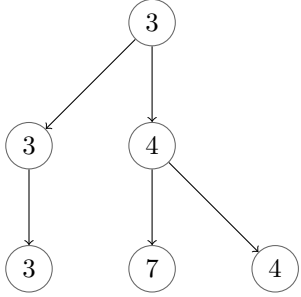


1 Quake Heaps

Quake heaps are a collection of **tournament trees**, where the value at the parent node is the minimum of the values at child nodes. Each node only has 1 or 2 children, and we can have more than one tree side by side at the same time. \forall node, $h(x) = \text{dis}(x, \text{descendant node})$.



Since every node has at most two children, then the height of each level n_{i+1} will be $\leq \alpha n_i$, where $\alpha \in (1/2, 1)$. Basically, every level will have $1/2-1$ times more nodes than the level directly downward. Its potential function is defined as $N + T + B / (2\alpha - 1)$, $n = \text{nodeNum}$, $T = \text{treeNum}$, $B = \text{deg-1 nodeNum}$. **Insert** $O(1)$, **Dec-Key** $O(1)$, **Extract-Min** $O(\log n)$. When we Dec-Key, we remove the min path from the top of tree to leaves in $O(\log n)$, then, we merge all the trees with height i .

2 Disjoint Sets

A data structure that maintains collection of disjoint sets. With **Make-Set(x)**, we create a singleton set $\{x\}$. With **Union(b,d)**, we make a single set out of the two sets containing b and d respectively. **Find-Set(x)** returns the **representative element** of set S_i . If DS doesn't change, then

the RE will stay the same.

2.1 Linked Lists

We can use LLs to maintain the data structure. We maintain a pointer from every element to the representative, so $O(1)$ Find-Set(x). To merge two sets, we would need $O(\min(S1, S2))$. It takes $O(n \log n + m)$ to perform seq. of m Make-Set(x), Find-Set(x), Union(x,y), in which there are n Make-Set(x) operations, due to the fact that we can update the pointers at least $O(\log n)$.

2.2 Forest Implementation

With this approach, we implement all the sets as a tree with elements pointing at the head. Here, Union(x,y) takes $O(1)$ since we only update the root pointers when switching elements. Just compare the size of the trees, and append the larger one to the smaller one. However, Find-Set(x) takes $O(h)$, where h is the height of the tree.

3 Graph Traversal

We can represent a graph by using **adjacency list** or **adjacency matrix**. There are differences in how much time it takes to check if there is a connection, vs. how much space it takes to store a graph. The adjacency list might make it harder to iterate and delete nodes, since it would have TC $O(\deg(u))$

Algorithm 1: BFS(G,S)

```

visited[1..n] = {no};
dis[1..n] = {inf};
parent[1..n] = {NIL};
EnQueue(Q,s);
while Q ≠ 0 do
    u = DeQueue(Q);
    for v ∈ Adj[u] do
        if visited[v] = no
            then
                EnQueue(Q,v);
            end
        end
    end
end

```

For this algorithm, all the nodes are enqueued at most once, since their visited field is changed when enqueued. Therefore, it takes $O(n + m)$

3.1 Applications

The **diameter** of a tree is the maximum distance between two nodes in the graph. If we run BFS(T,c) and record the node with largest d : this is o_1 or o_2 . There are 4 different cases.

3.2 DFS

For DFS, we keep visiting any previously unvisited nodes in G as soon as we find them. Then, we start to work on the node itself. We mark them **white** if they are not discovered yet; **grey** if they have been discovered but are not finished; and **black** if they have been completely explored. However, it will only discover the nodes reachable from the source node.

Proper DFS also will call DFS-Visit() for multiple starting nodes, usually those that might not be reachable

from previous starting nodes.

Algorithm 2: DFS-Visit(G,u)

```

time = time + 1;
u.d = time;
u.color = gray;
for all nodes v ∈ Adj[u] do
    if v.color == White
        then
            v.parent = u;
            DFS-Visit(G,v);
        end
    end
end
u.color = Black;
time = time + 1;
u.f = time;

```

3.3 Parenthesis Theorem

For any two nodes u and v , exactly one of the following holds:

- The intervals $[u.d, u.f]$ and $[v.d, v.f]$ are disjoint neither is a descendant of the other.
- The interval $[v.d, v.f]$ contains the interval $[u.d, u.f]$: v is an ancestor of u
- The interval $[u.d, u.f]$ contains the interval $[v.d, v.f]$: u is an ancestor of v .

There are four different types of edges:

- **tree edges**: v discovered while $v.color == \text{white}$
- **back edges**: while exploring (u,v) , $v.color == \text{Gray}$
- **forward edges**: while exploring (u,v) , $v.color == \text{black}$ and $u.d < v.d$
- **cross edges**: while expl. (u,v) , $v.color == \text{black}$ and $u.d > v.d$