Image segmentation using CRF

Santosh K, Srikanth M

Overview

- Given an image, segment it into objects and label them.
- We follow the approach described in [2].









Figure 1: Sample input and segmented output images [2].

Approach

- Pre-segment the image into patches at different scales.
- 2 Extract colour, texture, and SIFT features for each patch.
- Ompute global feature vector.
- Use SVM to predict class of each patch.
- Build a CRF model, where the patch labels are dependent on each other.
- Apply threshold on the posteriors from the CRF to obtain final segmentation.

Step 1: Pre-segmentation

- Pre-segment the image using graph cut minimization formulation [1].
- Segmentation is done at different scales (finer to coarser) by adjusting the parameters of the algorithm.

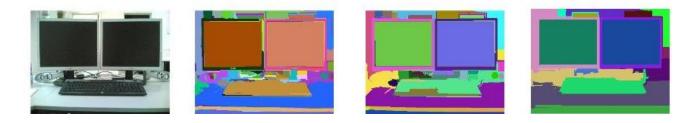


Figure 2: Example pre-segmented image on different scales.

Step 2: Feature extraction

- Colour features are extracted by applying HSV transformation and computing histogram.
 - Hue and saturation are binned to 10 x 10 2D histogram.
 - 2 Values are binned into 10-bin histogram.
 - 3 Results in 110 dimension feature vector for each patch.
- 2 Texture features using Gabor filters (we did not understand it yet).
- **3** Extracted SIFT key points and descriptors for each image and used k-means to cluster the descriptors into 1000 clusters.
 - We compute histogram over each patch, using the VQ indices of the descriptors.
 - 2 Results in a 1000 dimension feature vector for each patch.

Next steps: Building CRF

- Olass label for each patch cannot be predicted independent of other patches.
- 2 Each patch is dependent on other:
 - Spatial relation in the image.
 - Overlap between patches in each scale.
- 3 The dependency between patches is represented with the help of a tree.
- 4 Child nodes represent patch in finer level and parent node represents the patch in coarser level.

Building CRF

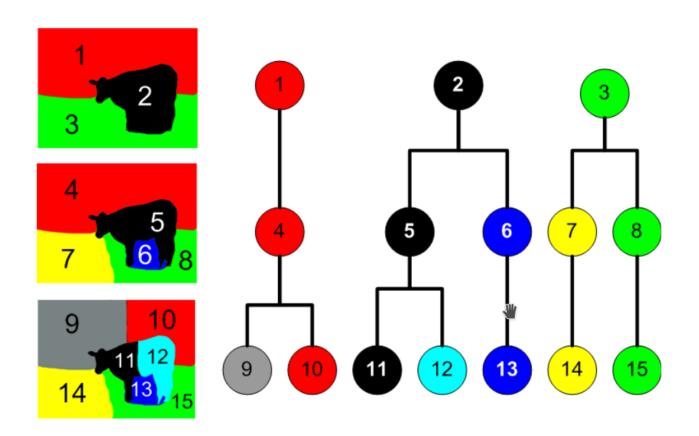


Figure 3: Example of a tree built from patches at different scales [3].

Building CRF

• If \mathbf{x} denotes the feature vector for a patch p and y_p denotes the corresponding label, then CRF for an image with P patches is represented (factorized as follows:)

$$P(\mathbf{y}, \mathbf{X}) \propto \prod_{p=1}^{P} \phi(y_p, \mathbf{x}) \prod_{q \in \pi(p)} \varphi(y_p, y_q)$$
 (1)

where $\pi(p)$ denotes the child nodes of patch p.

- The potential function ϕ represents local evidence for labelling patch p to one the object classes k, and φ represents the coupling (similarity) between patches at two different levels (parent and child from the tree).
- 3 The goal is to learn the potential functions ϕ and φ , from the training data (images and corresponding labels with boundaries).

Learning potential functions: ϕ

• $\phi(y_p, \mathbf{x})$ can be obtained from a classifier (support vector machines).

$$\phi(y_p, \mathbf{x}) \propto \phi(y_p \mid \mathbf{x}, \boldsymbol{\theta}) p(\mathbf{x} \mid \boldsymbol{\theta})$$
 (2)

where θ are the parameters of the classifier.

- 2 SVM with χ^2 kernel is observed to be good for histogram features.
- 3 Further convert the output of the classifier into probabilities using softmax function as,

$$\phi(y_p = k \mid \mathbf{x}) = \frac{\exp\{a_l \operatorname{sym}(\mathbf{x}, \mathcal{C}_k) + b_l\}}{\sum_{\forall j \in K} \exp\{a_l \operatorname{sym}(\mathbf{x}, \mathcal{C}_j) + b_l\}}$$
(3)

where l is the scale level, $l = \{1, 2, 3\}$, and b_l is the scaling parameter of the χ^2 kernel.

Learning potentials: φ

① The pairwise coupling or similarity between patches in two consecutive levels (i. e., for parent p at level l and child q at level l+1) is defined as,

$$\varphi(y_p, y_q) = \begin{pmatrix} e^{\gamma l} & e^{-\gamma l} \\ e^{-\gamma l} & e^{\gamma l} \end{pmatrix}$$
 (4)

2 Here, inference is done using junction tree algorithm (yet to understand).

References



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