

(8)

~~Both~~ Both of these notions can be formalized as "Homotopy" operations.

Defn: A homotopy is a family of ^{continuous} maps $F: X \times I \rightarrow Y$ $F(x, t) = f_t(x)$

Note: Haydee's Talk

Thursday Office Hours

Two maps $f, g: X \rightarrow Y$ are Homotopic if there is a homotopy $F: X \times I \rightarrow Y$ w/

$$F(x, 0) = f_0(x) = f(x)$$

$$F(x, 1) = f_1(x) = g(x)$$

So we can continuously deform one function to the other.

Sept 22 [2] Recall the definition of a homotopy of maps of X to A

Defn A retraction is a map $r: X \rightarrow X'$ s.t. $r(X) = A$ and $r|_A = Id_A$.

Note retractions are much weaker than deformation retractions. Every space retracts to a point via the constant map.

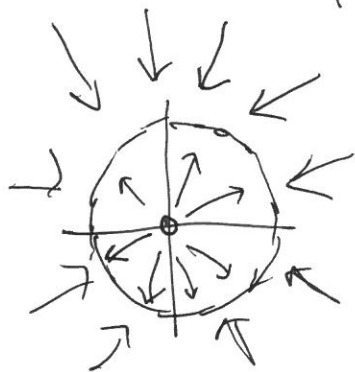
We can extend the notion of homotopy to relative homotopy:

Defn A Homotopy $F: X \times I \rightarrow X$ is a homotopy rel. $A \subseteq X$ if $f_t(a)$ is constant w.r.t. t .



$$E_X / X = \mathbb{R}^2 \setminus \{0\} \text{ and } S^1$$

$$F: X \times I \rightarrow X : (\vec{X}, t) \mapsto t \cdot \frac{\vec{X}}{\|\vec{X}\|} + (1-t)\vec{X}$$



~~$$(x, y) \mapsto \frac{x+y}{2}$$~~

Note: $f_0 \equiv \text{Id}_X$

$$f_1(\vec{X}) = \frac{\vec{X}}{\|\vec{X}\|}$$

and for $\vec{X} \in S^1$, $\|\vec{X}\| = 1$, so

$$F(x, t) = t \cdot \vec{X} + (1-t)\vec{X} = \vec{X}$$

So F is a (linear) homotopy rel S^1 .

Homotopy Equivalence: A much weaker notion of equivalence than a homeomorphism:

Defn: $f: X \rightarrow Y$ is a homotopy equivalence if $\exists g: Y \rightarrow X$ s.t. $g \circ f \simeq \text{Id}_X$ and $f \circ g \simeq \text{Id}_Y$.
If such a map f exists, X & Y are Homotopy equivalent.

Compare w/ homeo.

Contractibility: If X is homotopy equivalent to a point, then X is called Contractible.

Let's compare this to a deformation retract to a point:

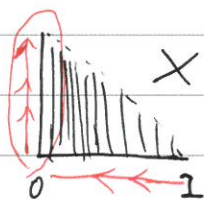
If $\exists F: X \times I \rightarrow X$ a deformation retract to a point, then ~~f_0~~ $f_0 \equiv \text{Id}_X$ and $f_1(x) = p$, with $f_t(p) = p$ always.

So $f: X \rightarrow p$ and $g: p \hookrightarrow X$, $f \circ g = \text{Id}_p$ and ~~$g \circ f$~~ $g \circ f = f_1 \approx f_0$.

Deformation ret \rightarrow pt \Rightarrow Contractible.

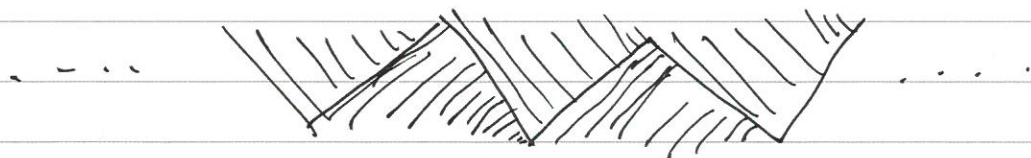
What about the other way?

Consider $X = [0,1] \times \{0\} \cup \bigcup_{r \in \mathbb{Q} \cap [0,1]} \{r\} \times [0,1-r]$



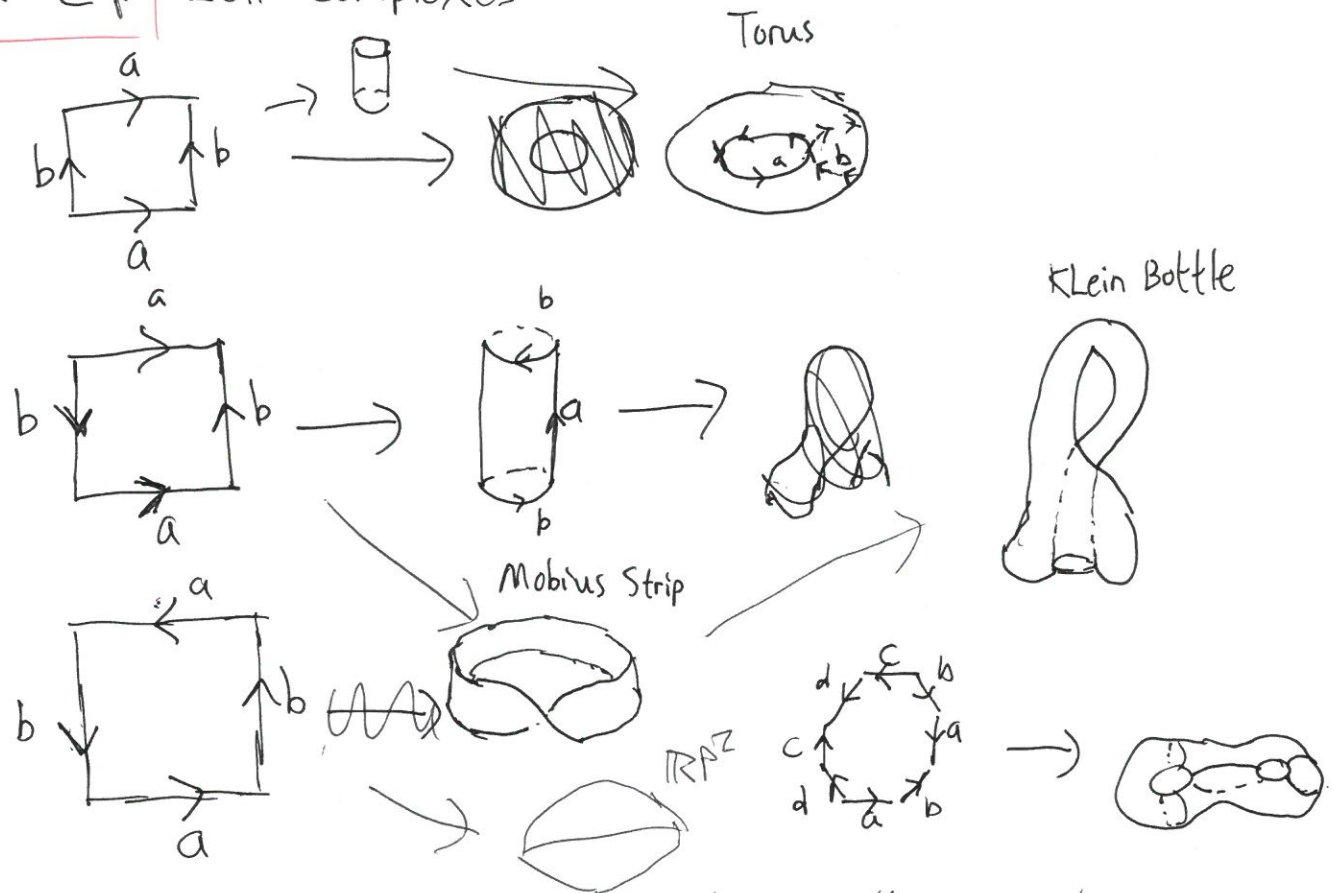
X def retracts to $^p [0,1] \times \{0\}$, but nowhere else and contracts to any point.

Construct Y by gluing ∞ -many of these together as shown



This space is contractible, but not a def retract.

Sept 27: Cell Complexes



Q: How can we generalize this notion to higher dimensions?

Cell Complex: Idea: We want to build a topological space by adjoining disks of higher dimensions to a space obtained previously.

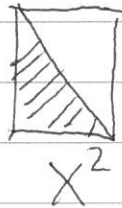
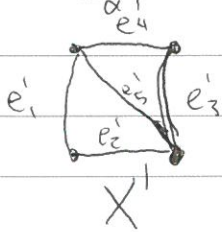
Formally: 1) Start w/ a discrete set P_0 (a collection of points). These are called 0-cells.

2) Inductively we form the "n-skeleton" X^n from X^{n-1} by attaching n-cells e_α^n to X^{n-1} .

Explicitly $e_\alpha^n: D^n \rightarrow X^{n-1}$, and Let

$Y^n = X^{n-1} \coprod \coprod_{\alpha} D_{\alpha}^n$. Then X^n is the quotient

space $X^n = Y^n / \sim$, where $x \in X^n$ and $y \in D_{\alpha}^n \subset S^{n-1}$ are equivalent iff $e_{\alpha}^n(y) = x$.



3) You can either iterate this process for finite n and let $X = X^n$ or continue indefinitely, and let $X = \bigcup X^n$. In the infinite case, $A \subset X$ is open iff $A \cap X^n$ is open for each n .

• Building ~~the~~ S^n : Take a point $P_{\#} = X^0$

Let $X^0 = X^1 = X^2 = \dots = X^{n-1}$

$$e_{\alpha}^n: \partial D^n = S^{n-1} \rightarrow P_{\#}$$

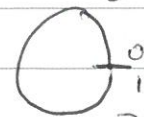
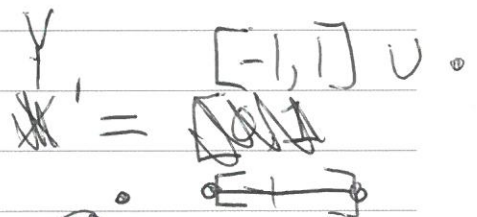
This gives S^n !

$$Ex / S^1 = X: X^0 = P$$

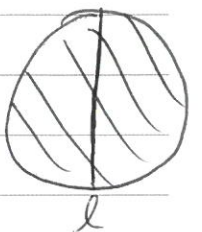
$$e_1^1(-1) = e_1^1(1) = P$$

$$S^2 = X: X^0 = P = X^1$$

$$e_1^2: \partial D^2 = S^1 \rightarrow P$$



$$X^2 =$$



2 ways $S^{n-1} \hookrightarrow S^n$

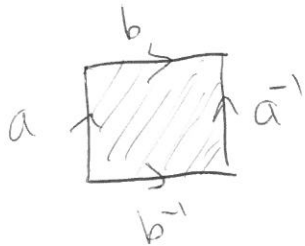


- Building a Torus: $X^0 = \mathcal{P}$, $X^1 = [\bar{0}, 1] \cup [\bar{1}, 1] \cup \mathcal{P}$
 $= \mathbb{D}_1^1 \cup \mathbb{D}_2^1 \cup \mathcal{P}$

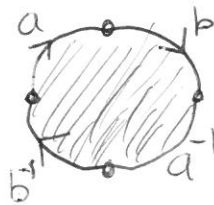
- $e_a^1: 2[-1, 1] = \{-1, 1\} \rightarrow \mathcal{P}$
 $= e_b^1$



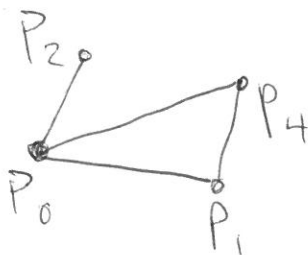
- $X^2 = \mathbb{D}^2 \cup X^1 / \sim$



- $e_*^2: \partial \mathbb{D}^2 = S^1 \rightarrow X^1$

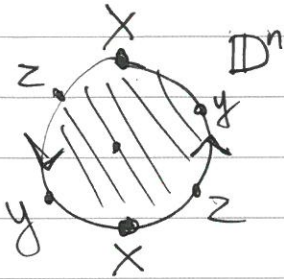


- Building a graph: $X^0 = \{P_i \mid P_i \text{ a vertex}\}$
 $X^1 = X^0 \cup \{[0, 1]_{i,j} \mid P_i - P_j \text{ an edge}\}$



- \mathbb{RP}^n : Space of lines in \mathbb{R}^{n+1}
 $= \mathbb{R}^{n+1} \setminus \{0\} / \sim$ $\vec{x} \sim \vec{y} \Leftrightarrow \lambda \cdot \vec{x} = \vec{y}$
 $= S^{n+1} / \sim$ $\vec{x} \sim -\vec{x}$ $\lambda \in \mathbb{R}$

We can view it as follows:



∂D^n identified to itself by antipodal map.

$\mathbb{R}P^{n-1} \hookrightarrow \mathbb{R}P^n$ by attaching on n -cell

$$e_\alpha^n: \partial D^n \rightarrow \mathbb{R}P^{n-1}$$

$$\begin{matrix} \cong \\ S^{n-1} \end{matrix}$$

$$\vec{x} \rightarrow \pm \vec{x}$$

Notes
 $\mathbb{R}P^n = \sim =$ attaching maps

Cell Complex = CW subcomplex

Sept 27 Operations on Spaces

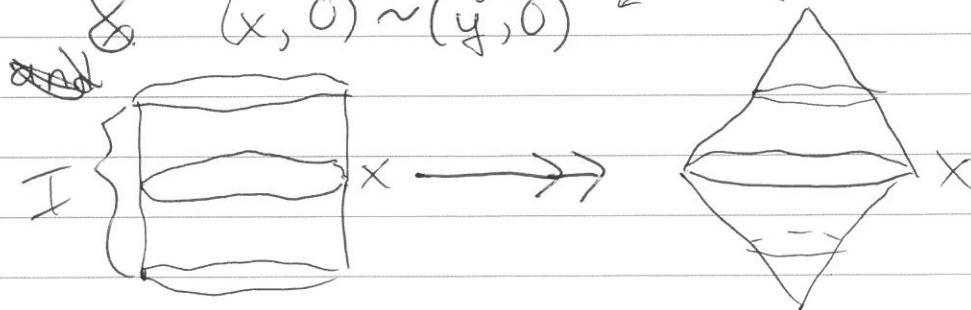
So far we have Subspace, Product, Quotient Topologies for any space. Let's add a few more!

I Suspension of a space X :

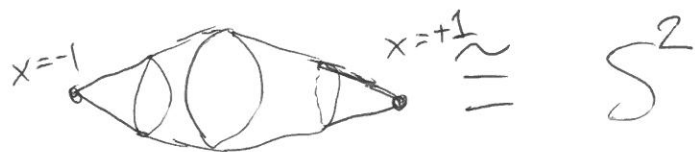
$$S(X) \text{ or } SX = X \times I / \sim$$

$$\text{where } (x, 1) \sim (y, 1) \leftarrow \forall x, y \in X$$

$$\& (x, 0) \sim (y, 0) \leftarrow$$



Example: $S^2 = S(S^1)$



$$S^2 = \{x^2 + y^2 + z^2 = 1\} \subseteq \mathbb{R}^3$$

|| If $x \neq \pm 1$, then $1 - x^2 = r^2$ for some $r > 0$

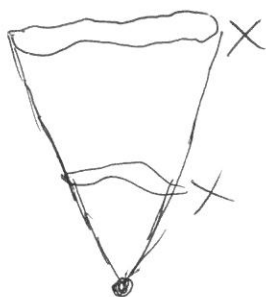
$$\{ \pm 1, 0, 0 \} \cup \{ (x, y, z) \mid y^2 + z^2 = r^2 = 1 - x^2 \}$$

In general, $S(S^n) = S^{n+1}$.

One can also form the cone over a space X by

$$CX = X \times I / \sim$$

$$(x, 1) \sim (y, 1) \quad \forall x, y \in X$$



$$SX = CX \cup CX$$

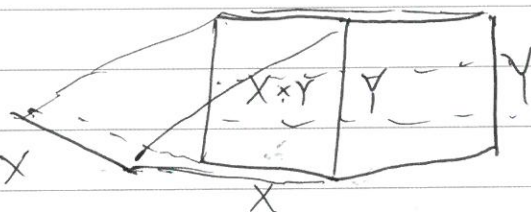
Join of 2 Spaces: One can do better.

~~QX~~ CX and SX can be thought of as all the line segments from X to an exterior point (or Z).

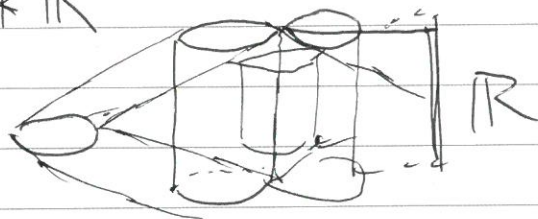
Take 2 Spaces $X \times Y$. We can form the space

$$J(X, Y) = X * Y = X \times Y \times I / \sim$$

$$\begin{aligned} (x, y_1, 0) &\sim (x, y_2, 0) & \forall y_1, y_2 \in Y \\ (x_1, y, 0) &\sim (x_2, y, 0) & \forall x_1, x_2 \in X \end{aligned}$$



Ex: $\mathbb{R}^n * \mathbb{R}^m$



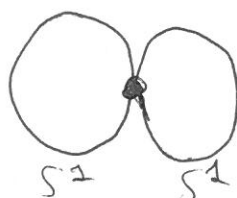
All lines from $X \times Y$ to X and Y preserving id_X and id_Y .



Wedge Sum: Take $x_\alpha \in X_\alpha$. We can form

$$\bigvee_\alpha X_\alpha = \bigsqcup_\alpha X_\alpha / \sim \quad X_\alpha \sim X_\beta \quad \forall \alpha, \beta$$

$$S^1 \vee S^1$$



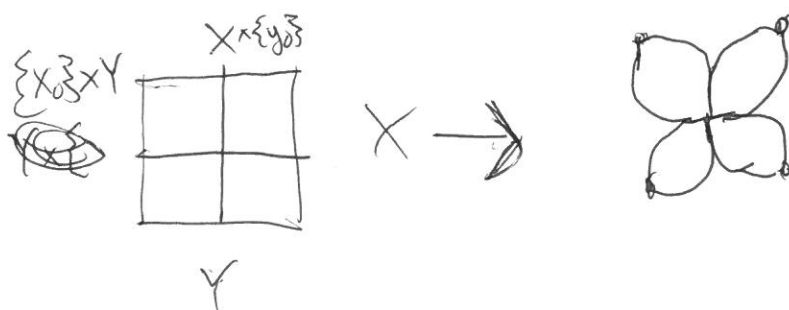
= figure 8

From Cell Complexes, ~~Every~~ X^n / X^{n-1}
has the structure of

$$\bigvee_\alpha S^n_\alpha$$

α runs through the n -cells of a complex

(smash product? $X \times Y / X \vee Y$)



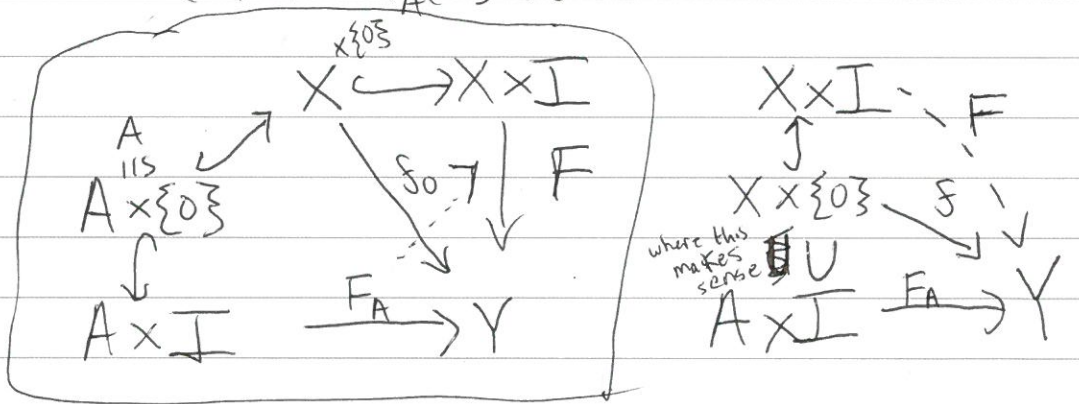
Sept 29 Homotopy Extension Property [HEP]

Defn: A pair ~~(X, A)~~ with $A \subseteq X$ a subspace is said to have the homotopy extension property if for every $f_0: X \rightarrow Y$ and ~~$f_0|_A: A \rightarrow Y$~~ ~~a homotopy w/~~ $F_A: A \times I \rightarrow Y$ w/

$$f_0|_A = F_A(a, 0)$$

Then $\exists F: X \times I \rightarrow Y$ extending F_A :

$$F(a, t) = F_A(a, t)$$



A different way to phrase this:

$$X \times \{0\} \cup A \times I \hookrightarrow Y$$

Extends to a retraction

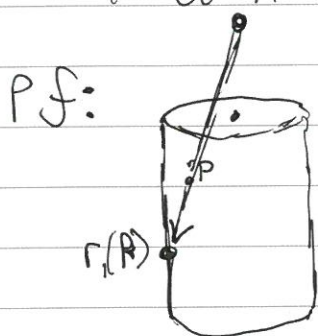
$$X \times I \rightarrow X \times \{0\} \cup A \times I$$

Thus, if (X, A) has the homotopy extn prop so does $(X \times Z, A \times Z)$.

Prop .16: If (X, A) is a CW pair, then (X, A) has the Homotopy extension property

Pf: First let's show our building blocks behave as desired:

Lemma: $\exists r_t: \mathbb{D}^n \times I \rightarrow \mathbb{D}^n \times I$ a deformation retraction of $\mathbb{D}^n \times I$ to $\mathbb{D}^n \times \{0\} \cup \partial \mathbb{D}^n \times I$



$r_t: \mathbb{D}^n \times I \rightarrow \mathbb{D}^n \times \{0\} \cup \partial \mathbb{D}^n \times I$ is a retraction. We can let

$$r_t = (1-t) \text{Id} + t \cdot r$$

So, it suffices to show a more general result:

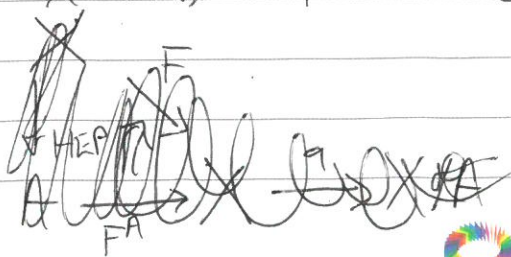
Prop: $X^n \times \{0\} \cup A^n \times I$ is a def. ret. of $X^n \times I$

Pf: Note $X^n \times I$ is obtained from $X^n \times 0 \cup (X^{n-1} \cup A) \times I$ by attaching $\mathbb{D}^n \times I$ to it along $\partial \mathbb{D}^n \times I$.

Lemma shows we can ~~center~~ def retract each of these so we do each in a subinterval of I . ✓

Prop .17: If (X, A) has HEP, and A is contractible, then $X \rightarrow X/A$ is a homotopy eq.

Pf



$$\begin{array}{ccc}
 X & \xrightarrow{f_t} & X \\
 \uparrow \pi & \searrow f_0 = \text{Id}_X & \\
 A & \xrightarrow{f_t} & X
 \end{array}
 \Rightarrow
 \begin{array}{ccc}
 X & \xrightarrow{f_t} & X \xrightarrow{q} X/A \\
 & & \uparrow \bar{f}_t \\
 X & \xrightarrow{q} & X/A \xrightarrow{\bar{f}_t} X/A
 \end{array}$$

sends A to a point

$$q \circ f_t = \bar{f}_t \circ q$$

$$\begin{array}{ccc}
 X & \xrightarrow{f_t} & X \\
 q \downarrow & \searrow \bar{f}_t & \downarrow q \\
 X/A & \xrightarrow{\bar{f}_t} & X/A
 \end{array}$$

Since $f_t(A) = P$, $\bar{f}_t: X/A \rightarrow X$. Call it g .

$$\begin{array}{ccc}
 X & \xrightarrow{q} & X/A \\
 & \searrow g & \\
 & & \checkmark
 \end{array}$$

$$q \circ g = \bar{f}_t \simeq \bar{f}_0 = \text{Id}_{X/A}$$

$$g \circ q = f_t \simeq f_0 = \text{Id}_X$$

Prop. 18: If (X, A) is a CW pair and

$f \simeq g: A \rightarrow X_0$, then

$$X_0 \sqcup_f X_1 \simeq X_0 \sqcup_g X_1 \quad \text{rel } X_0$$

First,

$$X_0 \sqcup_f X_1 = (X_0 \sqcup X_1) / \sim$$

$$x_0 \sim x_1 \iff x_0 \in A \text{ and } f(x_0) = x_1$$

P.F: Consider $X_0 \sqcup_F (X_1 \times I) \supseteq X_0 \sqcup_f X_1$

By 16 \Rightarrow They def retract to each subspace so they are hom equiv.