An Investigation into Trust and Reputation Frameworks for Collaborative Teams of Autonomous Underwater Vehicles

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- Context
- 2 Trust in Networks
 - What do we mean by trust?
 - What are TMFs?
 - Reasons for using Communication TMFs
 - Pre-existing Research
- Fusions of Trust Metrics
 - Vector Trust
 - Multi-Vector Trust
 - Challenges for Implementing Multi-vector Trust
- Development Plan
 - Publications
 - Thesis Plan



Research Context

- Project launched at QUB ECIT in 2011 under the DSTL/DGA Anglo French Defence Research Group PhD Programme
- What lessons from the Mobile Ad Hoc Network (MANET) space can be transferred to the marine environment?
- Teams of 3 16 Autonomous Underwater Vehicles (AUVs) Mine countermeasures, Hydrography, and Patrol Capabilities (MHPC)
- Defence focus, assumption of highly capable enemy attempting to compromise communications / operations
- Primary Simulation/Analysis work done in 12/13
- Moved to UoL Oct 13 after 2 mth placement @ DSTL PDW Naval Systems / Information Systems departments.
- CDE Project on Precision Timing for Positioning with NPL/Plextek



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Trust Management Frameworks

Context

 Provide information regarding the estimated future states and operations of nodes within networks

Trust Management Frameworks

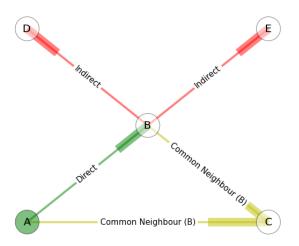
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Trust Management Frameworks

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- Enables nodes to form collaborative opinions on their cohort nodes based on
 - Direct Observation of Communications Behaviour (eg Successfully Forwarded Packets)
 - Common-Neighbour Recommendation
 - Indirect Reputation



Transitivity in Trust Networks



TMFs in Ad Hoc Autonomous Systems

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- Enable trust establishment from partial-strangers via indirect trust and direct observation
- Enables nodes to inform internal processes for global efficiency given observed network behaviour / 'wellness', similar to those found in human social networks eg
 - Update routing table based on 'safest' node chains (Phone Tree)
 - Maneuver away from misbehaving nodes (Shunning)
 - Inform as to 'trustworthiness' of forwarded information (Healthy sense of Skepticism)
 - Historic Distrust/Trust decaying over time (Forgiveness/Relationship Decay)

Reason for using TMFs in MANETs

- Provide Risk Mitigation against many classical MANET attacks
 - Black/Grayhole
 - Routing Loop
 - Selective misbehaviour / selfishness
- Generally; to constrain potential malicious behaviour that can operate without detection

Trust in Autonomous Systems

- Public Key Infrastructure Requires Centralised Control and pre-shared keys
- Resurrecting Duckling Uses in-action keying with a trusted source
- Evidence Based Trust Uses shared keys
- Reputation Based Trust Uses Packet forwarding success rate for prediction of future actions
 - CONFIDANT Trust-based router implementation using packet forwarding rate
 - OTMF Trust including transitive information from other nodes

- ... and there are plenty more along the same lines
- Predominantly use single metrics or only communications metrics



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 - MPTM Relationships and Multiple Metrics combined with Gray Interval assessment
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Vectorised Trust

- Application of several individual metrics for the construction of a single trust measurement
- For example:
 - $X = \{packet loss, signal strength, datarate, delay, throughput\}$
- This multi-parameter trust prevents 'smart' attackers; leveraging a known trust metric to subvert a TMF without detection
- Normally expressed as a vector, but can be condensed into an abstracted or weighted form for comparison [3]

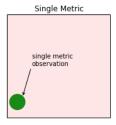
The Need for Multi-Domain Trust Assessment

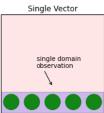
- Communications not the only target for an attacker (or failure);
 - Following to restricted area
 - Masquerading
 - Hardware Degradation
 - Resource attack via propulsive power
- Physical observation presents opportunity to further reduce the available threat surface while also discriminating between 'True' attacks and mechanical failure.
- Also could provide additional 'handshake' protocols for 'friendly' fleets/teams through reactionary behaviours

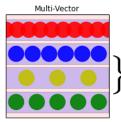
Multi-Vector Trust and the Threat Surface

Potential attacks exist across a multi-domain threat surface

Threat Surface for Trust Management Frameworks

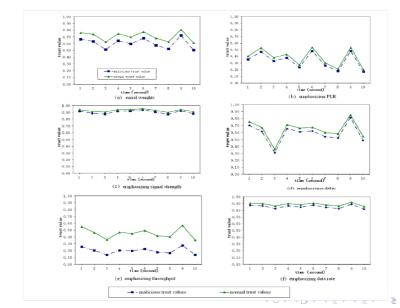






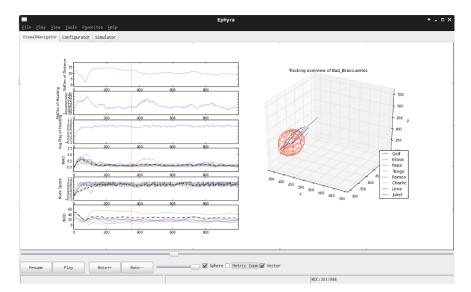
Combination of multiple domains, each containing multiple metrics

Malicious Behaviour Discrimination





Agent Based Behaviour Simulator



Context

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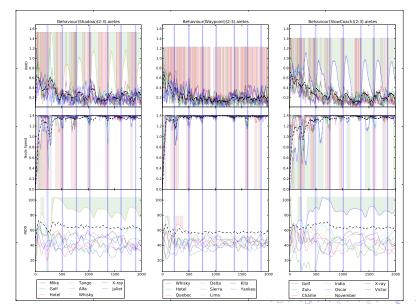
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 - Shadow
 - Spy
 - Sloth
 - Stalker
 - Scoundrel

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 - Slow Coach (non-malicious)
 - Spin Doctor (non-malicious)



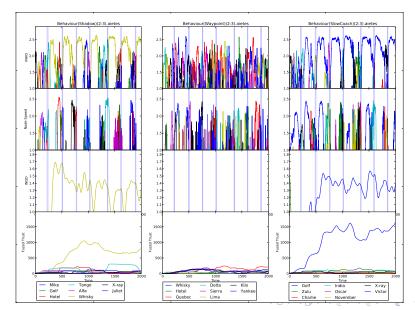
Raw Behavioural Metric Assessment in AUVs

Context





Behavioural Trust Assessment in AUVs





Behavioural Trust Assessment in AUVs

- Detection and identification based on basic weight-assessment classifier against windowed history of observations, with confidence based on a Grey Theoretic weight
- Currently >96% statistical accuracy of detection and confidence, but this needs much more rigorous analysis

Challenges in Multi-vector Trust

- How to define optimality in trust assessment when dealing with multiple vectors and transitive trust?
- Is there a quantifiable benefit to cross-domain comparison beyond single vector Trust?
- Is there an optimal generic cross-domain comparator?

Current Publications

- A Multi-Vector Trust Framework for Autonomous Systems [2]
 - Symposium paper to the Association for the Advancement of Artificial Intelligence on the current state of work, presenting our progress towards multi-vector trust
- Analysis of Trust Interfaces in Autonomous and Semi-Autonomous Collaborative MHPC Operations [1]
 - Part of a Five-Eyes defence strategy programme (TTCP) for assuring C3I capabilities as part of FF2020

Development Plan

- Behaviour Detection (Q3 14) Formal Analysis of Behavioural Trust Systems
 - ASON 2014 : Seventh Int. WS on Autonomous Self-Organizing Networks (Aug 14)
 - AHUC 2014: The Fourth Int. WS on Ad Hoc and Ubiquitous Computing (Aug 14)
 - ICCAR 2015 : WASET Int. Conf. on Control, Automation and Robotics (Dec 14)
- MANET/Marine comparison (Q4 14) Formal Comparison between Terrestrial MANET / Marine contexts
- Multi-Domain Trust Assessment (Q4 14) Combination of Communicative and Physical Behaviour Trusts
 - IEEE Trans. on Communications / Dependable and Secure Computing / Intelligent Systems
- Reactionary/Perturbative Trust (Q1 15) Exploration of reactionary behaviours for teams to 'shake down' suspects
 - SASO15:Self-Adaptive and Self-Organizing Systems,
 - SEAMS15: Software Engineering for Adaptive and Self-Managing Systems



Thesis plan

- Abstract, Acknowledgements, Introduction,
- Background Information on Trust and it's applications to MANETs
- Background Information on Maritime Uses of Autonomous Systems
- Trust in Autonomous Systems of Systems for Maritime Defence Applications
- Strategies for Multi-Domain Trust Assessment
- Modelling and Analysis of Collaborative Node Kinematic Behaviours in Underwater Acoustic MANETS
- Comparative Analysis of Multi-Domain Trust Assessment in Collaborative Mobile Networks
- Reactionary Behaviours to increase decentralised trust in isolated environments
- Conclusions, Bibliography



- Andrew Bolster. Analysis of Trust Interfaces in Autonomous and Semi-Autonomous Collaborative MHPC Operations. Tech. rep. The Technical Cooperation Program, 2014.
- Andrew Bolster and Alan Marshall. "A Multi-Vector Trust Framework for Autonomous Systems". In: 2014 AAAI Spring Symposium Series. Stanford, CA, 2014, pp. 17–19. URL: http://www.aaai.org/ocs/index.php/SSS/SSS14/paper/viewFile/7697/7724.

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Huaizhi Li and Mukesh Singhal. "Trust Management in Distributed Systems". In: Computer 40.2 (2007), pp. 45-53. ISSN: 00189162. DOI: 10.1109/MC.2007.76. URL: http://ieeexplore.ieee.org/lpdocs/epic03/wrapper.htm?arnumber=4085622.

Context

The End