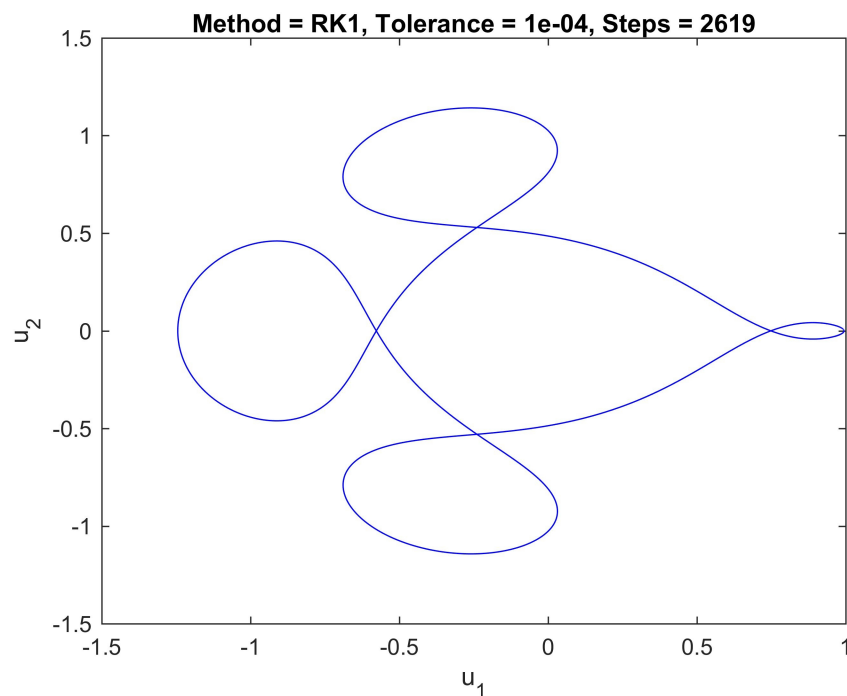
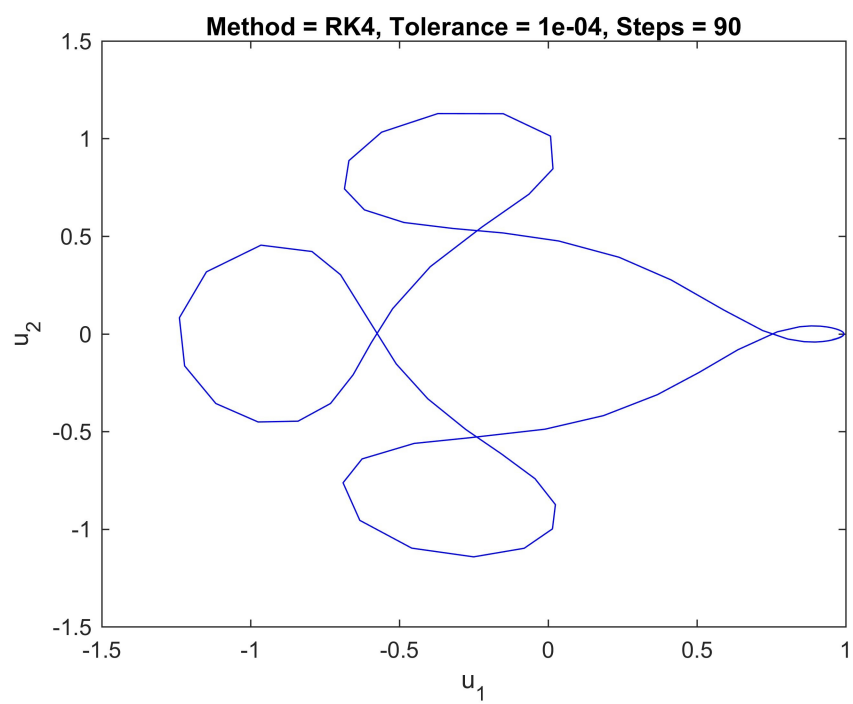
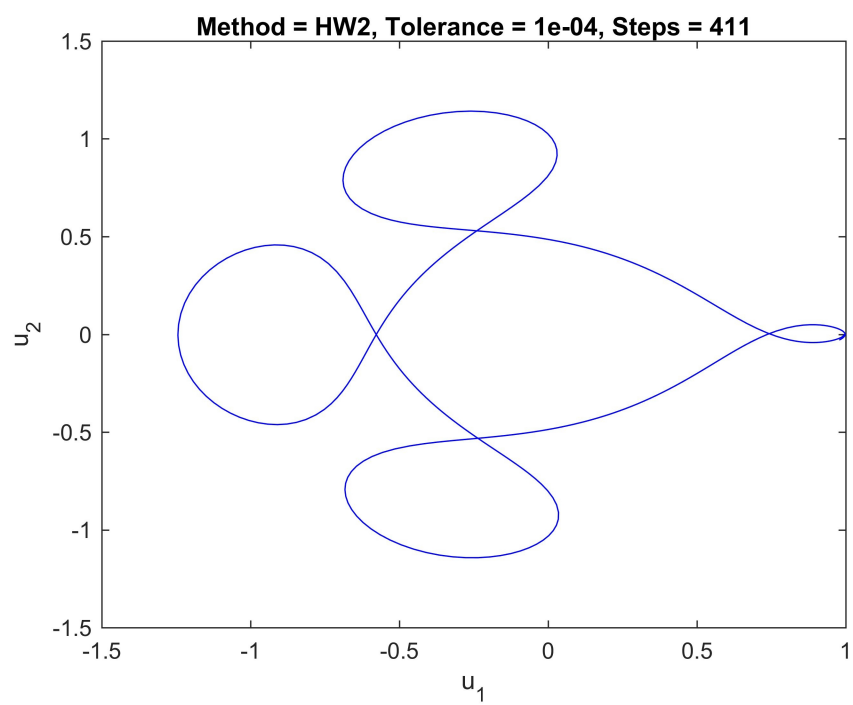


Andrew Alferman
MTH 552
Homework #4
Due Wed, Feb 15, 2017

- 1) The attached MATLAB code has been modified as directed. The code allows for either fixed stepsize or automatic stepsize to be selected, depending if the value assigned to “autostep” is true or false. The “method” variable represents the numerical method to be used; 'RK1' and 'ExplicitEuler' represent the Euler method, 'RK4' represents the RK method from problem 2 of Assignment 2, and 'HW2' represents the RK method from problem 2 of Assignment 2 (modified per email on 2/14/17). The “steps” variable counts how often the function f is being evaluated.

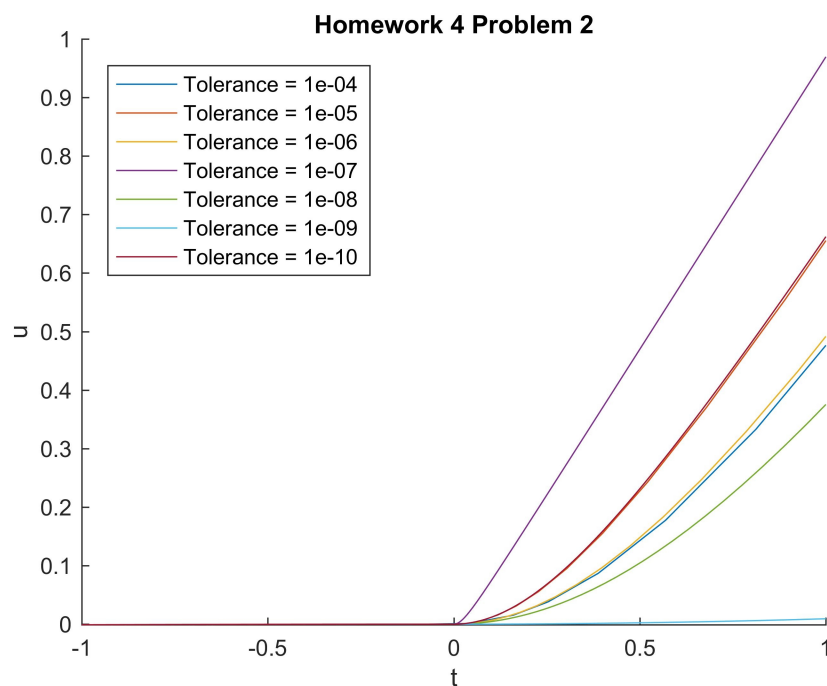
A tolerance of 1×10^{-4} was selected because it yielded plot of u_1 versus u_2 that was approximately correct visually for all three methods evaluated. A tolerance value of 2×10^{-4} with the HW2 method yielded a plot that was noticeably distorted near the completion of the first orbit, while the HW2 method and RK4 methods yielded acceptable plots at that tolerance value. The RK4 plot appeared slightly jagged in some portions of the orbit due to the small number of steps used. The code output the figures below. The number of steps can be found on each plot. All three methods came up with comparable plots, however the RK4 method was faster than the other two methods. On the computer used to produce the figures, the RK1 compiled in approximately 0.315 seconds, the HW2 method compiled in 0.270 seconds, and the RK4 method compiled in 0.244 seconds.





- 2) The attached code has been modified as directed. At first, it appears as if the solution to the IVP is completely flat for $-1 \leq t \leq 0$, while each of the curves for $0 < t \leq 1$ are different for each of the tolerances that were evaluated. This result is illustrated below:

Upon
closer



inspection, by limiting the y axis to $-0.001 \leq u \leq 0.001$ it can be seen that the IVP converges from $-1 \leq t \leq 0$, and the solution blows up when $t > 0$. The results do not converge when $t > 0$, and therefore the RK4 method may be unstable in this range.

