



Smart Parking Lot

Winter Quarter Review

Project Website: andrewhlu.com/spl

Problem

Drivers spend too much time in parking lots trying to find an open space. Many parking lots only have per-floor capacity indicators, and existing solutions are prohibitively expensive.

What if we could utilize low-cost sensors and a companion application to navigate drivers to empty parking spots faster, at a low cost to facility owners?

Smart Parking Lot Overview

The goal is to design a smart parking lot that will direct drivers to the nearest open parking space on campus in an efficient, accurate and clean manner.

We accomplish this using:

- Small, inexpensive parking lot sensors with long-distance and low-power transmission
- Modern, open-source, and cloud-based software solutions
- Easy-to-use mobile interfaces

Roles



Andrew Lu
Gateway Application
Web Application Frontend
and Backend



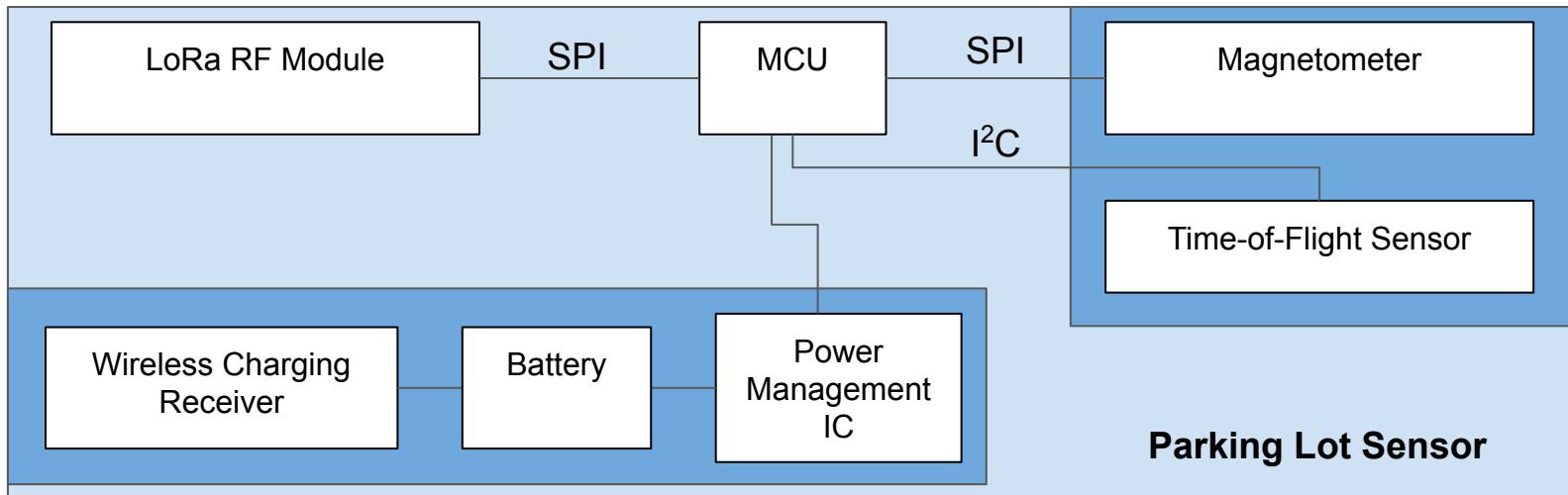
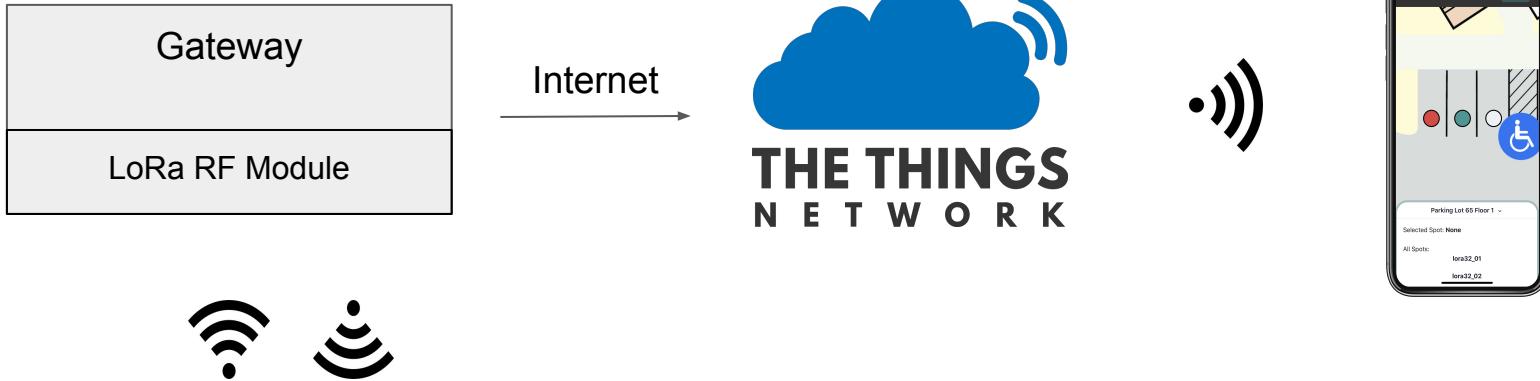
Luyao Han
Sensor Firmware
PCB Design
Wireless Charging



Finn Linderman
Wireless
Communication
Power Management



Jun Cho
LoRa Communication
The Things Network
Integration



Hardware Progress

Hardware Design

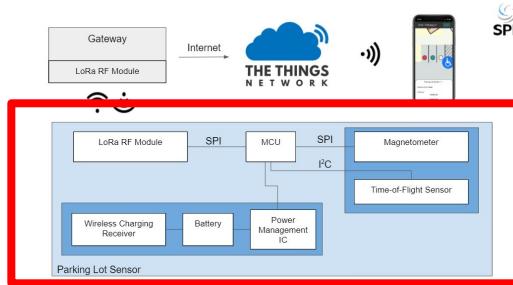
- PCB layout
- Sensors
- 3D-Printed Case

Function Verification

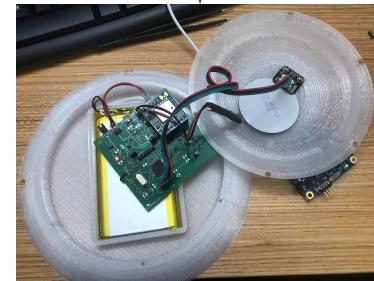
- Time-of-Flight (Lidar) Sensor
- Magnetometer
- Wireless Charging

Challenges

- LoRa Communication



Idea

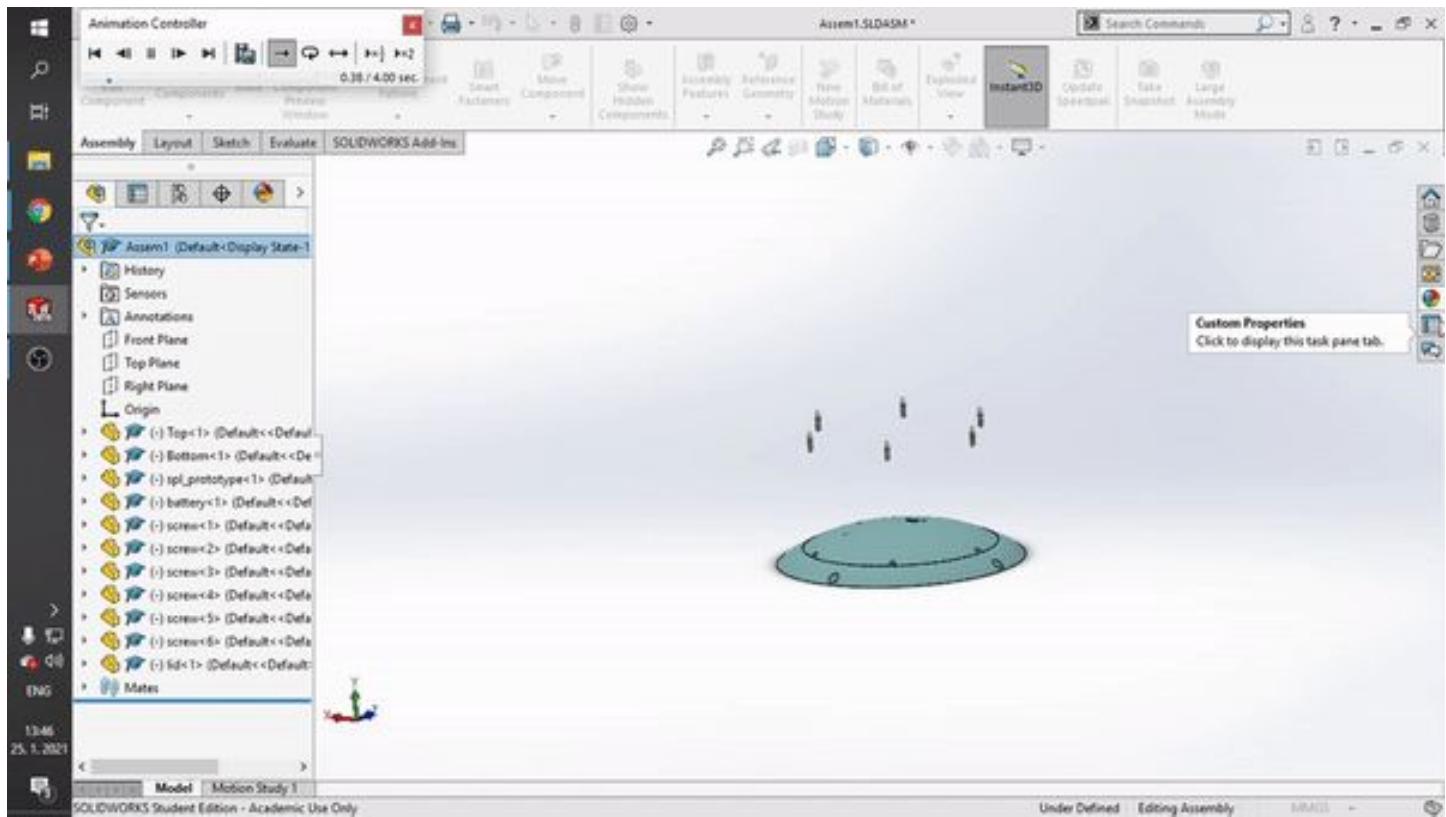


Hardware Implementation

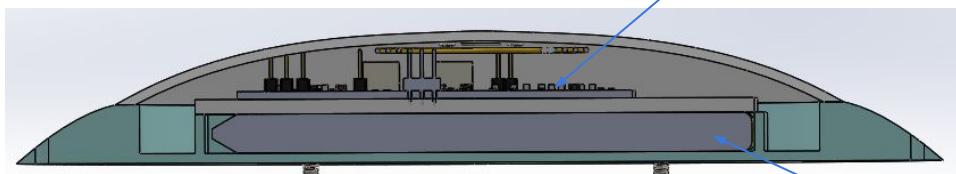


Application Scene Testing

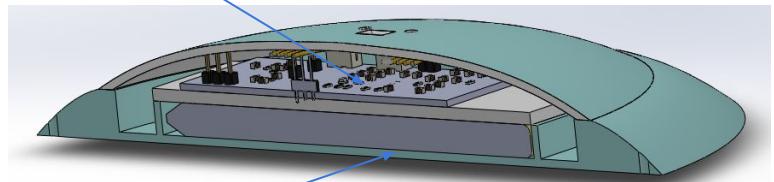
Hardware Explosion View



Sensor Unit Assembly



Section View



Section View

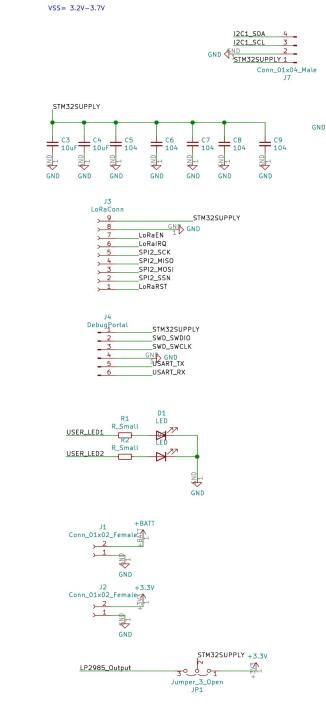


Physical Assembly

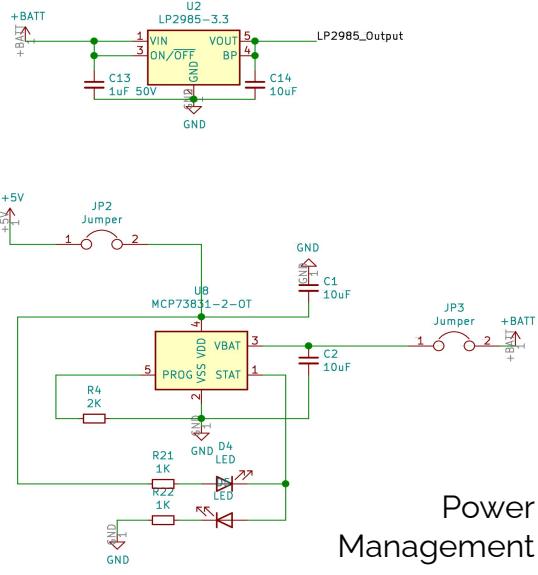


Application Scene

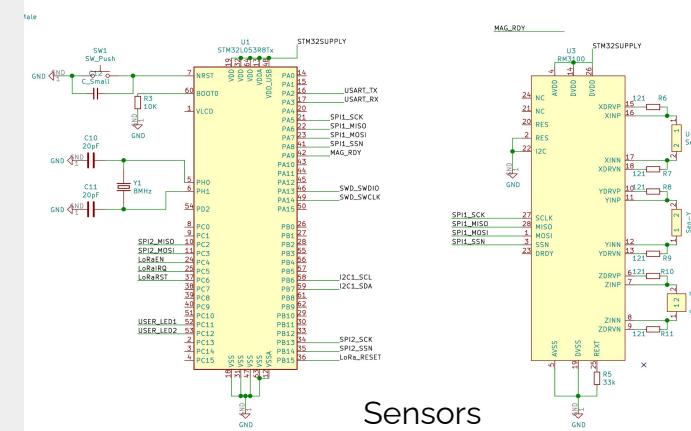
Schematics



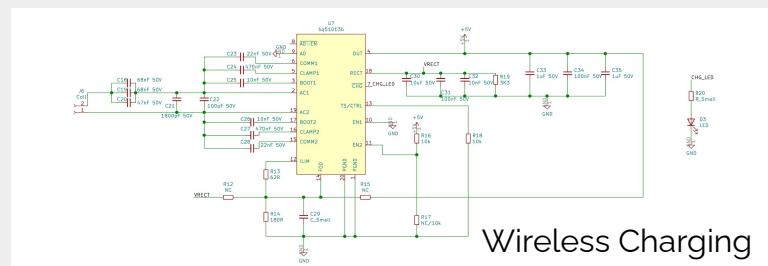
Connectors/Filtering



Power Management



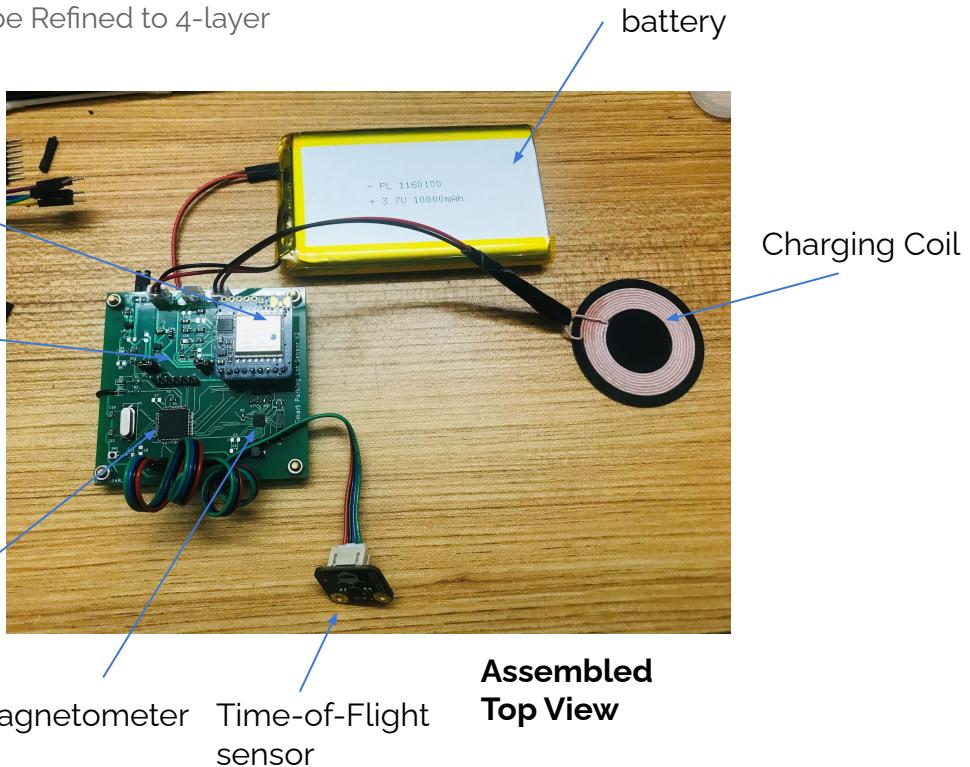
Sensors



Wireless Charging

PCB Assembly

- Designed with Kicad
- 60mm x 60 mm
- Estimated Power Consumption: 22 mA peak
- Will be Refined to 4-layer



Wireless Charging

Charging

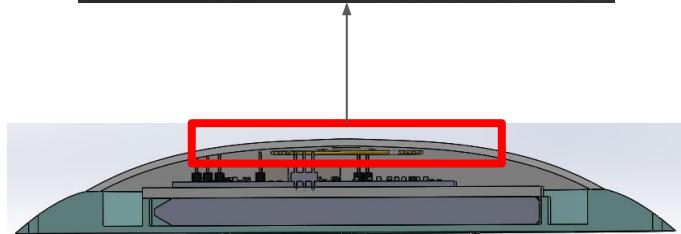
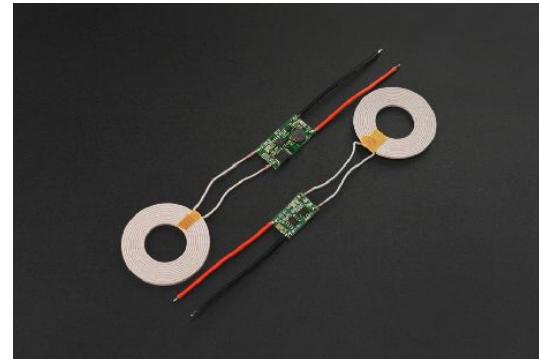
- Domed shaped unit attached to top of sensor unit

Estimates

- 5 years ~= 45000 hours
- Peak Power Consumption - 22 mA
- Charging - 4 hour

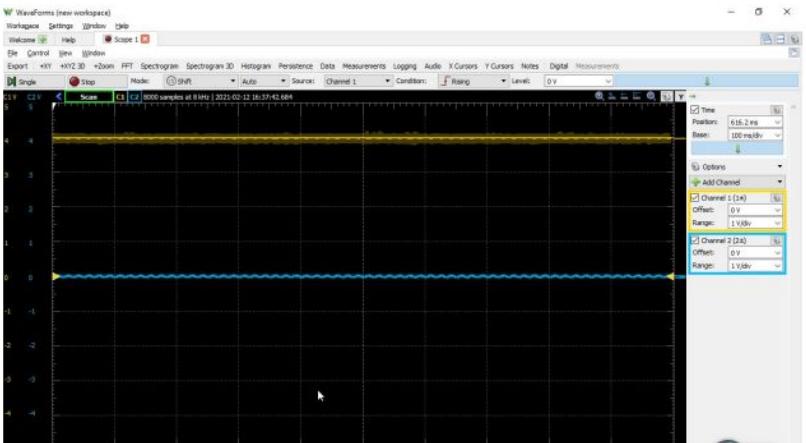
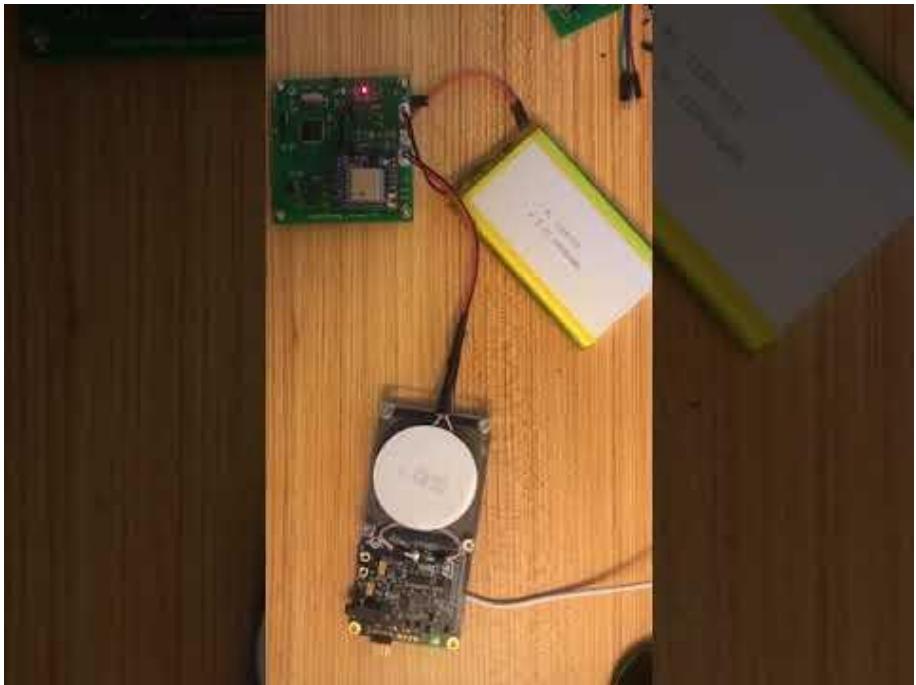
Advantages

- Sensors still operable when charging
- Maintenance WPC v1.2



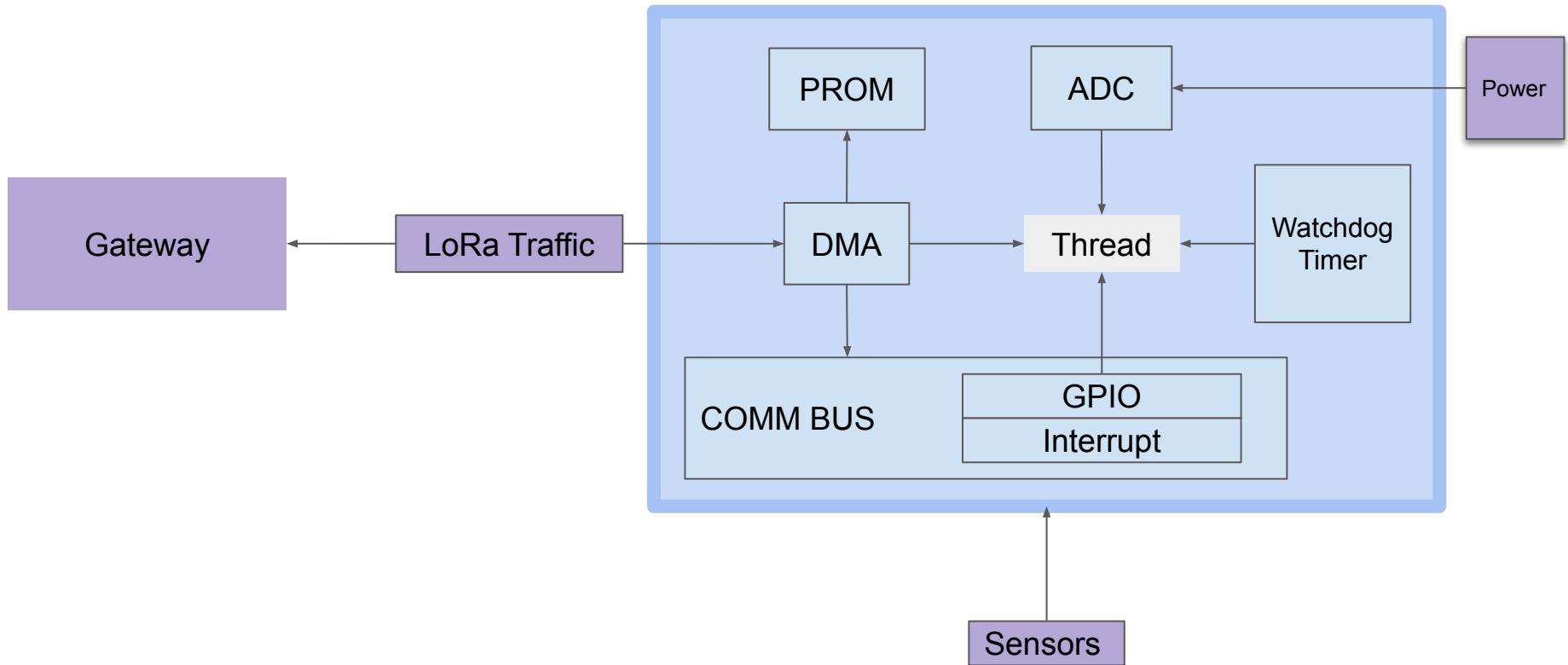
Section View Charging Coil

Wireless Charging Demo



Charging Voltage: 4.2V

Firmware Design Block Diagram



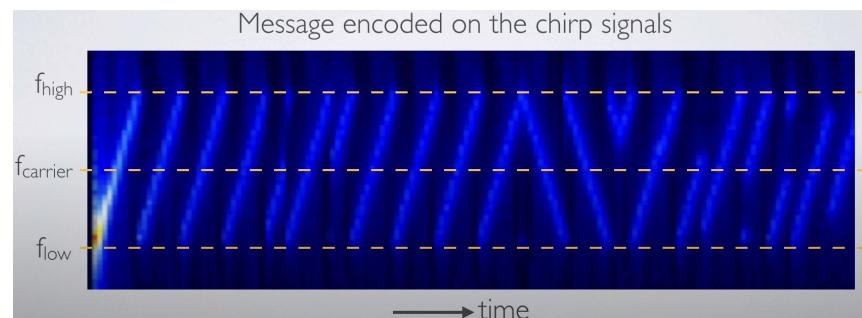
LoRa/LoRaWAN

Long Range Wide Area Network

- Long range (2 km up to several hundred km)
- Trades off having low bandwidth for long range and low power consumption
- Chirp Spread Spectrum Modulation
 - Similar to Frequency Shift Keying

LoRa vs. LoRaWAN

- LoRa = physical layer
- LoRaWAN = network stack
- LoRa can be used on its own as a communication protocol



LoRaWAN Testing

STM32 I-NUCLEO-LRWAN1

- 860 MHz to 1020 MHz frequency range
- 14 dBm to 20 dBm transmission power
- -137 dBm receiver sensitivity
- 2.0V to 3.6V voltage range



Heltec ESP32 LoRa 32 (V2)

- 868 MHz to 915 MHz frequency range
- 15.5 dBm to 19.5 dBm transmission power
- -139 dBm receiver sensitivity
- 3.3V to 7V voltage range



Dev Boards for Testing

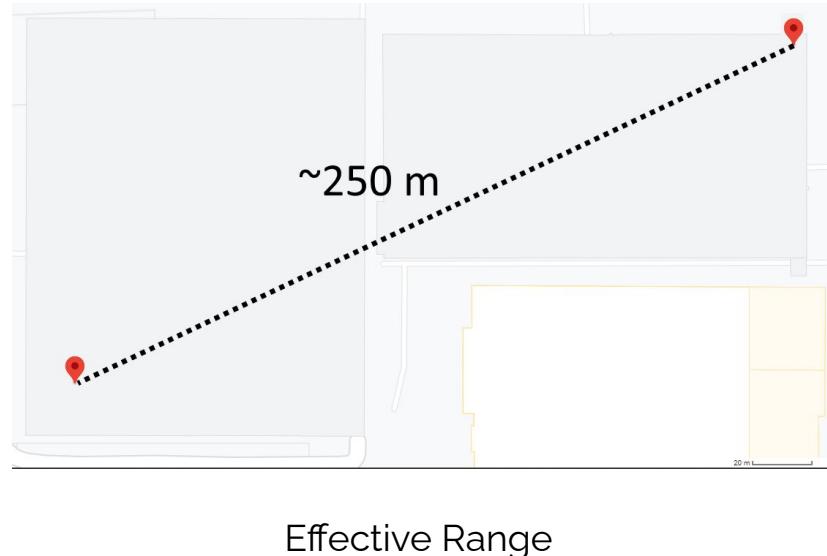
LoRaWAN Testing

Range Testing

- Tested connectivity across two interconnected parking structures
- Lost connection at about 250m (~820 ft) lateral distance through 5 floors

Multiple device Testing

- Simultaneous message sending through same channel
- Different channel receiver bandwidth testing



Gateway

The Things Industries TTIG-915 LoRaWAN Gateway

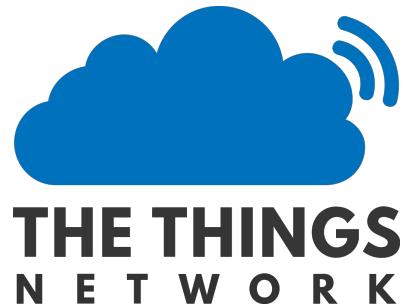
- 8-channel Omnidirectional Gateway
- +27 dBm transmit power
- Supports US 915 MHz Frequency Band
- Internet Connectivity using WiFi
- Officially Supported by *The Things Network*

Tested with LoRa development modules and
Raspberry Pi



The Things Network

- A free and open-source service for hosting LoRaWAN devices and gateways
- Scalable, secure, used by over 136,000 developers
- Provides API endpoints for retrieving device data packets using JSON
- Historical data from *The Things Network* will also be cached in a MongoDB database

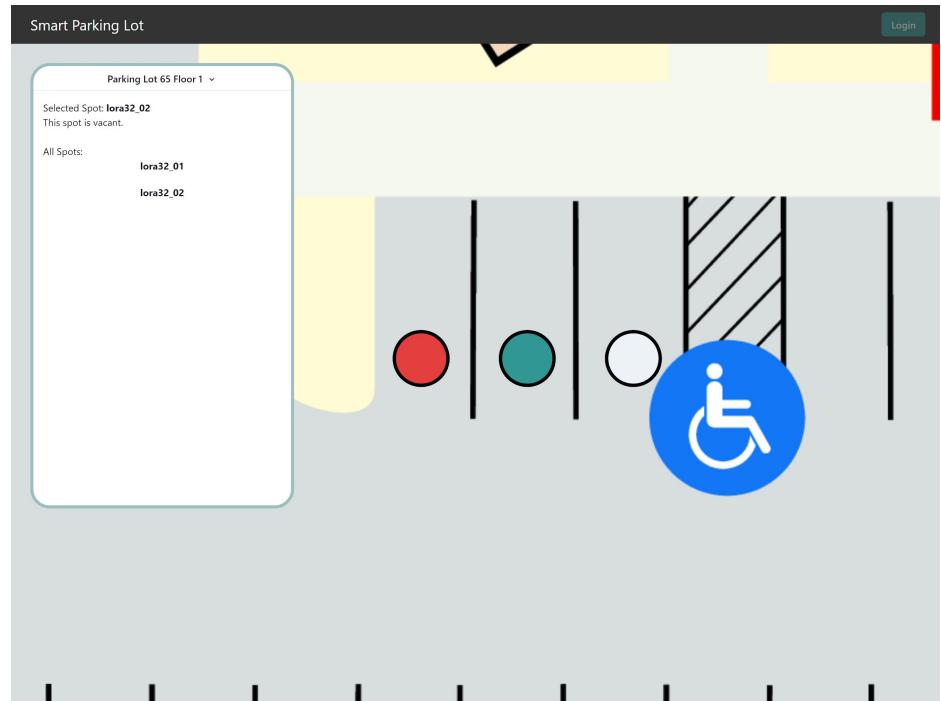
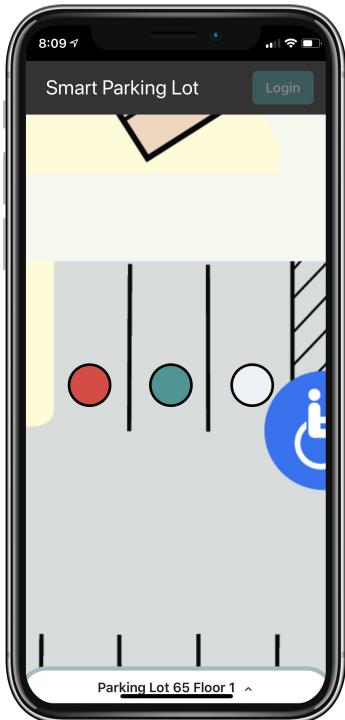


UI / Software Frameworks

- Starting with mobile-optimized web application, which will then be ported over to a native mobile application
- Frontend built using React and Chakra UI
- Backend built using Next JS
- Initial prototype implementing API routes to *The Things Network* completed and functional for current LoRa nodes



Progress - Software



Schedule: Spring Quarter

Winter Quarter, Week 10 to Spring Quarter, Week 1

Debug LoRaWan Firmware

Finish Web App, start testing

Field Test with the Assembled Unit

Start on final version of PCB

Spring Quarter, Week 2-4

Finish Testing for Web Application

Transfer Web App into Android / iOS Application

Spring Quarter, Week 5-7

Final Testing for Complete Solution



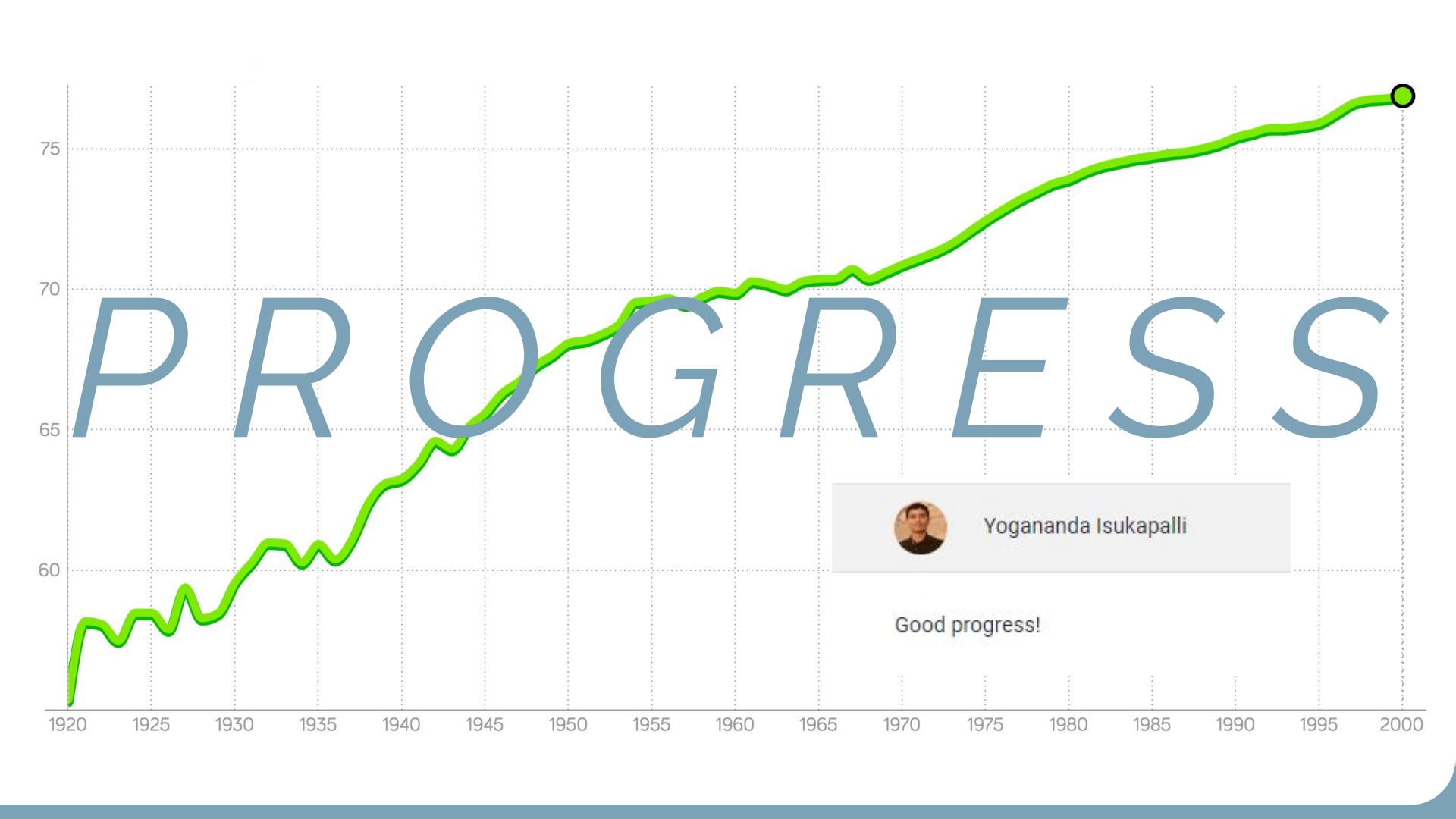
Thank you!

Questions?

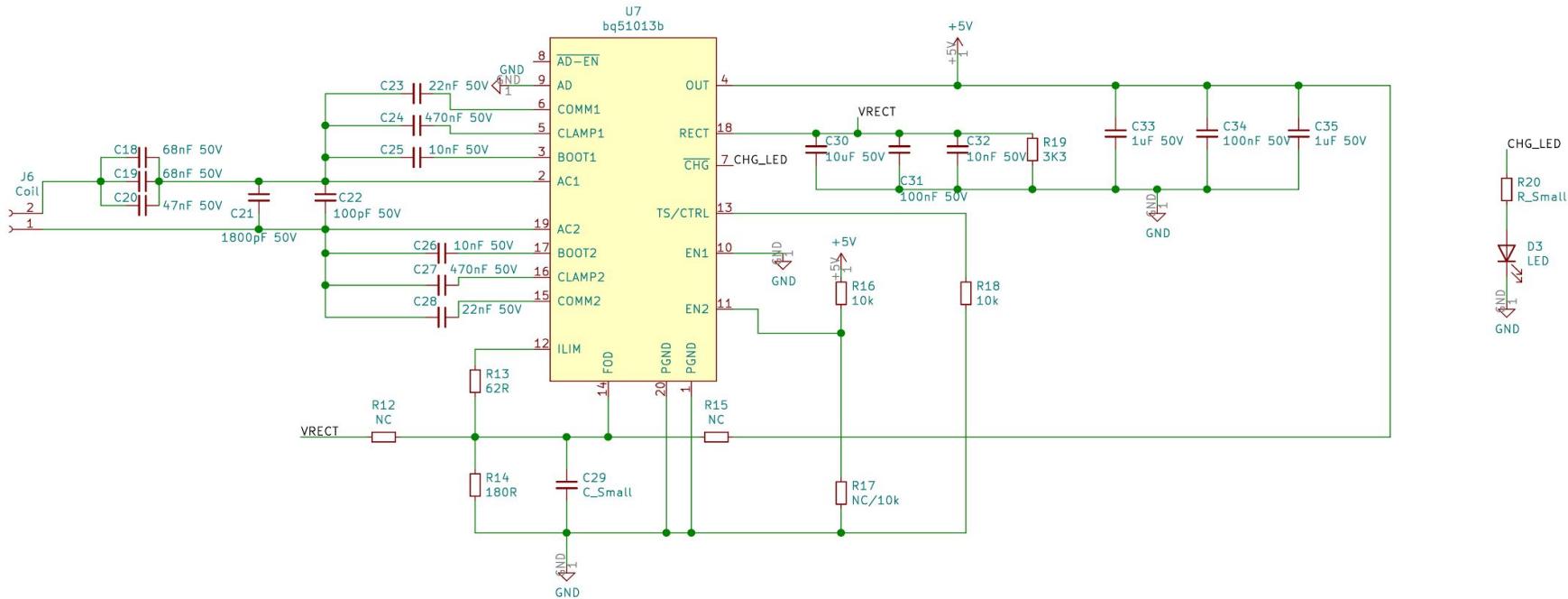
Acknowledgements

Professor **Yogananda Isukapalli**
Teaching Assistants **Boning Dong, Trenton Rochelle**





Wireless Charging Schematic



STM32L053r8

Power consumption

- low power consumption
- 88 µA/MHz in Run mode
- 0.27 µA Standby mode

Peripherals

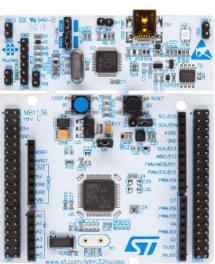
- SPI/I₂C/USART
- EEPROM for storing device ID

Firmware Development

- Nucleo

Packaging

- QFP64



ST Ultra-low power product line

STM32L5

- 32-bit Arm® Cortex®-M33 + FPU at 110 MHz
- From 256 to 512 Kbytes of Flash memory
- Lowest power mode + RAM + RTC: 0.35 µA

STM32L4+

- 32-bit Arm® Cortex®-M4 + FPU at 120 MHz
- From 512 Kbytes up to 2 Mbytes of Flash memory
- Lowest power mode + RAM + RTC: 0.39 µA

STM32L4

- 32-bit Arm® Cortex®-M4 + FPU at 80 MHz
- From 64 Kbytes to 1 Mbyte of Flash memory
- Lowest power mode + RAM + RTC: 0.34 µA

STM32L1

- 32-bit Arm® Cortex®-M3 at 32 MHz
- From 32 to 512 Kbytes of Flash memory
- Lowest power mode + RAM + RTC: 1.2 µA

STM32L0

- 32-bit Arm® Cortex®-M0+ at 32 MHz
- From 8 to 192 Kbytes of Flash memory
- Lowest power mode + RAM + RTC: 0.67 µA

STM8L

- 8-bit STM8 core at 16 MHz
- From 2 to 64 Kbytes of Flash memory
- Lowest Halt mode: 0.3 µA

Vehicle Detection Sensors

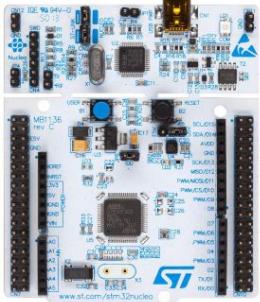
- Main Factors to consider
 - Power Consumption
 - Installation
 - Lifespan of component
- Sensing Technologies
 - Magnetometer
 - Magnetoresistive (inductive)
 - Hall Effect
 - Differential Hall Effect
 - Ultrasonic
 - Infrared
 - Light Grid

Vehicle Detection Sensors - Experiment Setup

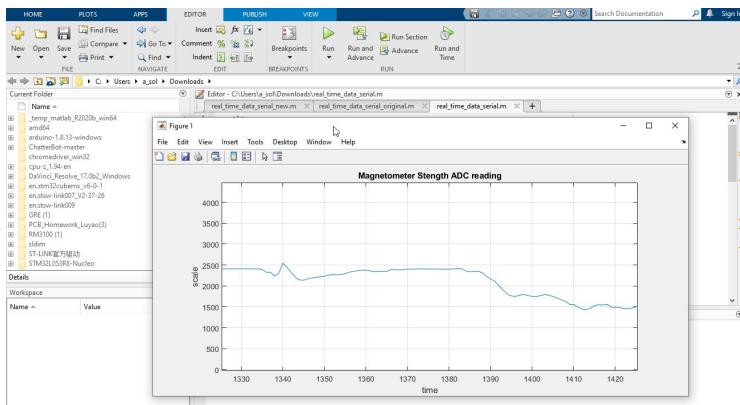
Sensor	Mechanism	Result
LM351LT	Hall Effect	Failure
TLE4921	Differential Hall Effect	Failure
RM3100	Magneto-Inductive	Success
HC-SR06	Ultrasonic Sensor	Success



SPI/I₂C/ADC



UART





Communication Modules					
Mechanism	Name	Type	Application Notes	Active Transmitting Power Consumption	Pricing?
LoRaWAN	SX1272	LoRa Shield	SPI interface		\$25 (Digikey)
	SX1261/1262	LoRa Shield	SPI interface		\$30 (Digikey)
	I-NUCLEO-LRWAN1	STM32 Expansion board	USART interface Also uses the SX1272 chip		\$28.90 (Digikey)
	STM32WLE5 Series	SoC with LoRa Connectivity	Still relatively new (released this month) Dev boards for this may not exist	15 mA at 10 dBm, 87 mA at 20 dBm	\$6 per chip (but just the chip)
	B-L072Z-LRWAN1	Dev board for Lora	Uses SX1276		\$46.50
ZigBee	P-NUCLEO-WB55	Dev board for Zigbee / BLE		75mA maximum MCU	\$43.75 (Digikey)
	STM32WB Series	SoC with Zigbee and BLE			
	Silicon Labs EFR32MG13	SoC with Zigbee and BLE	Used in IKEA's TRADFRI lineup of smart home products	8.5 mA at 0 dBm, 35.3 mA at 14 dBm	



SPL

	Name	Type	Sensitivity/Range	Application Notes	Will it Work?
Magnetoresistive	HMC1051/1052/1053	Part	Typical 1mV/gauss ±6 Gauss	Very complicated. Comes as an primitive analog package, need complicated op-amp circuits to harness the reading, then use ADC reading;	Used successfully to detect vehicle in USC research paper , page 53 It will work with constant ADC reading
	RM3100 Module (Amazon)	Module	Typical 15 nT ±800uT	SPI interface	Given vehicle magnetic field strength typically in uT range, it should response to vehicle passing
Ground Loop	N/A	N/A	N/A	Too expensive for installation/operation	
Hall Effect Switch	SM351LT	Part	±1.1mT Trip, ±0.2mT Release	Simple connection	Not likely, given the price we will try it
Differential Hall Effect Switch	TLE4921	Part	Adjustable through a back magnet, up to ±80 mT	Simple connection	Depends on bias of the back magnet

talking about technology used...