From SIAR to MixSIAR

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Learning outcomes

- Random effects models
- Understand how MixSIAR (and simmr) extends MixSIR and SIAR
- ▶ Understand the differences in likelihoods and priors

Revision: SIAR model in JAGS

▶ Let's move back to the proper SIAR model defined yesterday:

$$y_{ij} \sim N\left(\frac{\sum_{k=1}^{K} p_k q_{jk} (\mu_{s,jk} + \mu_{c,jk})}{\sum_{k=1}^{K} p_k q_{jk}}, \frac{\sum_{k=1}^{K} p_k^2 q_{jk}^2 (\sigma_{s,jk}^2 + \sigma_{c,jk}^2)}{(\sum_{k=1}^{K} p_k q_{jk})^2} + \sigma_j^2\right)$$

- We also have prior distributions (usually uniform) on σ^2 and a Dirichlet prior on p
- ▶ How is this model still a simplification of reality?

Expanding the SIAR model further

Some (of the many) possible extensions:

- 1. We are assuming that all consumers have identical dietary proportions
- 2. We are assuming that residuals, sources and TEFs are uncorrelated across isotopes
- 3. We are assuming that concentration dependence is known
- 4. We cannot add in any extra covariates (height, weight, etc, etc)

Mixed effects models in linear regression

- Often data are available in groups, for example wolves might belong to different packs
- We want to capture the different levels of variation, both within groups, and between groups
- Example: suppose y_{ij} is a measurement for individual i in group $j, i = 1, ..., N_i, j = 1, ..., M$
- ▶ We might use a model such as:

$$y_{ij} \sim N(\mu + b_j, \sigma^2), \ b_j \sim N(0, \sigma_b^2)$$

- Now b_j is called a random effect and measures the change in the mean for each group
- $ightharpoonup \sigma$ measures the standard deviation within a group whilst σ_b measures the standard deviation between groups

Fitting a random effects model in JAGS

modelstring ='

```
model {
  for(i in 1:N) { y[i] ~ dnorm(mu+b[group[i]],sigma^-2) }
  for(j in 1:M) { b[j] ~ dnorm(0,sigma_b^-2) }
  mu \sim dnorm(0,100^-2)
  sigma \sim dunif(0.100)
  sigma b \sim dunif(0.10)
}'
data=list(y=c(3.03, 2.68, 2.04, 3.23, 2.82, 2.46, 3.06, 3.06)
              3.02, 2.95, 3.12, 2.81, 2.69, 2.65, 2.49, 2.
              2.21, 3.92, 4.7, 3.53, 3.89, 3.86, 4.48),
          group=c(1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 2, 2, 2, 2
                  2, 2, 2, 3, 3, 3, 3, 3),
          N=23.M=3
model=jags.model(textConnection(modelstring), data=data)
output=coda.samples(model=model,
```

n.iter=1000)

variable.names=c("mu", "sigma", "sigma b

Output from the random effects model

t(round(apply(output[[1]],2,quantile,probs=c(0.025,0.5,0.9

```
## mu 0.64 3.28 6.40
## sigma 0.34 0.47 0.65
## sigma_b 0.36 1.15 6.14
```

- ▶ You need a reasonable number of groups to estimate σ_b well. When the number of groups is very small you might run into problems
- You could also include b in the variable.names if you want the deviations from the overall mean
- Convergence is often better if you hierarchically centre the model, which means set $b_j \sim N(\mu, \sigma_b^2)$ in the previous slides' JAGS code (if you look in the code for these slides that is what I ran)

Defining mixed effects models in the SIMM case

- ▶ In the SIMM case we might have information that some consumers might share the same dietary proportions
- We might be interested in how the dietary proportions vary between groups and within groups, just as in the simple example
- ▶ An issue is: how do we achieve this in the SIMM case?
- One solution was elegantly proposed by Semmens et al in their PLoS ONE 2009 paper

A hierchical SIMM

- Semmens et al differentiate between the overall or mean dietary proportions p_{mean} , and the deviations $p_{dev,j}$ from this mean for each group p_i
- ► They use the relationship:

$$p_j = w p_{mean} + (1 - w) p_{dev,j}$$

where w is a mixing constant which determines how much the group behaves like the mean (high w), or not (low w)

- ► They give the mean and the deviation dietary proportions $\mathsf{Dirichlet}(\alpha_1,\ldots,\alpha_K)$ prior distributions
- ▶ They give w a standard U(0,1) prior

More on random effects in proportions

- ➤ A slightly more flexible prior distribution for proportions is obtained by transforming the proportions instead
- ▶ We already met this with logistic regression where we can use:

$$f = logit(p) = log\left(rac{p}{1-p}
ight)$$
 or equivalently $p = rac{\exp(f)}{\exp(f) + 1}$

▶ When we have multiple proportions a generalisation of this is the *centralised log ratio* (CLR) or *softmax* transformation:

$$[p_1, \dots, p_K] = \left[\frac{\exp(f_1)}{\sum_j \exp(f_j)}, \dots, \frac{\exp(f_K)}{\sum_k \exp(f_k)}\right]$$

The CLR transformation

- In logistic regression we can put a prior distribution on f (i.e. logit(p)) e.g. $f \sim N(\alpha + \beta x, \sigma^2)$ which allows us to relate the probability p to a covariate x. We can use the normal distribution because f is unrestricted
- ▶ In CLR regression, we put a prior on the f_k so that each one relates to the covariate with different coefficient values
- ► The CLR transformation guarantees that all the dietary proportions will sum to 1
- More on this tomorrow

Random effects for individuals

- ► We don't necessarily need a grouping structure (e.g. pack, sex, etc) to be able to include random effects in a SIMM
- In a SIMM we might reasonably assume that every consumer is eating something slightly different and want to quantify the overall mean diet as well as the variability between consumers
- We can do this by modelling each consumer's dietary proportion p_{ik} with a normally distributed prior on the CLR transform of p

A 'simple' CLR example

mu_f[k] ~ dnorm(0,1)
sigma_f[k] ~ dgamma(2,1)

```
modelstring ='
model {
  for (j in 1:J) {
    for (i in 1:N) {
      y[i,j] ~ dnorm(inprod(p[i,]*q[,j], s_mean[,j]+c_mean
      var_y[i,j] \leftarrow inprod(pow(p[i,]*q[,j],2),s_sd[,j]^2+c_j
    }
  for(i in 1:N) {
    p[i,1:K] <- expf[i,]/sum(expf[i,])</pre>
    for(k in 1:K) {
      expf[i,k] \leftarrow exp(f[i,k])
      f[i,k] ~ dnorm(mu f[k],sigma f[k]^-2)
    }
  for(k in 1:K) {
```

CLR model: R code

Output

head(out_summ\$statistics,12)

```
##
                 Mean
                             SD
                                   Naive SE Time-series SE
## mu f[1] 1.5581860 0.7189221 0.007189221
                                                0.048242820
## mu f[2]
           -0.8399639 0.7076890 0.007076890
                                                0.047073694
## mu f[3]
           -0.5159795 0.8600470 0.008600470
                                                0.049480910
## mu f[4]
                                                0.035288128
           -0.1814058 0.8845321 0.008845321
## p[1,1]
            0.6658152 0.1965247 0.001965247
                                                0.004972411
## p[2,1]
            0.6346675 0.2021513 0.002021513
                                                0.004968236
## p[3,1]
            0.6852471 0.1927313 0.001927313
                                                0.004368923
## p[4,1]
            0.6613386 0.2039628 0.002039628
                                                0.004968406
## p[5,1]
            0.6564833 0.1975004 0.001975004
                                                0.005523575
## p[6,1]
            0.6934687 0.1928232 0.001928232
                                                0.004515495
## p[7,1]
            0.7016759 0.1835307 0.001835307
                                                0.004566265
## p[8,1]
            0.4486441 0.2194620 0.002194620
                                                0.007666217
```

Notes about the CLR model

- This is a great starter script for your own work. If you can understand this code and adapt it to your data you can get some really powerful results
- We can now put covariates in the model: we just have to expand μ_f in the previous JAGS code
- ▶ We now have individual dietary proportion estimates (p_{ik}) and overall dietary proportion estimates (via CLR transform of μ_k), and also estimates of the variability (from σ_f)
- Things start to get complicated with prior distributions at this stage. Be very careful and always examine prior sensitivity by re-running the model with slightly different prior distributions. Look at the effect on p (the effect on μ_f and σ_f is less important)

Summary

- We have looked at the differences between SIAR and MixSIAR
- ▶ We studied the CLR as an alternative to the Dirichlet
- ▶ We showed how to include random effects in a SIMM