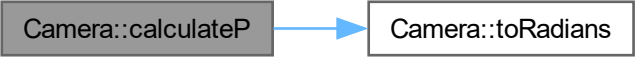


Camera::calculateP



```
graph LR; A[Camera::calculateP] --> B[Camera::toRadians]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box is filled with a dark gray color and contains the text 'Camera::calculateP'. The right box is white with a thin gray border and contains the text 'Camera::toRadians'.

Camera::toRadians