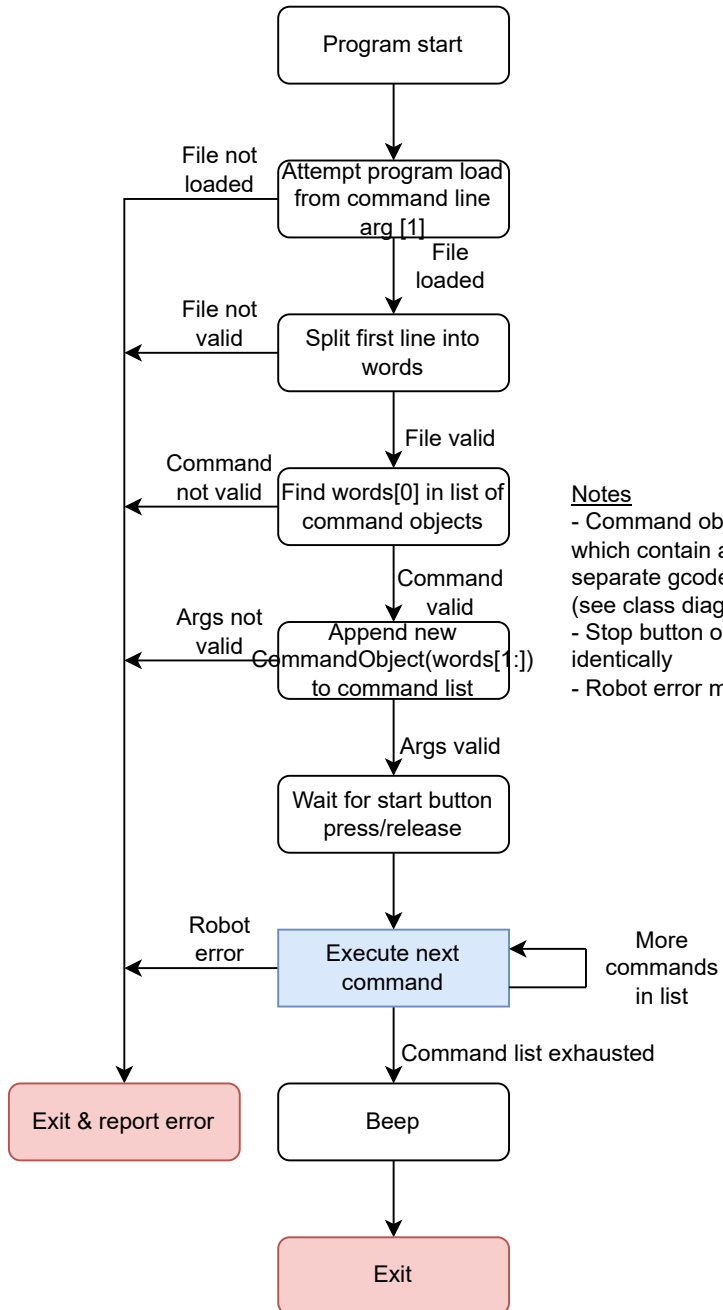


## Program Flow



### Notes

- Command objects contain methods of Robot() singleton, which contain actual hardware access etc. This is intended to separate gcode execution from hardware implementation (see class diagram)
- Stop button on breadboard & stop limit switch treated identically
- Robot error might be stop button press, error in method, etc.

# "UML" Class Diagram

