# **Operating Systems Homework 3 Report**

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#### **Video Link**

TBD

### **Questions**

1. What is a static kernel module? What is a dynamic kernel module? What is the other name of a dynamic kernel module? What are the differences between system calls and dynamic kernel modules(mention at least 3)?

A kernel module extends the functionality of the kernel without being part of it. These modules are loaded by the main kernel, so they are not part of the main kernel. We can load and unload these modules by demand by using the insmod and rmmod commands. Dynamic kernel modules, also known as **loadable kernel modules** can be loaded by the user to add custom functionality to the kernel. Static kernel functions, on the other hand, are loaded at boot time after the intiial ram file system loads the kernel, and are required by the system to boot.

There are some differences between kernel modules and system calls, which we implemented in our previous project. Firstly, system calls require us to recompile the entire kernel, since they can access some kernel resources. Kernel modules are also located outside the kernels, so modifying, inserting, or removing kernel modules does not require a recompile.

2. Why does adding a system call require kernel re-compilation, while adding a kernel module does not?

System calls are part of the kernel. This means that we cannot dynamically load new system kernels during execution of our operating system. System calls would be like adding a new function to a C source code file. In order for the function to be available we have to save the source file and recompile the program.

Kernel modules, on the other hand, are different because they are loaded in from the outside. They don't require the kernel to be recompiled because their source code is not directly inside the kernel. Continuing our C source code example, this would be like having a C program that reads variables from an external file and then adding a variable to that external file. Since we are not changing the source code of the program and instead adding modifications from outside, our program does not require a recompile. 3. What are the commands insmod, rmmod, and modinfo for? How do you use them?

These commands all deal with kernel modules. insmod inserts a module into the Linux kernel. The rmmod command removes a module from the Linux kernel, and the modinfo command shows the info associated with a particular kernel module.

To use these kenrel modules, we need to know the name of the module, as well as what program options we would like to provide.

### 4. Write the usage of the following commands:

• module\_init

The module\_init() system call will load the module into the kernel space. Once it allocates space and can initialize the module parameters, it will call the module's initialize() function, which we pass as an argument. In our module, we print the values of our kernel parameters out to the kernel ring buffer.

• module\_exit

In contrast to the module\_init() system call, the module\_exit() function takes care of wrapping up our module when the module is removed or otherwise terminated. The parameter is a function pointer to the cleanup routine we want to execute. In our case we again reprint the values to the kernel ring buffer, some of which might be changed.

• MODULE\_LICENSE

The MODULE\_LICENSE() specifies the license under which our module exists. The "GPL" string represents the "GNU Public License", specifically v2 of that license. This license enables the software to be distributed freely according to the philosophy of the Free Software Foundation. In our project, we use it by placing it at the top of the file.

• module\_param

The module\_param() command adds a parameter to our module, and we specify three parameters: the value to be modified, the type, and a mask for the permission. The last value is explained more in detail later.

• MODULE\_PARM\_DESC

This command specifies how to use the module parameter, what it does and how to use it. It is printed out when we inspect the module using modinfo, since that will print the descriptions for all the values.

- 5. What do the following terminal commands mean? (Explain what they do and what does the -x mean in each case):
  - cat

The cat command prints out the contents of a file to standard output. It can also concatenate files.

• ls -l

The ls command is one of the most fundamental commands in Linux, and it lists the contents in a directory. When we give it the -l option, it will use a "long listing" format, where it indicates the permissions on the directory contents, the user which created them, the group the user belogns to, the size, and the time each was created.

• dmesg -wH

The dmesg command prints the contents of the kernel ring buffer. This means that any message we write in the printk() function will appear in this buffer. The -wh options signify two things: that the buffer should wait for new messages (-w), and that the contents should be printed out in human readable format (-H).

• lsmod

The lsmod command will list all the currently loaded kernel modules and their status. It formats and prints out the contents of /proc/modules.

• lsmod | grep

The first command in this sequence is the same as the previous command, however, we "pipe", or send the results of lsmod to grep. grep looks for patterns in standard input, so we can use it to search whether our own kernel modules are running.

#### 6. There is a -644 in the line

```
1 module_param(studentId, int, 0644);
```

### inside paramsModule.c. What does 0644 mean?

The 0644 in the function call represents a mask for the parameter's visibility in sysfs. sysfs is a pseudo file-system which provides an interface to the kernel data structures. 0644 specifically means that our parameter will be "root-writeable". We could also specify 0444 if we wanted our parameter to be writable by any user.

More generally, a mask is a a value that is used in bitwise operations. So when the value 0644 is used in a bitwise operation with some other value, it will result in the permissions we can use.

### 7. What happens if the initialization function of the module returns -1? What type of error do you get?

This error means that the module was not able to be initialized. Normally, the function will return 0 in case that the module terminates normally. Maybe there was an error in the format of the function or the module was already loaded and thus the initialization function cannot run.

# 8. In section 1.3 - step 6, modinfo shows the information of some variables inside the module but two of them are not displayed. Why is it?

In the paramsModule.c file, the initialize() function runs as soon as we load the module. Inside this function, we print out the values of the module, and we only print out some of the kernel module values. The reason we don't see all the variables in the debug buffer is because those values are not print out when our module initializes.

### 9. What is the /sys/module folder for?

The /sys/module folder stores the information regarding all the currently loaded kernel modules. Inside the folder of each kernel module, we can find the current values used by the module. We can read and change the values, if we have the correct permissions. For the paramsModule02 and calculatorModule, we are mostly interested in the parameter values which the module stores in the /sys/module/\$(module name)/\$(parameter name).

# 10. In section 1.3 (paramsModule.c), the variable charparameter is of type charp. What is charp?

charp in the module parameter declaration refers to a **char** \*, or a pointer to a **char**. The macros used by the Linux kernel to check the validity of the parameters will eventually expand the value to a **char** pointer, which in C functions as a string.

### **Screenshot discussion**

**Figure 1:** Files associated with helloModule.

The first module we created in the project involves just printing a value to the kernel ring buffer when we load and remove the kernel module. The initialize function will execute whenever the kernel module is loaded and the clean\_exit function will be executed when the module is removed.

The Makefile on the top right corner specifies the rules for how to build and compile the files. The first line specifies that the

target file is in module form. The all and clean are different rules for where and how to compile certain files.

**Figure 2:** The output of the make command.

As specified previously, the make command specifies how the project or certain files are to be compiled. When the command is run in the command line, this is the output. In the output we see that the make program uses the /usr/src/linux-4.19.148 directory to make the kernel module file, helloModule.ko. Afterwards this resulting file will be the one that we load into the kernel.

```
O D usertest0616110@ubuntu:-/Desktop/Tests/Modules/helloModule

usertest0616110@ubuntu:-/Desktop/Tests/Modules/helloModule$ sudo insmod hel

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```

**Figure 3:** Message printed on the kernel ring buffer when we load the module.

In the helloModule.c file, we have a procedure specified when we initialize the module and when we remove the module. These functions get bound in the module\_init() and module\_exit()

function calls, to which we pass the function. The output in the screenshot is the output after the initialize function has been called.

Figure 4: Checking that our module is loaded with the lsmod command.

While our module is loaded from the previous step, we use the lsmod to list all the currently loaded kernel modules. We pipe this ouptut to the grep command which will look for the name of our module. We do this to check if the module has been loaded.

Figure 5: Unloading helloModule.

When we unload helloModule, we will see the state of the module parameters. In the future excercises we will change the values of the parameters in between the time of loading and unloading. Here, the code inside the clean\_exit() function is executed.

```
usertest0616110@ubuntu: ~/Desktop/Tests/Modules/helloModule
vmwgfx
                      282624
                      106496
                              1 vmwgfx
ttm
drm kms helper
                      167936
                              1 vmwgfx
                      16384 1 drm_kms_helper
16384 1 drm_kms_helper
syscopyarea
sysfillrect
sysimgblt
                      16384 1 drm kms helper
                       16384 1 drm_kms_helper
fb_sys_fops
                      475136
drm
                              7 vmwgfx,drm_kms_helper,ttm
                      151552
psmouse
e1000
                      143360
mptspi
                       24576
                              2
mptscsih
                       36864
                              1 mptspi
                       40960
                              0
ahci
libahci
                       32768
                              1 ahci
                              2 mptspi,mptscsih
mptbase
                       98304
scsi_transport_spi
                       32768 1 mptspi
pata_acpi
                       16384 0
usertest0616110@ubuntu:~/Desktop/Tests/Modules/helloModule$ sudo rmmod hell
oModule
usertest0616110@ubuntu:~/Desktop/Tests/Modules/helloModule$ lsmod | grep he
lloModule
usertest0616110@ubuntu:~/Desktop/Tests/Modules/helloModule$
```

**Figure 6:** Verifying that the module is unloaded.

In a previous screenshot, we searched for the loaded kernel module among the output of lsmod. Here we repeat the same command after using the rmmod command to remove the module. The lsmod | grep command returns nothing since helloModule has already been unloaded.

```
### Postableodue: x | paramsModue: x | p
```

Figure 7: The paramsModule and its Makefile.

The next kernel module we designed involved passing parameters to the module. In paramsModule02.c, the lines with the module\_param() function will add a parameter of a certain type to the module. If we have the modifyValues parameter toggled, then we will change some of the other parameters. We can toggle this value from the command line or dynamically from another file.

Figure 8: Module parameters printed when loaded and removed.

In terminal 1, we load and remove the module using the <code>insmod</code> and <code>rmmod</code> commands. This causes the module to execute the functions we specified in the <code>module\_init()</code> and <code>module\_exit()</code> functions. Thus the parameters are printed in the kernel ring buffer. In this step, we have not changed any of the parameters, so the values in the exit method will be the same as the ones in the input. Unless we specify the <code>modifyValues</code> parameter, we won't change their values..

```
🔊 😑 🏻 usertest0616110@ubuntu: ~/Desktop/Tests/Modules/paramsModule
usertest0616110@ubuntu:~/Desktop/Tests/Modules/paramsModule$ sudo modinfo param
       params
param
usertest0616110@ubuntu:~/Desktop/Tests/Modules/paramsModule$ sudo modinfo param
param
      params
usertest0616110@ubuntu:~/Desktop/Tests/Modules/paramsModule$ s
Display all 180 possibilities? (y or n)
usertest0616110@ubuntu:~/Desktop/Tests/Modules/paramsModule$ sls
No command 'sls' found, but there are 22 similar ones
sls: command not found
usertest0616110@ubuntu:~/Desktop/Tests/Modules/paramsModule$ ls
               Module.symvers paramsModule.ko
                                                  paramsModule.mod.o
Makefile
modules.order paramsModule.c paramsModule.mod.c paramsModule.o
usertest0616110@ubuntu:~/Desktop/Tests/Modules/paramsModule$ modinfo paramsModul
modinfo: ERROR: Module paramsModul.ko not found.
usertest0616110@ubuntu:~/Desktop/Tests/Modules/paramsModule$ modinfo paramsModul
e.ko
filename:
                /home/usertest0616110/Desktop/Tests/Modules/paramsModule/paramsM
odule.ko
author:
                Andres Ponce, 0616110
license:
                GPL
                437687D2ECFC63CA17B7D09
srcversion:
depends:
retpoline:
                paramsModule
name:
vermagic:
                4.19.148 SMP mod unload
               studentId:Parameter for student Id. (Leading zeros are omitted)
parm:
(int)
parm:
                secretValue:Parameter for secret value. (long)
                charparameter:states - Hello world (charp)
parm:
                modifyValues:Indicates if we must modify the original values or
parm:
not. (int)
usertest0616110@ubuntu:~/Desktop/Tests/Modules/paramsModule$ sudo rmmod paramsMo
usertest0616110@ubuntu:~/Desktop/Tests/Modules/paramsModule$ sudo insmod paramsM
odule.ko modifyValues=1
```

**Figure 9:** Getting information about the module with the modinfo command.

Figure 10: Changing some of the parameters by toggling modifyValues

In the first screenshot, we first print the module information, such as the parameter names, their types, and a short description. Next, we load the module again, except this time when we load the module we use the command

```
1 sudo insmod paramsModule.ko modifyValues=1
```

which will cause the values of some of the parameters. Our code will check this value and change some of the parameters in accordance with the code.

The next screenshot shows the values after they are changed. The modifyValues parameter will replace the studentId and message with some dummy values, which then get printed to the kernel ring buffer.

```
usertest0616110@ubuntu:~/Desktop/Tests/Modules/paramsModule$ sudo insmod paramsM
odule.ko studentId=616110 secretValue=8888<mark>.</mark>
```

Figure 11: Loading the module again with our own custom parameters.



**Figure 12:** The parameter's value written in the correct file.

**Figure 13:** The value we updated in the parameter file shows once we remove the module.

In the previous section, we had changed some parameters of our module from within the module file. The first screenshot shows how we can change the parameters of the file directly from the command line. The module is then loaded with those parameters and we can thus see it on the kernel ring buffer.

The kernel keeps track of the module paramter's values inside of a file. Originally, the secret value was 8888 but we can change it by going into the file and just replacing the old value with 7777. When we remove the module, we should see the updated value being printed on the kernel ring buffer.