

Lecture 9: Naive Bayes, SVM, Kernels

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Outline

- ① Probability basics
- ② Probabilistic Interpretation of Classification
- ③ Bayesian Classifiers, Naive Bayes
- ④ SVM and Kernels

Probability Basics

Sample Space

- **Sample Space:** A space of events that we assign probabilities to
- Events can be binary, multi-valued, or continuous
- Events are mutually exclusive
- Examples:
 - Coin flip: {head, tail}
 - Die roll: {1,2,3,4,5,6}
 - English words: a dictionary
 - Temperature: \mathbb{R}_+ (Kelvin)

Random Variable

- A variable, X , whose domain is the sample space, and whose value is somewhat uncertain
- Examples:
 - X = coin flip outcome
 - X = first word in tomorrow's headline news
 - X = tomorrow's temperature

Probability for Discrete Events

- Probability $P(X = a)$ is the fraction of times x takes value a
- Often we write it as $P(a)$
- Examples:
 - Fair Coin: $P(\text{head})=P(\text{tail})=0.5$
 - Slightly Biased Coin: $P(\text{head})=0.51$, $P(\text{tail})=0.49$
 - Two Face's Coin: $P(\text{head})=1$, $P(\text{tail})=0$
 - Fair Dice: $P(\text{getting } 1 \text{ in a die roll}) = 1/6$

Probability for Discrete Events

- $P(A = \text{"head or tail in a fair coin"})$

$$0.5 + 0.5 = 1$$

- $P(A = \text{"even number in a fair dice roll"})$

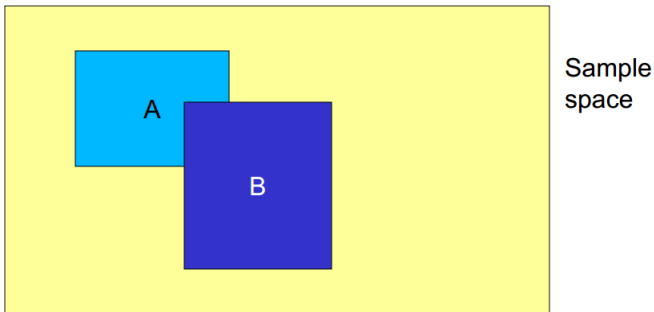
$$1/6 + 1/6 + 1/6 = 0.5$$

- $P(A = \text{"two dice rolls sum to 2 in a fair dice"})$

$$1/6 * 1/6 = 1/36$$

Axioms of Probability

- $P(A) \in [0,1]$
- $P(\text{true})=1, P(\text{false})=0$
- $P(A \vee B) = P(A) + P(B) - P(A \wedge B)$



Simple Corollaries

- $P(A') = 1 - P(A)$
- If A can take k different values a_1, \dots, a_k ,

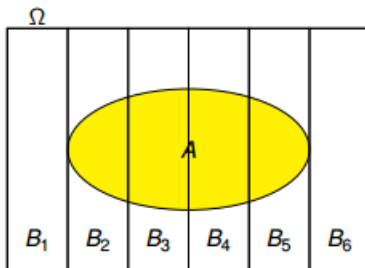
$$P(A = a_1) + \dots + P(A = a_k) = 1$$

- **Law of Total Probability:**

- $P(A) = P(A \cap B) + P(A \cap B')$
- $P(A) = \sum_{i=1}^k P(A \cap B = b_i)$ if B takes k values b_1, \dots, b_k

Law of Total Probability¹

Definition: A partition of the sample space Ω is a collection of disjoint events B_1, B_2, \dots, B_k whose union is Ω . Such a partition divides any set A into disjoint pieces:



¹<http://people.reed.edu/~jones/Courses/P02.pdf>

Probability Table

- Weather

Sunny	Cloudy	Rainy
200/365	100/365	65/365

- $P(\text{Weather} = \text{sunny}) = P(\text{sunny}) = 200/365$
- $P(\text{Weather}) = \{200/365, 100/365, 65/365\}$

Joint Probability Table

		weather		
temp		Sunny	Cloudy	Rainy
	hot	150/365	40/365	5/365
	cold	50/365	60/365	60/365

- $P(\text{temp}=\text{hot}, \text{weather}=\text{rainy}) = P(\text{hot}, \text{rainy}) = 5/365$
- The full joint probability table between N variables, each taking k values, has k^N entries (that's a lot!)

Marginal Probability Table

- Sum over other variables

		weather		
		Sunny	Cloudy	Rainy
temp	hot	150/365	40/365	5/365
	cold	50/365	60/365	60/365
Σ		200/365	100/365	65/365

$$P(\text{Weather}) = \{200/365, 100/365, 65/365\}$$

- The name comes from the old days when the sums are written on the margin of a page

Marginal Probability Table

- Sum over other variables

		weather			
		Sunny	Cloudy	Rainy	Σ
temp	hot	150/365	40/365	5/365	195/365
	cold	50/365	60/365	60/365	170/365

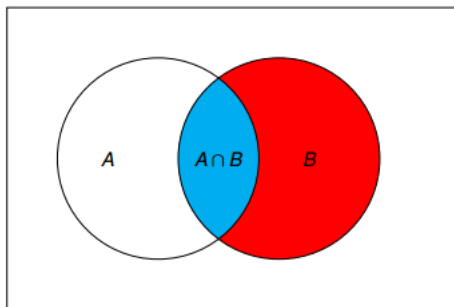
$$P(\text{temp}) = \{195/365, 170/365\}$$

- This is nothing but $P(B) = \sum_{i=1 \dots k} P(B \wedge A=a_i)$, if A can take k values

Conditional Probability

- $P(A = a|B = b)$ = fraction of times when random variable A took a value of a , within the region where random variable $B = b$

The definition $\mathbb{P}(A | B) = \mathbb{P}(A \cap B)/\mathbb{P}(B)$ restricts the sample space to B , and rescales to give $\mathbb{P}(B|B) = 1$:



Conditional Probability

- Consider a roll of a fair dice
- A : it rolled 1. $P(A) = 1/6$
- B : it rolled an odd number. $P(B) = 3/6 = 0.5$
- Suppose, I knew that B happened. What is the probability that A happened?

Conditional Probability

- Consider a roll of a fair dice
- A : it rolled 1. $P(A) = 1/6$
- B : it rolled an odd number. $P(B) = 3/6 = 0.5$
- Suppose, I knew that B happened. What is the probability that A happened?

-

$$P(A|B) = \frac{P(A \cap B)}{P(B)} = \frac{1/6}{1/2} = \frac{1}{3}$$

Conditional Probability

- **Conditional Probability:** $P(A|B) = \frac{P(A \cap B)}{P(B)}$
- **Multiplication Rule:** $P(A \cap B) = P(A|B)P(B)$
- **Chain Rule:**
 - $P(A_1, A_2) = P(A_1)P(A_2|A_1)$
 -

$$\begin{aligned}P(A_1, A_2, A_3) &= P(A_3|A_1, A_2)P(A_1, A_2) \\ &= P(A_3|A_1, A_2)P(A_2|A_1)P(A_1)\end{aligned}$$

-

$$\begin{aligned}P(A_1, A_2, A_3) &= P(A_1|A_2, A_3)P(A_2, A_3) \\ &= P(A_1|A_2, A_3)P(A_2|A_3)P(A_3)\end{aligned}$$

- $P\left(\bigcap_{i=1}^k A_i\right) = \prod_{i=1}^k P\left(A_i \mid \bigcap_{j=1}^{i-1} A_j\right)$

Bayes Theorem

- $P(A|B) = \frac{P(A \cap B)}{P(B)}$
- $P(B|A) = \frac{P(A \cap B)}{P(A)}$
- Proof of Bayes Theorem:

$$\begin{aligned}P(A \cap B) &= P(A|B)P(B) \\ &= P(B|A)P(A) \\ P(A|B)P(B) &= P(B|A)P(A) \\ P(A|B) &= \frac{P(B|A)P(A)}{P(B)}\end{aligned}$$

Independence

- Two events A, B are independent, if (all 3 definitions are equivalent)
 - $P(A \cap B) = P(A)P(B)$
 - $P(A|B) = P(A)$
 - $P(B|A) = P(B)$

Independence Misused

A famous statistician would never travel by airplane, because he had studied air travel and estimated that the probability of there being a bomb on any given flight was one in a million, and he was not prepared to accept these odds.

One day, a colleague met him at a conference far from home. "How did you get here, by train?"

"No, I flew"

"What about the possibility of a bomb?"

"Well, I began thinking that if the odds of one bomb are 1:million, then the odds of two bombs are $(1/1,000,000) \times (1/1,000,000)$. This is a very, very small probability, which I can accept. So now I bring my own bomb along!"

An innocent old math joke

Independence

- Independence between random variables is typically obtained via domain knowledge
- Suppose A and B be two independent random variables that can take k different values a_1, \dots, a_k and b_1, \dots, b_k
- The joint probability table typically has k^2 parameters
- If random variables are independent, then only $2k - 2$ parameters
 - $k = 2, 4$ vs 2
 - $k = 10, 100$ vs 18
 - $k = 100, 10,000$ vs 198
- This is something great for data mining!

Conditional Independence

- Random variables can be dependent, but **conditionally independent**
- Your house has an alarm
 - Neighbor John will call when he hears the alarm
 - Neighbor Mary will call when she hears the alarm
 - Assume John and Mary don't talk to each other
- JohnCall independent of MaryCall?

Conditional Independence

- Random variables can be dependent, but **conditionally independent**
- Your house has an alarm
 - Neighbor John will call when he hears the alarm
 - Neighbor Mary will call when she hears the alarm
 - Assume John and Mary don't talk to each other
- JohnCall independent of MaryCall?
 - No - If John called, likely the alarm went off, which increases the probability of Mary calling
 - $P(\text{MaryCall}|\text{JohnCall}) \neq P(\text{MaryCall})$

Conditional Independence

- If we know the status of the alarm, JohnCall won't affect Mary at all
- $P(\text{MaryCall}|\text{Alarm}, \text{JohnCall}) = P(\text{MaryCall}|\text{Alarm})$
- We say JohnCall and MaryCall are **conditionally independent**, given Alarm
- In general A, B are conditionally independent given C
 - $P(A|B, C) = P(A|C)$ or
 - $P(B|A, C) = P(B|C)$ or
 - $P(A, B|C) = P(A|C) * P(B|C)$

Probabilistic Interpretation of Classification

Probabilistic Classifiers

- Type of classifiers that, given an input, produces a *probability distribution* over a set of classes
 - Probability that this email is spam is X and not spam is Y
 - Probability that this person has tumour is X and no tumour is Y
 - Probability that this digit is 0 is X , 1 is Y , ...
- Most state of the art classifiers are probabilistic
- Even k -NN and Decision trees have probabilistic interpretations

Prior Probability

- $P(A)$: Prior or unconditional probability of A
- Your belief in A in the absence of additional information
- Uninformative priors
 - Principle of indifference: Assign equal probabilities to all possibilities
 - Coin toss, $P(\text{head})=P(\text{tail})=1/2$
- Often you get from domain knowledge or from data
- $P(\text{email is spam}) = 0.8$

Conditional Probability as Belief Update

- $P(A)$: Prior belief in A
- $P(A|B)$: Belief after obtaining information B
- $P(A|B, C)$: Belief after obtaining information B and C

Conditional Probability as Belief Update²

- Suppose you work as security guard in Airport
- Your job: look at people in security line and choose some for additional screening
- You want to pick passengers with high “risk”
- A: Passenger is high risk
- By experience, you know only 0.1% of passengers are high risk (Prior probability)

²[http:](http://www.quora.com/In-laymans-terms-how-does-Naive-Bayes-work)

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Conditional Probability as Belief Update³

- Consider a random person:
 - The probability that this person is high risk is A is 0.1%
 - Suppose you notice that the person is male

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Conditional Probability as Belief Update³

- Consider a random person:
 - The probability that this person is high risk is A is 0.1%
 - Suppose you notice that the person is male
 - There are more male criminals than female ones
 - The passenger is nervous

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Conditional Probability as Belief Update³

- Consider a random person:
 - The probability that this person is high risk is A is 0.1%
 - Suppose you notice that the person is male
 - There are more male criminals than female ones
 - The passenger is nervous
 - Most criminals are nervous but most normal passengers are not
 - The passenger is a kid

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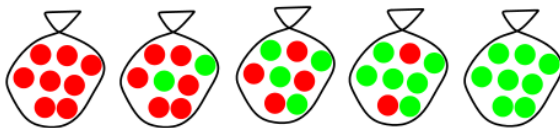
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- Consider a random person:
 - The probability that this person is high risk is A is 0.1%
 - Suppose you notice that the person is male
 - There are more male criminals than female ones
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Conditional Probability as Belief Update



Then we observe candies drawn from some bag: ● ● ● ● ● ● ● ● ● ●

What kind of bag is it? What flavour will the next candy be?

Conditional Probability

- $X, A = \langle A_1, A_2, \dots, A_d \rangle$: Input feature vector
- Y, C : Class value to predict
- $P(C|A)$ vs $P(A|C)$

Conditional Probability

- $X, A = \langle A_1, A_2, \dots, A_d \rangle$: Input feature vector
- Y, C : Class value to predict
- $P(C|A)$ vs $P(A|C)$
- Key terms
 - $P(A), P(C)$: Prior probability
 - $P(A|C)$: Class conditional probability or likelihood (from training data)
 - $P(C|A)$: Posterior probability

Likelihood vs Posterior

- $P(A|C)$: Likelihood, $P(C|A)$: Posterior
- Examples:
 - $P(\text{Viagra}|\text{Spam})$ and $P(\text{Spam}|\text{Viagra})$:

Likelihood vs Posterior

- $P(A|C)$: Likelihood, $P(C|A)$: Posterior
- Examples:
 - $P(\text{Viagra}|\text{Spam})$ and $P(\text{Spam}|\text{Viagra})$: Likelihood, Posterior
 - $P(\text{High temperature}|\text{Flu})$ and $P(\text{Flu}|\text{High Temperature})$:

Likelihood vs Posterior

- $P(A|C)$: Likelihood, $P(C|A)$: Posterior
- Examples:
 - $P(\text{Viagra}|\text{Spam})$ and $P(\text{Spam}|\text{Viagra})$: Likelihood, Posterior
 - $P(\text{High temperature}|\text{Flu})$ and $P(\text{Flu}|\text{High Temperature})$: Likelihood, Posterior
 - $P(\text{Fever, Headache, Cough}|\text{Flu})$ and $P(\text{Flu}|\text{Fever, Headache, Cough})$
 - $P(\text{Viagra, Nigeria, Lottery}|\text{Spam})$ and $P(\text{Spam}|\text{Viagra, Nigeria, Lottery})$

Bayes' Theorem

- Training data gives us likelihood and prior
- Prediction requires Posterior
- Bayes rule allows us to do statistical inference
- $P(C|A) = \frac{P(A|C)P(C)}{P(A)}$
- $P(C|A) \propto P(A|C)P(C)$
- Posterior \propto Likelihood \times Prior

Bayes Decision Rule

- “When you hear hoofbeats, think of horses not zebras”
- When predicting, assign the class with highest posterior probability
- To categorize email:
 - Compute $P(\text{spam}|\text{email})$ and $P(\text{not spam}|\text{email})$
 - If $P(\text{spam}|\text{email}) > P(\text{not spam}|\text{email})$, decide email as spam.
Else as not-spam

Bayesian Classifiers

- A probabilistic framework for solving classification problems
- Conditional Probability:

$$P(C | A) = \frac{P(A, C)}{P(A)}$$

$$P(A | C) = \frac{P(A, C)}{P(C)}$$

- Bayes theorem:

$$P(C | A) = \frac{P(A | C)P(C)}{P(A)}$$

Example of Bayes Theorem

- Given:

- A doctor knows that meningitis causes stiff neck 50% of the time
- Prior probability of any patient having meningitis is $1/50,000$
- Prior probability of any patient having stiff neck is $1/20$

- If a patient has stiff neck, what's the probability he/she has meningitis?

$$P(M | S) = \frac{P(S | M)P(M)}{P(S)} = \frac{0.5 \times 1/50000}{1/20} = 0.0002$$

- Consider each attribute and class label as random variables
- Given a record with attributes (A_1, A_2, \dots, A_n)
 - Goal is to predict class C
 - Specifically, we want to find the value of C that maximizes $P(C | A_1, A_2, \dots, A_n)$
- Can we estimate $P(C | A_1, A_2, \dots, A_n)$ directly from data?

Bayesian Classifiers

- Approach:

- compute the posterior probability $P(C | A_1, A_2, \dots, A_n)$ for all values of C using the Bayes theorem

$$P(C | A_1 A_2 \dots A_n) = \frac{P(A_1 A_2 \dots A_n | C) P(C)}{P(A_1 A_2 \dots A_n)}$$

- Choose value of C that maximizes $P(C | A_1, A_2, \dots, A_n)$
- Equivalent to choosing value of C that maximizes $P(A_1, A_2, \dots, A_n | C) P(C)$

- How to estimate $P(A_1, A_2, \dots, A_n | C)$?

- Assume independence among attributes A_i when class is given:
 - $P(A_1, A_2, \dots, A_n | C) = P(A_1 | C_j) P(A_2 | C_j) \dots P(A_n | C_j)$
 - Can estimate $P(A_i | C_j)$ for all A_i and C_j .
 - New point is classified to C_j if $P(C_j) \prod P(A_i | C_j)$ is maximal.

How to Estimate Probabilities from Data?

Tid	Refund	Marital Status	Taxable Income	Evade
1	Yes	Single	125K	No
2	No	Married	100K	No
3	No	Single	70K	No
4	Yes	Married	120K	No
5	No	Divorced	95K	Yes
6	No	Married	60K	No
7	Yes	Divorced	220K	No
8	No	Single	85K	Yes
9	No	Married	75K	No
10	No	Single	90K	Yes

- Class: $P(C) = N_C/N$

- e.g., $P(\text{No}) = 7/10$,
 $P(\text{Yes}) = 3/10$

- For discrete attributes:

$$P(A_i | C_k) = |A_{ik}| / N_{C_k}$$

- where $|A_{ik}|$ is number of instances having attribute A_i and belongs to class C_k
 - Examples:

$$P(\text{Status}=\text{Married}|\text{No}) = 4/7$$
$$P(\text{Refund}=\text{Yes}|\text{Yes})=0$$

How to Estimate Probabilities from Data?

- For continuous attributes:
 - **Discretize** the range into bins
 - ◆ one ordinal attribute per bin
 - ◆ violates independence assumption ^k
 - **Two-way split:** $(A < v)$ or $(A > v)$
 - ◆ choose only one of the two splits as new attribute
 - **Probability density estimation:**
 - ◆ Assume attribute follows a normal distribution
 - ◆ Use data to estimate parameters of distribution (e.g., mean and standard deviation)
 - ◆ Once probability distribution is known, can use it to estimate the conditional probability $P(A_i|c)$

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8	No	Single	85K	Yes
9	No	Married	75K	No
10	No	Single	90K	Yes

- Normal distribution:

$$P(A_i | c_j) = \frac{1}{\sqrt{2\pi\sigma_{ij}^2}} e^{-\frac{(A_i - \mu_j)^2}{2\sigma_{ij}^2}}$$

- One for each (A_i, c_i) pair

- For (Income, Class=No):

- If Class=No

- ◆ sample mean = 110
- ◆ sample variance = 2975

$$P(\text{Income} = 120 | \text{No}) = \frac{1}{\sqrt{2\pi(54.54)}} e^{-\frac{(120-110)^2}{2(2975)}} = 0.0072$$

Example of Naive Bayes Classifier

Given a Test Record:

$$X = (\text{Refund} = \text{No}, \text{Married}, \text{Income} = 120\text{K})$$

naive Bayes Classifier:

$P(\text{Refund}=\text{Yes}|\text{No}) = 3/7$
 $P(\text{Refund}=\text{No}|\text{No}) = 4/7$
 $P(\text{Refund}=\text{Yes}|\text{Yes}) = 0$
 $P(\text{Refund}=\text{No}|\text{Yes}) = 1$
 $P(\text{Marital Status}=\text{Single}|\text{No}) = 2/7$
 $P(\text{Marital Status}=\text{Divorced}|\text{No}) = 1/7$
 $P(\text{Marital Status}=\text{Married}|\text{No}) = 4/7$
 $P(\text{Marital Status}=\text{Single}|\text{Yes}) = 2/7$
 $P(\text{Marital Status}=\text{Divorced}|\text{Yes}) = 1/7$
 $P(\text{Marital Status}=\text{Married}|\text{Yes}) = 0$

For taxable income:

If class=No: sample mean=110
 sample variance=2975
If class=Yes: sample mean=90
 sample variance=25

- $P(X|\text{Class}=\text{No}) = P(\text{Refund}=\text{No}|\text{Class}=\text{No})$
 $\times P(\text{Married}|\text{Class}=\text{No})$
 $\times P(\text{Income}=120\text{K}|\text{Class}=\text{No})$
 $= 4/7 \times 4/7 \times 0.0072 = 0.0024$
- $P(X|\text{Class}=\text{Yes}) = P(\text{Refund}=\text{No}|\text{Class}=\text{Yes})$
 $\times P(\text{Married}|\text{Class}=\text{Yes})$
 $\times P(\text{Income}=120\text{K}|\text{Class}=\text{Yes})$
 $= 1 \times 0 \times 1.2 \times 10^{-9} = 0$

Since $P(X|\text{No})P(\text{No}) > P(X|\text{Yes})P(\text{Yes})$

Therefore $P(\text{No}|X) > P(\text{Yes}|X)$
 $\Rightarrow \text{Class} = \text{No}$

Naive Bayes Classifier

- If one of the conditional probability is zero, then the entire expression becomes zero
- Probability estimation:

$$\text{Original : } P(A_i | C) = \frac{N_{ic}}{N_c}$$

$$\text{Laplace : } P(A_i | C) = \frac{N_{ic} + 1}{N_c + c}$$

$$\text{m - estimate : } P(A_i | C) = \frac{N_{ic} + mp}{N_c + m}$$

c: number of classes

p: prior probability

m: parameter

Example of Naive Bayes Classifier

Name	Give Birth	Can Fly	Live in Water	Have Legs	Class
human	yes	no	no	yes	mammals
python	no	no	no	no	non-mammals
salmon	no	no	yes	no	non-mammals
whale	yes	no	yes	no	mammals
frog	no	no	sometimes	yes	non-mammals
komodo	no	no	no	yes	non-mammals
bat	yes	yes	no	yes	mammals
pigeon	no	yes	no	yes	non-mammals
cat	yes	no	no	yes	mammals
leopard shark	yes	no	yes	no	non-mammals
turtle	no	no	sometimes	yes	non-mammals
penguin	no	no	sometimes	yes	non-mammals
porcupine	yes	no	no	yes	mammals
eel	no	no	yes	no	non-mammals
salamander	no	no	sometimes	yes	non-mammals
gila monster	no	no	no	yes	non-mammals
platypus	no	no	no	yes	mammals
owl	no	yes	no	yes	non-mammals
dolphin	yes	no	yes	no	mammals
eagle	no	yes	no	yes	non-mammals

A: attributes

M: mammals

N: non-mammals

$$P(A|M) = \frac{6}{7} \times \frac{6}{7} \times \frac{2}{7} \times \frac{2}{7} = 0.06$$

$$P(A|N) = \frac{1}{13} \times \frac{10}{13} \times \frac{3}{13} \times \frac{4}{13} = 0.0042$$

$$P(A|M)P(M) = 0.06 \times \frac{7}{20} = 0.021$$

$$P(A|N)P(N) = 0.004 \times \frac{13}{20} = 0.0027$$

Give Birth	Can Fly	Live in Water	Have Legs	Class
yes	no	yes	no	?

$$P(A|M)P(M) > P(A|N)P(N)$$

=> Mammals

Naive Bayes Classifier Summary

- Robust to isolated noise points
- Handle missing values by ignoring the instance during probability estimate calculations
- Robust to irrelevant attributes
- Independence assumption may not hold for some attributes
 - Use other techniques such as Bayesian Belief Networks (BBN)

Support Vector Machines

Major Concepts:

- Probabilistic interpretation of Classification
- Bayesian Classifiers
- Naive Bayes Classifier
- Support Vector Machines (SVM)
- Kernels

Slide Material References

- Slides from ISLR book
- Slides from Jerry Zhu
- See also the footnotes