Week 15: Primer on probability, likelihood, & Bayesian methods

ANTH 674: Research Design & Analysis in Anthropology
Professor Andrew Du

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Office Hours: Thursdays, 9:00am–12:00pm In person: GSB 312

Virtual: https://tinyurl.com/F22ANTH674

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Statistics vignette

- How often should 40-year-olds have a mammogram to screen for breast cancer?
- In 2009, US gov't advised 40-year-olds <u>NOT</u> to have annual mammograms (caused an uproar)
- WHY???

https://www.hopkinsmedicine.org/news/media/releases/despite_new_recommer dations_women_in_40s_continue_to_get_routine_mammograms_at_same_rate

Announcements

- · Lecture will span Monday & Wednesday
- · Leftover time on Wed. will be for the tutorial
- No homework this week
- Class presentations on **Dec. 5**th
 - Afterwards, will do course surveys (bring laptop)
- No lab on Dec. 7th
- Final paper due on **Dec. 12**th at 10pm

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Some relevant numbers

- Mammograms catch breast cancer in 40-year-olds 80% of the time (true positive rate) (National Cancer Institute)
- False positive rate is 10% (New England Journal of Medicine)

What's the probability an asymptomatic person w/ no history of breast cancer has it, given an abnormal mammogram?

QUITE low!

- The answer is 3%
- This is because the background rate of breast cancer is very rare: 0.4% (Cancer, Journal of the American Medical Association)

https://www.komen.org/breast-cancer/screening/when-to-screen/average-risk-women, https://www.breastcancer.org/research-news/screening-at-40-instead-of-50-saves-lives

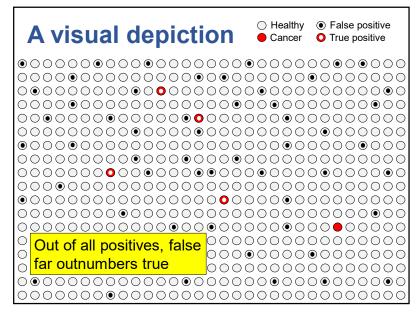
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Or one can use Bayes' theorem

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$$P(C|+) = \frac{P(+|C)P(C)}{P(+)}$$

- P(+|C) = true positive rate = 0.8
- P(C) = background cancer rate = 0.004
- P(+) = positive mammogram rate = (true positives + false positives) / everyone = 0.1

•
$$P(C|+) = \frac{0.8 \times 0.004}{0.1} = 0.03$$



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Lecture outline

- Probability theory
 - · Fundamentals of probability
 - Probability distributions
- Likelihood
 - Fundamentals of likelihood & maximum likelihood estimation
 - Hypothesis testing & model selection
- Bayesian
 - Subjective probability
 - Prior information & calculating the posterior

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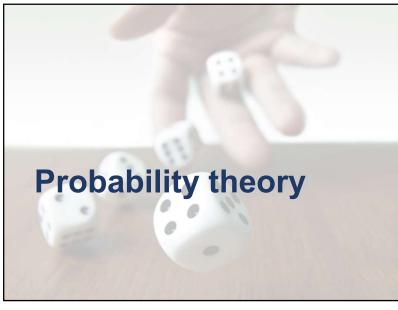
Foundations of model building

- I covered a <u>LOT</u> of methods in this course, so you can pick the best one for your question
- Even better is constructing <u>your own</u> method or model, <u>perfectly</u> suited for your question
- The topics covered in this lecture are the foundation for building your own models



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What is probability?

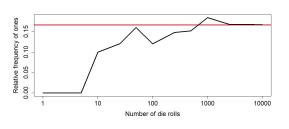
- How likely an outcome is
 - E.g., What is the probability a coin flip is heads?
- Can never predict outcome w/ 100% certainty because of variation in process of interest
- Probability lies at the foundation of all statistics



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The frequentist perspective

- *P* = # outcomes / # trials (<u>range</u>: 0–1)
- Specifically, the relative frequency of some outcome as # trials → infinity
- E.g., how would you infer probability of rolling a 1?

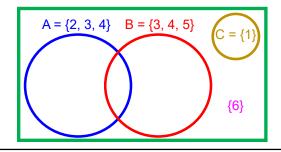




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Probability definitions

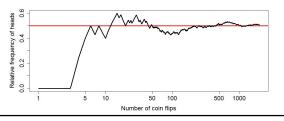
- Sample space: set of all possible outcomes
- **Event**: any subset of the sample space
 - E.g., P(A) = probability of event A happening





The frequentist perspective

- <u>SUPER</u> empirical! Requires that a trial can be repeated many, many times (at least in principle)
- Infinity trials not feasible, so this is considered theoretically or need representative sample
 - E.g., statistician John Kerrich flipped coin 2,000 times while imprisoned by Nazis in WW2





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First axiom of probability

- The sum of all probabilities of outcomes within sample space = 1.0
 - 1. Events must be **mutually exclusive**: no elements in common, e.g., {1, 2} and {3, 4}
 - 2. Events must be **exhaustive**: covers all possible outcomes, e.g., {1, 2, 3} and {4, 5, 6}



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First axiom of probability





Outcomes are <u>mutually exclusive</u> (no overlap)
 <u>exhaustive</u> (together, comprise entire sample space: {1, 2, 3, 4, 5, 6})

- Can use 1st axiom to calculate probability of the <u>complement</u> of an event, i.e., the probability an event <u>doesn't</u> happen in sample space
- Complements are represented with a ' or c
 - $P(A') = P(A^c) = 1 P(A)$
 - E.g., $P(\{1\}^c) = 1 P(\{1\}) = 1 1/6 = 5/6$
- Works because complements are always mutually exclusive and exhaustive

P(A) + P(B) + P() = 1/2 + 1/3 + 1/6 = 1.0 $A = \{1, 2, 3\}$ P(A) = 1/2 $B = \{4, 5\}$ P(B) = 1/3

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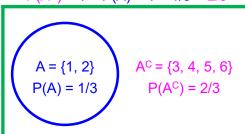
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Complements



 By definition, are <u>mutually exclusive</u> (no overlap) & <u>exhaustive</u> (together, comprise entire sample space)

$$P(A^{C}) = 1 - P(A) = 1 - 1/3 = 2/3$$



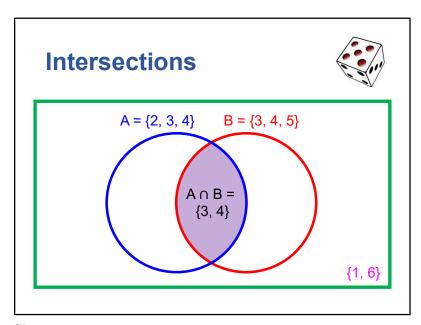
Intersections

- The common outcomes between two (or more) events
- \bullet Intersections are represented with \cap
- "AND" statement in logic; & in R
- E.g., $\{1, 2, 3\} \cap \{3, 4, 5\} = \{3\}$
- $P(\{1, 2, 3\} \cap \{3, 4, 5\}) = P(\{3\}) = 1/6$



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Unions

- The union of two (or more) events is the set of all outcomes that are in either or both events
- Unions are represented with a ∪
- "OR" statement in logic; | in R
- E.g., $\{1, 2, 3\} \cup \{3, 4, 5\} = \{1, 2, 3, 4, 5\}$
- $P(\{1, 2, 3\} \cup \{3, 4, 5\}) = P(\{1, 2, 3, 4, 5\}) = 5/6$

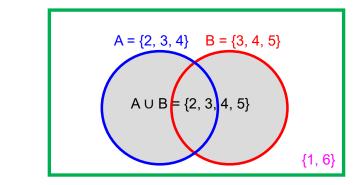


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Unions





Conditional probability

- Probability of an event, given prior occurrence of another event
- P(A | B) is probability that A happens, given that B has happened
 - "Probability of A given B" or "probability of A conditional on B"
- E.g., probability of rolling a one, given that you rolled an odd number

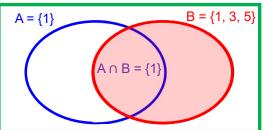


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Conditional probability



- P(A | B), e.g., P({1} | {1, 3, 5})
- B becomes new sample space
- W/in B, calculate probability of A also happening



B = {1, 3, 5}

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

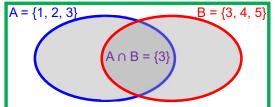
$$P(\{1\}|\{1,3,5\}) = \frac{1/6}{1/2}$$

$$= 1/3$$

The addition rule



- Associated with unions, e.g., {1, 2, 3} ∪ {3, 4, 5}
- $P(A \cup B) = P(A) + P(B) P(A \cap B)$
- $P(A \cup B) = P(A) + P(B)$ **IF** A and B are mutually exclusive, i.e., $P(A \cap B) = 0$



 $P(A \cup B) = \frac{1}{2} + \frac{1}{2} - \frac{1}{6} = \frac{5}{6}$

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The multiplication rule

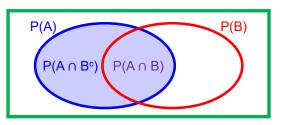
· Associated with intersections

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- $P(A \cap B) = P(A) \times P(B|A) = P(B) \times P(A|B)$
 - Just a rearrangement of conditional probability formula
- If A happening does not affect P(B) and vice versa, A and B are independent events
 - P(B|A) = P(B) and P(A|B) = P(A)
- **<u>IF</u>** A & B are independ., $P(A \cap B) = P(A) \times P(B)$
 - E.g., if relative frequency of dominant allele in population is p, relative frequency of homozygous dominant genotype is p^2

Law of total probability

- Transforms conditional and/or intersection probabilities into <u>marginal probability</u> AKA <u>unconditional probability</u> (e.g., P(A), P(B))
- $P(A) = P(A \cap B) + P(A \cap B^C)$
- Also $P(A) = P(B) \times P(A \mid B) + P(B^{C}) \times P(A \mid B^{C})$



Questions?



E.g., Type I error



- What is the probability of getting <u>at least</u> one false positive, given 100 tests and $\alpha = 0.05$?
- This is the complement of getting <u>no</u> false positives for all 100 tests
 - 1. P(false pos.) = 0.05
 - 2. P(false pos.°) = 1 0.05 = 0.95
 - 3. $[P(false pos.^c)]^{100} = 0.95^{100} \approx 0.006$
 - · Assumes tests are independent
 - 4. $1 [P(false pos.^c)]^{100} \approx 1 0.006 \approx 0.994$
 - 5. $1-(1-\alpha)^n$

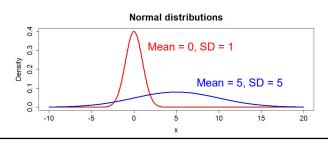
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Probability distributions

What is a probability distribution?

- A function that describes how likely certain values are in a <u>random variable</u>, i.e., where outcomes are not 100% predictable
- Shape is described by **parameters**



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Two types of distributions

1. Discrete probability distributions

- Describes random variables whose outcomes are finite or countable (e.g., integers)
- AKA probability <u>mass</u> function (PMF)
- E.g., binomial distribution, Poisson distribution

2. Continuous probability distributions

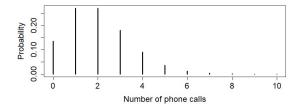
- Describes random variables whose outcomes can take on any value within a smooth interval
- AKA probability density function (PDF)
- E.g., normal distribution, lognormal distribution

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*parameters in red

Discrete: Poisson PMF

- Describes probability of getting X occurrences of an event in a fixed area or time period, given an average # occurrences in area/time (λ)
- E.g., probability of getting *X* phone calls in an hour, given average calls/hour is 2

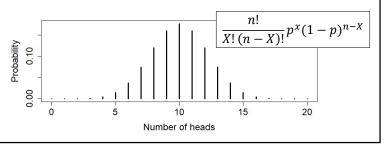


*parameters in red

*parameters in red

Discrete: binomial PMF

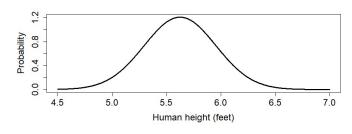
- Describes probability of getting X successes in n trials, given a probability of success, p
- E.g., probability of flipping *X* heads in 20 flips, given probability of heads is 0.5



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Continuous: normal PDF

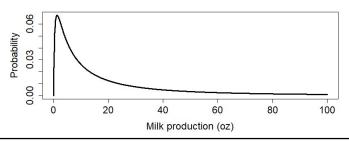
- Describes how likely a value of X is, given the mean (μ) and SD (σ)
- X is outcome of additive processes
- E.g., human heights in a population



*parameters in red

Continuous: Iognormal PDF

- Describes how likely a value of X is, given the mean (μ) and SD (σ) in log space
- *X* is product of multiplicative processes
- E.g., milk production by cows



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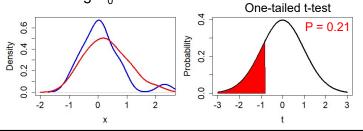
Simplified modeling recipe

- 1. Figure out the P(A) that addresses your research question & how to derive P(A) from other probabilities, e.g., P(A | B), P(B)
- 2. Figure out how to represent each probability with a distribution
- 3. Carry out the math to get your probability model



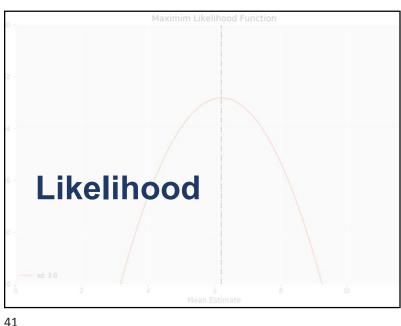
Cumulative distribution function (CDF)

- Calculates probability that *X* is ≤ some value for **any** distribution
- E.g., P-values: probability of getting null statistic more extreme than observed statistic, assuming H₀ is true



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Fundamentals of likelihood & maximum likelihood estimation

What is likelihood?

- A principled **frequentist** framework for statistical inference and modeling
 - 1. Parameter estimation
 - 2. Hypothesis testing
 - 3. Model selection
- · A lot of methods can be derived, and thus unified, with likelihood (e.g., t-tests, OLS)
- First developed by R.A. Fisher



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Defining likelihood

- · Traditional frequentist tests calculate P(Data | Model), e.g., P-value
- Likelihood inverts the conditional probability to get L(Model | Data)
- E.g., probability asks what is the probability of getting 4 heads out of 10 coin flips (data), given that p = 0.5 (assumed model parameter)
- Likelihood asks how likely is p = 0.5 (model parameter), given that you get 4 heads out of 10 coin flips (data)

Another example



Weather (parameter)

	<u></u>					
Э)		Cold	Warm			
Attire (data)	Jacket	0.8	0.1			
	T-shirt	0.2	0.9			
	Total	1.0	1.0			

• P(attire | cold)

- L(weather | jacket)
- Likelihoods don't have to sum to one (not true probabilities)
- P(jacket | cold) = L(cold | jacket)
- Probability is a statement about observed data
- Likelihood is a statement about the parameter(s)

From Wang (2010)

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E.g., lion stalking success

- In Ngorongoro Crater (Tanzania), Elliott et al. (1977) found that lions had 34 out 157 successful stalks of wildebeest and zebra
- Of the entire (partially sampled) population of lions, what is the rate of successful stalks at Ngorongoro?



Maximum likelihood estimate (MLE)

- Likelihood provides a framework for estimating unknown parameter(s) in a system
- MLE is the parameter value(s) that makes the observed data most probable (i.e., has the highest likelihood)
 - E.g., on previous slide, MLE is "cold"
 - Given the person wore a jacket, "cold" has a higher likelihood (0.8) than "warm" (0.1)

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MLE of stalking success rate

X: number of successful stalks (34)

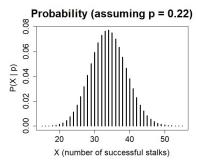
n: number of total stalks (157)

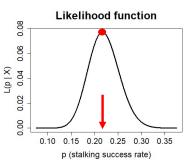
p: stalking success rate

- Assuming stalks are independent, can model rate (p) with binomial distribution
- A good naïve guess of *p* is 34 / 157 ≈ 0.22 (cf. frequentist definition of probability)

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MLE of stalking success rate





- <u>Likelihood function</u> likelihoods values as fxn. of parameter values (numerically equal to $P(X \mid p)$)
- MLE = value of p that gives the highest likelihood

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Getting MLE of p

1.
$$L(p|X) = \frac{n!}{X!(n-X)!}p^X(1-p)^{n-X}$$
 (binomial dist.)

2.
$$\log L(P|X) = \log \left(\frac{n!}{X!(n-X)!}\right) + X\log(p) + (n-X)\log(1-p)$$

3.
$$\frac{d}{dp} \log L(p) = 0 + \frac{X}{p} - \frac{n-X}{1-p}$$

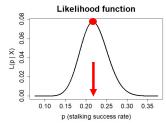
4.
$$\frac{X}{\hat{p}} - \frac{n-X}{1-\hat{p}} = 0$$
 (the hat indicates an estimated parameter)

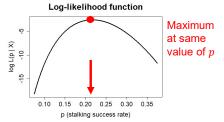
$$5. \ \widehat{p} = \frac{X}{n}$$

6.
$$\operatorname{se}(\hat{p}) = \sqrt{\frac{\hat{p}(1-\hat{p})}{n}}$$
 (derived using log-likelihood function)

MLE of stalking success rate

- How to find MLE of p (tip of bell curve)?
- Take derivative of function, set it to zero (maxima of function), and solve for p
- Easier to do this with **log-likelihood** function





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MLE of stalking success rate

• So
$$\hat{p} = \frac{X}{n} = \frac{34}{157} \approx 0.22$$

- This matches our naïve estimate, but we derived it formally
- MLE has good statistical properties: as $n \to \infty$,
 - · Estimate is unbiased
 - Has the smallest possible variance among all unbiased estimators
 - Sampling distribution is normal

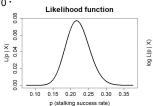
Questions?

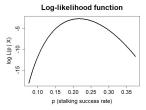


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Hypothesis testing

- $L(M_0 \mid X) = 7.7e-6$; $log L(M_0 \mid X) = -11.8$
- $L(M_1 \mid X) = 0.08$; $log L(M_1 \mid X) = -2.6$
- More complex models (more free parameters) always fit the data better
- How to know if M_1 fits data significantly better than M_0 ?





Hypothesis testing



- Let's say the literature says lion stalking success rates should be 0.1 (H₀ → M₀)
- We can test if the underlying parameter generating our observed data (i.e., MLE; M₁) is significantly different from 0.1
- <u>Mo</u>: P(success. stalk) = p = 0.1
 zero free parameters
- $\underline{\mathbf{M}}_{\underline{\mathbf{1}}}$: p is free to vary (i.e., is estimated)
 - one free parameter
- Which model fits the data better?

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Likelihood ratio tests (LRT)

 If models are nested (complex model has ≥1 extra parameter), can use LRT to test if more complex model (M₁) is sig. better than simpler one (M₀)

$$LR = -2(\log L[M_0] - \log L[M_1])$$

- \bullet If M_0 is supported by the data, the two likelihoods should not differ by more than sampling error
- LR follows χ^2 dist. w/ degrees of freedom = difference in # free parameters between models
- For our example, LR = -2(-11.8 [-2.6]) = 18.4

Model selection



 Formalized way of competing hypotheses (models) against each other on equal footing

 The Akaike Information Criterion (AIC) balances goodness of fit (logL) and model complexity (K = # free parameters)

$$AIC = -2\log L + 2K$$

 AIC measures amount of information lost in approximating reality w/ model (lower AIC is better)

• Can transform into weights (sum to one across models, w/ larger weights → more support)

Our lion stalking example

Model	Descrip.	logL	K	AIC*	AIC weight
M_0	p = 0.1	-11.8	0	23.55	2.7e-4
M ₁	p free to vary	-2.6	1	7.13	0.9997

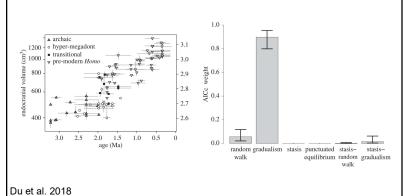
*General rule: >2 difference in AIC → good support

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Another example



How did hominin brain size increase over time?



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Questions?





Bayesian paradigm

- There are two main differences compared to the frequentist paradigm:
- 1. A different definition of probability (i.e., subjective probability)
- 2. The incorporation of **prior information** in models

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Probability: a test

- Are you a frequentist or Bayesian?
- I flip a coin and then cover it with my hand





• What is the probability that the coin is heads?

Subjective probability





- Recall that the frequentist definition of probability is the relative frequency of some outcome as # trials → infinity
- Problematic for unique events
 - E.g., what is the probability that Vermont is larger than New Hampshire?
- Subjective probability quantifies our <u>uncertainty</u> or <u>degree of belief</u> in some event, whether it is repeatable or not

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Treatment of parameters

- The <u>frequentist</u> paradigm treats parameters as fixed quantities
 - E.g., the average height of <u>all</u> humans on Earth
- Randomness is introduced by the sampling process (e.g., each sample of data gives a different mean estimate of height)
- The <u>Bayesian</u> paradigm treats parameters themselves as <u>random b/c of our uncertainty</u> <u>about them</u>

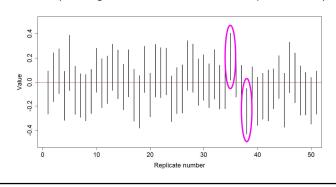
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E.g., 95% Cls

- <u>Frequentist</u>: fixed parameter is either inside CI or not (in long run, 5% of CIs exclude parameter)
- <u>Bayesian</u>: treats parameter as random due to uncertainty, so 95% CI interpreted as a 95% probability parameter is inside CI
 - A Bayesian confidence interval is called a **credible interval**

E.g., 95% Cls

• <u>Frequentist</u>: fixed parameter is either inside CI or not (in long run, 5% of CIs exclude parameter)



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Prior information

- The main debate: should one incorporate prior knowledge about quantity of interest, external to the dataset?
- E.g., I carry out a presidential approval rating poll in an area and got 41%, even though other organizations got around 55%
- Should I adjust my results upwards (e.g., average 41% and 55%)?
- Unscientific and unethical? Or smart to "stand on the shoulder of giants"?

DID THE SUN JUST EXPLODE?

(IT'S NIGHT, SO WE'RE NOT SURE.)

THIS NEUTRINO DETECTOR MEASURES

VHEIHER THE SUN HAS GONE NOVA.

(THEN, IT'ROUS TWO DICE. IF THEY
BOTH COME UP SIX, IT LIES TO US.
OTHERVISE, IT TELLS THE TRUIH.

LET'S TRY.
DETECTOR! HAS THE
SUN GONE NOVA?

REAL

YES.

BET YOU \$50
IT HASNT.

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Prior information

- It can be argued that **every** researcher incorporates their own biases into their studies
- E.g., researcher finds implausible results and runs experiment for longer
- The Bayesian paradigm enables researchers to incorporate prior information in their models in a principled, formalized manner

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How to incorporate prior information?

A P

• Bayes' theorem (or Bayes' rule):

Thomas Bayes

Prior probability: quantifies prior information

<u>Likelihood:</u> summarizes the data

 $P(H|D) = \frac{P(H)P(D|H)}{P(D)}$

Posterior probability: probability of hypothesis/model given the data

Scaling factor: Makes area under P(H|D) distribution sum to one

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Example: lost wallets

 What is the probability (p) that police officers will return lost wallets to owners but steal some money?





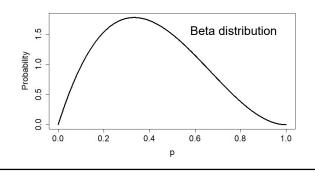
From Wang (2010)

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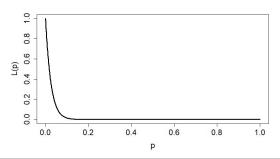
1. Formulate the prior, P(H)

- What do **YOU** think the probability is?
- Quantify this with a probability distribution



2. Collect data & formulate likelihood function, P(D | H)

- In experiment run by *Primetime*, 40 out of 40 officers returned wallets w/ <u>NO</u> money missing
- Create likelihood function using binomial dist.



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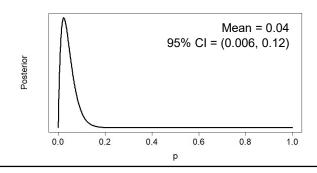
3. Update prior w/ data, P(H | D)

- Bayes' theorem: $P(H|D) = \frac{P(H)P(D|H)}{P(D)}$
- Oftentimes, we ignore the scaling factor, P(D)
 - Probability distribution looks identical; only scale of y-axis changes
 - OK b/c only care about which values of p are more probable relative to each other
- So $P(H|D) \propto P(H)P(D|H)$
 - ullet Prior can be thought of as weighting certain values of p in the likelihood
 - If prior is uninformative (all values of p likely), just doing a likelihood analysis

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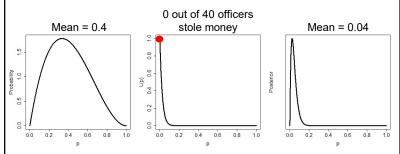
3. Update prior w/ data, P(H | D)

- $P(H|D) \propto P(H)P(D|H)$
- Multiply prior by the likelihood



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Prior, likelihood, posterior

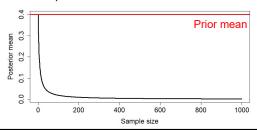


- **NB**: w/ zero officers stealing money, MLE of p is zero
- Do we actually expect <u>NO</u> officers to steal money?

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Influence of dataset size

- Assuming we collect more data and still no officers steal money
- At small n, prior dominates
- At larger n, MLE dominates ("data speak for themselves")



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Summary

- Probability theory quantifies how likely certain events are and how likely certain values in data are
- Likelihood is a principled framework for inferring parameters, testing hypotheses, and comparing models
- Bayesian methods offer a formalized framework for combining prior information w/ the likelihood

