# Learning algorithms using logic

(inductive logic programming)

input	output
cat	С
dog	d
bear	?

input	output
cat	С
dog	d
bear	b

input	output
cat	С
dog	d
bear	b

def f(a):
 return head(a)

input	output
cat	С
dog	d
bear	b

 $\forall A. \forall B. head(A,B) \rightarrow f(A,B)$ 

input	output
cat	С
dog	d
bear	b

 $\forall A. \forall B. f(A,B) \leftarrow head(A,B)$ 

input	output
cat	С
dog	d
bear	b

$$f(A,B) \leftarrow head(A,B)$$

input	output
cat	С
dog	d
bear	b

$$f(A,B):-head(A,B).$$

input	output
cat	а
dog	Ο
bear	?

input	output
cat	а
dog	Ο
bear	e

```
def f(a):
    c = tail(a)
    b = head(c)
    return b
```

input	output
cat	а
dog	Ο
bear	е

 $\forall A. \forall B. \forall C \text{ tail}(A,C) \land \text{head}(C,B) \rightarrow f(A,B)$ 

input	output
cat	а
dog	Ο
bear	e

 $f(A,B) \leftarrow tail(A,C) \land head(C,B)$ 

input	output
cat	а
dog	Ο
bear	e

 $f(A,B) \leftarrow tail(A,C), head(C,B)$ 

input	output
cat	а
dog	Ο
bear	e

input	output	
dog	9	
sheep	р	
chicken	?	

input	output
dog	9
sheep	р
chicken	n

```
def f(a):
    return a[-1]
```

input	output	
dog	9	
sheep	р	
chicken	n	

```
def f(a):
    t = tail(a)
    if empty(t):
        return head(a)
    return f(t)
```

input	output	
dog	9	
sheep	р	
chicken	n	

```
tail(A,C) \wedge empty(C) \wedge head(A,B) \rightarrow f(A,B) tail(A,C) \wedge f(C,B) \rightarrow f(A,B)
```

input	output	
dog	9	
sheep	р	
chicken	n	

```
f(A,B) \leftarrow tail(A,C), empty(C), head(A,B)
f(A,B) \leftarrow tail(A,C), f(C,B)
```

input	output	
dog	9	
sheep	р	
chicken	n	

```
f(A,B):- tail(A,C),empty(C),head(A,B).
f(A,B):- tail(A,C),f(C,B).
```

input	output
ecv	cat
fqi	dog
iqqug	?

input	output
ecv	cat
fqi	dog
iqqug	goose

```
f(A,B):-
    map(f1,A,B).
f1(A,B):-
    char_code(A,C),
    succ(D,C),
    succ(E,D),
    char_code(B,E).
```

#### eastbound

# 

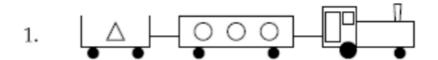








#### westbound







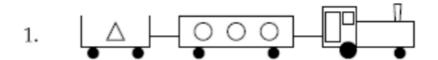




#### eastbound

#### westbound

















```
eastbound(A):-
   has_car(A,B),
   short(B),
   closed(B).
```

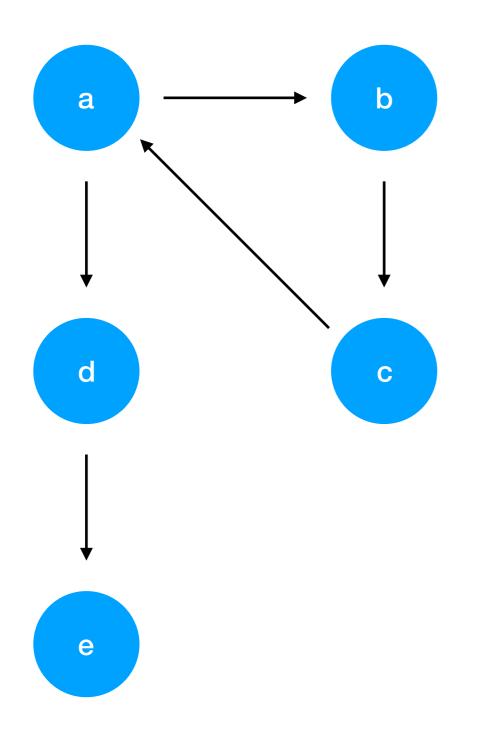
## ILP learning from entailment setting

## Input:

- Sets of atoms E+ and E-
- Logic program BK

## Output:

- logic program H s.t
- BK ∪ H ⊨ E+
- BK ∪ H !⊨ E-



```
% bk
edge(a,b).
edge(b,c).
edge(c,a).
edge(a,d).
edge(d,e).
```

```
% examples
pos(reachable(a,c)).
pos(reachable(b,e)).
neg(reachable(d,a)).
```

```
reachable(A,B):- edge(A,B).
reachable(A,B):- edge(A,C),reachable(C,B).
```

## **ILP** approaches

#### Set covering

- generalise a specific clause (Progol, Aleph)
- specialise a general clause (FOIL)

#### Generate and test

- Answer set programming (HEXMIL, ILASP, INSPIRE)
- PL systems

Neural-ILP (DILP and now about 10<sup>6</sup> other systems)

Proof search (Metagol)

## Metagol

- Prolog meta-interpreter
- 50 lines of code
- Proof search
- Uses metarules to guide the search
- Supports:
  - Recursion
  - Predicate invention
  - Higher-order programs

# Meta-interpreter 1

```
prove(Atom):-
    call(Atom).
```

#### Meta-interpreter 2

```
prove(true).

prove(Atom):-
    clause(Atom, Body),
    prove(Body).

prove((Atom, Atoms)):-
    prove(Atom),
    prove(Atom),
```

#### Meta-interpreter 3

```
prove([]).

prove([Atom|Atoms]):-
    clause(Atom,Body),
    body_as_list(Body,BList),
    prove(BList).
```

### Metagol 1

```
prove([]).
prove([Atom|Atoms]):-
    prove_aux(Atom),
    prove(Atoms).
prove_aux(Atom):-
    call(Atom).
prove_aux(Atom):-
    metarule(Atom, Body),
    prove(Body).
```

### Metagol 2

```
prove([],P,P).
prove([Atom|Atoms],P1,P2):-
    prove_aux(Atom, P1, P3),
    prove(Atoms, P3, P2).
prove_aux(Atom, P, P):-
    call(Atom).
prove_aux(Atom, P1, P2):-
    metarule(Atom, Body, Subs),
    save(Subs,P1,P3),
    prove(Body, P3, P2).
```

#### **Metarules**

$$P(A,B) \leftarrow Q(A,B)$$
 $P(A,B) \leftarrow Q(B,A)$ 
 $P(A,B) \leftarrow Q(A),R(A,B)$ 
 $P(A,B) \leftarrow Q(A,B),R(B)$ 
 $P(A,B) \leftarrow Q(A,C),R(C,B)$ 

## Logical reduction of metarules [ILP14, ILP18]

$$P(A,B) \leftarrow Q(A,B)$$
  
 $P(A,B) \leftarrow Q(B,A)$   
 $P(A,B) \leftarrow Q(A,C), R(B,C)$   
 $P(A,B) \leftarrow Q(A,C), R(C,B)$   
 $P(A,B) \leftarrow Q(B,A), R(A,B)$   
 $P(A,B) \leftarrow Q(B,A), R(B,A)$   
 $P(A,B) \leftarrow Q(B,C), R(A,C)$   
 $P(A,B) \leftarrow Q(B,C), R(C,A)$   
 $P(A,B) \leftarrow Q(C,A), R(B,C)$   
 $P(A,B) \leftarrow Q(C,A), R(C,B)$   
 $P(A,B) \leftarrow Q(C,B), R(A,C)$   
 $P(A,B) \leftarrow Q(C,B), R(A,C)$ 

## Logical reduction of metarules [ILP14, ILP18]

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 $P(A,B) \leftarrow Q(B,C), R(C,A)$   
 $P(A,B) \leftarrow Q(C,A), R(B,C)$   
 $P(A,B) \leftarrow Q(C,A), R(C,B)$   
 $P(A,B) \leftarrow Q(C,B), R(A,C)$   
 $P(A,B) \leftarrow Q(C,B), R(A,C)$   
 $P(A,B) \leftarrow Q(C,B), R(C,A)$ 

Learning game rules

```
% examples
fizz(4,4).
fizz(3,fizz).
fizz(10,buzz).
fizz(11,11).
fizz(30,fizzbuzz).
```

```
% examples
fizz(4,4).
fizz(3,fizz).
fizz(10,buzz).
fizz(11,11).
fizz(30,fizzbuzz).
```

```
% hypothesis
fizzbuzz(N, fizz):-
    divisible(N,3),
    not(divisible(N,5)).
fizzbuzz(N,buzz):-
    not(divisible(N,3)),
    divisible(N, 5).
fizzbuzz(N, fizzbuzz):-
    divisible(N, 15).
fizzbuzz(N,N):-
    not(divisible(N,3)),
    not(divisible(N,5)).
```

Game	R	L	D	P
Minimal Decay	2	6	0	1
Minimal Even	8	19	0	1
Rainbow	10	48	0	1
Rock Paper Scissors	12	36	0	1
GT Chicken	16	78	0	2
GT Attrition	16	60	0	2
Coins	16	45	0	1
Buttons and Lights	16	44	1	1
Leafy	17	80	2	2
GT Prisoner	17	75	0	2
Eight Puzzle	17	60	2	1
Lightboard	18	69	2	2
Knights Tour	18	46	2	1
Sukoshi	19	49	1	2
Walkabout	22	66	2	2
Horseshoe	22	59	2	2
GT Ultimatum	22	67	0	2
Tron	23	76	2	2
9x Buttons and Lights	24	77	2	1
Hunter	24	69	2	1
GT Centipede	24	69	0	2
Fizz Buzz	25	74	0	1
Untwisty Corridor	27	68	0	1
Don't Touch	29	84	2	2
Tiger vs Dogs	30	88	2	2

Game	R	L	D	P
Sheep and Wolf	30	89	2	2
Duikoshi	31	76	2	2
TicTacToe	32	92	2	2
HexForThree	35	130	2	3
Connect 4	36	124	2	4
Breakthrough	36	126	2	2
Centipede	37	134	2	1
Forager	40	106	2	1
Sudoku	41	101	2	1
Sokoban	41	172	2	1
9x TicTacToe	42	149	2	2
Switches	44	183	2	1
Battle of Numbers	44	134	2	2
Free For All	46	130	2	2
Alquerque	49	134	2	2
Kono	50	134	2	2
Checkers	52	167	2	2
Pentago	53	188	2	2
Platform Jumpers	62	168	2	2
Pilgrimage	80	240	2	2
Firesheep	85	290	2	2
Farming Quandries	88	451	2	2
TTCC4	94	301	2	2
Frogs and Toads	97	431	2	2
Asylum	101	273	2	2

# Learning higher-order programs

[IJCAI16]

Input	Output
[[i,j,c,a,i],[2,0,1,6]]	[[i,j,c,a]]
[[1,1],[a,a],[x,x]]	[[1],[a]]
[[1,2,3,4,5],[1,2,3,4,5]]	[[1,2,3,4]]
[[1,2],[1,2,3],[1,2,3,4],[1,2,3,4,5]]	[[1],[1,2],[1,2,3]]

```
f(A,B):-f4(A,C),f3(C,B).
f4(A,B):-map(A,B,f3).
f3(A,B):-f2(A,C),f1(C,B).
f2(A,B):-f1(A,C),tail(C,B).
f1(A,B):-reduceback(A,B,concat).
```

```
f(A,B):-map(A,C,f2),f2(C,B).
f2(A,B):-f1(A,C),tail(C,D),f1(D,B).
f1(A,B):-reduceback(A,B,concat).
```

Lifelong learning

[ECAI14]

task	input	output
f	philip.larkin@sj.ox.ac.uk	Philip Larkin

task	input	output
f	philip.larkin@sj.ox.ac.uk	Philip Larkin

```
f(A,B):-
   f1(A,C),
   skip1(C,D),
   space(D,E),
   f1(E,F),
   skiprest(F,B).
f1(A,B):-
   uppercase(A,C),
   copyword(C,B).
```

### 10 seconds

task	input	output
g	tony	Tony

task	input	output
g	tony	Tony

g(A,B):-uppercase(A,C),copyword(C,B).

task	input	output
g	tony	Tony
f	philip.larkin@sj.ox.ac.uk	Philip Larkin

g(A,B):-uppercase(A,C),copyword(C,B).

task	input	output
g	tony	Tony
f	philip.larkin@sj.ox.ac.uk	Philip Larkin

#### 2 seconds

# Learning efficient programs

[IJCAI15, MLJ18]

input	output
[s,h,e,e,p]	е
[a,l,p,a,c,a]	а
[c,h,i,c,k,e,n]	?

input	output
[s,h,e,e,p]	е
[a,l,p,a,c,a]	а
[c,h,i,c,k,e,n]	C

```
f(A,B):-head(A,B),tail(A,C),element(C,B).
f(A,B):-tail(A,C),f(C,B).
```

input	output
[s,h,e,e,p]	е
[a,l,p,a,c,a]	а
[c,h,i,c,k,e,n]	C

```
f(A,B):-mergesort(A,C),f1(C,B).
f1(A,B):-head(A,B),tail(A,C),head(C,B).
f1(A,B):-tail(A,C),f1(C,B).
```

input	output
My name is John.	John
My name is Bill.	Bill
My name is Josh.	Josh
My name is Albert.	Albert
My name is Richard.	Richard

```
f(A,B):-
    tail(A,C),
    dropLast(C,D),
    dropWhile(D,B,not_uppercase).
```

```
% learning f/2
% clauses: 1
% clauses: 2
% clauses: 3
% is better: 67
% is better: 57
% clauses: 4
% is better: 55
% clauses: 5
% is better: 53
% is better: 51
% is better: 49
% is better: 46
% clauses: 6
% is better: 41
% is better: 36
% is better: 31
f(A,B):-tail(A,C),f_1(C,B).
f_1(A,B):-f_2(A,C),dropLast(C,B).
f_2(A,B):-f_3(A,C),f_3(C,B).
f_3(A,B):-tail(A,C),f_4(C,B).
f_4(A,B):-f_5(A,C),f_5(C,B).
f_5(A,B):-tail(A,C),tail(C,B).
```

```
f(A,B):-
    tail(A,C),
    tail(C,D),
    tail(D,E),
    tail(E,F),
    tail(F,G),
    tail(G,H),
    tail(H,I),
    tail(I,J),
    tail(J,K),
    tail(K,L),
    tail(L,M),
    dropLast(M,B).
```

```
f(A,B):-
    tail(A,C),
    tail(C,D),
    tail(D,E),
    tail(E,F),
    tail(F,G),
    tail(G,H),
    tail(H,I),
    tail(I,J),
    tail(J,K),
    tail(K,L),
    tail(L,M),
    dropLast(M,B).
```

does this last

## The good

- Generalisation
- Abstraction
- Data efficient
- Readable hypotheses
- Include prior knowledge
- Reason about the learning

### The bad

- Tricky on messy problems
- Tricky on big problems
- Need to know what you are doing

- S. Tourret and A. Cropper. SLD-resolution reduction of second-order horn fragments.. JELIA 2019.
- Andrew Cropper, Stephen H. Muggleton: Learning efficient logic programs.
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- Andrew Cropper, Stephen H. Muggleton: Learning Efficient Logical Robot Strategies Involving Composable Objects. IJCAI 2015.
- Stephen H. Muggleton, Dianhuan Lin, Alireza Tamaddoni-Nezhad: Metainterpretive learning of higher-order dyadic datalog: predicate invention revisited.
   Machine Learning 2015.

https://github.com/metagol/metagol