masternode** = the upper masternode where alpha is equal 1

$G(2*(i + c)-1, 2*id1(masternode)-1) = \alpha$

$G(2*(i + c)-1, 2*id1(masternode-1)-1) = 1 - \alpha$

$G(2*(i + c), 2*id1(masternode)) = \alpha$

$G(2*(i + c), 2*id1(masternode-1)) = 1 - \alpha$

END DO

Gs = G(:, slavedofs)

Gm = G(:, masterdofs)

T = zeros(2*number of RVE nodes, 2*number of master nodes)

T(masterdofs, :) = identity matrix

T(slavedofs, :) = -inv(Gs) * Gm

- Eliminate the columns in T corresponding to the constrained corner DOFs