Single and Multi-Metric Trust Management Frameworks for use in Underwater Autonomous Networks

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Recent Advances of Trust, Security and Privacy in Computing Communications (RATSP)

Multi-Metric Trust in UANs

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► Trust Methods in the MANET space applied to other arenas (e.g. underwater acoustics).

- ► These Trust Management Frameworks (TMFs) require reassessment to work the sparse, noisy and contested marine communications environment.
- ► Most rely on one¹type of observation (metric)
- ▶ Recent work (MTFM [1]) introduces the use of multiple types of continuous metrics for assessment.
- How do these Single and Multi-Metric Frameworks perform in the challenging marine communications environment?
- What metrics are suitable for use underwater?

¹Packet Loss Rate (PLR) or other binary interaction success observation

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► TMFs provide information to assist the estimation of future states and actions of nodes within networks.

- Centralised methods (CA/TTP/PKI) unsuitable for dynamic decentralised networks[2].
- Need to detect, identify, & mitigate threats in a distributed fashion.

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► Hermes [3] - Bayesian estimation based on PLR; encapsulates both "Trust" and "Confidence")

- ► OTMF [4] Collaborative Assessments of Bayesian Trust, PLR.
- ► TSR [5] Builds HMM into Dynamic Source Routing (DSR), Session Loss Rate.
- CONFIDANT [6] Probabilistic PLR assessment, includes some topology and reputational weighting.
- Fuzzy Trust-Based Filtering [7] Fuzzy classification on the nature of packet delivery (eg. "late", "unreliable", "unknown", etc.)

Most can be generalised as single-value estimations of PLR/Successful Routes, with the incorporation of some *meta*-observations e.g. Topology

Single Metric TMFs present opportunities for malicious

constrained environments (e.g. power, mobility, channel

actors to undermine the operation of a network.

operating concern, but is significant in resource

occupancy, physical location)

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▶ Not an issue in networks where Comms. is the primary

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 Multi-metric Trust For MANETS (MTFM) [1] - Uses additional metrics such as Power, Throughput, Delay, etc. in addition to PLR to assess trust, as well as incorporating topological and metric weighting.

- Use of multiple metrics allows classification of behaviours through dynamic metric weighting.
- Use of Grey Relational Grading to provide dynamic runtime normalisation, assessing comparative trust within a cohort of actors.

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deferences

 $\theta_{k,j}^{t} = \frac{\min_{k} |a_{k,j}^{t} - g_{j}^{t}| + \rho \max_{k} |a_{k,j}^{t} - g_{j}^{t}|}{|a_{k,i}^{t} - g_{i}^{t}| + \rho \max_{k} |a_{k,i}^{t} - g_{i}^{t}|}$ (1)

$$\phi_{k,j}^{t} = \frac{\min_{k} |a_{k,j}^{t} - b_{j}^{t}| + \rho \max_{k} |a_{k,j}^{t} - b_{j}^{t}|}{|a_{k,j}^{t} - b_{j}^{t}| + \rho \max_{k} |a_{k,j}^{t} - b_{j}^{t}|} \qquad (2)$$

$$[\theta_k^t, \phi_k^t] = \left[\sum_{j=0}^M h_j \theta_{k,j}^t, \sum_{j=0}^M h_j \phi_{k,j}^t \right]$$
(3)

$$T_k^t = (1 + (\phi_k^t)^2 / (\theta_k^t)^2)^{-1}$$
 (4)

Where $a_{k,j}^t$ is the value of an observed metric x_j for a given node k at time t, g and b are respectively the "good" and "bad" reference metric sequences from $\{a_{k,j}^t k=1,2\dots K\}$, $H=[h_0\dots h_M]$ is a metric weighting vector such that $\sum h_j=1$

Multi-Metric TMF III

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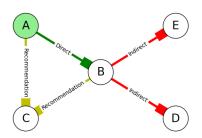
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This Grey Trust value is then combined²with the shared assessments from other actors in the network weighted based on their relative topology to provide a final value; $T_{i,i}^{MTFM}$



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Guo et al.[1] demonstrated that MTFM operates favourably in 802.11 based terrestrial MANETs against OTMF and Hermes, and can accurately detect, identify, & characterise misbehaviours within a group of six nodes, with n_0 as the primary observer and n_1 as the misbehaver.

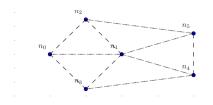


Fig. 1: Initial Node Layouts in [1]

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Key Characteristics of the Marine Acoustic Channel [8, 9, 10, 11]:

- ► Slow propagation (1400*ms*⁻¹) incurring long delays
- Inter-symbol interference
- Doppler Spreading
- Non-Linear propagation due to refraction
- Fast & Slow fades from environmental factors (flora/fauna/surface and seabed conditions)
- Freq. dependant attenuation
- Significant destructive multipath effects

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The attenuation that occurs in an underwater acoustic channel over a distance d for a signal about frequency f in linear power is given as $A_{aco}(d, f) = A_0 d^k a(f)^d$ and in dB form as:

$$10 \log A_{aco}(d, f) / A_0 = k \cdot 10 \log d + d \cdot 10 \log a(f)$$
 (5)

where A_0 is a normalising constant, k is a spreading factor (commonly taken as 1.5 [10]), and a(f) is the absorption coefficient, approximated using Thorp's formula [11]

$$10\log a(f) = \frac{0.11 \cdot f^2}{1 + f^2} + \frac{44 \cdot f^2}{4100 + f^2} + 2.75 \times 10^{-4} f^2 + 0.003$$
(6)

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Compared to RF Free space PL: $(A_{RF}(d, f) \approx (\frac{4\pi df}{c})^2)$

- Exponential in d: $A_{\rm aco} \propto f^{2d}$ vs $A_{\rm RF} \propto (df)^2$
- Quadratic f factor four orders higher in $f \propto A_{\rm aco}$ vs $f \propto A_{\rm RF}$

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Context:

- Fleets of up to 16 collaborating
 Autonomous Underwater
 Vehicles(AUVs)
- Constrained in Power, Mobility, Processing, Storage Capacity
- Tasked to perform ongoing survey of an area

Communications Efficiency is not the only operational asset at risk from malicious exploitation



Fig. 2: REMUS 100 AUV as deployed at NATO CMRE La Spezia

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► Simulations based on SimPy [12], Network stack using AUVNetSim [13] and channel constraints based on Stojaovic and Stefanov [10, 11] ▶ Details

- ► Established a safe operating zone in terms of communications rate and node distances to optimise for delay/throughput at 0.015pps and avg. init. range 300m Details
- Six per-link communications metrics: TX/RX
 Throughput/Power, Delay and PLR, lacking the 802.11
 Data Rate metric from [1]

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Two misbehaviours developed:

- ▶ Malicious Power Control(MPC) attacker n_1 aims to make n_0 appear selfish by increasing power to all nodes except to/from n_0
- ► Selfish Target Selection(STS) n₁ preferentially communicates with nodes close to it, to conserve its own power.

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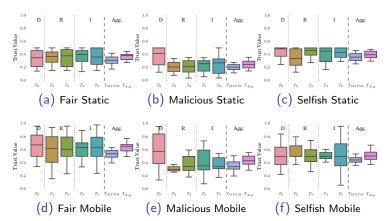


Fig. 3: Observations of n_1 ($T_{1,X}$), showing Direct, Recommender and Indirect relationships and T_{MTFM} and T_{AVG} Closeup

Key Observations:

- Mobility greatly increases variation in instantaneously observed trust
- $ightharpoonup T_{MTFM}$ remains more stable in both mobility cases when compared to either single-node assessments or T_{Avg}
- Raw T_{MTGM} isn't perfect; in Fig 6e demonstrates huge variability in Direct assessment (T_{1,0}) that isn't reflected in T_{MTFM}. Partially expected in this directed attack.
- ► Larger general variability in observations in "Fair" case compared to misbehaviours

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Blind Comparison of Single/Multi-metric TMFs

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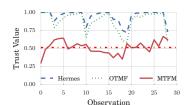
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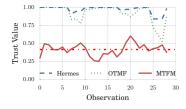
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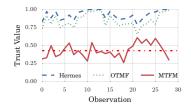
Blind Comparison of Single/Multi-metric TMFs I



(a) Fair Scenario



(c) Selfish Target Selection Scenario



(b) Malicious Power Control Scenario

 $T_{1,0}$ for Hermes, OTMF and MTFM assessment values for fair and malicious behaviours in the fully mobile scenario (mean of MTFM also shown)

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- Neither misbehaviour, while impacting network fairness, directly affects PLR
- ► MTFM's Cohort Comparison means in the fair case, 0.5 is expected
- ▶ In OTMF/Hermes, T 1 is expected
- Neither OTMF, Hermes or Blind MTFM are particularly effective
- ► MTFM indicates 10% selectivity between Fair and Either Misbehaviour

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From 3, metric emphasise can be adjusted, highlighting misbehaviour in particular metric areas

$$[\theta_k^t, \phi_k^t] = \left[\sum_{j=0}^M h_j \theta_{k,j}^t, \sum_{j=0}^M h_j \phi_{k,j}^t \right]$$
 (7)

$$T_k^t = (1 + (\phi_k^t)^2 / (\theta_k^t)^2)^{-1}$$
 (8)

Malicious Power Control - Weighted Emphasis

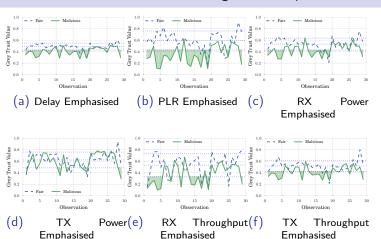


Fig. 4: $T_{1,MTFM}$ in the All Mobile case for the Malicious Power Control behaviour, including dashed $\pm \sigma$ envelope about the fair scenario Coseup

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Selfish Target Selection - Weighted Emphasis

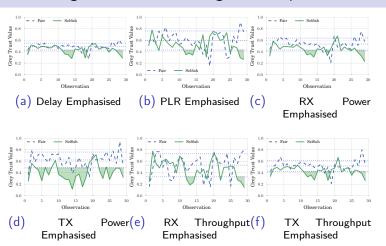


Fig. 5: $T_{1,MTFM}$ in the All Mobile case for the Selfish Target Selection behaviour, including dashed $\pm \sigma$ envelope about the fair scenario Closeup

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Key Observations:

- ▶ In MPC case:
 - Consistently outside $\pm \sigma$ in all but P_{TX} , particularly PLR
 - ▶ Less so in Delay, P_{RX} and T_{TX}
- In STS case:
 - ▶ Less overall impact, except when P_{TX}
- In General:
 - Qualatatively similar to similar experiments performed in [1] in RF Terrestrial MANET
 - ► Lower differences between misbehaviour/fair cases
 - Less consistent deviations
 - More useful than OTMF/Hermes but still not perfect

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- ▶ Distributed Random Forest Regression [14]
- ▶ 729 Metric Weight Vectors (H), 512 random trees
- ▶ 16 Random starts of each of the 3 scenarios for 6 nodes for 6 hour "missions"
- ▶ Targeting area of $\pm \sigma$ deviation $\int abs(T_m \overline{T}_f) \sigma_{T_f}$
- Regression identifies the significance of metrics in classifying between the three possible behaviours

Regression of Metric Significance II



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	0.6		Fair/MP	c	Fair/STS		MPC/STS
o	0.5						
Significance	0.4						
	0.3						
Relative	0.2						
Rela	0.1						
	0.0		P_{RX}	P_{TX}	mP.	TP.	DI B
		Delay	r_{RX}	TTX	T_{RX}^{P}	T_{TX}^{P}	PLR

Correlation	Delay	P_{RX}	P_{TX}	T_{RX}^{P}	T_{TX}^{P}	PLR
Fair / MPC Fair / STS MPC / STS	0.199	0.159	-0.416	0.708	-0.238	-0.401
Fair / STS	0.179	-0.009	0.724	-0.697	-0.145	-0.052
MPC / STS	0.058	-0.134	0.146	-0.768	0.052	0.146

Key Observations:

- PLR not necessarily the most important metric
- Combination of Significance and Correlations demonstrate selectivity opportunity
- MTFM has capability to finely discriminate between similar misbehaviours
- PLR impact is minimal in STS, would not be detected by OTMF/Hermes even in less sparse/harsh environment
- ► Identifying this classification "comb" is computationally intensive and grows exponentially with number of metrics involved for brute force regression

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- Include Physical Observations in Metric Set
 - Assess benefits / drawbacks of domain separation / joining
 - Assess complexity vs selectivity of derived classifications
- Perform / Initiate practical trials in collaborations with NATO CMRE

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 Trust Underwater is Hard, but it's mostly the environments' fault

- ► Single-Metric Trust is unstable in such an environment
- Multi-Metric Trust works and can discriminate between behaviours
- ▶ Not all metrics are equally useful
- Outlook
 - Extending to include Physical Metrics
 - Developing runtime heuristics to improve complexity
 - Perform untrained classification performance on real data

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$$T_{i,j}^{MTFM} = \frac{1}{2} \cdot \max_{s} \{f_{s}(T_{i,j})\} T_{i,j}$$

$$+ \frac{1}{2} \frac{2|N_{R}|}{2|N_{R}| + |N_{I}|} \sum_{n \in N_{R}} \max_{s} \{f_{s}(T_{i,n})\} T_{i,n}$$

$$+ \frac{1}{2} \frac{|N_{I}|}{2|N_{R}| + |N_{I}|} \sum_{n \in N_{L}} \max_{s} \{f_{s}(T_{i,n})\} T_{i,n}$$
(9)

Where $T_{i,n}$ is the subjective trust assessment of n_i by n_n , and $f_s = [f_1, f_2, f_3]$ given as...

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$$f_1(x) = -x + 1$$

$$f_2(x) = \begin{cases} 2x & \text{if } x \le 0.5 \\ -2x + 2 & \text{if } x > 0.5 \end{cases}$$

$$f_3(x) = x$$
(10)

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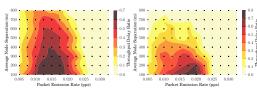
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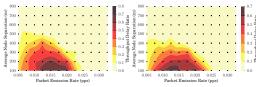
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- (a) All Nodes Static
- (b) n_1 Random Walk



(c) All nodes but $n_1(d)$ All nodes Random Random Walk Walk

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Table 1: Comparison of system model constraints as applied between Terrestrial and Marine communications

Parameter	Unit	Terrestrial	Marine
Simulated Duration	s	300	18000
Trust Sampling Period	S	1	600
Simulated Area	km^2	0.7	0.7-4
Transmission Range	km	0.25	1.5
Physical Layer		RF(802.11)	Acoustic
Propagation Speed	m/s	3×10^8	1490
Center Frequency	Hz	$2.6 imes 10^9$	2×10^4
Bandwidth	Hz	22×10^6	$1 imes 10^4$
MAC Type		CSMA/DCF	CSMA/CA
Routing Protocol		DSDV	FBR
Max Speed	ms^{-1}	5	1.5
Max Data Rate	bps	$5 imes 10^6$	≈ 240
Packet Size	bits	4096	9600
Single Transmission Duration	s	10	32
Single Transmission Size	bits	10 ⁷	9600

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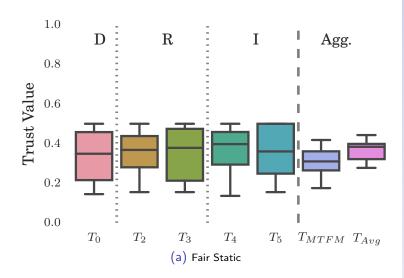
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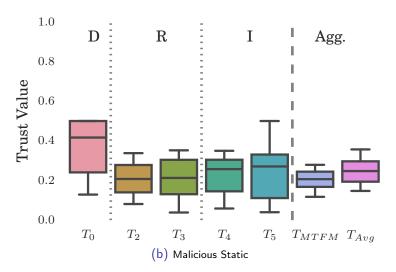


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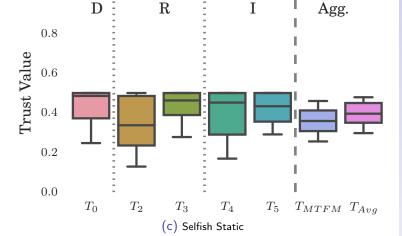
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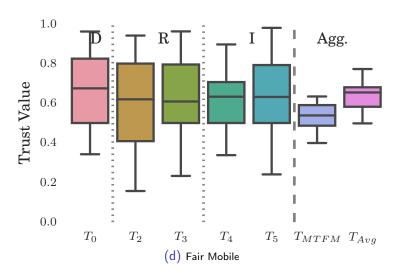


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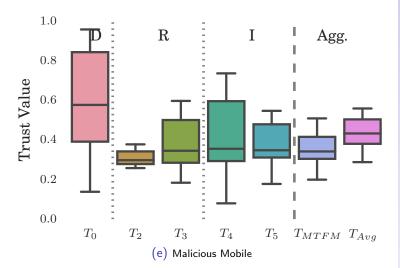
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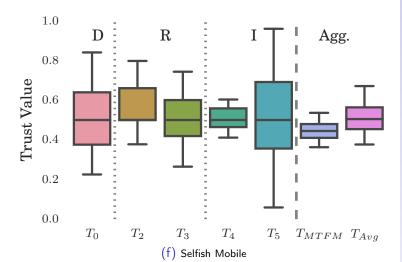


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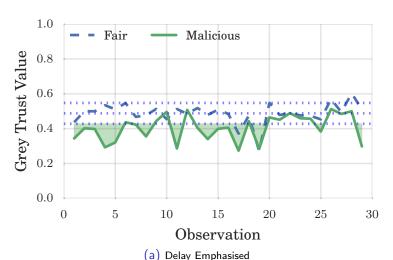
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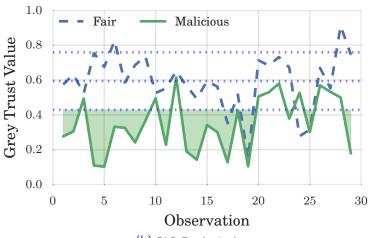
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(b) PLR Emphasised

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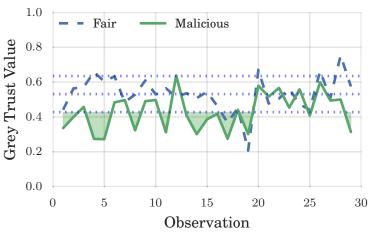
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(c) RX Power Emphasised

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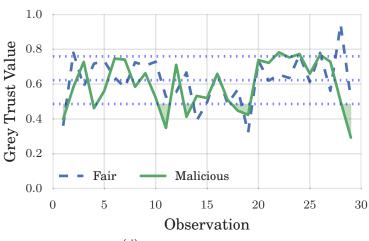
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(d) TX Power Emphasised

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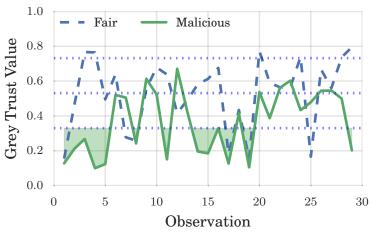
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(e) RX Throughput Emphasised

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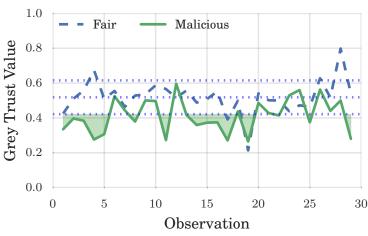
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(f) TX Throughput Emphasised



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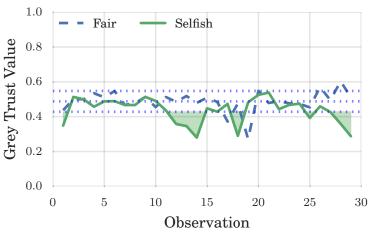
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(a) Delay Emphasised

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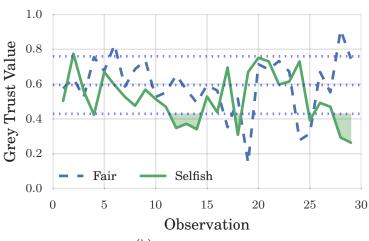
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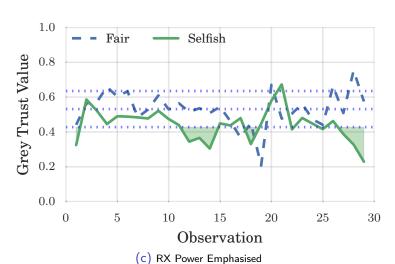


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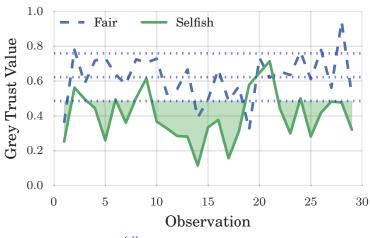
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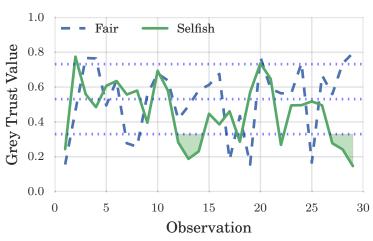
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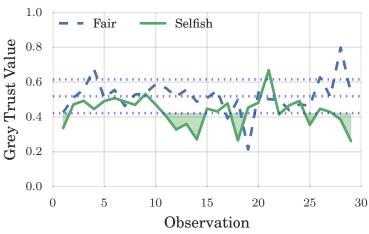
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