

**EDUCATION**

<b>Princeton, NJ</b>	<b>Princeton University</b>	<b>June 2019</b>
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- B.S.E. in Electrical Engineering, June 2019. GPA: 3.8/4.0, Major: 3.9/4.0
- Minors in Computer Science, Robotics and Intelligent Sensing
- Relevant Coursework: Electronic Circuit Design; Integrated Circuits; Digital Logic Design; Electronic Devices; Information Security; Information Signals; Computer Architecture; Algorithms and Data Structures

**EMPLOYMENT**

<b>EE Intern - Hardware</b>	<b>Intuitive Surgical</b>	<b>Summer 2018</b>
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- Collaborated with UX, mechanical engineering, and software teams to develop project specifications
- Performed schematic capture in OrCAD CIS Capture and layout in Allegro PCB Designer
- Designed boards utilizing technologies such as wireless power transfer, magnetic sensing, and eye tracking
- Wrote and executed test protocols for various PCAs

<b>EE Intern - Firmware</b>	<b>Intuitive Surgical</b>	<b>Summer 2017</b>
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- Developed modules in Verilog to automate I<sup>2</sup>C polling and error recovery (hung bus, NACK, etc.)
- Generated comprehensive testbenches in SystemVerilog; simulated and debugged in QuestaSim
- Built modules on Xilinx FPGA, interfaced with time-of-flight sensors on PCBs
- Wrote javascript interface to hardware, tested module using both RAM and Xilinx IPIC control

<b>Research Assistant</b>	<b>Princeton University Physics Department</b>	<b>Summer 2016</b>
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- Developed tracking system to simulate light beam paths in Python
- Built silicon photomultiplier photon annihilation detector system, tested with LED pulser
- Debugged detection of cosmic rays and photon annihilations using DRS4 oscilloscope

<b>Student Grader</b>	<b>Princeton University CS Department</b>	<b>Fall 2016 – present</b>
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- Evaluated student programs and provided feedback for introductory computer science course

**TECHNICAL EXPERIENCE**

- **Drone landing platform:** Built an omni-drive robot platform equipped with PixyCams to detect a flying drone. Featured steering control algorithms so that platform would locate drone, mirror its movement from the ground, and catch it upon landing, without any communication with the drone.
- **Grounded Low Voltage System:** Starting from specification, performed schematic capture, PCB layout/routing, and assembly for several critical monitoring systems on formula car (BMS, pre-charge, etc.) Individual work as part of formula hybrid team.
- **Lockness Monster:** IoT-enabled smart bike lock designed for integration into frame. Designed prototype in CAD, 3D printed, implemented using an Electric Imp IoT kit. Controlled with web, iPhone, or Pebble app.
- **PU Computer:** Programmed, tested, and implemented a 16-bit, Turing complete microprocessor. Coded in Verilog, implemented on FPGA.

**SKILLS**

- PCA Design: schematic capture (OrCAD, Cadence Virtuoso, EAGLE), layout (Allegro, EAGLE)
- CAD: Autodesk Inventor, PTC Creo 4.0, SolidWorks CircuitWorks
- Circuitry: Digital/analog circuit design, PSPICE, oscilloscopes, SMD rework
- Programming: Java, C, C++, Python, Matlab, Verilog
- Scripting: Linux/Bash, PowerShell
- FPGA programming experience: Vivado, QuestaSim, iVerilog

**EXTRACURRICULARS**

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| • Princeton Racing Electric, Electrical Subteam                | <b>Fall 2017 - Present</b>     |
| • 3D Printing Club   | <b>Fall 2017 - Present</b>     |
| • Princeton Autonomous Vehicle Engineering, Mechanical Subteam | <b>Fall 2015 – Spring 2017</b> |