# Andrew Lee

🕈 Davis, CA, 95616 🔀 awclee@ucdavis.edu 🌐 andrewcwlee.github.jo 🛅 andrewcwlee

### **Education**

University of California, Davis

May 2023 - Present

Ph.D. in Computer Science

• Advisor: Iman Soltani, Ph.D.

Sep 2021 - May 2023

University of California, Davis

Davis, CA

Davis, CA

Hanyang University

Feb 2020

Bachelor of Science in Mechanical Engineering

Master of Science in Computer Science (changed degree objective to Ph.D.)

Seoul, South Korea

• Undergraduate Thesis: Compact Motor-Driven Walk-Support Device for Reducing Muscle Load

• Advisor: Sukkee Um, Ph.D.

## **Publications**

± indicates equal contribution.

[2] Ian Chuang<sup>‡</sup>, Andrew Lee<sup>‡</sup>, Dechen Gao, Iman Soltani. Active Vision Might Be All You Need: Exploring Active Vision in **Bimanual Robotic Manipulation**. arXiv preprint. 2024.

[1] Andrew Lee, Ian Chuang, Ling-Yuan Chen, Iman Soltani. InterACT: Inter-dependency Aware Action Chunking with Hierarchical Attention Transformers for Bimanual Manipulation. Conference on Robot Learning (CoRL). 2024.

## **Experience**

#### Laboratory for AI, Robotics and Automation (LARA)

Iun 2022 – Present

Graduate Student Researcher

Davis, CA

- Led multiple robotics research projects utilizing the ALOHA 2 bimanual manipulation setup.
- Contributed to several Caltrans-funded projects, including the development of an ADA ramp detection and measurement system and an Infrared Advanced Driver Assistance System (IR-ADAS) for enhanced safety in low-visibility conditions.

# **Projects**

#### ADA-Ramp

**Caltrans** 

- Developed and implemented a comprehensive ramp detection and measurement pipeline, converting large-scale raw point cloud data into accurate bounding boxes, slope calculations, and width measurements.
- Utilized Faster R-CNN for precise ADA ramp detection within the pipeline.

#### **IR-ADAS**

Caltrans

- Developed an Infrared Advanced Driver Assistance System (ADAS) to enhance safety and operational efficiency for emergency tow trucks and snowplows in low-visibility environments.
- Implemented the system on Jetson Nano Orin using TensorRT and YOLOv7, enabling real-time obstacle detection and hazard avoidance for improved situational awareness.

### Awards and Honors

2024 Computer Science Graduate Group (GGCS) Summer Ph.D. Fellowship

May 2024