

Single and Multi-Metric Trust Management Frameworks for use in Underwater Autonomous Networks

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Recent Advances of Trust, Security and Privacy in
Computing Communications (RATSP)

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Challenges to Trust in Underwater Networks

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- ▶ Methods developed for establishing Communications Trust in the MANET space increasingly applied to other arenas such as the underwater realm.
- ▶ These Trust Management Frameworks (TMFs) must be reassessed with respect to the sparse, noisy and contested marine communications environment.
- ▶ Most MANET TMFs rely on one¹ type of observation (metric); recent work (MTFM [1]) introduces the use of multiple types of continuous metrics for assessment.
- ▶ How do these Single and Multi-Metric Frameworks perform in the challenging marine communications environment?
- ▶ What metrics are suitable for use underwater?

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¹Packet Loss Rate (PLR) or other binary success observation

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Trust in Conventional MANETS

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- ▶ TMFs provide information to assist the estimation of future states and actions of nodes within networks.
- ▶ Centralised methods (CA/TTP/PKI) unsuitable for dynamic decentralised networks[2].
- ▶ Need to detect, identify, & mitigate threats in a distributed fashion.

- ▶ *Hermes* [3] - Bayesian estimation based on PLR; encapsulates both “Trust” and “Confidence”)
- ▶ *OTMF* [4] - Collaborative Assessments of Bayesian Trust, PLR.
- ▶ *TSR* [5] - Builds HMM into Dynamic Source Routing (DSR), Session Loss Rate.
- ▶ *CONFIDANT* [6] - Probabilistic PLR assessment, includes some topology and reputational weighting.
- ▶ *Fuzzy Trust-Based Filtering* [7] - Fuzzy classification on the *nature* of packet delivery (eg. “late”, “unreliable”, “unknown”, etc.)

Most can be generalised as single-value estimations of PLR/Successful Routes, with the incorporation of some *meta*-observations eg Topology

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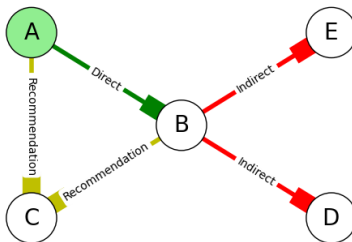
- ▶ Single Metric TMFs present opportunities for malicious actors to undermine the operation of a network if their attack does not directly impact packet delivery.
- ▶ Not an issue in networks where Comms. is the primary operating concern, but is significant in resource constrained environments (eg power, mobility, channel occupancy, physical location)

- ▶ *Multi-metric Trust For MANETS (MTFM)* [1] - Uses additional metrics such as Power, Throughput, Delay, etc. in addition to PLR to assess trust, as well as incorporating topological and metric weighting.
- ▶ Use of multiple metrics allows classification of behaviours through dynamic metric weighting.
- ▶ Use of Grey Relational Grading to provide dynamic runtime normalisation, assessing *comparative* trust within a cohort of actors.

$$T_k^t = (1 + (\phi_k^t)^2 / (\theta_k^t)^2)^{-1} \quad (4)$$

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This Grey Trust value is then combined² with the shared assessments from other actors in the network weighted based on their relative topology to provide a final value; $T_{i,j}^{MTFM}$



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Multi-Metric Compared to Single in MANETs

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Guo et al.[1] demonstrated that MTFM operates favourably in 802.11 based terrestrial MANETs against OTMF and Hermes, and can accurately detect, identify, & characterise misbehaviours within a group of six nodes, with n_0 as the primary observer and n_1 as the misbehavior.

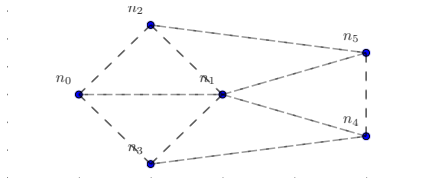


Fig. 1: Initial Node Layouts in [1]

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Key Characteristics of the Marine Acoustic Channel [8, 9, 10, 11]:

- ▶ Slow propagation ($1400ms^{-1}$) incurring long delays
- ▶ Inter-symbol interference
- ▶ Doppler Spreading
- ▶ Non-Linear propagation due to refraction
- ▶ Fast & Slow fades from environmental factors (flora/fauna/surface and seabed conditions)
- ▶ Freq. dependant attenuation
- ▶ Significant destructive multipath effects

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The attenuation that occurs in an underwater acoustic channel over a distance d for a signal about frequency f in linear power is given as $A_{\text{aco}}(d, f) = A_0 d^k a(f)^d$ and in dB form as;

$$10 \log A_{\text{aco}}(d, f)/A_0 = k \cdot 10 \log d + d \cdot 10 \log a(f) \quad (5)$$

where A_0 is a normalising constant, k is a spreading factor (commonly taken as 1.5 [10]), and $a(f)$ is the absorption coefficient, approximated using Thorp's formula [11]

$$10 \log a(f) = \frac{0.11 \cdot f^2}{1 + f^2} + \frac{44 \cdot f^2}{4100 + f^2} + 2.75 \times 10^{-4} f^2 + 0.003 \quad (6)$$

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Compared to RF Free space PL: $(A_{\text{RF}}(d, f) \approx (\frac{4\pi df}{c})^2)$

- ▶ Exponential in d : $A_{\text{aco}} \propto f^{2d}$ vs $A_{\text{RF}} \propto (df)^2$
- ▶ Quadratic f factor four orders higher in $f \propto A_{\text{aco}}$ vs $f \propto A_{\text{RF}}$

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- ▶ Simulations based on SimPy [12], Network stack using AUVNetSim [13] and channel constraints based on Stojaovic and Stefanov [10, 11] [▶ Details](#)
- ▶ Established a safe operating zone in terms of communications rate and node distances to optimise for delay/throughput at 0.015pps and avg. init. range 300m [▶ Details](#)
- ▶ Six per-link communications metrics: TX/RX Throughput/Power, Delay and PLR, lacking the 802.11 Data Rate metric from [1]

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Two misbehaviours developed:

- ▶ *Malicious Power Control*(MPC) - attacker n_1 aims to make n_0 appear selfish by increasing power to all nodes except to/from n_0
- ▶ *Selfish Target Selection*(STS) - n_1 preferentially communicates with nodes close to it, to conserve its own power.

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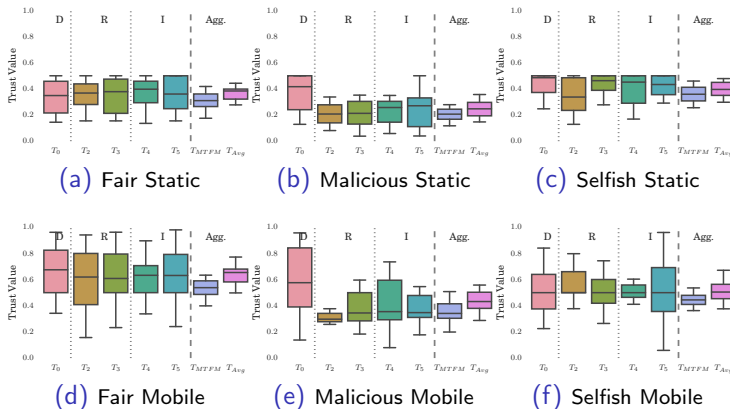
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Multi-Metric Operation I

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Fig. 3: Observations of n_1 ($T_{1,X}$), showing Direct, Recommender and Indirect relationships and T_{MTFM} and T_{Avg} [Closeup](#)

Key Observations:

- ▶ Mobility greatly increases variation in instantaneously observed trust
- ▶ T_{MTFM} remains more stable in both mobility cases when compared to either single-node assessments or T_{Avg}
- ▶ Raw T_{MTGM} isn't perfect; in Fig 6e demonstrates huge variability in Direct assessment ($T_{1,0}$) that isn't reflected in T_{MTFM} . Partially expected in this directed attack.
- ▶ Larger general variability in observations in “Fair” case compared to misbehaviours

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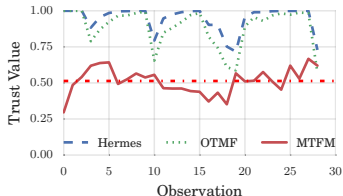
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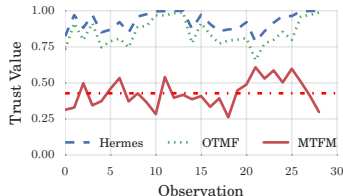
Blind Comparison of Single/Multi-metric TMFs I

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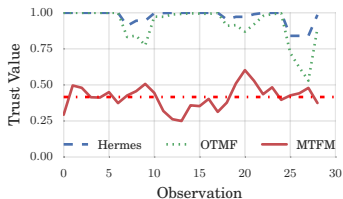
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(a) Fair Scenario



(b) Malicious Power Control Scenario



(c) Selfish Target Selection Scenario

$T_{1,0}$ for Hermes, OTMF and MTFM assessment values for fair and malicious behaviours in the fully mobile scenario (mean of MTFM also shown)

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Key Observations:

- ▶ Neither misbehaviour, while impacting network fairness, directly affects PLR
- ▶ MTFM's Cohort Comparison means in the fair case, 0.5 is expected
- ▶ In OTMF/Hermes, $T = 1$ is expected
- ▶ Neither OTMF, Hermes or Blind MTFM are particularly effective
- ▶ MTFM indicates 10% selectivity between Fair and Either Misbehaviour

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From 3, metric emphasise can be adjusted, highlighting misbehaviour in particular metric areas

$$[\theta_k^t, \phi_k^t] = \left[\sum_{j=0}^M h_j \theta_{k,j}^t, \sum_{j=0}^M h_j \phi_{k,j}^t \right] \quad (7)$$

$$T_k^t = (1 + (\phi_k^t)^2 / (\theta_k^t)^2)^{-1} \quad (8)$$

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Malicious Power Control - Weighted Emphasis

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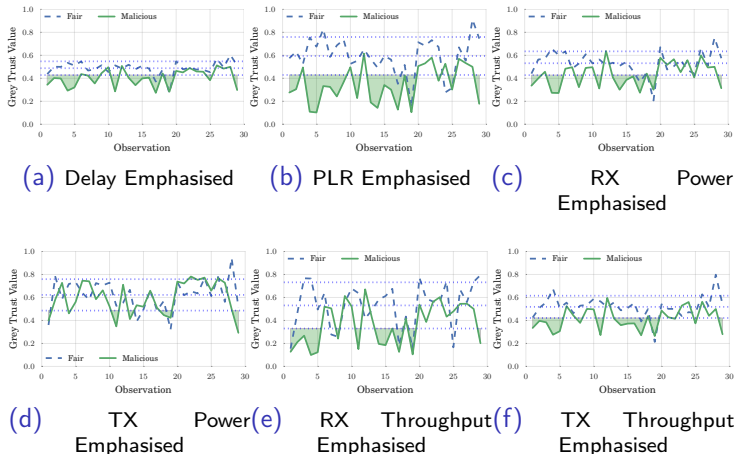


Fig. 4: $T_{1,MTFM}$ in the All Mobile case for the Malicious Power Control behaviour, including dashed $\pm\sigma$ envelope about the fair scenario [Closeup](#)

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Selfish Target Selection - Weighted Emphasis

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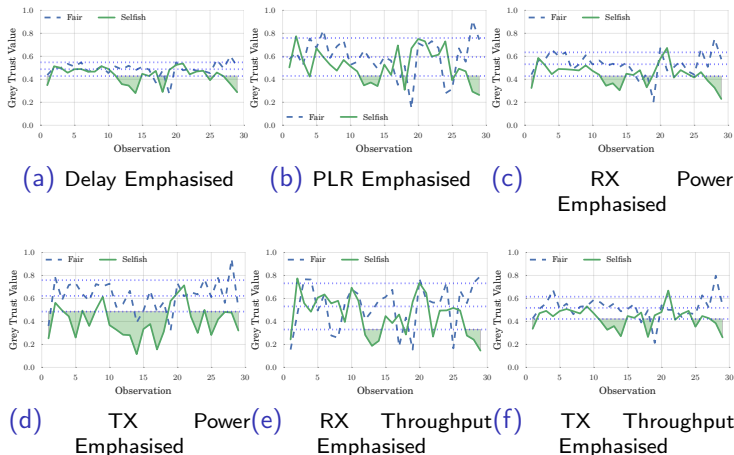


Fig. 5: $T_{1,MTFM}$ in the All Mobile case for the Selfish Target Selection behaviour, including dashed $\pm\sigma$ envelope about the fair scenario [Closeup](#)

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Key Observations:

- ▶ In MPC case:
 - ▶ Consistently outside $\pm\sigma$ in all but P_{TX} , particularly PLR
 - ▶ Less so in Delay, P_{RX} and T_{TX}
- ▶ In STS case:
 - ▶ Less overall impact, except when P_{TX}
- ▶ In General:
 - ▶ Qualatatively similar to similar experiments performed in [1] in RF Terrestrial MANET
 - ▶ Lower differences between misbehaviour/fair cases
 - ▶ Less consistent deviations
 - ▶ More useful than OTMF/Hermes but still not perfect

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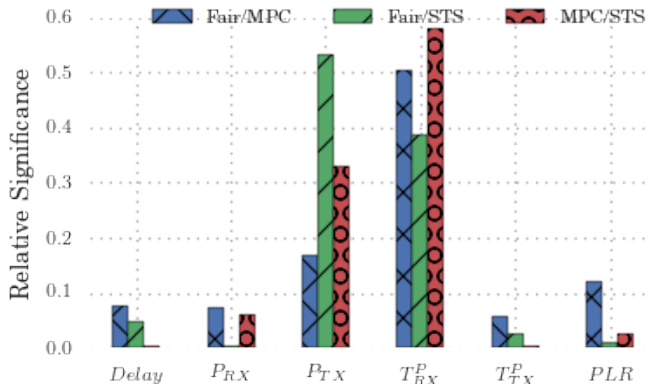
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- ▶ Distributed Random Forest Regression [14]
- ▶ 729 Metric Weight Vectors (H), 512 random trees
- ▶ 16 Random starts of each of the 3 scenarios for 6 nodes for 6 hour “missions”
- ▶ Targeting area of $\pm\sigma$ deviation $\int abs(T_m - \overline{T}_f) - \sigma_{T_f}$
- ▶ Regression identifies the significance of metrics in classifying between the three possible behaviours

Regression of Metric Significance II



Correlation	Delay	P_{RX}	P_{TX}	T_{RX}^P	T_{TX}^P	PLR
Fair / MPC	0.199	0.159	-0.416	0.708	-0.238	-0.401
Fair / STS	0.179	-0.009	0.724	-0.697	-0.145	-0.052
MPC / STS	0.058	-0.134	0.146	-0.768	0.052	0.146

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Key Observations:

- ▶ PLR not necessarily the most important metric
- ▶ Combination of Significance and Correlations demonstrate selectivity opportunity
- ▶ MTFM has capability to finely discriminate between similar misbehaviours
- ▶ PLR impact is minimal in STS, would not be detected by OTMF/Hermes even in less sparse/harsh environment
- ▶ Identifying this classification “comb” is computationally intensive and grows exponentially with number of metrics involved for brute force regression

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- ▶ Include Physical Observations in Metric Set
 - ▶ Assess benefits / drawbacks of domain separation / joining
 - ▶ Assess complexity vs selectivity of derived classifications
- ▶ Perform / Initiate practical trials in collaborations with NATO CMRE

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- ▶ Trust Underwater is **Hard**, but it's mostly the environments' fault
- ▶ Single-Metric Trust is **unstable** in such an environment
- ▶ Multi-Metric Trust works and can **discriminate between behaviours**
- ▶ **Not all metrics** are equally useful
- ▶ Outlook
 - ▶ Extending to include Physical Metrics
 - ▶ Developing runtime heuristics to improve complexity
 - ▶ Perform untrained classification performance on real data



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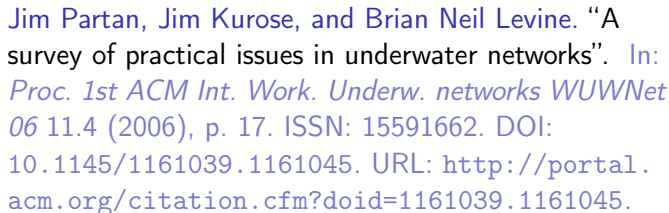
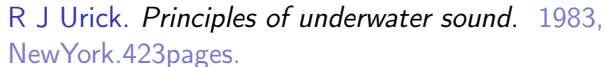
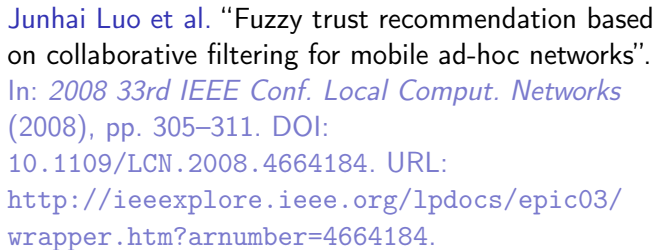
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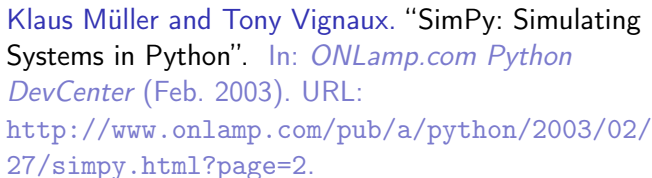
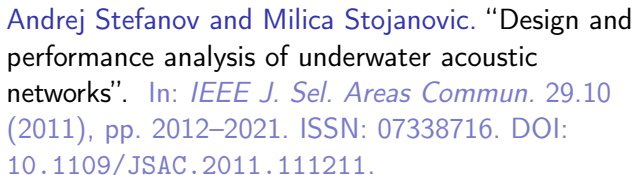
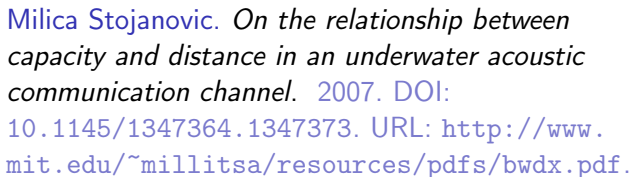
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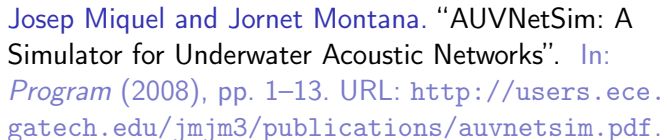
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$$\begin{aligned} T_{i,j}^{MTFM} = & \frac{1}{2} \cdot \max_s \{f_s(T_{i,j})\} T_{i,j} \\ & + \frac{1}{2} \frac{2|N_R|}{2|N_R| + |N_I|} \sum_{n \in N_R} \max_s \{f_s(T_{i,n})\} T_{i,n} \\ & + \frac{1}{2} \frac{|N_I|}{2|N_R| + |N_I|} \sum_{n \in N_I} \max_s \{f_s(T_{i,n})\} T_{i,n} \end{aligned} \quad (9)$$

Where $T_{i,n}$ is the subjective trust assessment of n_i by n_n ,
and $f_s = [f_1, f_2, f_3]$ given as...

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$$\begin{aligned}f_1(x) &= -x + 1 \\f_2(x) &= \begin{cases} 2x & \text{if } x \leq 0.5 \\ -2x + 2 & \text{if } x > 0.5 \end{cases} \\f_3(x) &= x\end{aligned}\tag{10}$$

Comms Scaling Graphs I

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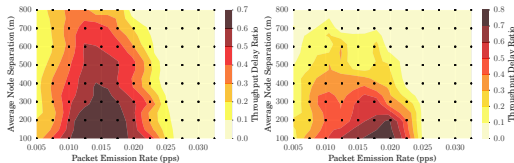
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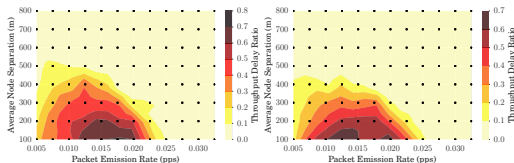
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(a) All Nodes Static

(b) n_1 Random Walk



(c) All nodes but
Random Walk

(d) All nodes Random
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System Model Constraints

Table 1: Comparison of system model constraints as applied between Terrestrial and Marine communications

Parameter	Unit	Terrestrial	Marine
Simulated Duration	<i>s</i>	300	18000
Trust Sampling Period	<i>s</i>	1	600
Simulated Area	<i>km</i> ²	0.7	0.7-4
Transmission Range	<i>km</i>	0.25	1.5
Physical Layer		RF(802.11)	Acoustic
Propagation Speed	<i>m/s</i>	3×10^8	1490
Center Frequency	<i>Hz</i>	2.6×10^9	2×10^4
Bandwidth	<i>Hz</i>	22×10^6	1×10^4
MAC Type		CSMA/DCF	CSMA/CA
Routing Protocol		DSDV	FBR
Max Speed	<i>ms</i> ⁻¹	5	1.5
Max Data Rate	<i>bps</i>	5×10^6	≈ 240
Packet Size	bits	4096	9600
Single Transmission Duration	<i>s</i>	10	32
Single Transmission Size	bits	10^7	9600

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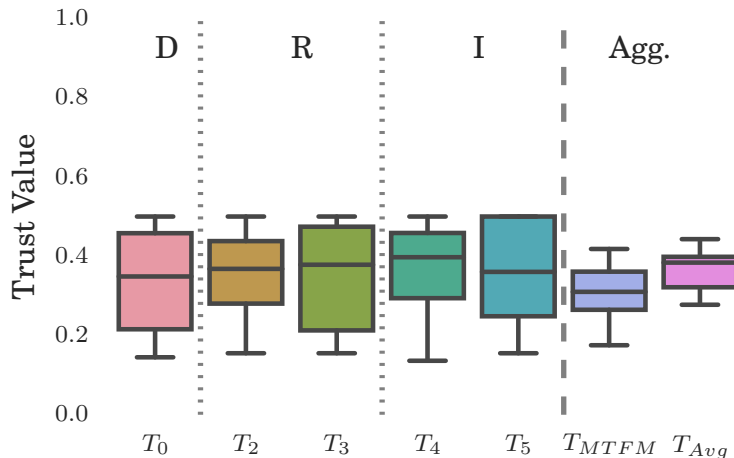
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(a) Fair Static

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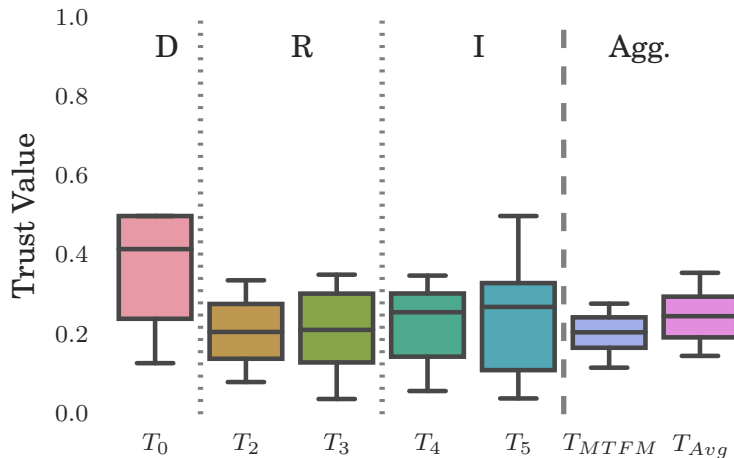
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(b) Malicious Static

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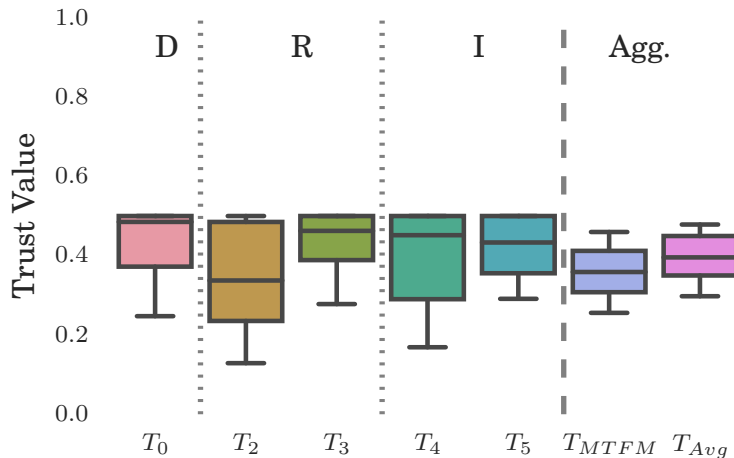
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(c) Selfish Static

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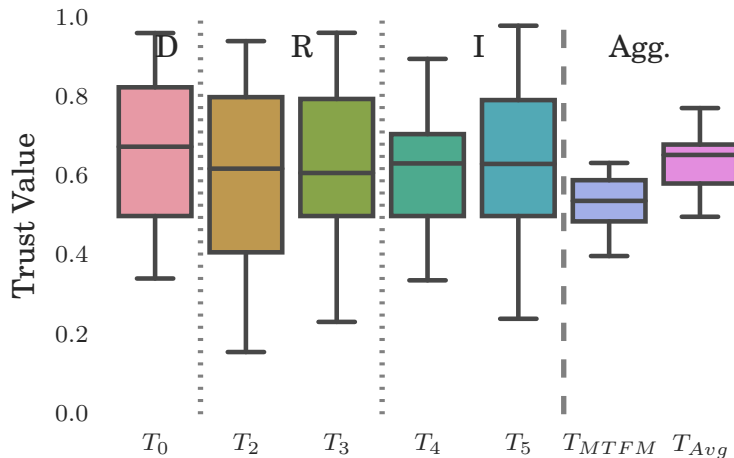
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(d) Fair Mobile

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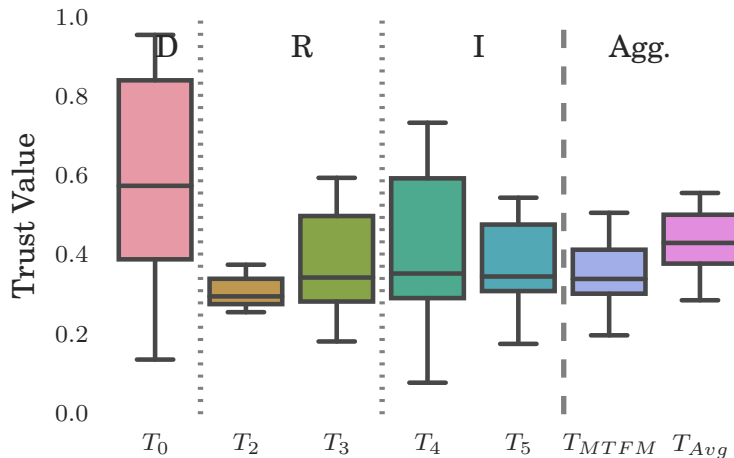
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(e) Malicious Mobile

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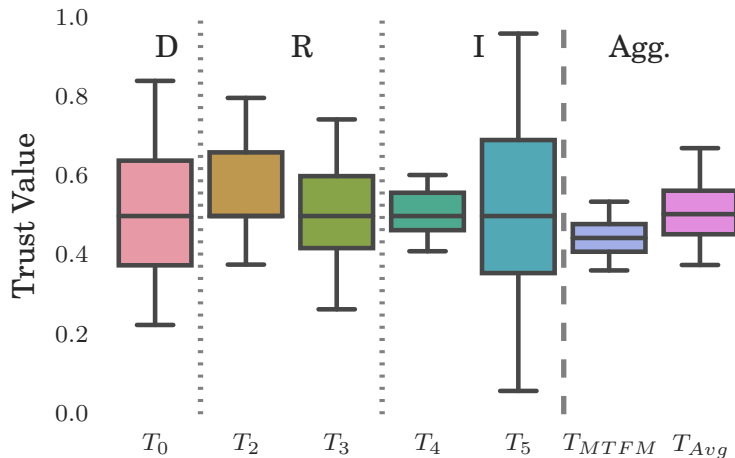
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(f) Selfish Mobile

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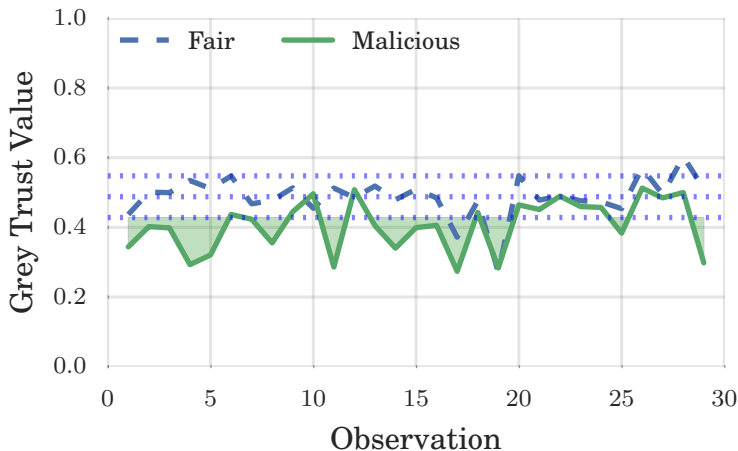
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(a) Delay Emphasised

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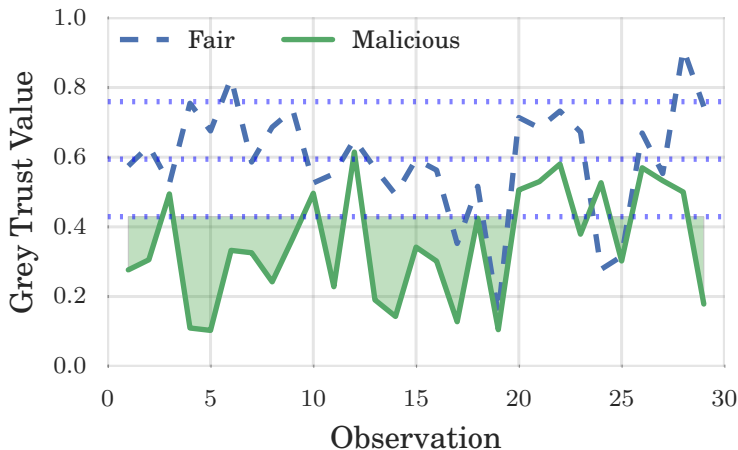
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(b) PLR Emphasised

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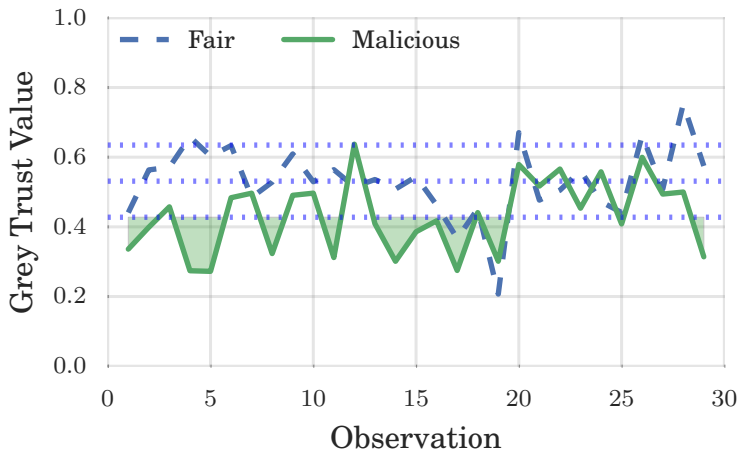
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(c) RX Power Emphasised

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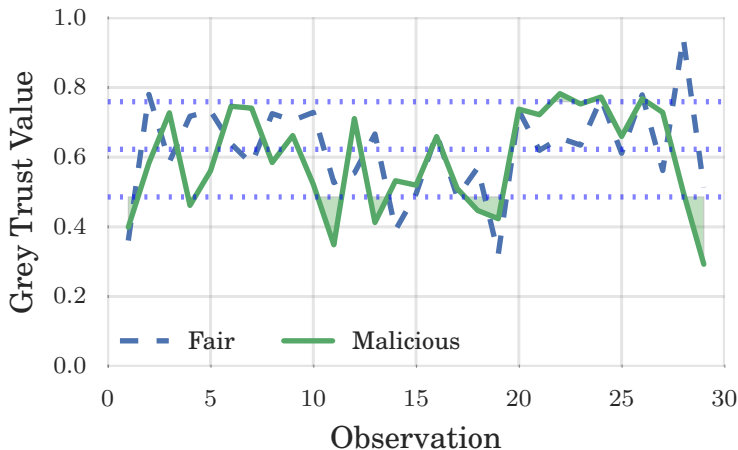
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(d) TX Power Emphasised

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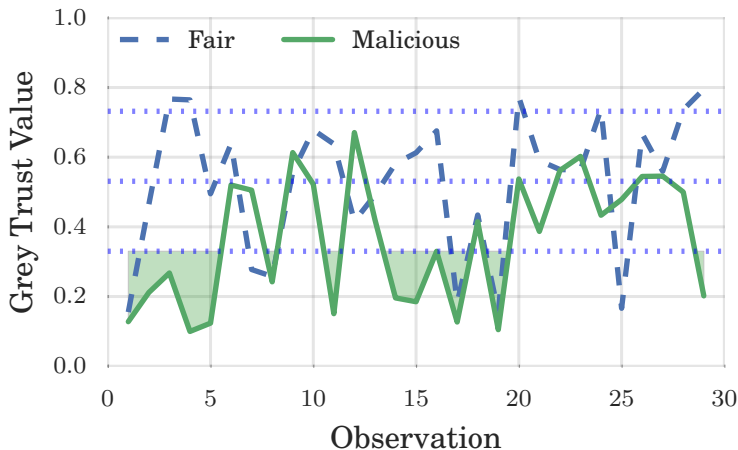
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(e) RX Throughput Emphasised

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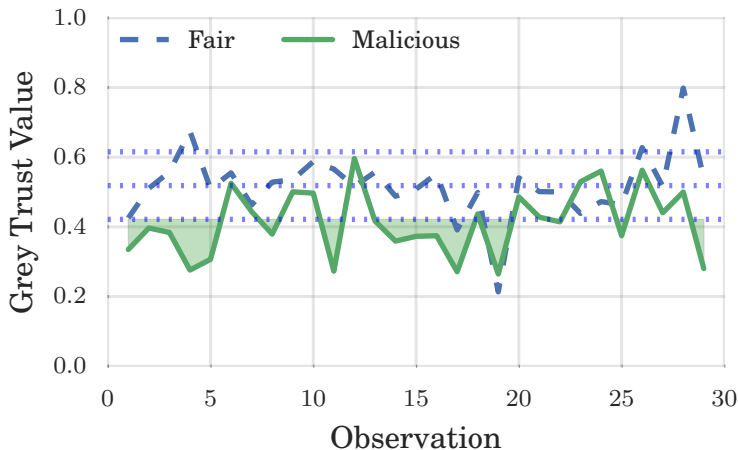
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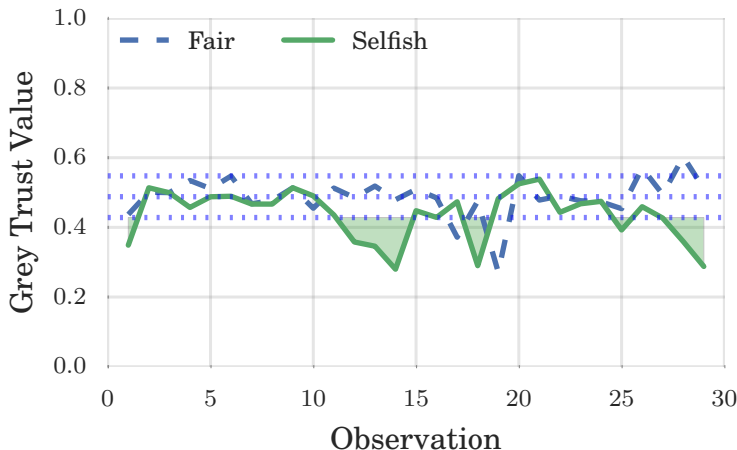
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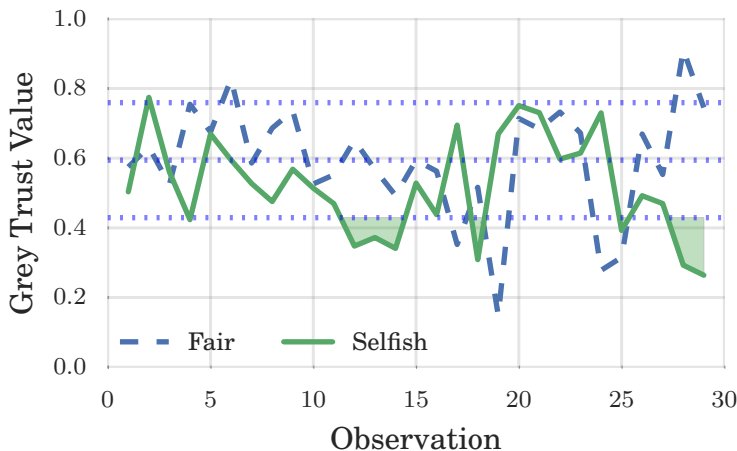
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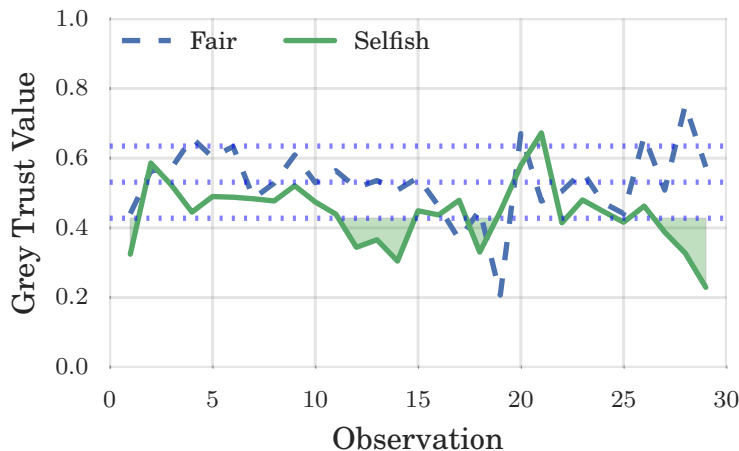
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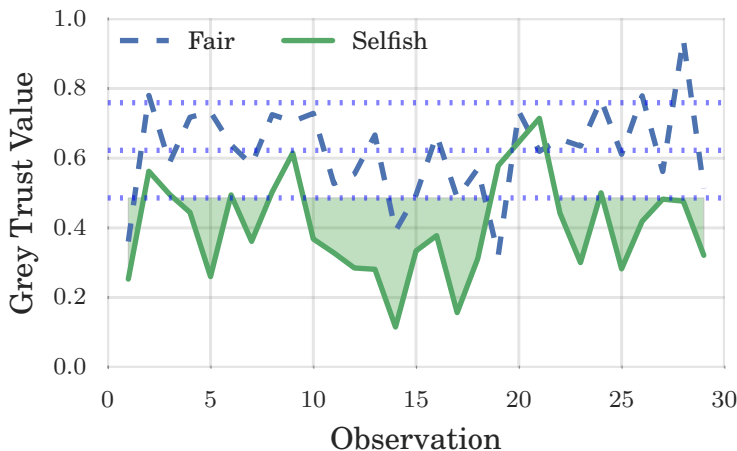
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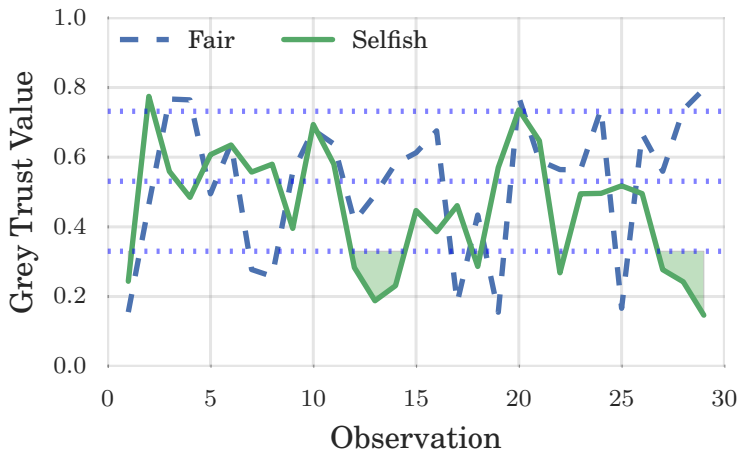
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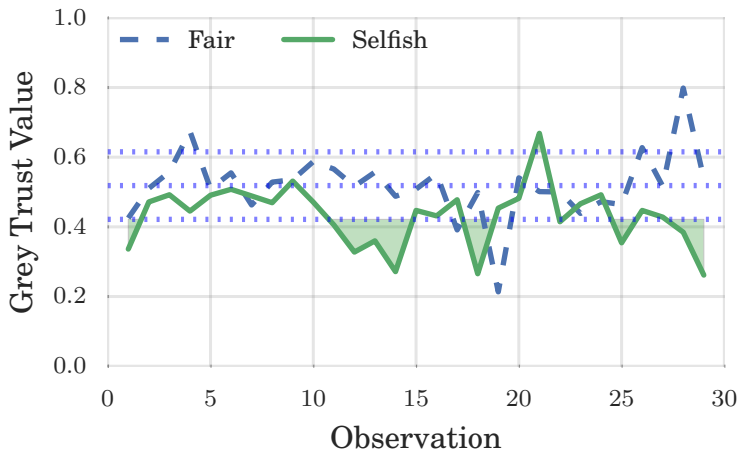
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