

## Simulation 1

Simulation builds out a complete steady state drive and equivalent DC motor circuit model of problem 7.4 from the textbook

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### Variables

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```
Ra = 0.35; % [ohms]
La = 1.5e-3; % [H]
ke = 0.5; % [V/rad/s]
kt = 0.5; % [Nm/A]
Jm = 0.02; % [kgm^2]
T = 3; % [Nm]
w = 1500*((2*pi)/60); % [rad/s]
Vdc = 200; % [V]
fs = 25000; % [Hz]
```

### Calculations

---

```
Ia = T/kt; % [A]
ea = ke*w; % [V]
Va = Ra*Ia + ea; % [V]
d = Va/Vdc; % reference for signals
```

### Simulink model

---

```
open_system('Simulation_1_model');
sim('Simulation_1_model');
```



```

title('Load Current');
xlabel('Time (sec)');
ylabel('Current (I)');
hold

% Load current zoomed
figure
plot(load_current.time(50001:50301),load_current.data(50001:50301));
title('Load Current (Zoomed)');
xlabel('Time (sec)');
ylabel('Current (I)');
hold

```

Current plot held  
 Current plot held  
 Current plot held  
 Current plot held  
 Current plot held  
 Current plot held







