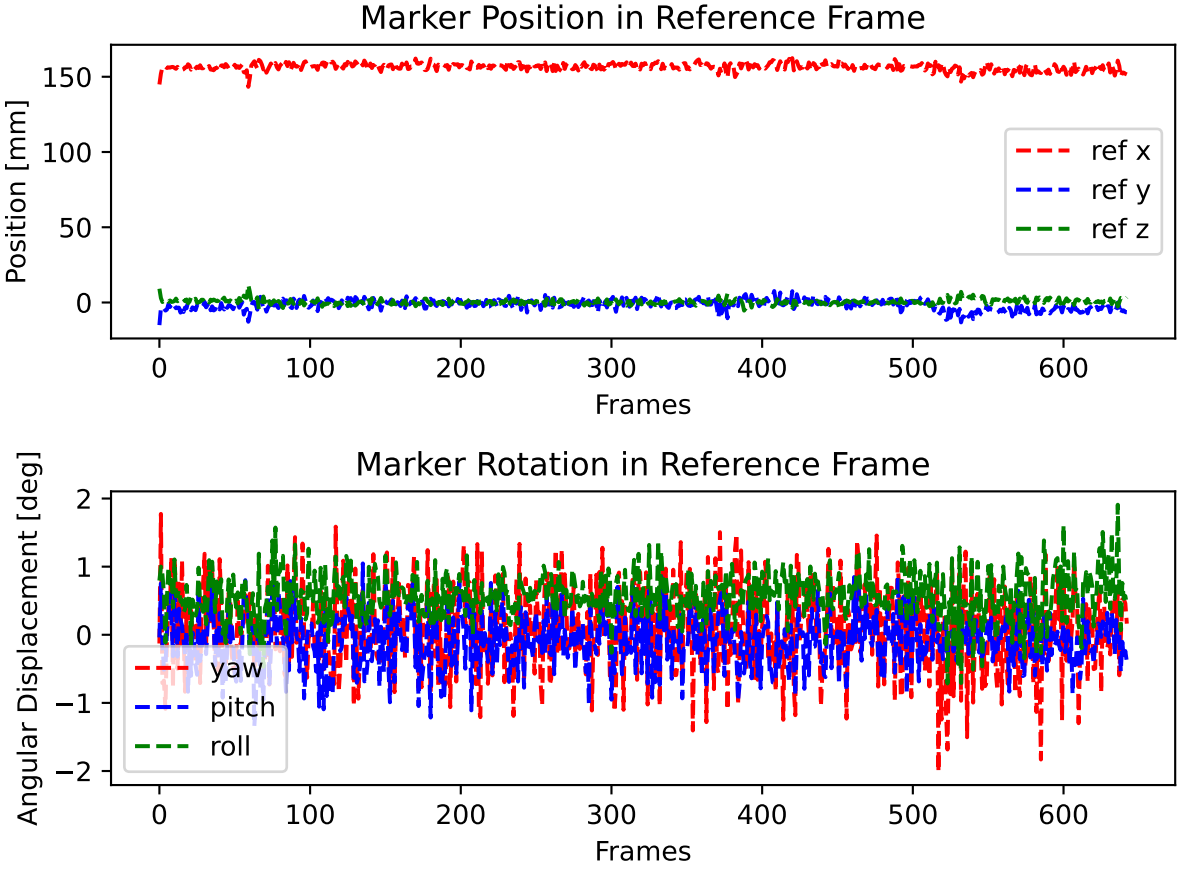
Marker Position in Reference Frame
Position [mm]
150
100
50
0
ref x
ref y
ref z
0
100
200
300
400
500
600
Frames
Marker Rotation in Reference Frame
Angular Displacement [deg]
2
1
0
−1
−2
yaw
pitch
roll
0
100
200
300
400
500
600
Frames