

Can predicate invention in
meta-interpretive learning compensate
for incomplete background knowledge?

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Outline

- robot planning
 - experiments
- predicate invention
- related work
- conclusions and future work

Robot moving a ball - all actions

robot and ball finish here, robot not holding the ball

robot actions:

left/2

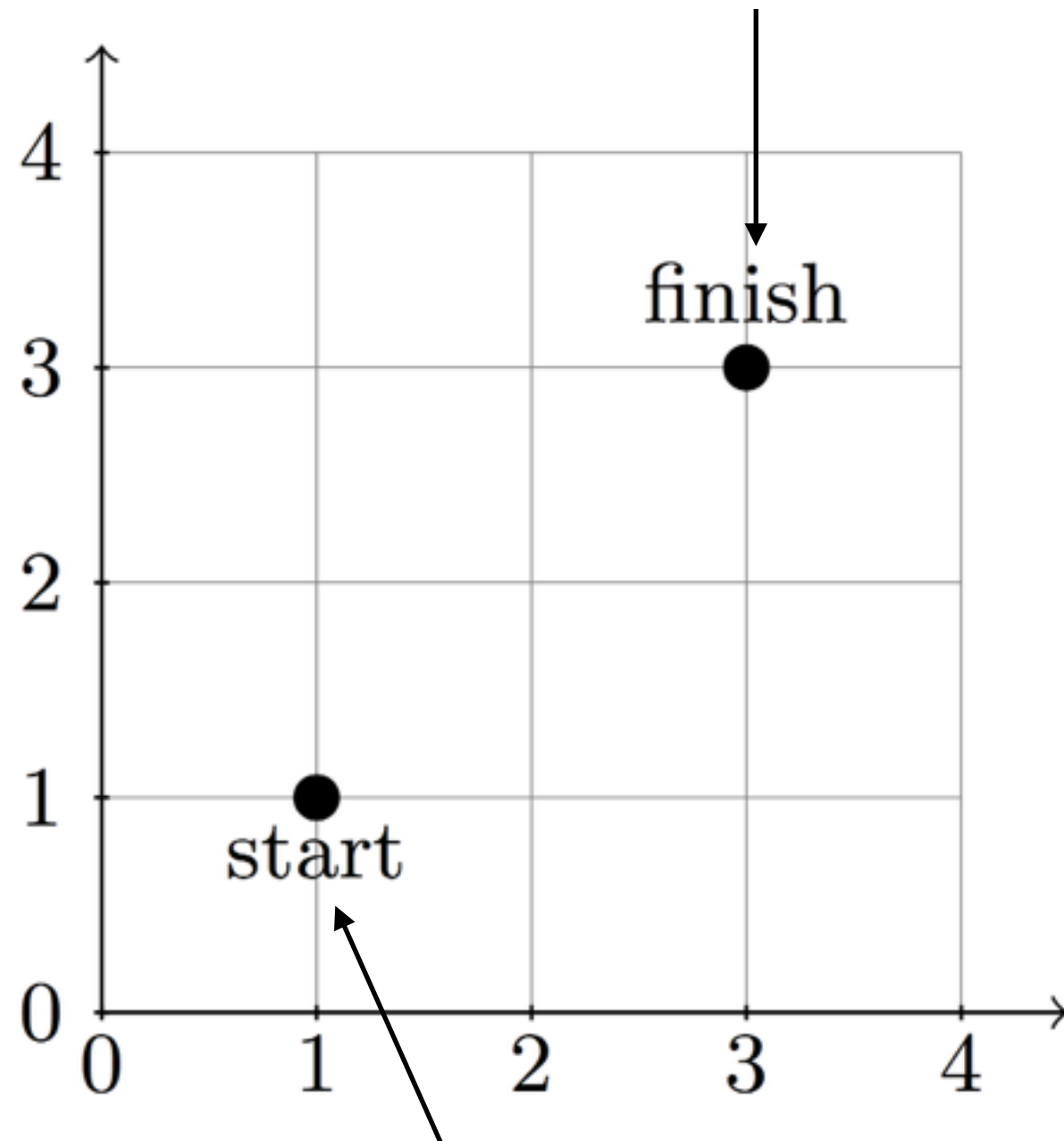
right/2

forwards/2

backwards/2

grab/2

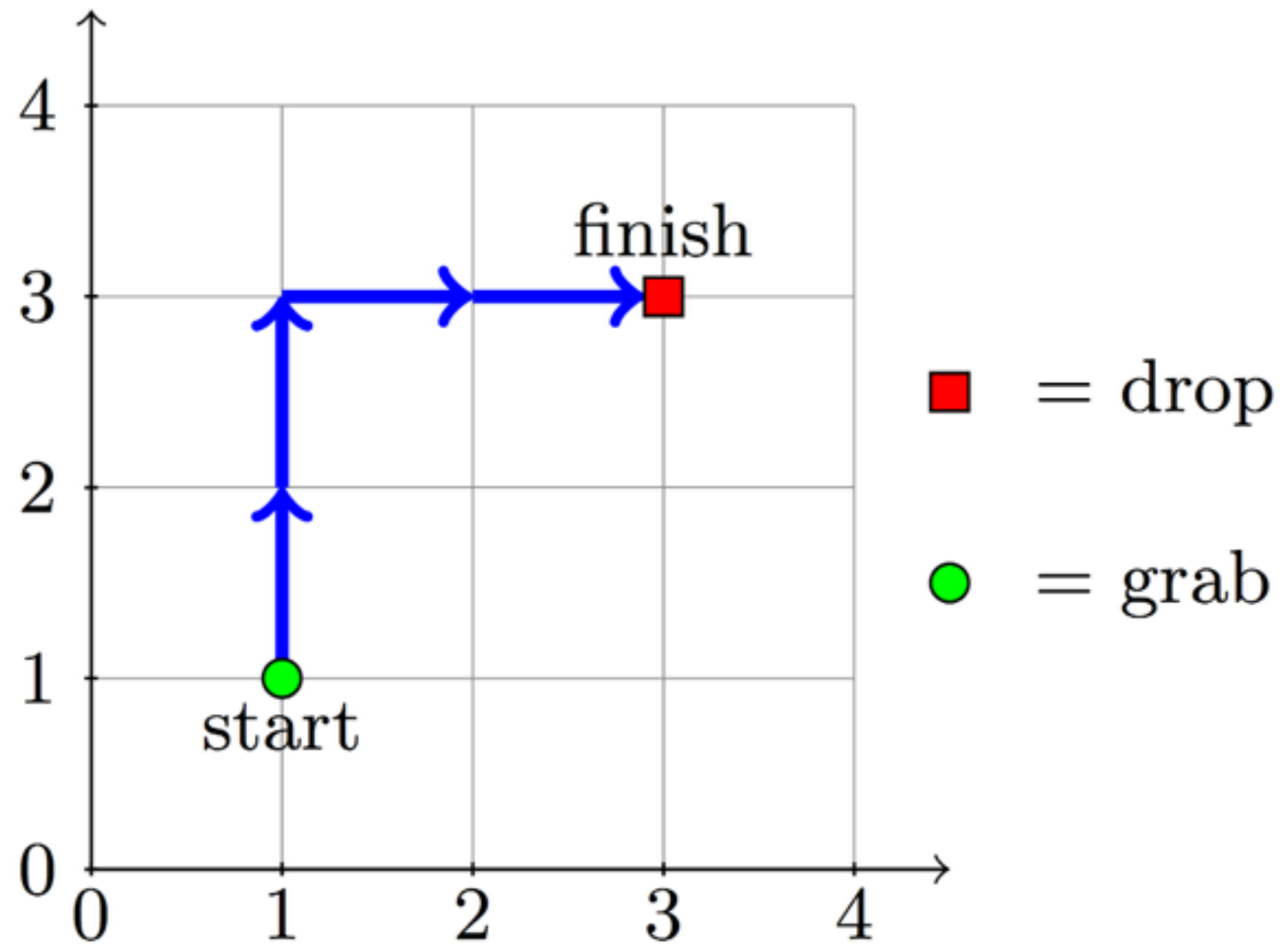
drop/2



robot and ball start here, robot not holding the ball

Possible plan

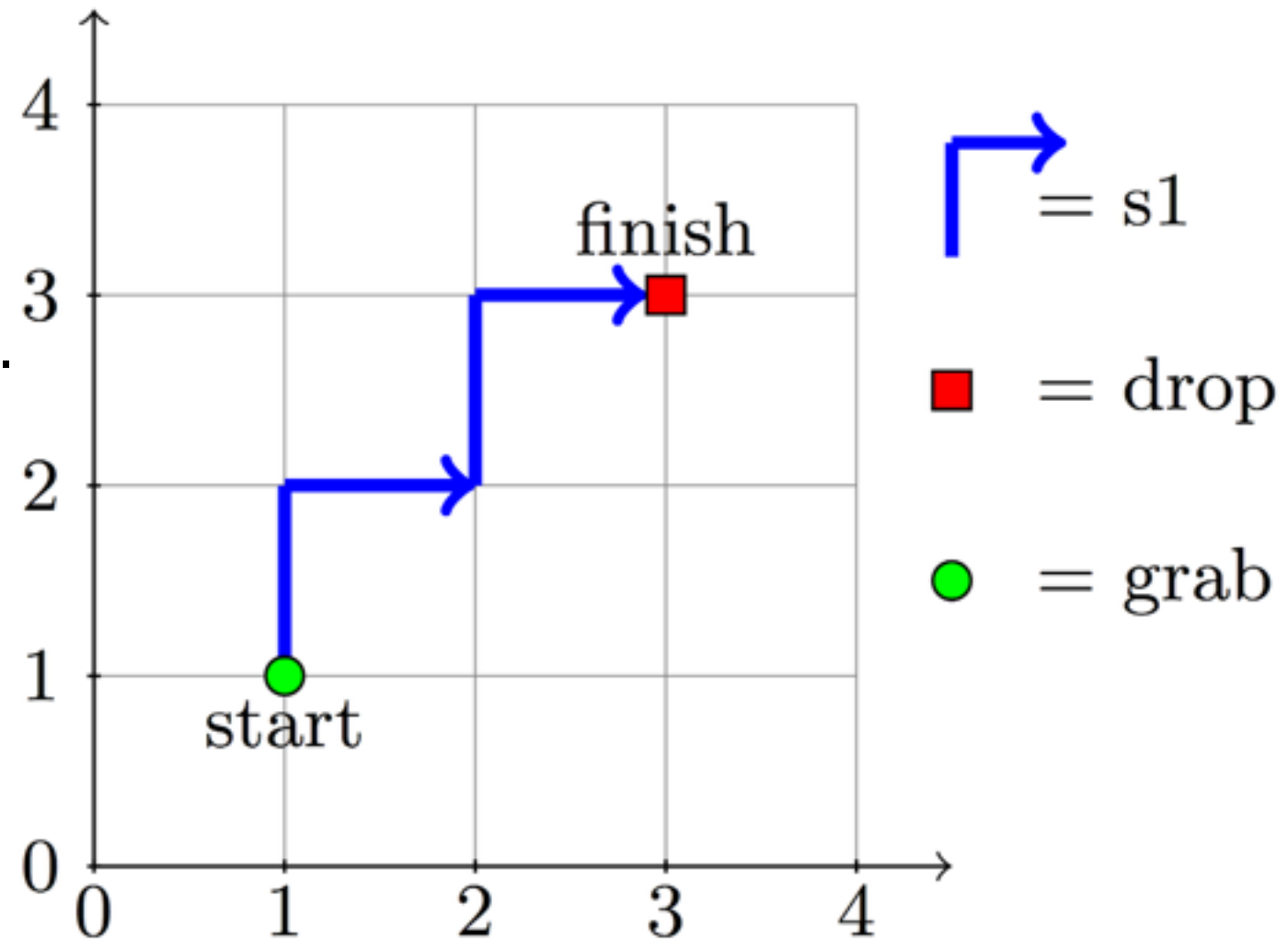
```
move_ball(X,Y) :-  
  grab(X,Z1)  
  forwards(Z1,Z2),  
  forwards(Z2,Z3),  
  right(Z3,Z4),  
  right(Z4,Z5),  
  drop(Z5,Y).
```



Plan learned with MIL

```
s1(X,Y):- forwards(X,Z),right(Z,Y).  
s2(X,Y):- s1(X,Z),s1(Z,Y).  
s3(X,Y):- grab(X,Z), s2(Z,Y).  
move(X,Y):- s3(X,Z),drop(Z,Y).
```

s1,s3,s3 are invented predicates



Robot moving a ball - missing actions

robot and ball finish here, robot not holding the ball

robot actions:

left/2

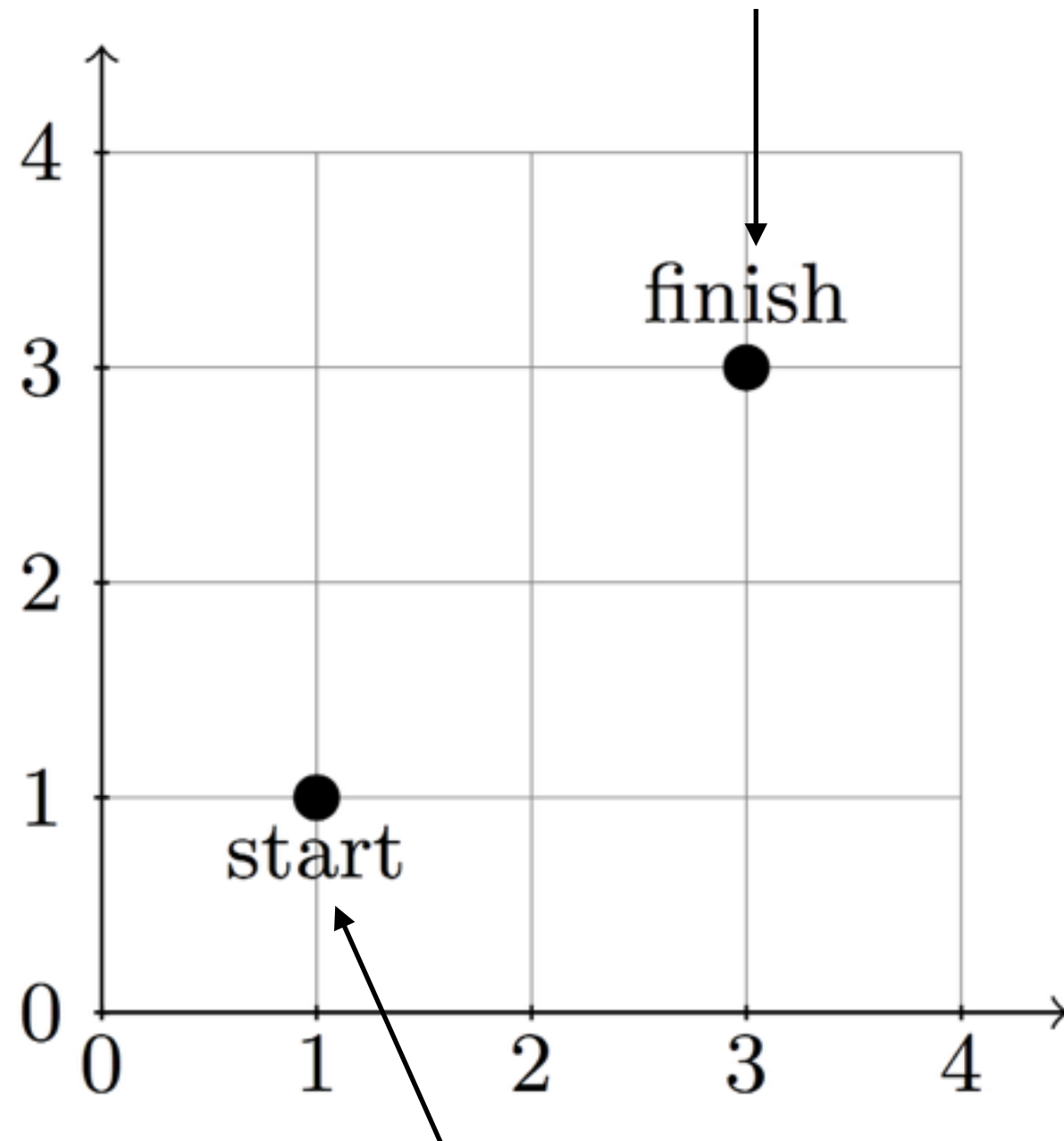
right/2

~~forwards/2~~

backwards/2

grab/2

~~drop/2~~

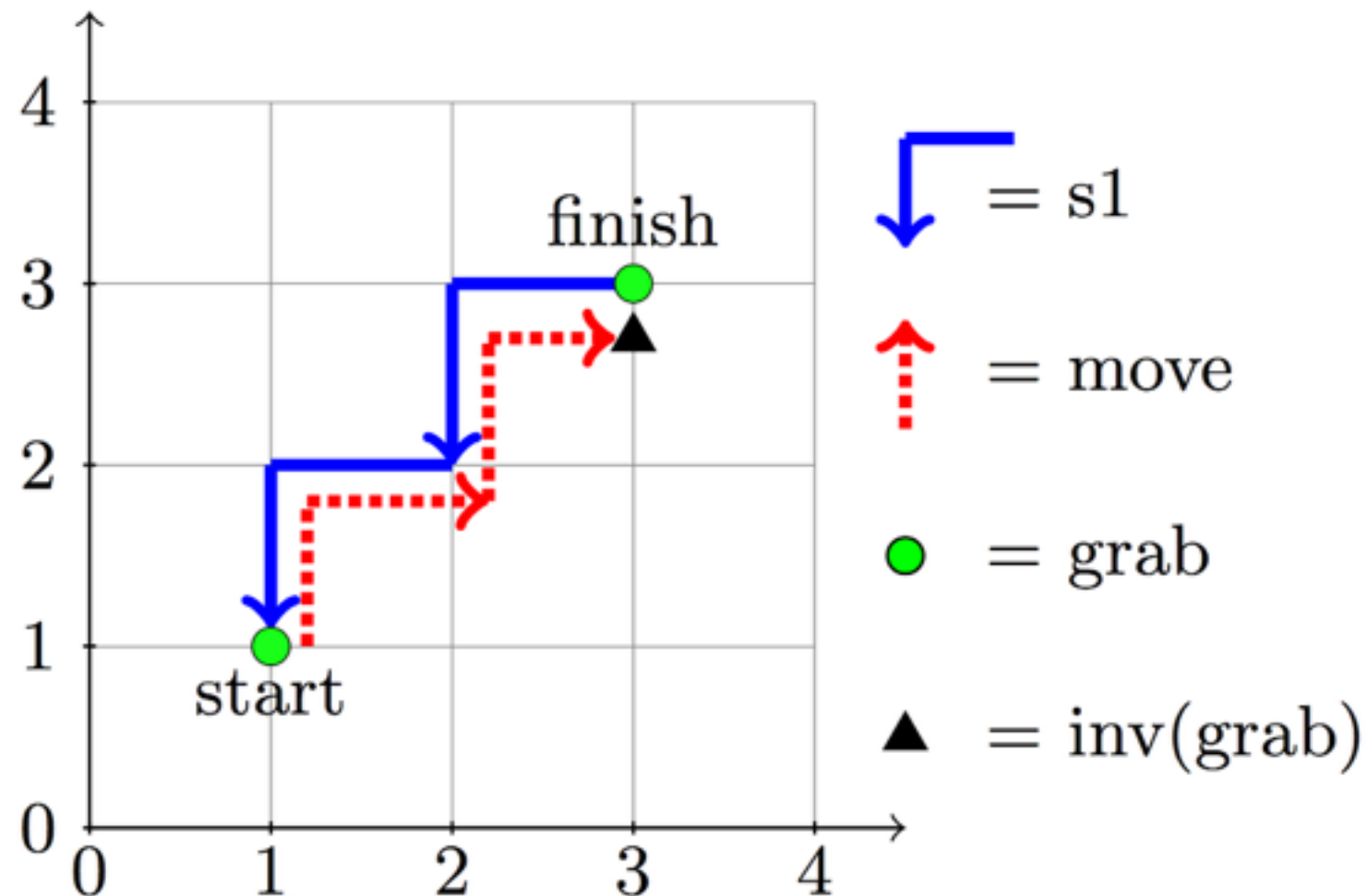


robot and ball start here, robot not holding the ball

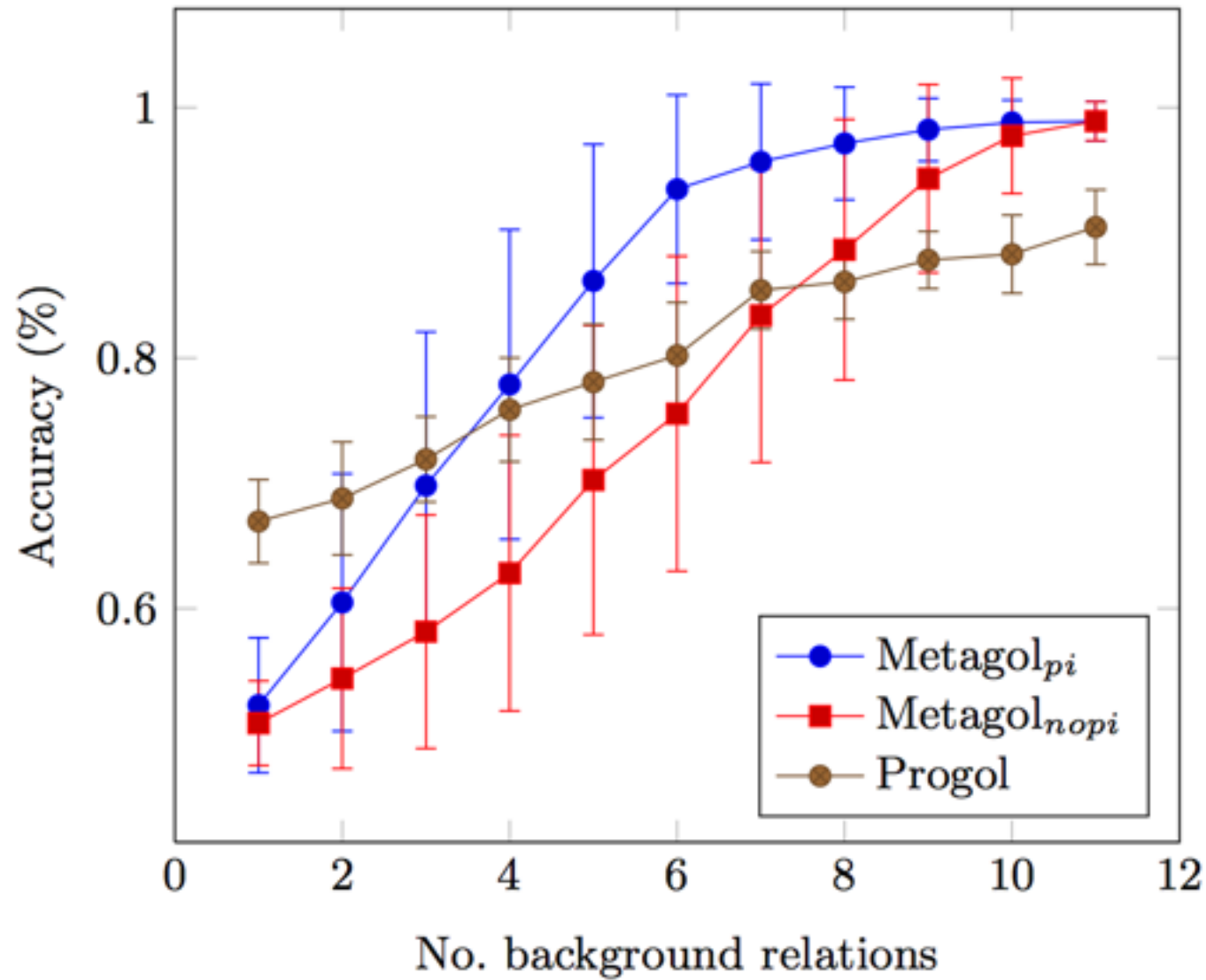
Plan learned with MIL

```
s1(X,Y):- left(X,Z), back(Z,Y).  
s2(X,Y):- grab(X,Z), s1(Z,Y).  
s3(X,Y):- s2(X,Z), s1(Z,Y).  
s4(X,Y):- s3(Y,X).  
move(X,Y):- grab(X,Z), s4(Z,Y).
```

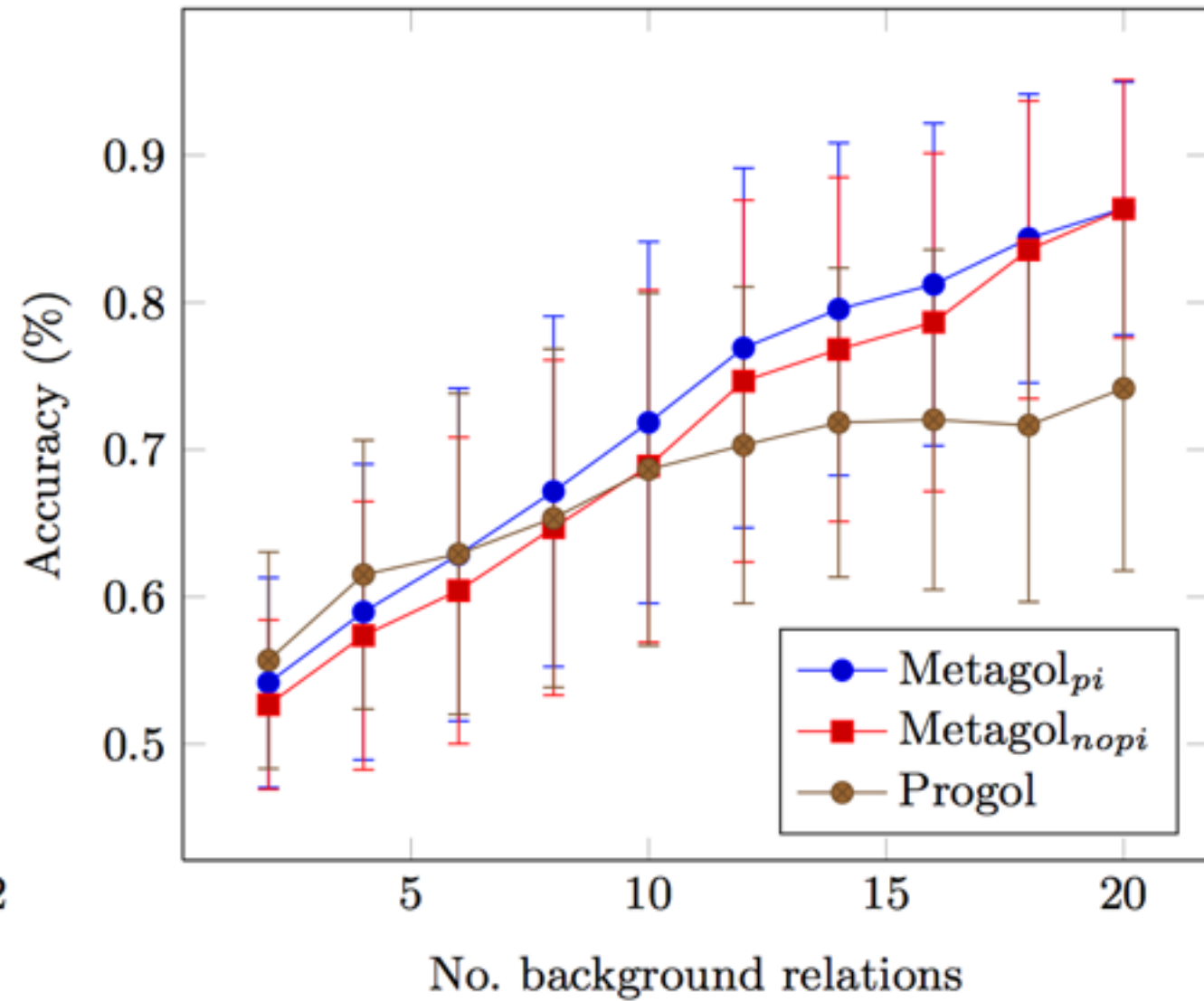
s1, s3, s3, s4 are invented predicates



Experiments



(a) Hinton's kinship dataset



(b) Our kinship dataset

- (a) 12 dyadic predicates and 104 examples uniformly distributed
(b) 21 dyadic predicates and 154 examples normally distributed

Learning great-great-grandparent relation

How can we learn the great-great-grandparent relation if we only have mother and father relation?

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s2 = invented *parent* relation

s2(X,Y):- father(X,Y).

s2(X,Y):- mother(X,Y).

s3(X,Y):- s2(X,Z), s2(Z,Y).

gggparent(X,Y):- s3(X,Z), s2(Z,Y).

s3 = invented *grandparent* relation

Related work

Missing data (feature based ML)

- Ghahramani & Jordan (1995)
- Marlin (2006)

Incomplete background knowledge

- Srinivasan, et al., (1995)
- Muggleton (2011)

Effect of missing predicates

- Liu and Zhong (1999)

Compensating for incomplete background knowledge

- Dzeroski (1993)

Dimensionality reduction

- Furnkranz (1997)

Conclusions and future work

Conclusions

- MIL can compensate for missing background predicates through predicate invention.
- Purposely remove background predicates to improve efficiency, analogous to dimensionality reduction.

Future work

- Automate removal of redundant background predicates
- Naming invented predicates