Optimization Design Homework 1

Andrés Ponce 彭思安 P76107116

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1 Find the stationary points for the following functions. Also identify(for each stationary point), the local maximum, minimum, or neither (by using second order derivative or Hessian matrix.)

1.1 $f(x) = x^3 \exp(-x^2)$, for -2 < x < 2.

The stationary points are those where f'(x) = 0, so we first find the first derivative. By using the product rule,

$$f'(x) = 3x^{2} \exp(-x^{2}) - 2x^{4} \exp(-x^{2}) = -x^{2} \exp(-x^{2})(2x^{4} - 3x^{2})$$
(1.1)

which is zero at x = 0, and by solving $2x^4 - 3x^2$ we get the other roots $x = \pm \frac{\sqrt{3}}{\sqrt{2}}$. Theorem 2.2 gives the sufficient condition for a minimum or maximum point for single variables. We must find a point where $f^m(x^*) \neq 0$, so we find f''(x). We again use the product rule on Equation 1.1 and factor the result to obtain

$$f''(x) = -x \exp(-x^2)(4x^4 + 2x^2 - 6)$$
 (1.2)

where $f''(\frac{\sqrt{3}}{\sqrt{2}}) < 0$ and $f''(-\frac{\sqrt{3}}{\sqrt{2}}) > 0$ However, f''(0) = 0, so we find the third derivative by using the same procedure

$$f'''(x) = -x \exp(-x^2)(20x^3 + 6x + 8x^4 + 4x^2 - 12) - 6\exp(-x^2)$$
 (1.3)

where f'''(0) = 6, however since n = 3, 0 does not correspond to either a maximum nor minimum point. In the end, $-\frac{\sqrt{3}}{\sqrt{2}}$ is a minimum, 0 is neither, and $\frac{\sqrt{3}}{\sqrt{2}}$ is a maximum.

1.2
$$f(x, y) = -x^2 - 3y^2 + 12xy$$

For a multivariable equation, solving for x and y in the partial derivatives will give us the stationary points.

$$\frac{\partial f}{\partial x} = -2x + 12y \tag{1.4}$$

$$\frac{\partial f}{\partial y} = -6y + 12x\tag{1.5}$$

We first solve for y in Equation 1.5 and we get y=2x. Substituing for y in Equation 1.4, we get

$$-2x + 24x = 22x$$

$$22x = 0$$

which means x = 0. Substituting again x = 0 in Equation 1.5 we get -6y = 0 which means y = 0. The stationary point for f is (0,0).

To determine the nature of the stationary points, we have to find the Hessian matrix, which involves finding the second order partial derivatives.

$$\frac{\partial^2 f}{\partial^2 x} = -2 \quad \frac{\partial^2 f}{\partial^2 y} = -6 \tag{1.6}$$

$$\frac{\partial^2 f}{\partial y \partial x} = 12 \quad \frac{\partial^2 f}{\partial x \partial y} = 12 \tag{1.7}$$

and build the Hessian matrix

$$\mathbf{H} = \begin{bmatrix} -2 & 12 \\ 12 & -6 \end{bmatrix}$$

We can check for positive or negative definiteness by looking at the sign of $|\mathbf{H}_1|$ and $|\mathbf{H}_2|$. Here $|\mathbf{H}_1| = -2$ and $|\mathbf{H}_2| = (-6)(-2) - (12)(12) = -136$. Since both determinants are negative, we conclude (0,0) is neither a maximum nor minimum of f.

2 A QUADRATIC FUNCTION OF n VARIABLES HAS THE FOLLOWING STANDARD FORM

$$f(\mathbf{x}) = \mathbf{x}^T A \mathbf{x} / 2 + \mathbf{b}^T \mathbf{x} + c$$

, where ${\pmb x}$ is the vector containing the n variables. Vector ${\pmb b}(n\times 1)$ and symmetric matrix ${\pmb A}(n\times n)$ contain constant coefficients. For the following two quadratic functions $f_a({\pmb x})=x_1^2+2x_1x_2+3x_2^2$ and $f_b({\pmb x})=-x_1^2-x_2^2-x_3^2+2x_1x_2+6x_1x_3+4x_1-5x_3+7$, please

2.1 Rewrite these functions in the standard quadratic function form.

In the standard quadratic form, the first product $\mathbf{x}^T A \mathbf{x}$ produces the quadratic terms and the combinations $\mathbf{x}_i \mathbf{x}_j, i \neq j$. For f_a , on the diagonals of A we place the coefficients of the quadratic terms, in this case 2 and 6. Outside of the diagonals we place the half of the combinations $\mathbf{x}_1 \mathbf{x}_2$, or 2 in this case. The product $\mathbf{b}^T \mathbf{x}$ would take care of any single first order variables $x_i, i = 1, 2$; however f_a does not have such factors. The final quadratic form for $f_a(\mathbf{x})$ is

$$f_a(\mathbf{x}) = \frac{1}{2} \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 2 & 2 \\ 2 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + 0 \tag{2.1}$$

The process is similar for f_b . On the diagonals we place the coefficients of the second order components, and off the diagonals the coefficients of $x_i x_j, i \neq j$. Next, **b** will contain

the first order coefficients, here 4,0,-5 for x_1,x_2,x_3 , respectively. The standard quadratic formula for $f_b(\boldsymbol{x})$ is

$$f_b(\mathbf{x}) = \frac{1}{2} \begin{bmatrix} x_1 & x_2 & x_3 \end{bmatrix} \begin{bmatrix} -2 & 2 & 6 \\ 2 & -2 & 0 \\ 6 & 0 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 4 & 0 & -5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + 7 \tag{2.2}$$

2.2 For these functions, show that $\nabla f = Ax + b$.

The gradient vector $\nabla f(\mathbf{x})$ is the vector containing the partial derivatives $\frac{\partial f}{\partial x_i}$.

$$\nabla f_a(\mathbf{x}) = \begin{bmatrix} 2x_1 + 2x_2 \\ 2x_1 + 6x_2 \end{bmatrix}$$

and the product Ax + b is

$$\begin{bmatrix} 2 & 2 \\ 2 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 2x_1 + 2x_2 \\ 2x_1 + 6x_2 \end{bmatrix}$$

which shows that $\nabla f_a(\mathbf{x}) = A\mathbf{x} + \mathbf{b}$.

For the second equation

$$\nabla f_b(\mathbf{x}) = \begin{bmatrix} -2x_1 + 2x_2 + 6x_3 + 4 \\ -2x_2 + 2x_1 \\ -2x_3 + 6x_1 - 5 \end{bmatrix}$$

and the product Ax + b is

$$\begin{bmatrix} -2 & 2 & 6 \\ 2 & -2 & 0 \\ 6 & 0 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 4 \\ 0 \\ -5 \end{bmatrix} = \begin{bmatrix} -2x_1 + 2x_2 + 6x_3 + 4 \\ -2x_2 + 2x_1 \\ -2x_3 + 6x_1 - 5 \end{bmatrix}$$

which again shows $\nabla f_b(\mathbf{x}) = A\mathbf{x} + \mathbf{b}$.

2.3 For these functions, determine whether the matrix A is positive definite, negative definite, or indefinite.

The textbook mentions two methods to check whether the matrix is positive definite, negative definite, or semi-definite. The first method involves checking the signs of the eigenvalues of A. The second involves checking the sign of the determinants of the submatrices A_1, A_2, \ldots, A_n . For $f_a(\mathbf{x})$ this would be

$$|A_1| = |2|$$
 and $|A_2| = \begin{vmatrix} 2 & 2 \\ 2 & 6 \end{vmatrix} = (2)(6) - (2)(2) = 8$

Since $|A_1|$ and $|A_2|$ are positive, A is positive definite.

For $f_b(\mathbf{x})$ we repeat the same procedure, we check the signs of $|A_1|, |A_2|$ and $|A_3|$.

$$|A_1| = -2$$

 $|A_2| = (-2)(-2) - (2)(2) = 0$
 $|A_3| = -2(4) - 2(-4) + 6(-12) = 72$

Since there are both negative and positive determinants for the submatrices of A, the matrix of $f_b(\mathbf{x})$ is indefinite.

3 Minimize the following functions subject to equality and/or inequality constraints. For problems with inequality constraints, identify the active ones. To know whether a point is local minimum, perform function evalutation at 2 nearby points (which satisfy constraints) to show that what you found is local minimum.

3.1 $f(x, y) = 1/(xy)^2$, subject to $x^2 + y^2 = 1$

Using the Lagrange multiplier method, we first define our Lagrange function L

$$L(x, y, \lambda) = \frac{1}{(xy)^2} + \lambda(1 - x^2 - y^2)$$

and find the partial derivatives of x, y, and λ .

$$\frac{\partial L}{\partial x} = -2x^{-3}y^{-2} - 2\lambda x \tag{3.1}$$

$$\frac{\partial L}{\partial y} = -2x^{-2}y^{-3} - 2\lambda y \tag{3.2}$$

$$\frac{\partial L}{\partial \lambda} = 1 - x^2 - y^2 \tag{3.3}$$

When we solve for λ in Equation 3.1, we get $\lambda = -x^{-4}y^{-2}$. Substituting for λ in Equation 3.2, we get

$$-2x^{-2}y^{-3} - 2y(-x^{-4}y^{-2})$$

which in the end gives us y = x. Plugging this result in Equation 3.3, we get the result

$$x = y = \frac{1}{\sqrt{2}}$$

which gives us a value of 4 in f. To show $(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$ is a local minimum, we plot some nearby points. We chose the points (0.69, 0.7238) and (0.72, 0.694), which lie on either side of our proposed minimum, and evaluate

$$f(0.69, 0.7238) = 4.009$$

$$f(0.72, 0.694) = 4.005$$

which supports our claim that $(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$ is a minimum.

3.2
$$f(x, y) = x^2 - 2x + y^2 - 10y$$
, subject to $-x^2 + y \le 4$ and $-(x-2)^2 + y \le 3$