From simmr to MixSIAR

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Learning outcomes

- ► Random effects models
- Understand how MixSIAR extends simmr
- ▶ Understand the differences in likelihoods and priors

Revision: simmr model in JAGS

Let's go back to the model defined earlier:

$$y_{ij} \sim N\left(\frac{\sum_{k=1}^{K} p_k q_{jk}(\mu_{s,jk} + \mu_{c,jk})}{\sum_{k=1}^{K} p_k q_{jk}}, \frac{\sum_{k=1}^{K} p_k^2 q_{jk}^2(\sigma_{s,jk}^2 + \sigma_{c,jk}^2)}{(\sum_{k=1}^{K} p_k q_{jk})^2} + \sigma_j^2\right)$$

- We also have prior distributions (usually uniform) on σ^2 and a Dirichlet prior on p
- How is this model still a simplification of reality?

Expanding the SIAR model further

Some (of the many) possible extensions:

- 1. We are assuming that all consumers have identical dietary proportions
- 2. We are assuming that residuals, sources and TEFs are uncorrelated across isotopes
- 3. We are assuming that concentration dependence is known
- 4. We cannot add in any extra covariates (height, weight, etc, etc)

Mixed effects models in linear regression

- Often data are available in groups, for example wolves might belong to different packs
- We want to capture the different levels of variation, both within groups, and between groups
- Example: suppose y_{ij} is a measurement for individual i in group j, $i = 1, ..., N_j$, j = 1, ..., M
- ▶ We might use a model such as:

$$y_{ij} \sim N(\mu + b_j, \sigma^2), \ b_j \sim N(0, \sigma_b^2)$$

- Now b_j is called a *random effect* and measures the change in the mean for each group
- $ightharpoonup \sigma$ measures the standard deviation within a group whilst σ_b measures the standard deviation between groups

Fitting a random effects model in JAGS

```
model code ='
model {
  for(i in 1:N) { y[i] ~ dnorm(mu+b[group[i]], sigma^-2) }
  for(j in 1:M) { b[j] ~ dnorm(0,sigma_b^-2) }
  mu \sim dnorm(0,100^-2)
  sigma \sim dunif(0,100)
  sigma b \sim dunif(0.10)
1
data=list(v=c(3.03, 2.68, 2.04, 3.23, 2.82, 2.46, 3.06, 3.05,
             3.02, 2.95, 3.12, 2.81, 2.69, 2.65, 2.49, 2.73,
             2.21, 3.92, 4.7, 3.53, 3.89, 3.86, 4.48),
         2, 2, 2, 3, 3, 3, 3, 3),
         N=23.M=3
model_run = jags(data = data,
                parameters.to.save = c("mu", "sigma", "sigma_b"),
                model.file = textConnection(model code))
```

Output from the random effects model

print(model run)

```
## Inference for Bugs model at "5", fit using jags,
   3 chains, each with 2000 iterations (first 1000 discarded)
   n.sims = 3000 iterations saved
           mu.vect sd.vect 2.5%
                                    25%
                                           50%
                                                  75% 97.5% Rhat n.eff
## m11
             3.234 1.462 0.182 2.766 3.230 3.750 6.269 1.004
             0.470 0.081 0.349 0.412 0.456 0.515 0.652 1.004
## sigma
                                                                    780
## sigma b 1.964 1.713 0.380 0.843 1.360 2.431 7.207 1.008
                                                                    290
## deviance 28.992 3.189 25.043 26.681 28.300 30.491 37.026 1.003
                                                                    710
## For each parameter, n.eff is a crude measure of effective sample size.
## and Rhat is the potential scale reduction factor (at convergence, Rhat=1).
## DIC info (using the rule, pD = var(deviance)/2)
## pD = 5.1 and DIC = 34.1
## DIC is an estimate of expected predictive error (lower deviance is better).
```

- \blacktriangleright You need a reasonable number of groups to estimate σ_b well. When the number of groups is very small you might run into problems
- You could also include b in the variable.names if you want the deviations from the overall mean
- Convergence is often better if you hierarchically centre the model, which means set $b_j \sim N(\mu, \sigma_b^2)$ in the previous slides' JAGS code (if you look in the code for these slides that is what I ran)

Defining mixed effects models in the SIMM case

- ► In the SIMM case we might have information that some consumers might share the same dietary proportions
- ► We might be interested in how the dietary proportions vary between groups and within groups, just as in the simple example
- ▶ An issue is: how do we achieve this in the SIMM case?
- ▶ There are two ways to deal with probability distributions for proportions; use a direct probability distribution (e.g. the Dirichlet) or *transform* to another set of parameters

More on random effects in proportions

- ► A slightly more flexible prior distribution for proportions is obtained by transforming the proportions instead
- ▶ We already met this with logistic regression where we can use:

$$f = logit(p) = log\left(rac{p}{1-p}
ight)$$
 or equivalently $p = rac{\exp(f)}{\exp(f) + 1}$

When we have multiple proportions a generalisation of this is the centralised log ratio (CLR) or softmax transformation:

$$[p_1, \dots, p_K] = \left[\frac{\exp(f_1)}{\sum_j \exp(f_j)}, \dots, \frac{\exp(f_K)}{\sum_k \exp(f_k)} \right]$$

The CLR transformation

- In logistic regression we can put a prior distribution on f (i.e. logit(p)) e.g. $f \sim N(\alpha + \beta x, \sigma^2)$ which allows us to relate the probability p to a covariate x. We can use the normal distribution because f is unrestricted
- ▶ In CLR regression, we put a prior on the f_k so that each one relates to the covariate with different coefficient values
- The CLR transformation guarantees that all the dietary proportions will sum to 1

Random effects for individuals

- ► We don't necessarily need a grouping structure (e.g. pack, sex, etc) to be able to include random effects in a SIMM
- ▶ In a SIMM we might reasonably assume that every consumer is eating something slightly different and want to quantify the overall mean diet as well as the variability between consumers
- We can do this by modelling each consumer's dietary proportion p_{ik} with a normally distributed prior on the CLR transform of p

A 'simple' CLR example

```
model code ='
model {
 for (i in 1:J) {
   for (i in 1:N) {
      v[i,j] \sim dnorm(inprod(p[i,]*q[,i], s mean[,i]+c mean[,i]) / inprod(p[i,],q[,i]), 1/var v[i,i])
      var_y[i,j] \leftarrow inprod(pow(p[i,]*q[,j],2),s_sd[,j]^2+c_sd[,j]^2)/pow(inprod(p[i,],q[,j]),2) + pow(sigma[j],2)
  for(i in 1:N) {
    p[i,1:K] <- expf[i,]/sum(expf[i,])
    for(k in 1:K) {
      expf[i,k] \leftarrow exp(f[i,k])
      f[i,k] ~ dnorm(mu_f[k],sigma_f[k]^-2)
  for(k in 1:K) {
    mu f[k] ~ dnorm(0,1)
    sigma f[k] ~ dgamma(2,1)
  for(i in 1:J) { sigma[i] ~ dunif(0.10) }
```

CLR model: R code

```
data=with(geese data dav1,
          list(y=mixtures,s_mean=source_means,
          s sd=source sds.
          c mean=correction means, c sd=correction sds,
          q=concentration means, N=nrow(mixtures),
          J=ncol(mixtures), K=length(source names)))
model run = jags(data = data,
                 parameters.to.save = c('p','sigma',
                                      'mu f', 'sigma f'),
                 model.file = textConnection(model code))
out summ = print(model run)$summary
```

Output

head(out summ, 12)

```
##
                              sd
                                       2.5%
                                                   25%
                                                              50%
                                                                         75%
                 mean
## deviance 54.5079242 6.1474360 44.76279915 49.9407469 53.7172180 58.0983481
## mu f[1]
            1.5999664 0.7661743 -0.01350619 1.0840624 1.6193483
                                                                   2.1065034
## mu f[2] -0.6960659 0.7389286 -2.23183434 -1.1758914 -0.6563889 -0.1919280
## mu f[3]
           -0.3846159 0.8693606 -2.07215211 -0.9615864 -0.4230721
                                                                   0.2160105
## mu f[4]
           -0.1398987 0.8361297 -1.81956857 -0.6751933 -0.1325097
                                                                   0.3754026
## p[1,1]
            0.6566798 0.2021004
                                 0.18434999
                                             0.5329714
                                                        0.6803838
                                                                   0.8089097
## p[2,1]
            0.6434648 0.2063434
                                 0.17959004
                                             0.5105568
                                                        0.6683021
                                                                   0.8014731
## p[3,1]
            0.6906719 0.1917650
                                 0.25854862
                                             0.5674411
                                                        0.7147720
                                                                   0.8362919
## p[4,1]
            0.6686381 0.2032589
                                 0.21423196
                                             0.5407938
                                                        0.6949525
                                                                   0.8261137
## p[5,1]
            0.6551692 0.2006426
                                 0.20051719
                                             0.5342385
                                                        0.6754302
                                                                   0.8067303
## p[6,1]
                                 0.25786712
            0.7019593 0.1963186
                                             0.5769374
                                                        0.7284246
                                                                   0.8592100
## p[7,1]
            0.7042350 0.1839797
                                 0.29305968
                                             0.5927219
                                                        0.7307162
                                                                   0.8429555
##
                 97.5%
                          Rhat n.eff
## deviance 68.6213500 1.007506
                                 290
## mu f[1]
            3.0520765 1.130180
                                  21
## mu f[2]
                                  19
            0.6339623 1.157124
             4 00004400 4 054700
```

Notes about the CLR model

- ► This is a great starter script for your own work. If you can understand this code and adapt it to your data you can get some really powerful results
- We can now put covariates in the model: we just have to expand μ_f in the previous JAGS code
- We now have individual dietary proportion estimates (p_{ik}) and overall dietary proportion estimates (via CLR transform of μ_k), and also estimates of the variability (from σ_f)
- Things start to get complicated with prior distributions at this stage. Be very careful and always examine prior sensitivity by re-running the model with slightly different prior distributions. Look at the effect on p (the effect on μ_f and σ_f is less important)

Summary

- ▶ We have looked at the differences between SIAR and MixSIAR
- ▶ We studied the CLR as an alternative to the Dirichlet
- We showed how to include random effects in a SIMM