

# Relational decomposition for program synthesis

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What is this talk about?

A different way to look at program synthesis

# What is program synthesis?

Given:

- examples, typically input -> output

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- examples, typically input -> output

Find:

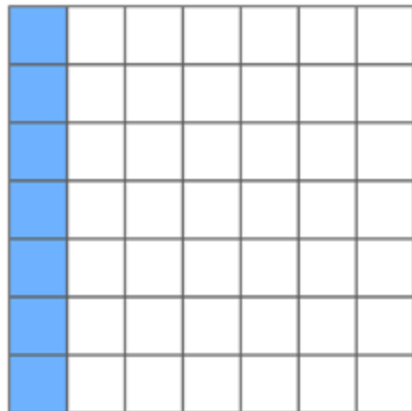
- a computer program that generalises them

Input	Output
[l, i, o, n]	[l, a, i, o, n]
[t, i, g, e, r]	[t, a, i, g, e, r]

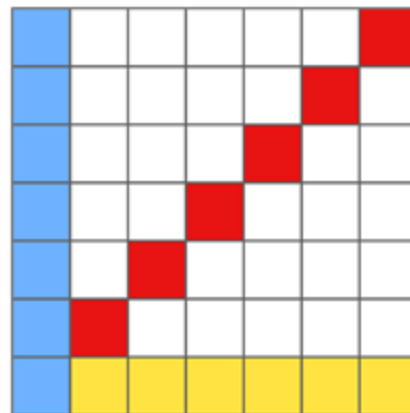
Input	Output
[l, i, o, n]	[l, a, i, o, n]
[t, i, g, e, r]	[t, a, i, g, e, r]

```
def f(xs):  
    return cons(head(xs), cons('a', tail(xs)))
```

input



output



Why is synthesis hard?

Infinite search space of undecidable  
programs



Why is synthesis hard?

Search space is bigger for harder problems

Standard approach

Find a sequence of functions to map an input  
to an output

Input	Output
[l, i, o, n]	[l, a, i, o, n]
[t, i, g, e, r]	[t, a, i, g, e, r]

```
def f(xs):  
    return cons(head(xs), cons('a', tail(xs)))
```

Input	Output
[l, i, o, n]	[l, i, a, o, n]
[t, i, g, e, r]	[t, i, a, g, e, r]

Input	Output
[l, i, o, n]	[l, i, a, o, n]
[t, i, g, e, r]	[t, i, a, g, e, r]

```
def f(xs):  
    return cons(head(xs),cons(head(tail(xs)),cons('a',tail(tail(xs)))))
```

Our idea

**Look a problem differently**

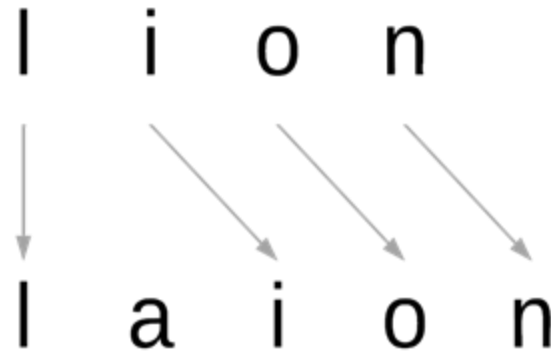
Our approach

Find relations between input and output  
elements

Input	Output
[l, i, o, n]	[l, a, i, o, n]



Input	Output
[l, i, o, n]	[l, a, i, o, n]



Input	Output
[l, i, o, n]	[l, a, i, o, n]

Input	Output
[l, i, o, n]	[l, a, i, o, n]

in(1,l).

in(2,i).


in(3,o).

in(4,n).

Input	Output
[l, i, o, n]	[l, a, i, o, n]

```
out(1, l).  
out(2, a).  
out(3, i).  
out(4, o).  
out(5, n).
```

Input	Output
[l, i, o, n]	[l, a, i, o, n]

<pre>in(1, l). in(2, i). in(3, o). in(4, n).</pre>		<pre>out(1, l). out(2, a). out(3, i). out(4, o). out(5, n).</pre>
--	---	---

Input	Output
[l, i, o, n]	[l, a, i, o, n]

`out(1,V):- in(1,V).`

`out(2,a).`

`out(I,V):- I>2, in(I-1,V).`

Input	Output
[l, i, o, n]	[l, a, i, o, n]

the output at index 1 is the input at index 1

the output at index 2 is a

the output at index  $l > 2$  is the input at index  $l-1$

Input	Output
[l, i, o, n]	[l, <b>a</b> , i, o, n]

the output at index 1 is the input at index 1

the output at index 2 is a

the output at index  $l > 2$  is the input at index  $l-1$



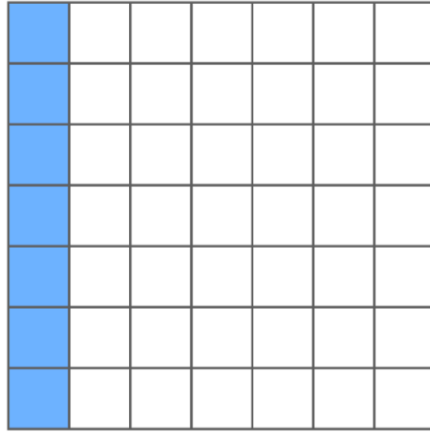
Input	Output
[l, i, o, n]	[l, a, <b>i</b> , <b>o</b> , <b>n</b> ]

the output at index 1 is the input at index 1

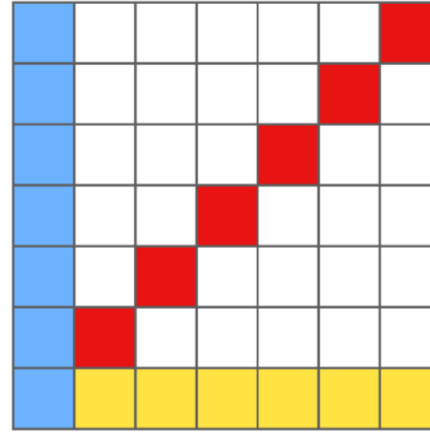
the output at index 2 is a

the output at index  $l > 2$  is the input at index  $l-1$

Input



Output



## Input

■						
■						
■						
■						
■						
■						
■						

`in(1,1,blue).`

`in(1,2,blue).`

`in(1,3,blue).`

`...`

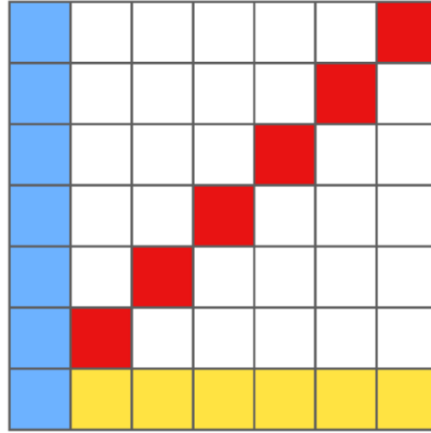
`empty(2,1).`

`empty(2,1).`

`empty(2,1).`

`... .`

## Output



`out(1,1,blue).` `out(1,7,yellow).`

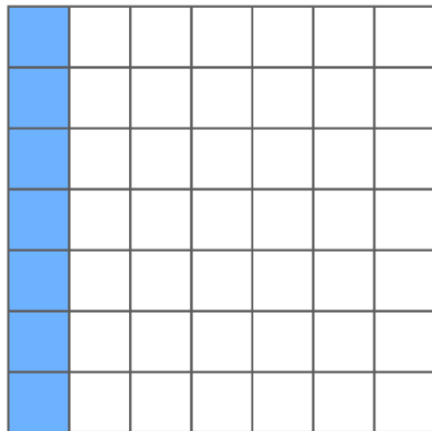
`out(1,2,blue).` `out(2,7,yellow).`

`out(1,3,blue).` `out(3,7,yellow).`

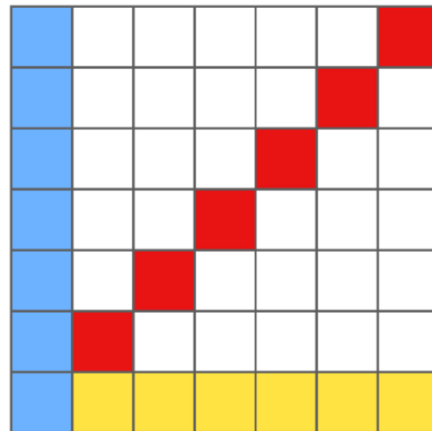
`...`

`... .`

Input



Output

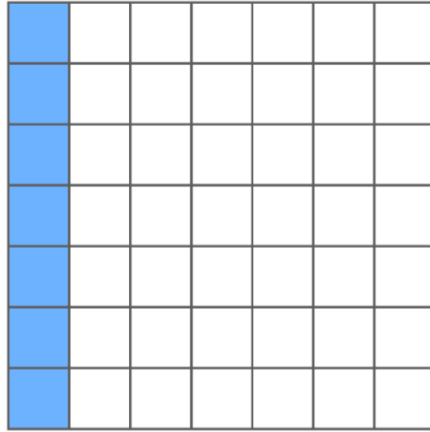


```
out(X,Y,C):- in(X,Y,C).
```

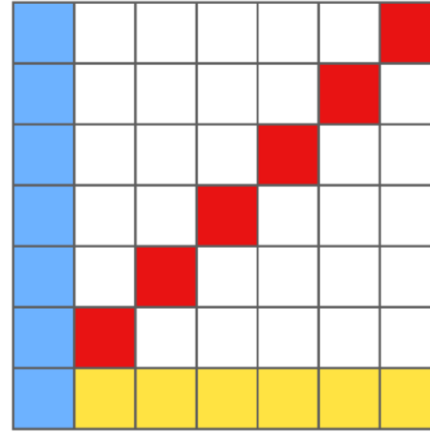
```
out(X,Y,yellow):- empty(X,Y), height(X).
```

```
out(X,Y,red):- empty(X,Y), height(X+Y-1).
```

Input

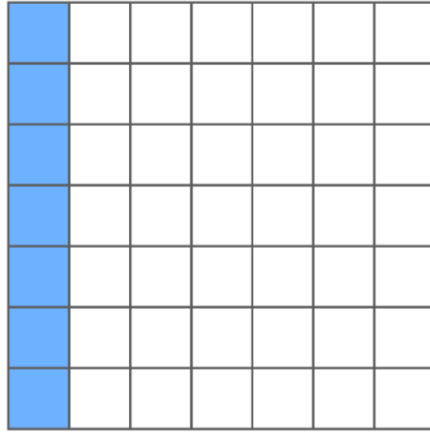


Output

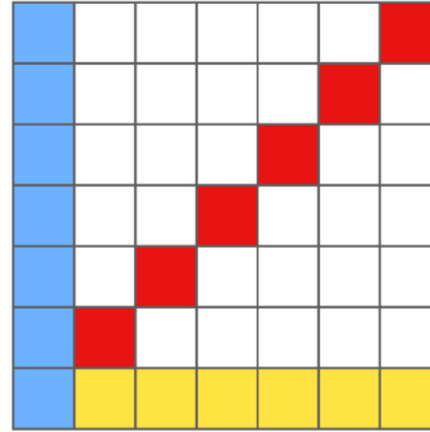


1. An output pixel is colour C if it is colour C in the input

Input

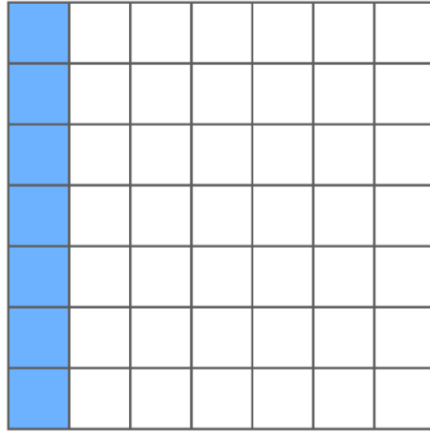


Output

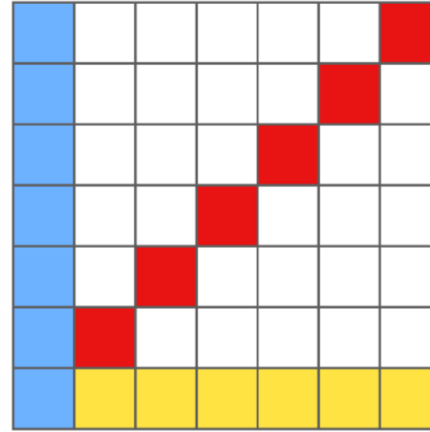


2. An output pixel is yellow if it is in the bottom row and empty in the input

Input



Output



3. An output pixel is red if it is empty and on the diagonal



How?

Inductive logic programming

How?

Logical machine learning

# Inductive logic programming

# Inductive logic programming

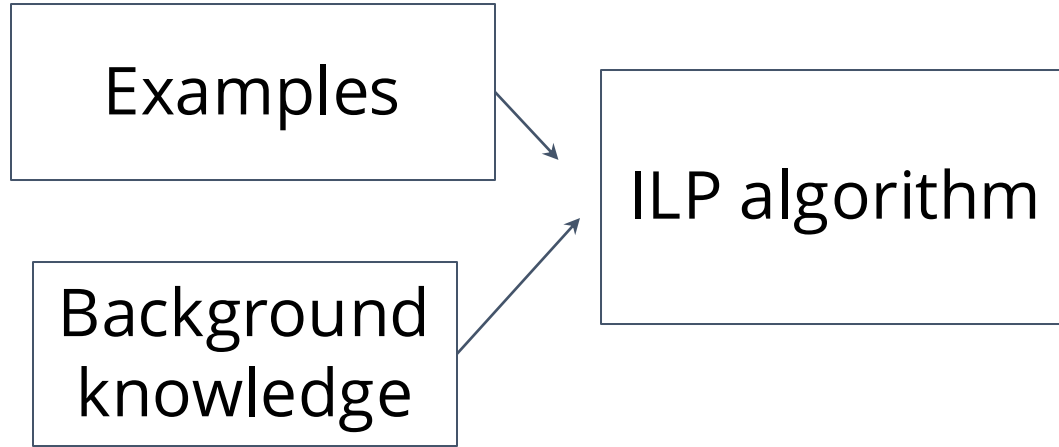
Examples

# Inductive logic programming

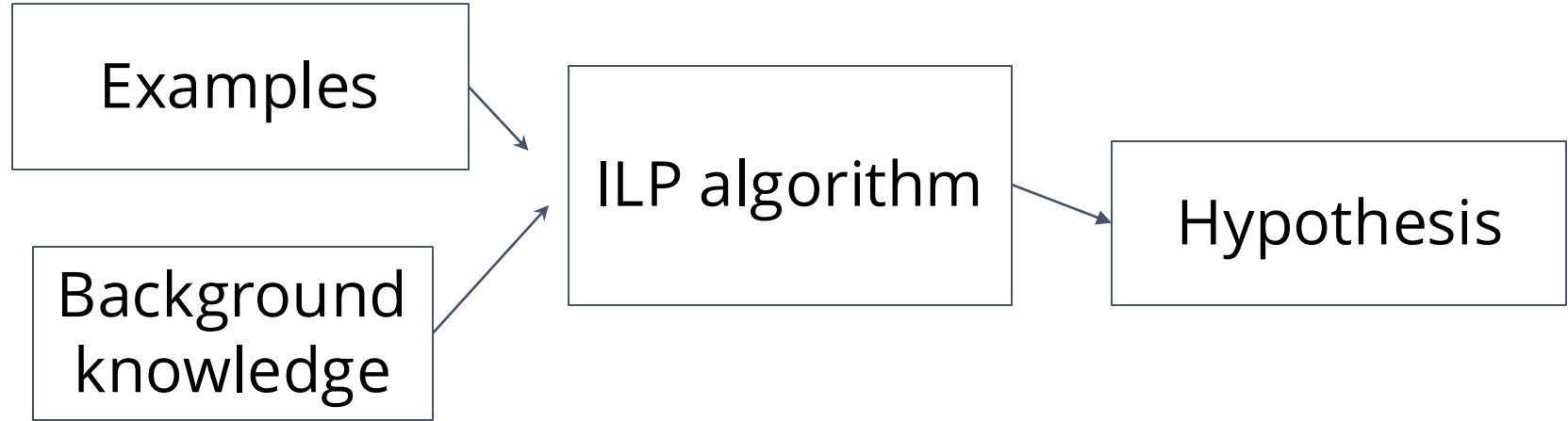
Examples

Background  
knowledge

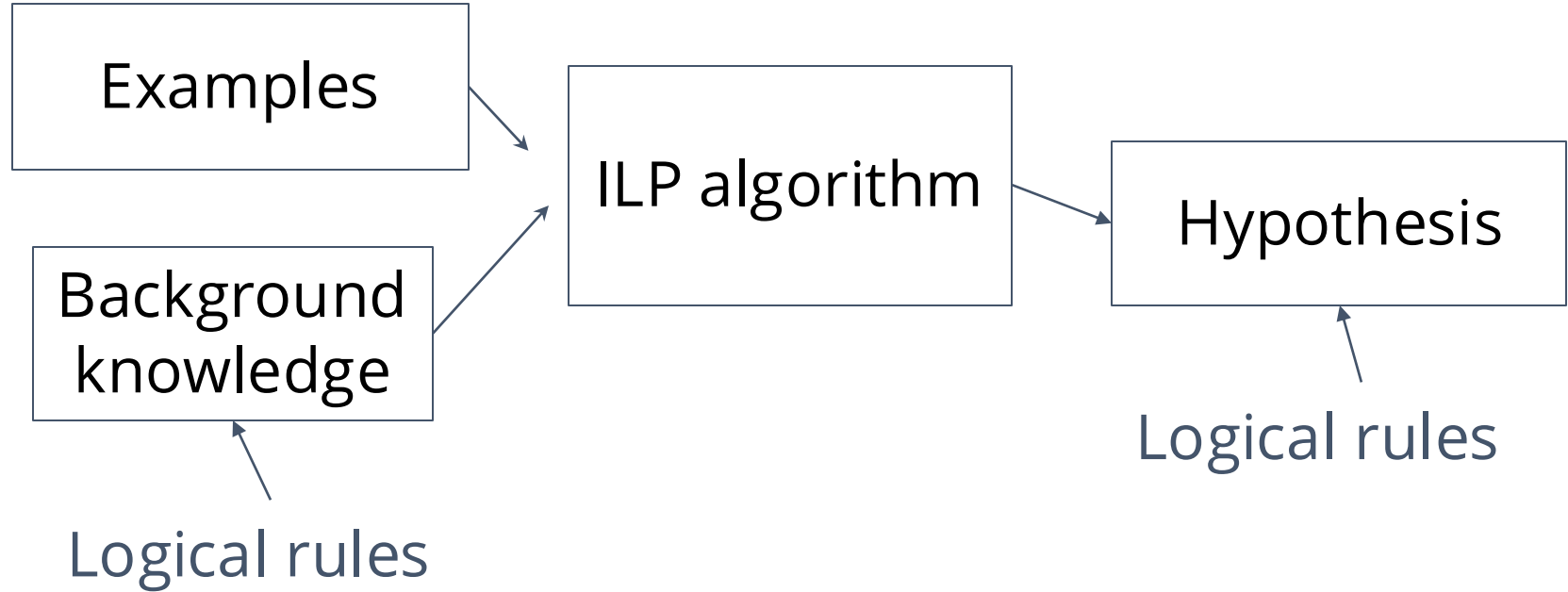
# Inductive logic programming



# Inductive logic programming



# Inductive logic programming





Input	Output
[l, i, o, n]	[l, a, i, o, n]

```
% examples  
out(1,l).  
out(2,a).  
out(3,i).  
out(4,o).  
out(5,n).
```

Input	Output
[l, i, o, n]	[l, a, i, o, n]

```
% examples  
out(1,l).  
out(2,a).  
out(3,i).  
out(4,o).  
out(5,n).
```

```
% bk  
in(1,l).  
in(2,i).  
in(3,o).  
in(4,n).  
<(2,3).  
<(2,4).  
>(5,2).  
...
```

Input	Output
[l, i, o, n]	[l, a, i, o, n]

```
% examples  
out(1,l).  
out(2,a).  
out(3,i).  
out(4,o).  
out(5,n).
```

```
% bk  
in(1,l).  
in(2,i).  
in(3,o).  
in(4,n).  
<(2,3).  
<(2,4).  
>(5,2).  
...
```



```
graph LR; A["% examples<br/>out(1,l).<br/>out(2,a).<br/>out(3,i).<br/>out(4,o).<br/>out(5,n)."] --> C["ILP<br/>algorithm"]; B["% bk<br/>in(1,l).<br/>in(2,i).<br/>in(3,o).<br/>in(4,n).<br/><(2,3).<br/><(2,4).<br/>>(5,2).<br/>..."] --> C;
```

ILP  
algorithm

```
% examples  
out(1,l).  
out(2,a).  
out(3,i).  
out(4,o).  
out(5,n).
```

```
% bk  
in(1,l).  
in(2,i).  
in(3,o).  
in(4,n).  
<(2,3).  
<(2,4).  
>(5,2).  
...
```

ILP  
algorithm

```
% hypothesis  
out(1,V) ← in(1,V).  
out(2,a).  
out(I,V) ← I>2, in(I-1,V).
```

Does it work?

Does it work?

Our approach:

- Off-the-shelf ILP system
- Learn from raw data + simple arithmetic

Does it work?

Others (non-relational):

- Domain-specific algorithms
- Domain-specific functions



# 1D-ARC



Figure 4: The *denoise* task from *1D-ARC*.

Task include *mirror*, *fill*, or *hollow*.

# 1D-ARC

U5



<b>Time</b>	<b>ARGA</b>	<b>BEN</b>	<b>MB</b>	<b>HL</b>	<b>Decom</b>
1	<b>93±6</b>	na	0±0	0±0	59±7
10	<b>94±6</b>	na	0±0	0±0	63±7
60	<b>94±6</b>	na	0±0	0±0	69±6

# 1D-ARC

U5

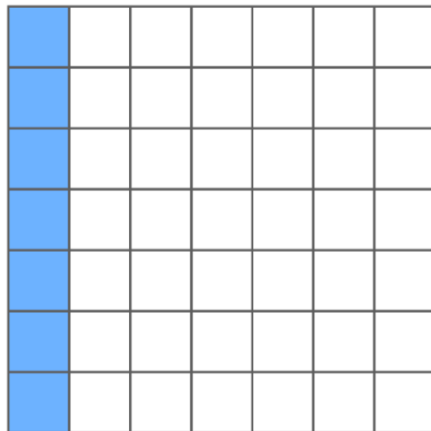


<b>Time</b>	<b>ARGA</b>	<b>BEN</b>	<b>MB</b>	<b>HL</b>	<b>Decom</b>
1	<b>93±6</b>	na	0±0	0±0	59±7
10	<b>94±6</b>	na	0±0	0±0	63±7
60	<b>94±6</b>	na	0±0	0±0	69±6

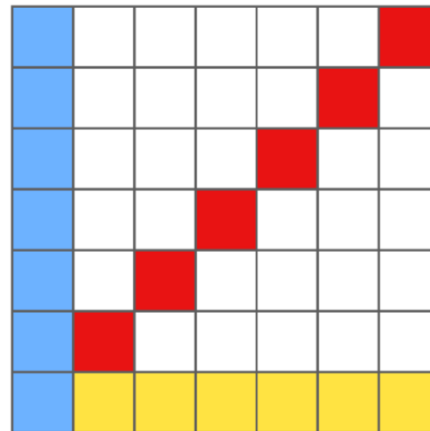
ARGA uses 15 domain-specific operators, including *mirror*, *fill*, and *hollow*.

# ARC1

Input



Output



# ARC1

U5



Time	ARGA	BEN	MB	HL	Decom
1	$8 \pm 1$	$6 \pm \text{na}$	$0 \pm 0$	$0 \pm 0$	<b><math>15 \pm 1</math></b>
10	$11 \pm 2$	<b><math>25 \pm \text{na}</math></b>	$0 \pm 0$	$0 \pm 0$	$20 \pm 1$
60	$12 \pm 2$	na	$0 \pm 0$	$0 \pm 0$	<b><math>22 \pm 1</math></b>

BEN uses domain-specific object detection features and domain-specific functions, such as *denoise*, *mirror*, *rotate*

# List functions

*the list [8, 2, 7, 0, 3]*

[1, 4, 9, 7] → [8, 2, 7, 0, 3]  
[8, 4, 5, 0, 2, 1, 9, 3, 7] → [8, 2, 7, 0, 3]  
[4, 9, 1, 8, 5, 0] → [8, 2, 7, 0, 3]  
[1, 5, 4, 7, 0] → [8, 2, 7, 0, 3]  
[6] → [8, 2, 7, 0, 3]

*add 2 to every item*

[7, 3, 4] → [9, 5, 6]  
[2, 3, 1, 0, 5] → [4, 5, 3, 2, 7]  
[3, 6, 5, 7, 1, 2, 4] → [5, 8, 7, 9, 3, 4, 6]  
[5, 6, 1, 0] → [7, 8, 3, 2]  
[3, 4, 1, 2, 0, 7] → [5, 6, 3, 4, 2, 9]

*swap the first and last items*

[0, 9, 1, 8] → [8, 9, 1, 0]  
[8, 1, 4, 7, 5, 2] → [2, 1, 4, 7, 5, 8]  
[6, 2, 8, 7] → [7, 2, 8, 6]  
[0, 6] → [6, 0]  
[6, 9, 5] → [5, 9, 6]

*(0.78)*

*remove all but item 3*

[7, 39, 31, 4] → [31]  
[23, 57, 65, 52, 51] → [65]  
[9, 35] → []  
[79, 97, 98, 4, 6, 89] → [98]  
[48] → []

*(0.49)*

*(0.68)*

*replace item 6 with a 3*

[6, 1, 9, 0, 7, 2] → [6, 1, 9, 0, 7, 3]  
[7, 2, 1, 6] → [7, 2, 1, 6]  
[9, 6, 2, 0, 8, 7, 4, 5] → [9, 6, 2, 0, 8, 3, 4, 5]  
[1, 9, 7, 0, 5, 4, 8] → [1, 9, 7, 0, 5, 3, 8]  
[4, 0, 7] → [4, 0, 7]

*(0.35)*

*(0.63)*

*first N items after item 1, N is the value of item 1*

[3, 1, 9, 0, 7] → [1, 9, 0]  
[2, 1, 3, 4, 6, 9] → [1, 3]  
[4, 1, 2, 3, 5, 0, 7, 6, 9, 8] → [1, 2, 3, 5]  
[1, 5, 4, 2, 8, 3, 0, 6] → [5]  
[5, 2, 1, 0, 4, 3, 7, 6] → [2, 1, 0, 4, 3]

*(0.26)*

# List functions

U5



<b>Time</b>	<b>ARGA</b>	<b>BEN</b>	<b>MB</b>	<b>HL</b>	<b>Decom</b>
1	$0\pm0$	na	$0\pm0$	<b><math>31\pm2</math></b>	$27\pm2$
10	$0\pm0$	na	$7\pm1$	$33\pm2$	<b><math>46\pm2</math></b>
60	$0\pm0$	na	$8\pm1$	$35\pm3$	<b><math>52\pm2</math></b>

HL is designed for the list function dataset

# Why does it work?

- Decomposes a training example into multiple examples



# What is missing?

- Better search

# What is missing?

- Go beyond raw data (add counting)

# Conclusion

- Looking at a problem differently can improve learning performance

Interested?

ILP system Popper

<https://github.com/logic-and-learning-lab/Popper>

(Just Google Popper + ILP)