

Carnegie Mellon University

Thesis Defense:

A Method to Design Hybrid Lattice Support Structures for LPBF Additive Manufacturing

Integrated
Design
Innovation
Group

Lisha White, PhD. Candidate, Carnegie Mellon University

Committee Members:

Dr. Jonathan Cagan¹, Dr. Yongjie Jessica Zhang¹

Dr. Anthony Rollett², Dr. Guanglu Zhang¹

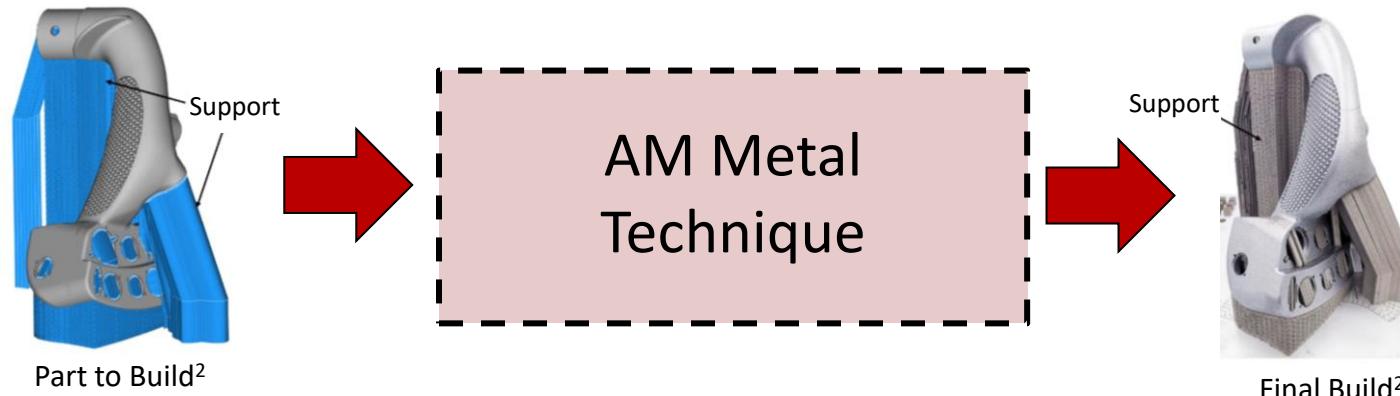
1. Carnegie Mellon University, Department of Mechanical Engineering
2. Carnegie Mellon University Department of Material Science and Engineering

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3			Conclusions
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2	Obj. 3.3	

Additive Manufacturing (AM) of Metals¹

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✓ Pros	- Cons	• Example Techniques
<ul style="list-style-type: none"> ✓ Complex geometry ✓ Mass customization ✓ No specialized tooling 	<ul style="list-style-type: none"> - Initial start-up costs - Limited materials - Build time vs. accuracy 	<ul style="list-style-type: none"> • Directed Energy Deposition • Material Extrusion • Powder Bed Fusion

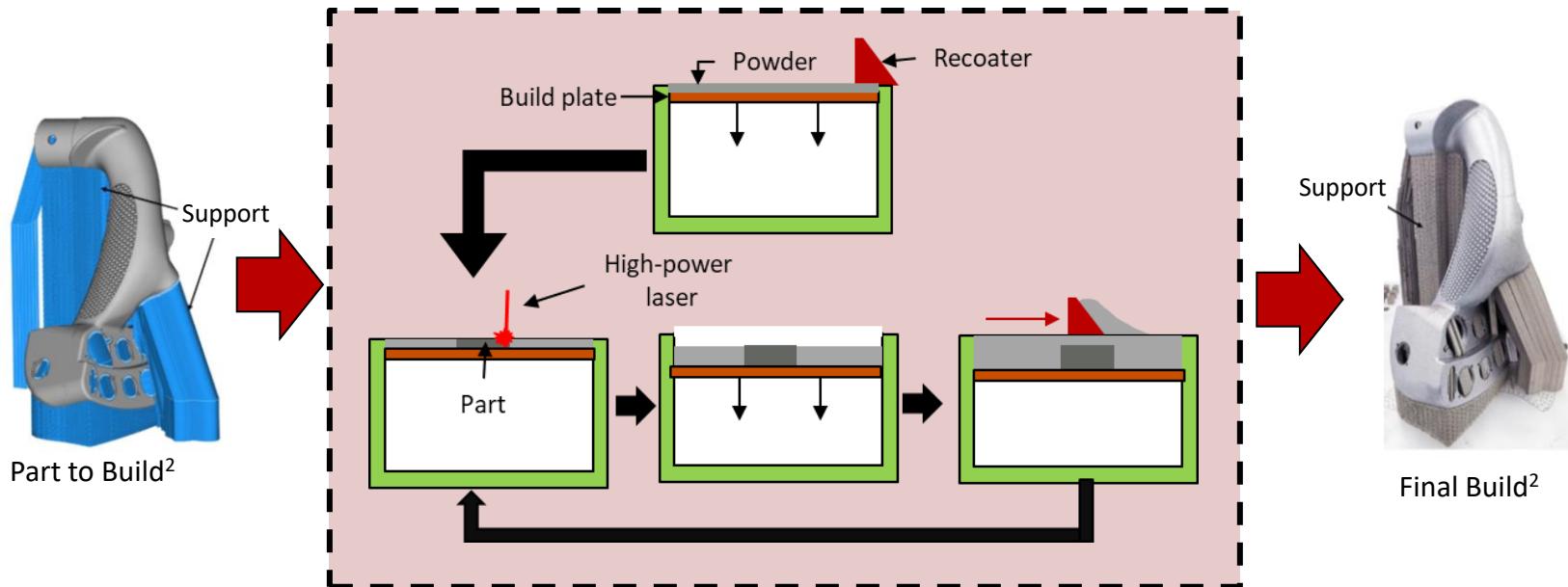


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Laser Powder Bed Fusion (LPBF)

3

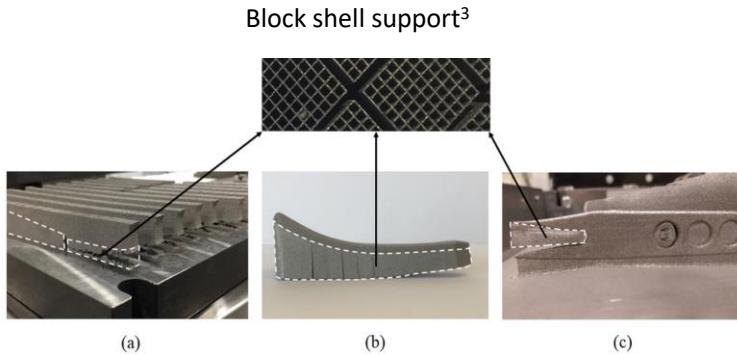
Layer-wise addition of material to create a part using a high-power laser to melt metal alloy powder¹



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Laser Powder Bed Fusion (LPBF)

Residual Stress

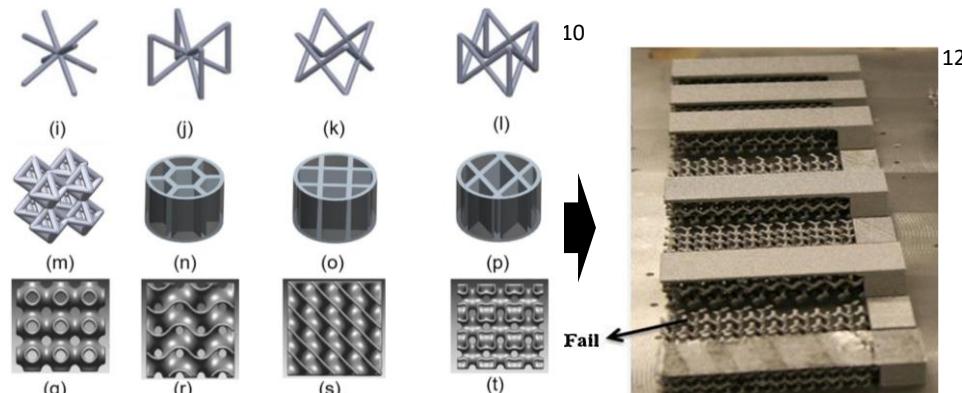


Support Structure Purpose^{4,5}:

- **Dissipate Heat**^{5,6,7}
- Maintenance of structural integrity^{3,8,9}

Lattice Structures for AM

- Individual unit cells distributed to control bulk properties^{10,11}



3. Cheng, L., et. al (2019)

4. Jiang, J. et. al (2018)

5. Huang, R., et. al (2020)

6. Bartsch, K., et. al (2019)

7. Lee, K.H., et.al (2022)

8. Bartsch, K., et. al (2018)

9. Pellens, J., et.al (2020)

10. Nazir, A., et. al (2019)

11. Liang, H et. al (2011)

12. Hussein, A., et. al (2013)

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Limitations to Lattice Support Structure Design

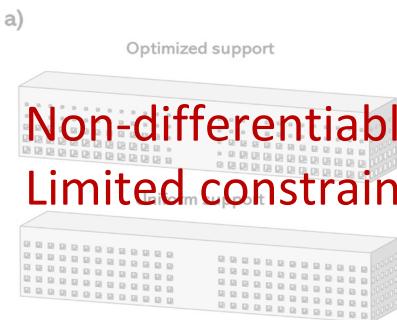
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Gradient-Based Optimizer^{13,14}

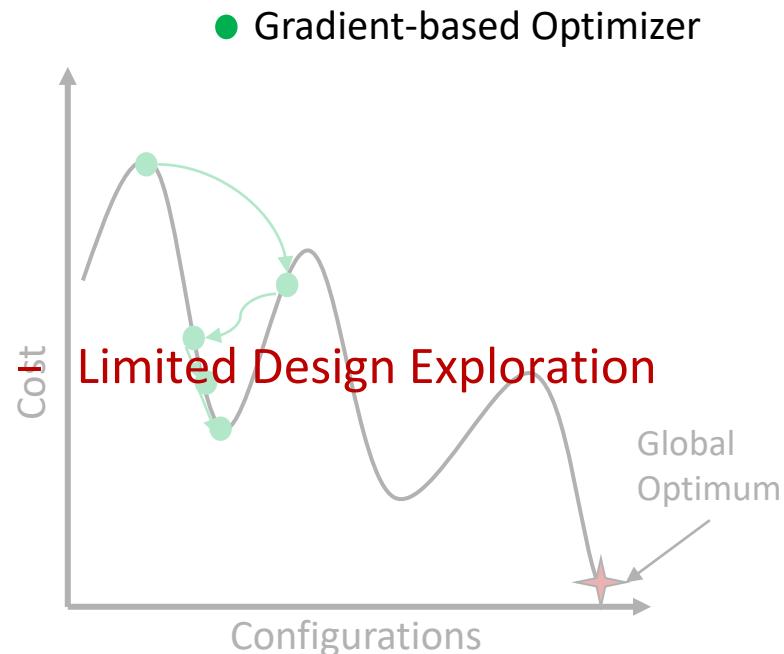
- ✓ Ideal for differentiable objective functions
- ✓ Fast convergence

Optimize density distribution^{4,10,11,19}

Minimize thermal gradient w.r.t density



- Non-differentiable objective function
- Limited constraint consideration



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Limitations to Lattice Support Structure Design

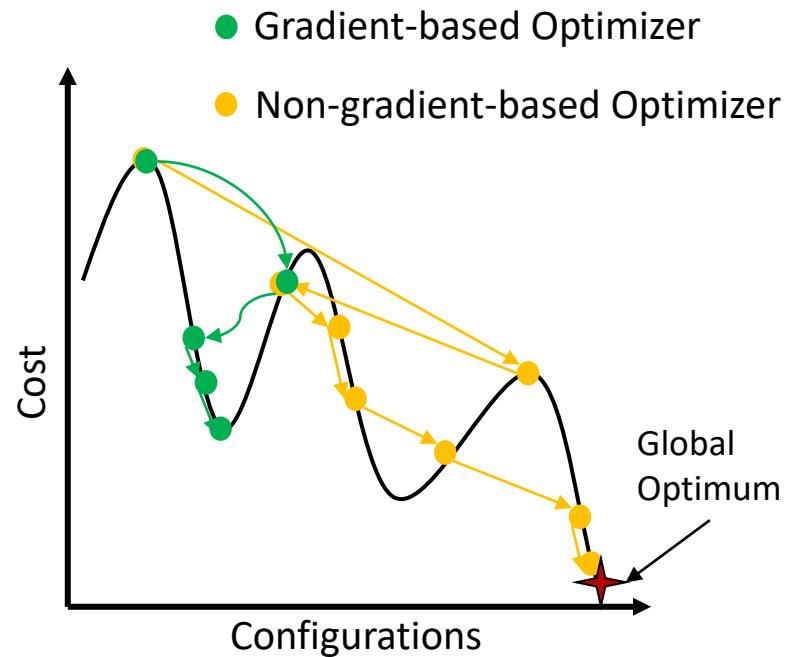
6

Gradient-Based Optimizer^{13,14}

- ✓ Ideal for differentiable objective functions
- ✓ Fast convergence
- Limited design exploration

Non-Gradient-Based Optimizers¹⁴⁻¹⁶

- ✓ Larger design domain exploration
- Computational Expensive



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1. How can designers *efficiently* find optimally directed lattice support structure solutions that improve heat dissipation while satisfying multiple AM constraints for LPBF?

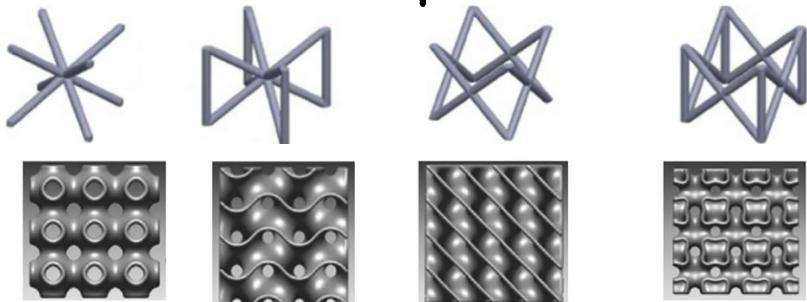
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Lattice Structures for AM

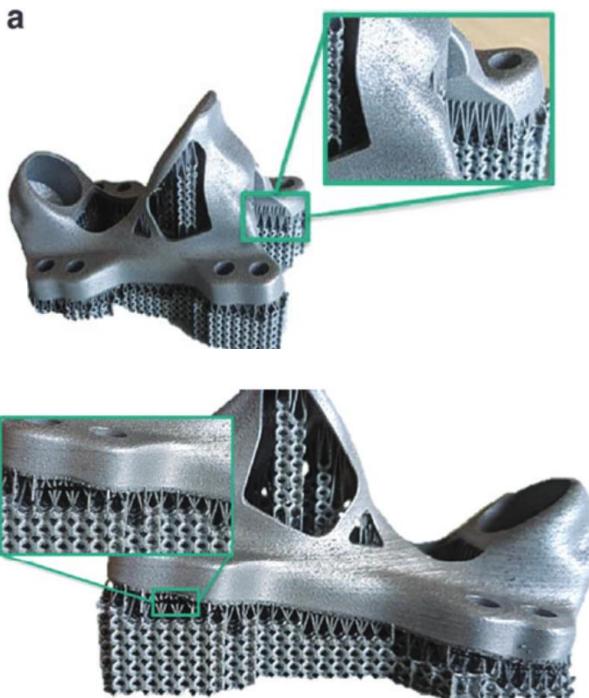
Proposed Lattice Support Structure Methods



Potential Unit Cells¹⁰



Pin Connection^{17,18}:



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1. How can designers *efficiently* find optimally directed lattice support structure solutions that improve heat dissipation while satisfying multiple AM constraints for LPBF?
2. How can lattice support structures be computationally designed to be *attached* to complex structures?



Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
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Thesis Statement

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To reduce manufacturing and design costs of support structures in laser powder-bed fusion, lattice support structures can be computationally designed to maximize the dissipation of heat while constraining residual stress and deformation for complex structures. By utilizing a modified simulated annealing-based method, designers can efficiently generate optimally directed configurations of pre-defined unit cells with specified functionality at reduced computational costs.



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Thesis Statement Breakdown

11

To reduce manufacturing and design costs of support structures in laser powder-bed fusion, lattice support structures can be computationally designed to maximize the dissipation of heat while constraining residual stress and deformation for complex structures...

Objective 1: A Modified Simulated Annealing Based Method to Design Thermally Conductive Hybrid Lattice Support Structures for LPBF

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Thesis Statement Breakdown

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Objective 1: A Modified Simulated Annealing Based Method to Design Thermally Conductive Hybrid Lattice Support Structures for LPBF

Objective 2: An Optimally Directed Lattice Support Structure Design Method for Heat Dissipation and Structural Integrity in LPBF



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To reduce manufacturing and design costs of support structures in laser powder-bed fusion, lattice support structures can be computationally designed to maximize the dissipation of heat while constraining residual stress for complex structures...

Objective 1: A Modified Simulated Annealing Based Method to Design Thermally Conductive Hybrid Lattice Support Structures for LPBF

Objective 2: An Optimally Directed Lattice Support Structure Design Method for Heat Dissipation and Structural Integrity in LPBF

Objective 3: A Multi-Sized Unit Cell Approach to Design Lattice Support Structures for Complex Geometries



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Overview

Objective 1: A Modified Simulated Annealing Based Method to Design Thermally Conductive Hybrid Lattice Support Structures for LPBF

Objective 1.1: Maximize heat dissipation

Objective 1.2: Introduce expedited evaluation and design exploration

Objective 2: An Optimally Directed Lattice Support Structure Design Method for Heat Dissipation and Structural Integrity in LPBF

Objective 2.1: Incorporating structural constraints

Objective 2.2: Expediting thermal and structural property predictions

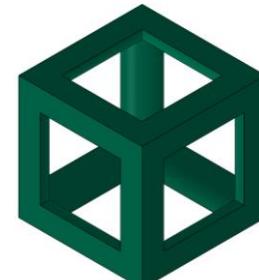
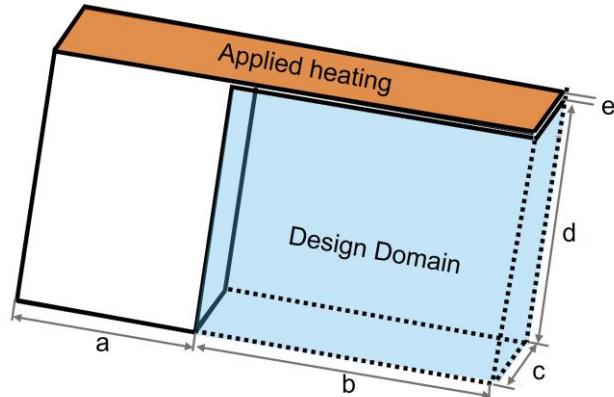
Objective 3: A Multi-Sized Unit Cell Approach to Design Lattice Support Structures for Complex Geometries

Objective 3.1: Reduce material waste in transition subdomain

Objective 3.2: Identify Geometric Representation

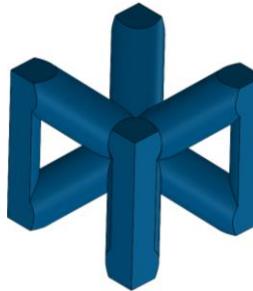
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Problem Overview

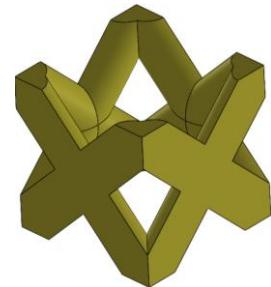


Simple Cubic ^{4,12,10,19}
(SC)

Design Variables (x)



BC Vertical Struts ^{20,21}
(BV)

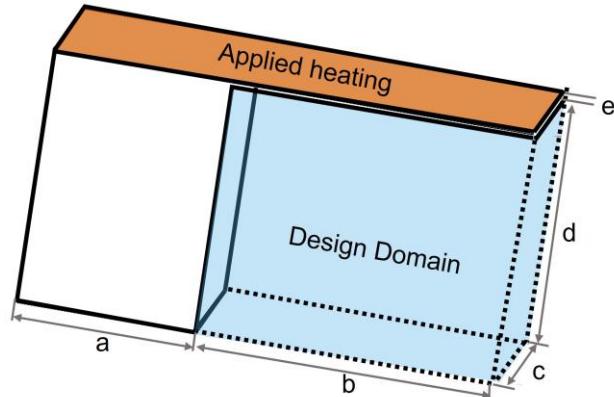


Face-Centred ^{9,21,22}
(FC)

Find $x = [x_1, x_2, \dots, x_n]$ to
 minimize $Q_{in} = Q(x),$
 subject to $KT = q,$
 Material Cost $\rightarrow V(x) < \varepsilon_v * V_{max}$ and
 $A(x) < \varepsilon_A * A_{max},$

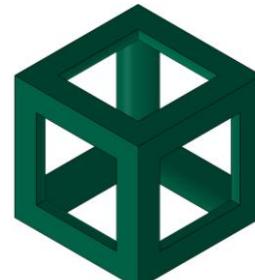
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Problem Overview

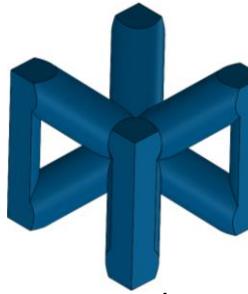


Find $x = [x_1, x_2, \dots, x_n]$ to
minimize $Q_{in} = Q(x)$,
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 $V(x) < \varepsilon_v * V_{max}$ and
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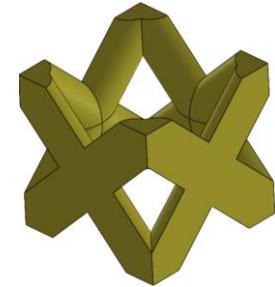
Design Variables (x)



Simple Cubic ^{4,12,10,19}
(SC)



BC Vertical Struts ^{20,21}
(BV)



Face-Centred ^{9,21,22}
(FC)

Physical properties of the unit cells for AlSi10Mg

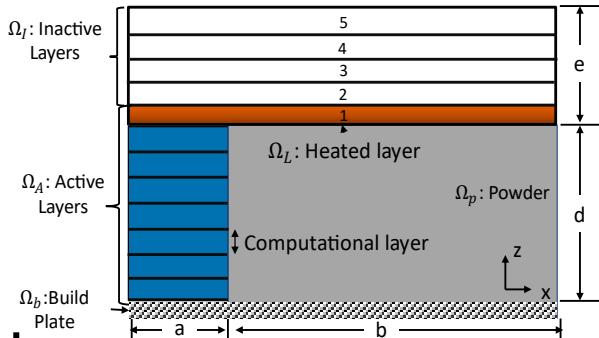
Unit Cell	K_{eff} [W/m°C]	Volume [mm ³]	Area _{XY} [mm ²]	Area _{XZ} [mm ²]
Solid	110	8	4	4
SC	12.37	1.82	2.31	2.31
BV	24.39	2.82	0.567	1.30
FC	39.43	3.69	0.846	3.24

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
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Defining design domain and boundary conditions

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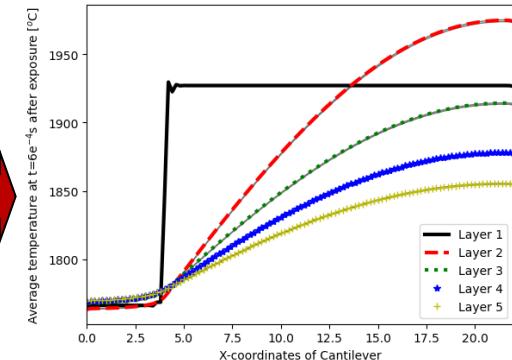
Equivalent Flash Heating Part-Scale^{10,23,24}:



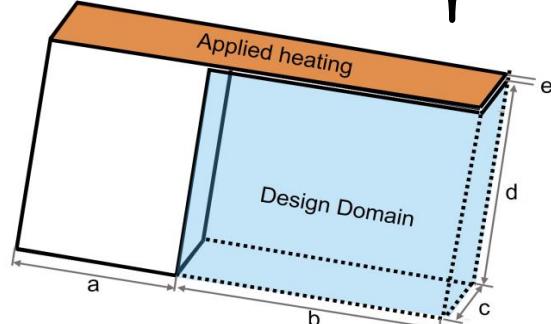
Heating + Cooling

$$\begin{cases} \rho c \frac{dT_i(t, x)}{dt} = \nabla \cdot (k \nabla T_i(t, x)) + q(x) \\ -(k \nabla T_i(t, x)) \cdot n = h \nabla T_i(t, x) \\ T_i(t, x) = T_{base} \\ T = T_{powder} \end{cases}$$

Layer-by-Layer Temperature



Equivalent steady-state²⁴:



$$\begin{cases} \nabla \cdot (K \nabla T) + q = 0 \\ T(x, y, 0) = T_{base} \\ T(x, y, g) = T_{source} \end{cases}$$

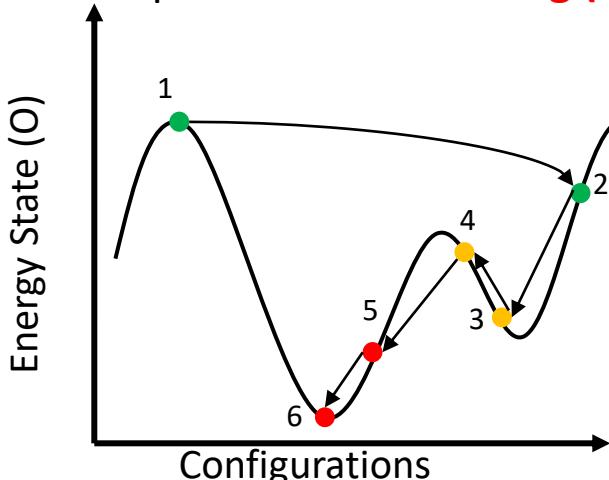
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Simulated Annealing (SA)

Analogous to the annealing of metals

Stages:

1. High temperature: **Exploration (1 → 3)**
2. Mid-temperature: **Intermediate (3 → 5)**
3. Low temperature: **Fine-tuning (5 → 6)**



- Annealing Schedule:

$$T_{k+1} = \alpha * T'_k$$

- Probabilistic acceptance of designs:

$$P_{acc} = exp\left(-\frac{O_2 - O_1}{T'_k}\right)$$

Pros:

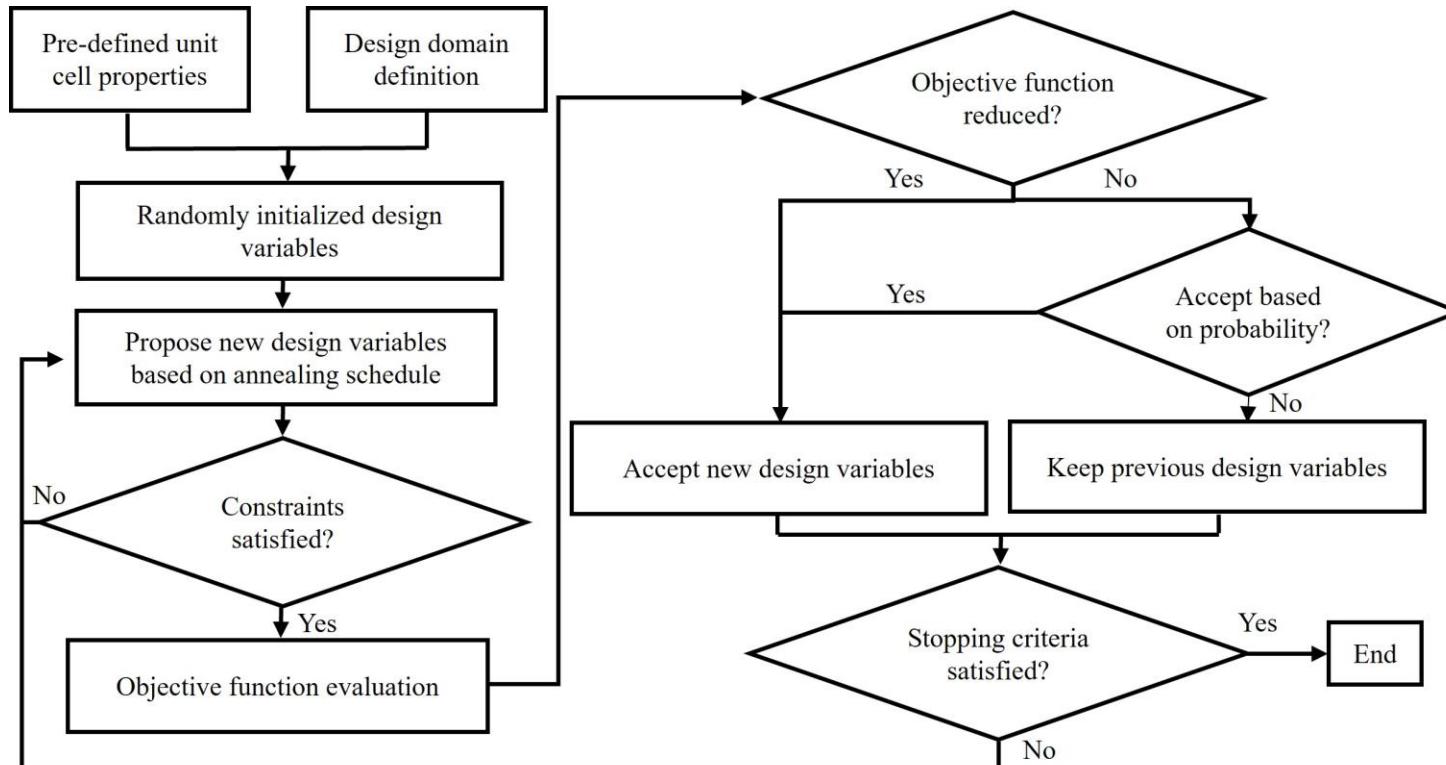
- Wider exploration of design space
- Allows hill climbing even at later stages (3 → 4)

Cons:

- Computationally expensive

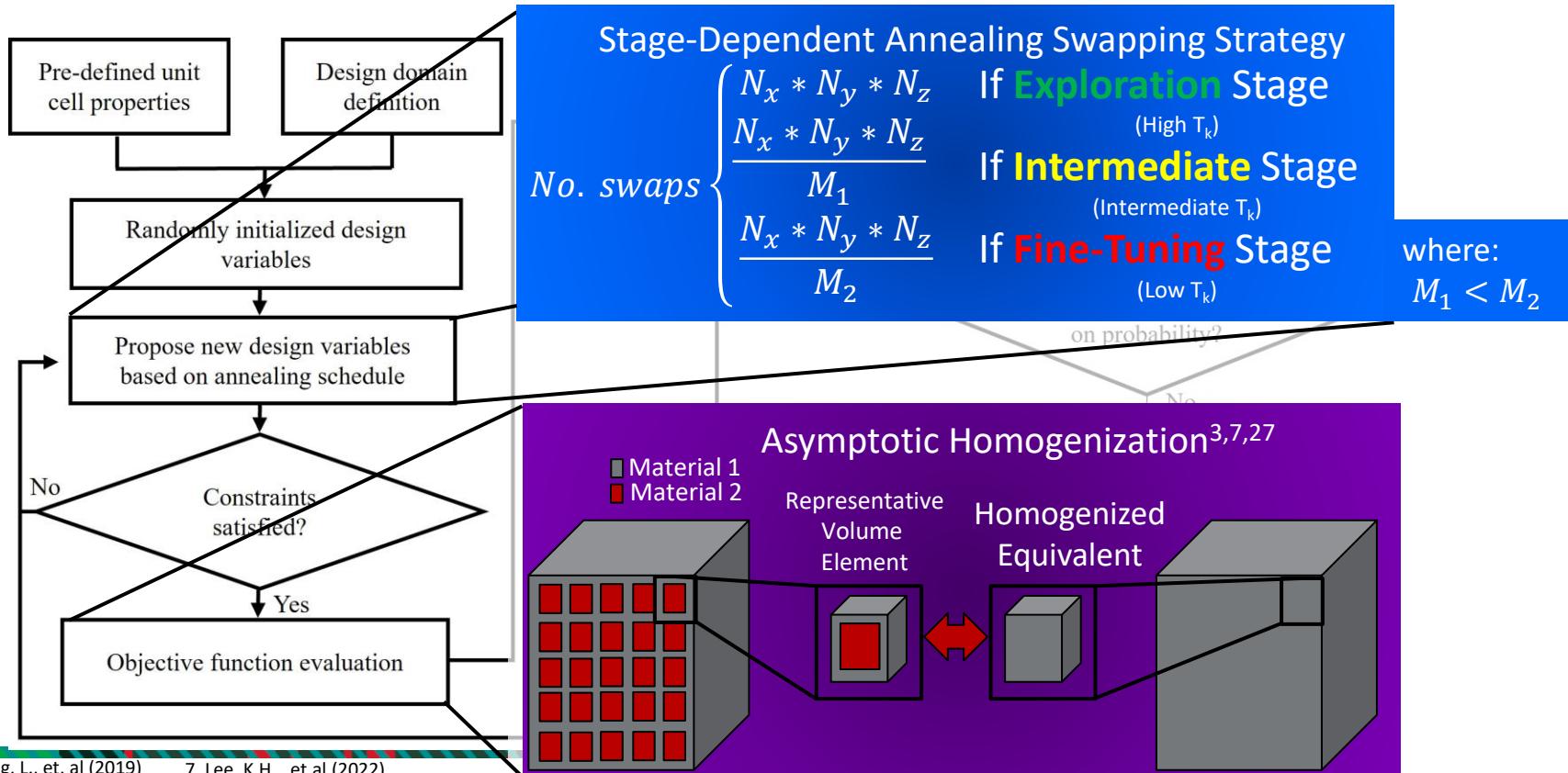
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Flowchart of Traditional SA Method



Flowchart of Modified-SA-Based Method

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Flowchart of Modified-SA-Based Method (M-SAM)

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SA
Hyperparameters:

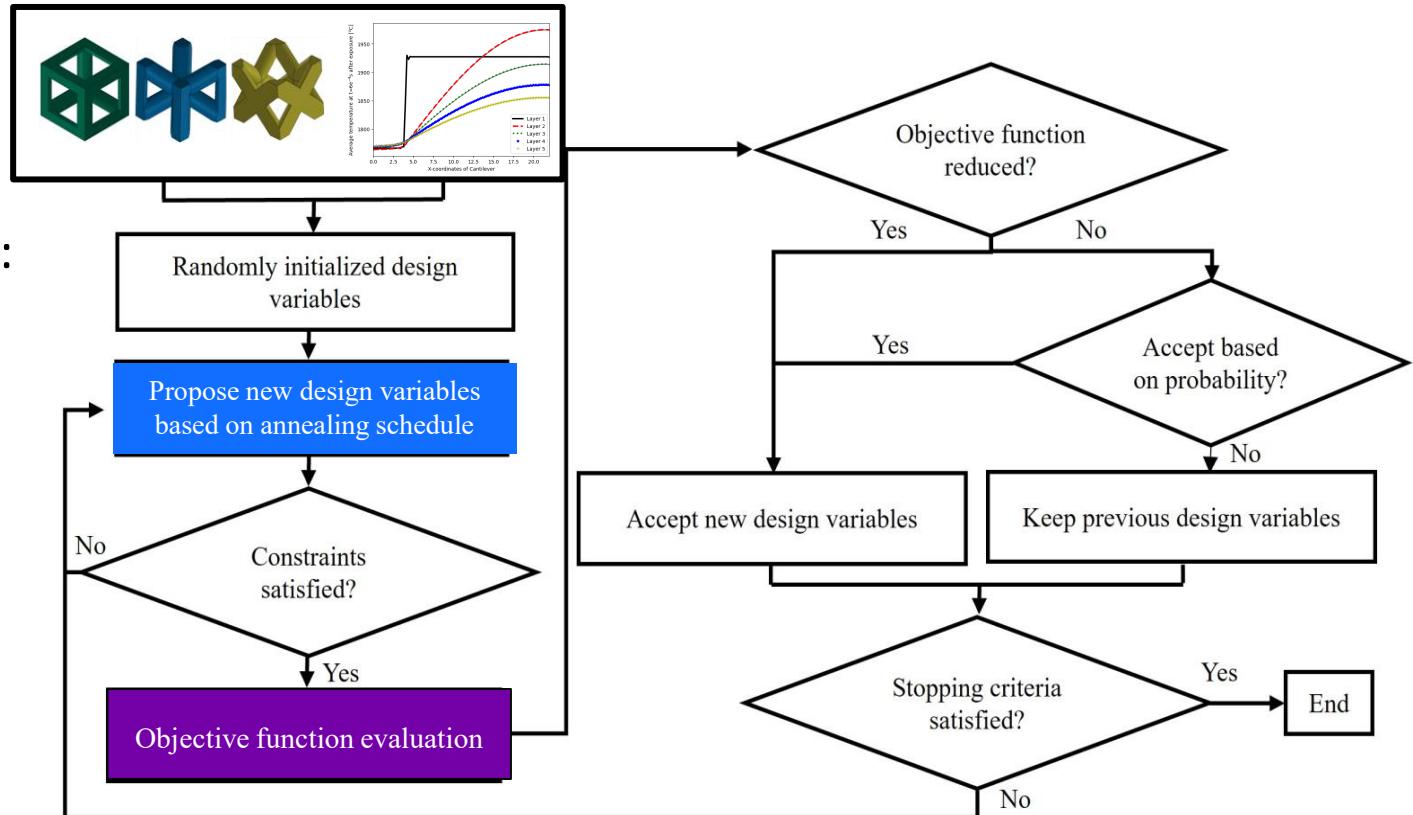
$$T_0 = 50$$

$$\alpha = 0.5$$

Constraints:

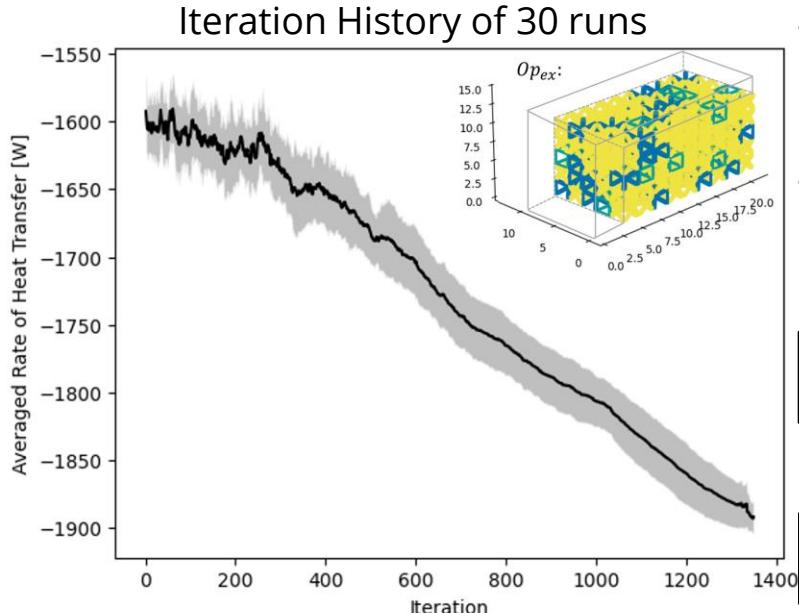
$$V_{\max} = 750 \text{ mm}^3$$

$$A_{\max} = 140 \text{ mm}^2$$



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Case Study of Cantilever Beam



Comparison of support designs*

	$ Q_{in} $ [W]	Volume V(x) [mm ³]	Area A(x) [mm ²]	SC/BV/FC	Constraint Satisfaction V(x) < 750 A(x) < 140
Solid	4,546	1,800	280	0/0/0	No
SC Only	1,196	409	161	225/0/0	No
BV Only	1,607	634	57	0/225/0	Yes
FC Only	2,124	830	120	0/0/225	No
Op_{Avg}	1,887 (15.0)	745 (5.56)	108 (4.94)	18/58/149 (3.23/5.43/5.34)	Yes

*standard deviation in ()

Compared to
BV Only

Average of ~16%
Heat dissipation

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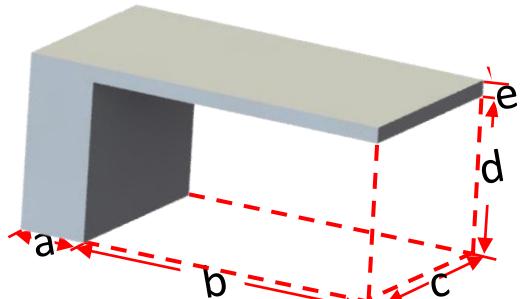
Objective 3.1:
Reduce material waste in transition subdomain

Objective 3.2:
Automating Unit Cell Placement

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Definition of Model

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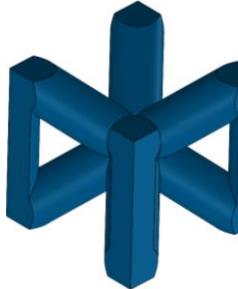


Example: Cantilever Beam

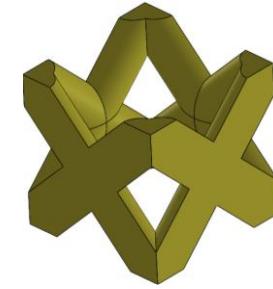
Find $x = [x_1, x_2, \dots, x_n]$ to
 minimize $Q_{in} = Q(x)$,
 subject to $KT = q$, $CU = F$, Static-Structural
 $V(x) < \varepsilon_v * V_{max}$ and
 $A(x) < \varepsilon_A * A_{max}$,
 $\frac{\sigma_{PN}}{\sigma_y} \leq 1$
 $U_{tot} \leq U_{max}$



Simple Cubic ^{4,12,10,19}
(SC)



BC Vertical Struts ^{20,21}
(BV)



Face-Centred ^{9,21,22}
(FC)

Design Variables (x)

Unit Cell	$K_{eff} \left[\frac{W}{mC} \right]$	Volume [mm ³]	$Area_{XY}$ [mm ²]	$Area_{YZ}$ [mm ²]	E_{eff_z} [Pa]	$E_{eff_{Y,X}}$ [Pa]	G_{xy} [Pa]	G_{xz}/G_{yz} [Pa]
Solid	110	8	4	4	7.4E+10	7.4E+10	2.782E+10	2.782E+10
SC	12.37	1.82	2.31	2.31	7.64E+09	7.64E+09	5.419E+08	5.419E+08
BV	24.39	2.82	0.567	1.30	9.73E+09	3.69E+09	4.375E+09	4.175E+09
FC	39.43	3.69	0.846	3.24	1.95E+10	1.34E+10	1.598E+08	6.873E+09

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Structural Constraints

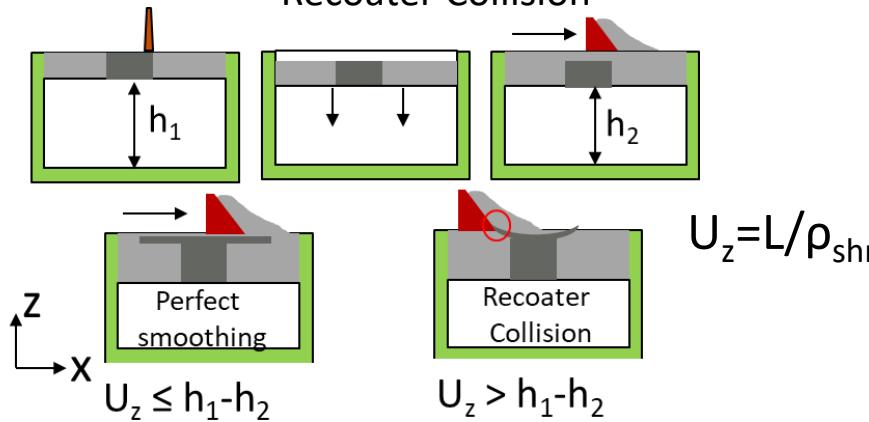
P-Norm Stress^{4,28:}

$$\sigma_j^{PN}(x) = \left(\frac{1}{N_j} \sum_{a \in \Omega_j} (\sigma_a^{vM}(x))^p \right)^{\frac{1}{p}}$$

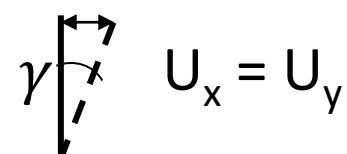
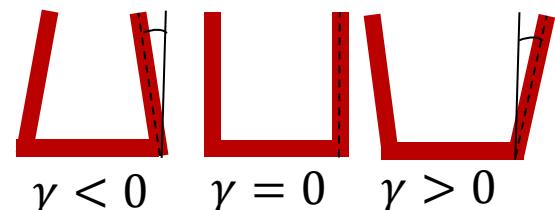
$\sigma_j^{PN} > \sigma_y$:= plastic deformation
 $\sigma_j^{PN} < \sigma_y$:= elastic deformation

Maximum Total Displacement: $U_{tot} = \sqrt{U_x^2 + U_y^2 + U_z^2}$

Recoater Collision^{11,29,30}



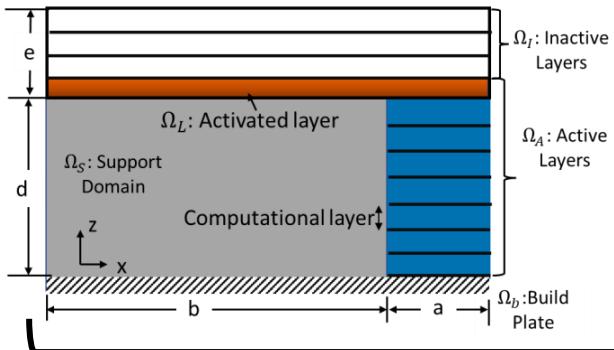
Draft Angle (γ)³¹



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Defining design domain and boundary conditions

Part Scale Modeling



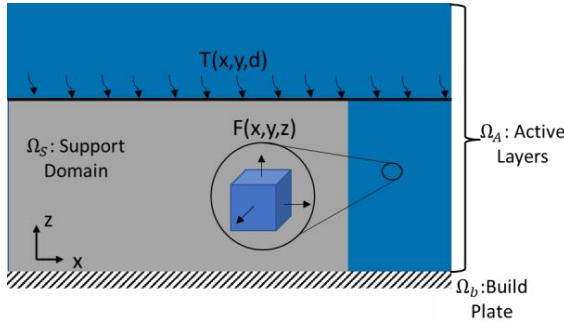
1. Inherent Strain Method
(ISM) 4,11,29,30,32,33

$$\left\{ \begin{array}{l} \nabla \cdot \sigma_i = 0 \\ \sigma_i = C\varepsilon_e^i \\ \varepsilon_{tot}^i = \varepsilon_e^i + \varepsilon_p^i + \varepsilon_{in}^i \end{array} \right.$$

2. Equivalent Flash Heating
(EFH) 10,23,24

$$+ \quad \left\{ \begin{array}{l} \text{Heating: } \rho c \frac{dT_i(t,x)}{dt} = \nabla \cdot (k\nabla T_i(t,x)) + q(x) \\ \text{Cooling: } -(k\nabla T_i(t,x)) \cdot n = h\nabla T_i(t,x) \\ T_i(t,x) = T_{base} \\ T = T_{powder} \end{array} \right.$$

Equivalent Steady-State



Static Structural²⁹

$$\left\{ \begin{array}{l} \nabla \cdot \sigma + \mathbf{F} = 0 \\ U(x, y, 0) = 0 \end{array} \right.$$

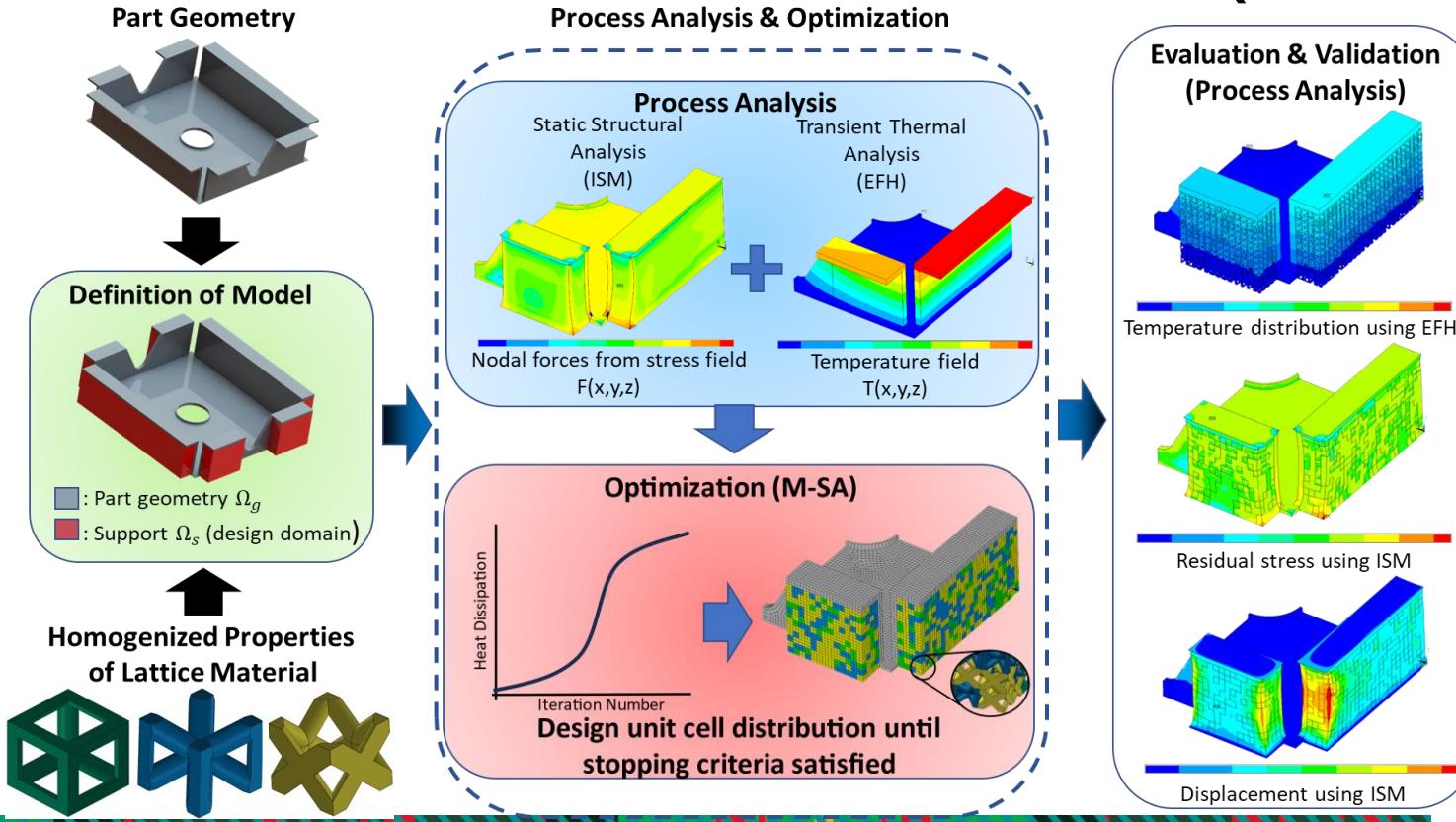
Steady-State Thermal²⁴

$$\left\{ \begin{array}{l} \nabla \cdot (K\nabla T) + \mathbf{q} = 0 \\ T(x, y, 0) = T_{base} \\ T(x, y, d) = T_{source} \end{array} \right.$$

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

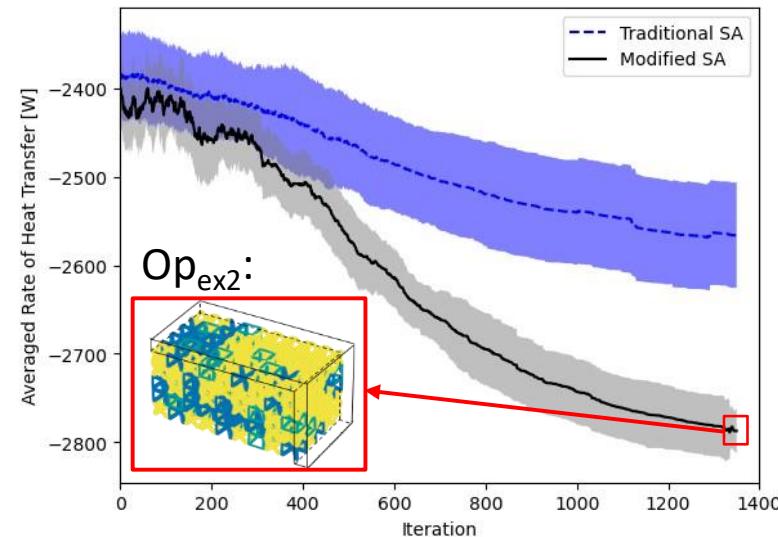
Flowchart of Modified SA-based Method (M-SAM)

27



Case Study of Cantilever Beam

Iteration History of 30 runs



Objective = -2,815 W, Volume = 735 mm³,
Area = 108 mm², p-Norm = 0.366, U_{sum} =
24.2 mm

Comparison of support designs*

	Q _{in}	V(x)	A(x)	P-norm Stress	Max(U _{sum}) [μ m]	SC/BV/FC	V(x)<750 A(x)<140 P-norm < 0.66 Max(U _{sum}) < 32
Solid	7,128	1,800	280	0.293	8.06	--	No
SC Only	1,743	409	161	0.359	31.7	225/0/0	No
BV Only	2,405	634	57	0.365	30.8	0/225/0	Yes
FC Only	3,235	830	120	0.352	15.6	0/0/225	No
Op _{avg,2}	2,773 (47.1)	722 (11.7)	107 (6.82)	0.360 (0.00614)	24.0 (1.34)	27/63/133 (5.3/8.0/9.4)	Yes

*standard deviation in ()

Compared to BV Only

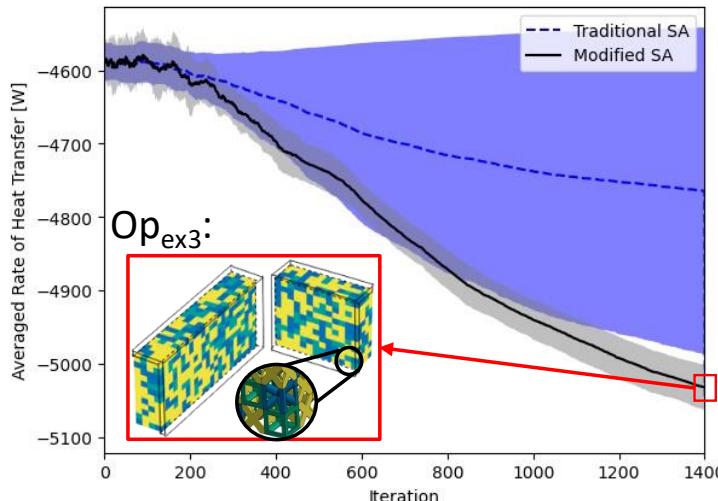
Average of ~14% Heat dissipation

Average of ~25% Distortion

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Case Study of Aerospace Bracket

Iteration History of 30 runs



Objective = -5,039 W, Volume = 5,481 mm³,
 Area = 1,243 mm², p-Norm = 0.648, U_{sum} = 69.7
 mm

Comparison of support designs*

	Q _{in}	V(x)	A(x)	P-norm Stress	Max(U _{sum}) [μm]	SC/BV/FC	V(x) < 5,900 A(x) < 1,360 P-norm < 0.66 Max(U _{sum}) < 76
Solid	12,479	14,208	2,368	0.609	14	--	No
SC Only	3,524	3,232	1,367	0.648	96.0	1,776/0/0	No
BV Only	4,624	5,008	66	0.648	97.5	0/1,776/0	No
FC Only	6,004	6,553	1,568	0.637	74.7	0/0/1,776	No
Op _{avg,3}	4,902 (29.4)	5,315 (36.2)	1,222 (13.7)	0.643 (0.0037)	72.8 (2.3)	388/589/799 (16/20/30)	Yes

*standard deviation in ()

SC Only
Satisfies
Constraints

Average of ~60%
Material Cost

Average of ~47%
Post-processing
Cost

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Overview

Objective 1: A Modified Simulated Annealing Based Method to Design Thermally Conductive Hybrid Lattice Support Structures for LPBF

Objective 1.1: Maximize heat dissipation

Objective 1.2: Introduce expedited evaluation and design exploration

Objective 2: An Optimally Directed Lattice Support Structure Design Method for Heat Dissipation and Structural Integrity in LPBF

Objective 2.1: Incorporating structural constraints

Objective 2.2: Expediting thermal and structural property predictions

Objective 3: A Multi-Sized Unit Cell Approach to Design Lattice Support Structures for Complex Geometries

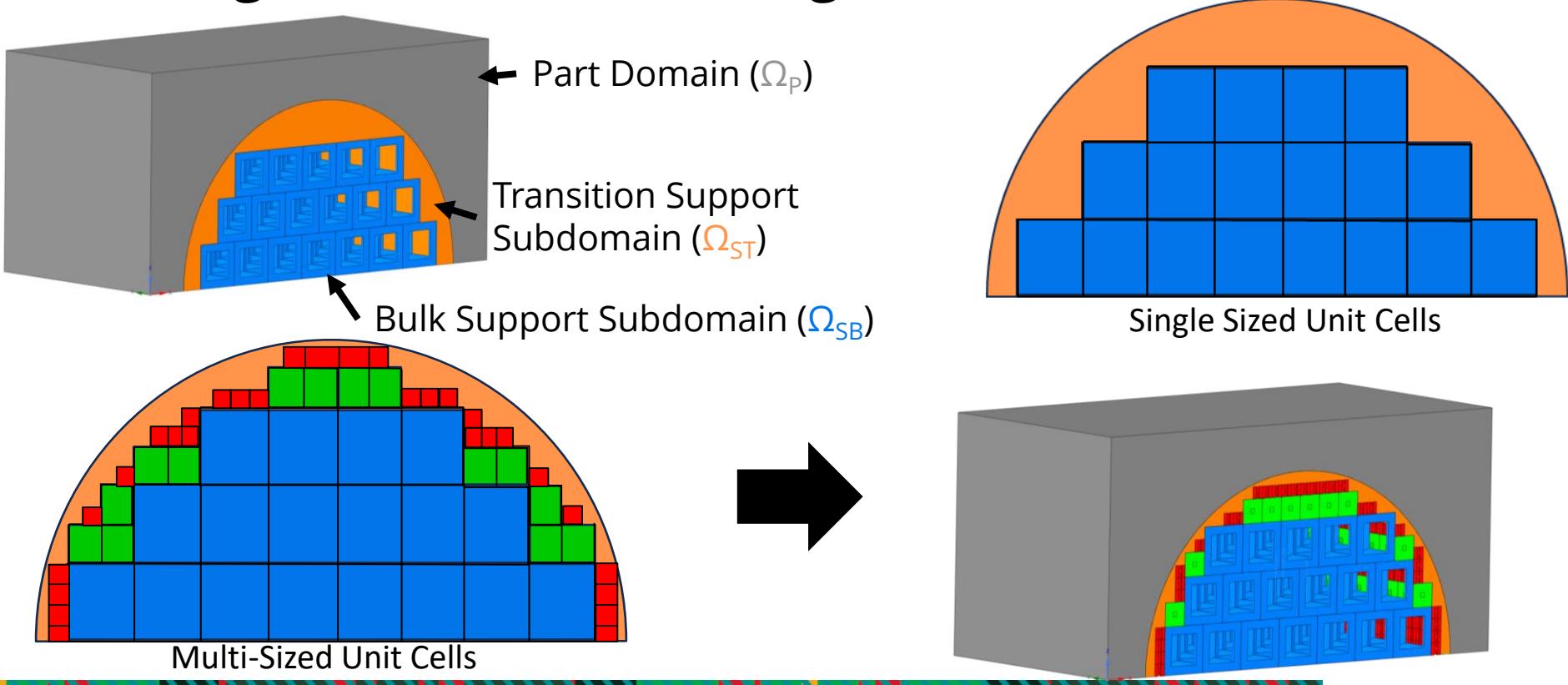
Objective 3.1: Reduce material waste in transition subdomain

Objective 3.2: Automating Unit Cell Placement

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Reducing Material Waste using Multi-Sized Unit Cells

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Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Definition of Model

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Example: Symmetric Curved Pipe

Find $x = [x_1, x_2, \dots, x_n]$ and $y = [y_1, y_2, \dots, y_m]$ to

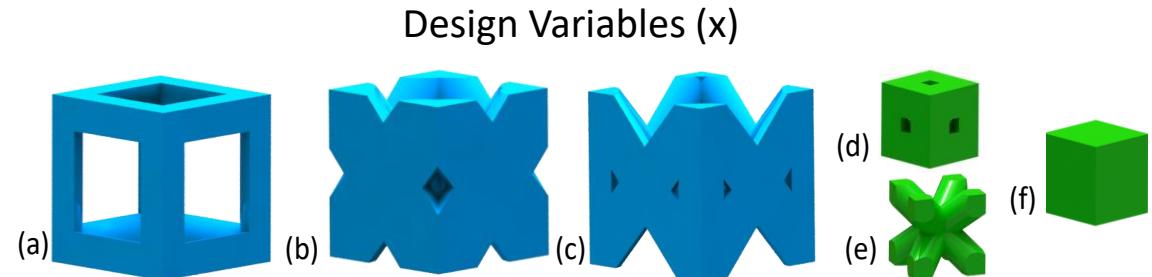
minimize $Q_{in} = Q(x)$,

subject to $KT = q$,
 $CU = F$,

$$\frac{\sigma_j^{PN}}{\sigma_y} \leq \sigma_{max},$$

$$U_z \leq U_{max}, \text{ and}$$

$$V(x) < V_{max}$$



Physical properties of the unit cells for Haynes 282

Size	Unit Cell	$K_{eff,z} \left[\frac{W}{mc} \right]$	$E_{eff,z} \left[GPa \right]$	$G_{xy} \left[GPa \right]$	$G_{xz}/G_{yz} \left[GPa \right]$	Volume $[mm^3]$
2 mm	(a) SC	1.54	30.8	2.92	2.92	1.82
	(b) FC	5.58	79.5	14.6	32.6	3.69
	(c) TR	2.96	31.3	2.07	1.39	3.02
1 mm	(d) sc	6.84	135	44.8	44.8	0.7839
	(e) bc ^{21,22,35}	3.79	39.4	26.7	26.7	0.5571
(f) sol		10.30	217	82.2	82.2	1

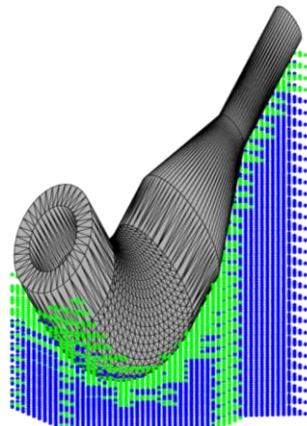
Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Voxel-Mesh Based Multi-Sized Unit Cell Approach

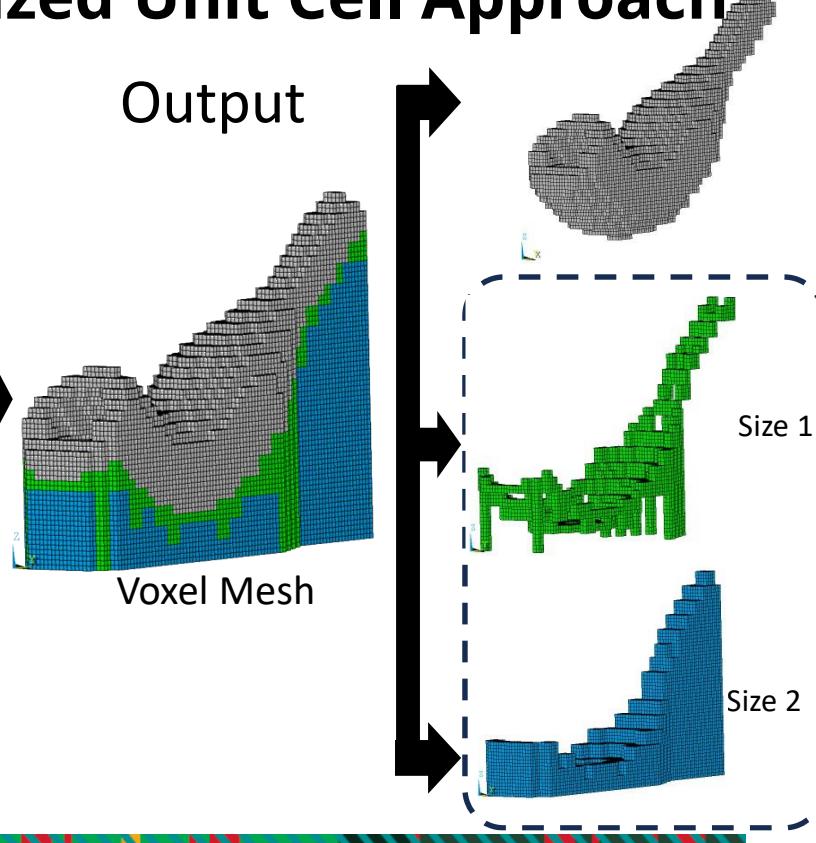
Input



Voxelization



Output



Part Domain +
Transition
Subdomains

Size 1

Bulk Support
Subdomain

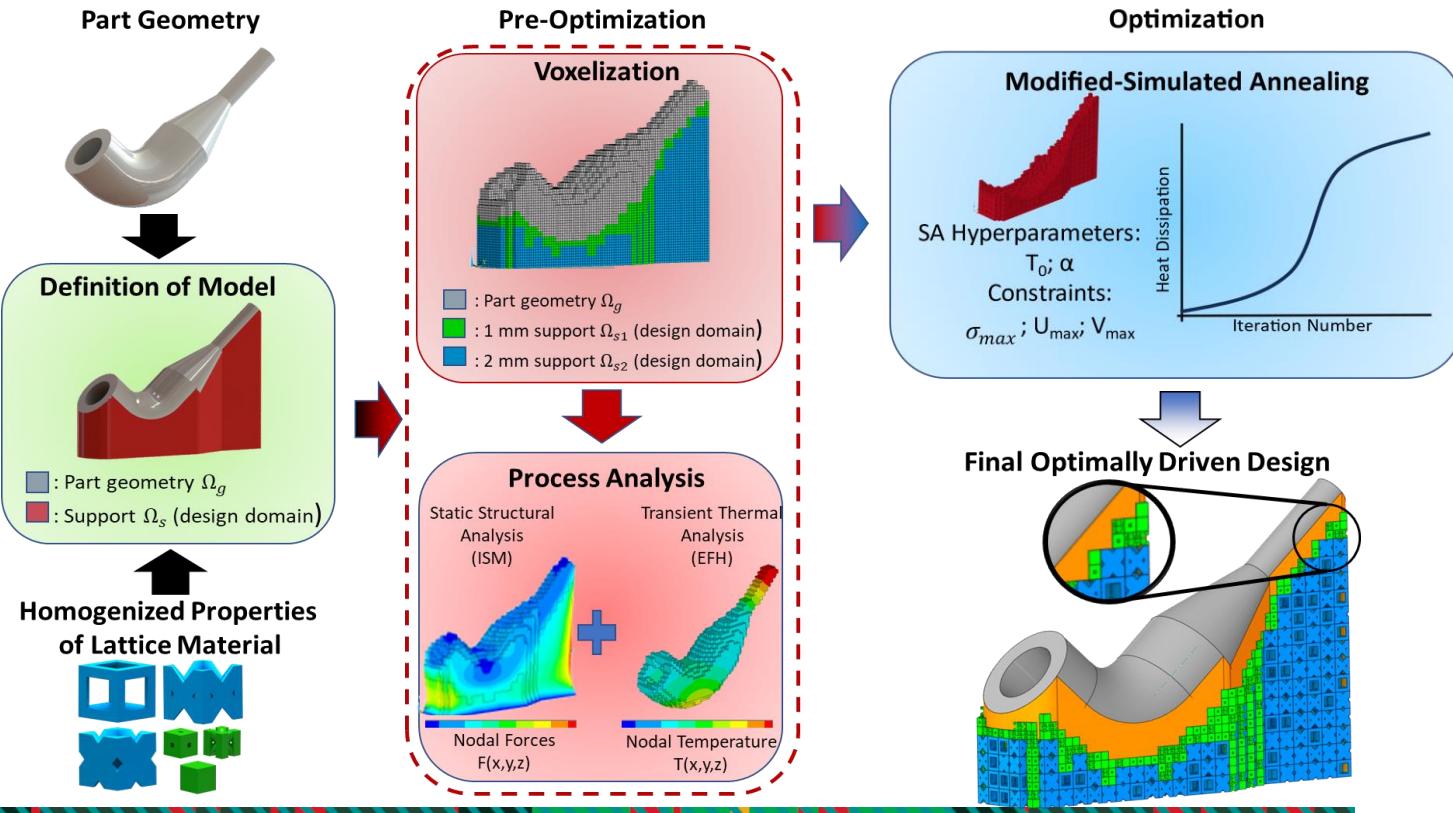
Size 2

- Convert to voxel³⁶
- Identify support domain
- Sort voxels based on unit size

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Flow Chart of Modified M-SAM

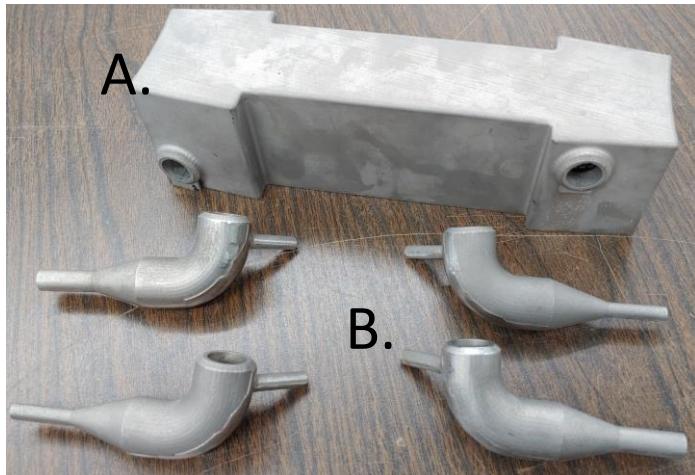
34



Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Case Study of Heat Exchanger Adapters

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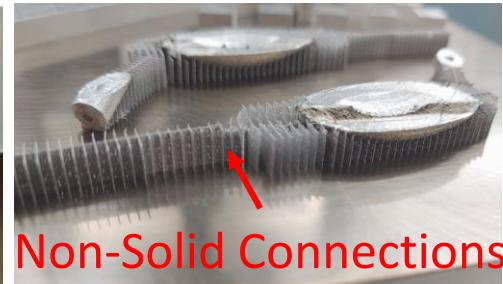
A. sCO₂ heat exchanger

B. Heat Exchanger Adapters

Failed
Prints



Line supports³⁷



Non-Solid Connections

Successful
Prints



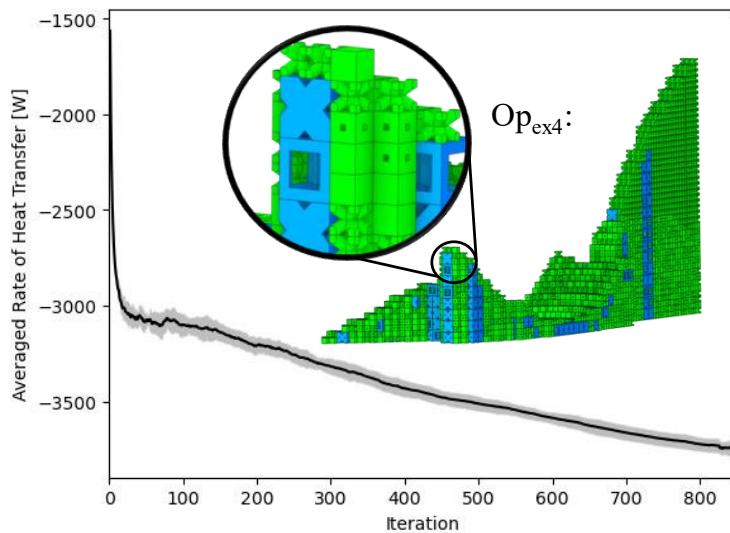
Solid Support

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Case Study of Heat Exchanger Adapter

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Iteration History of 30 runs



Objective = -3,742 W, Volume = 3,807mm³,
p-Norm = 0.08, U_{sum} = 18.24 mm

Comparison of support designs*

	Q _{in}	V(x)	P-norm Stress	Max(U _z) [μm]	SC/TR/FC sc/bv/sol	V(x) < 3,808 P-norm < 0.66 Max(U _z) < 40
Solid	6,470	7,617	0.053	4.6	--	No
SC Only	3,182	3,711	0.166	19.45	631/0/0 0/0/2,563	Yes
TR Only	3,756	4,468	0.108	13.07	0/631/0 0/0/2,563	No
FC Only	4,775	4,891	0.072	8.08	0/0/1,776 0/0/2,563	No
Op_{avg,4}	3,742 (38)	3,802 (8.8)	0.087 (0.004)	16.0 (0.51)	151/185/295 645/1,228/689 (6/12/11/18/16/21)	Yes

*standard deviation in ()

Compared
to SC Only



Average of ~16%
Heat Dissipation



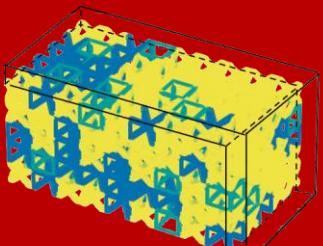
Average of ~19%
Distortion

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

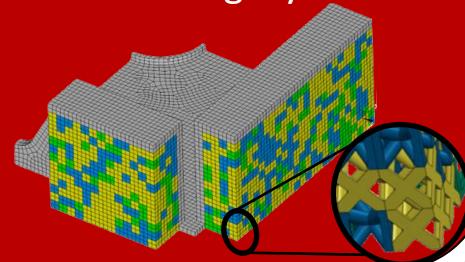
Summary

Question 1: How can designers *efficiently* find optimally directed lattice support structure solutions that improve heat dissipation while satisfying multiple AM constraints for LPBF?

Objective 1: A Modified Simulated Annealing Based Method to Design Thermally Conductive Hybrid Lattice Support Structures for LPBF

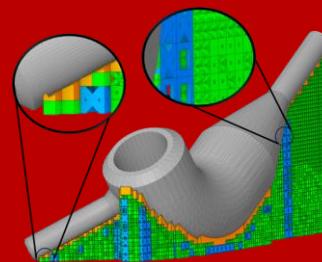


Objective 2: An Optimally Directed Lattice Support Structure Design Method for Heat Dissipation and Structural Integrity in LPBF



Question 2: How can lattice support structures be computationally designed to be *attached* to complex structures?

Objective 3: A Multi-Sized Unit Cell Approach to Design Lattice Support Structures for Complex Geometries



Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

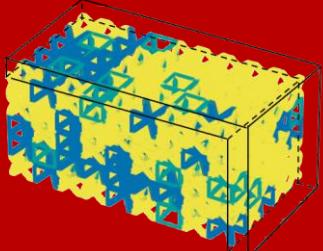
Contributions

1. Introducing a method to **increase efficiency** of non-gradient-based optimizers with reduced computational costs

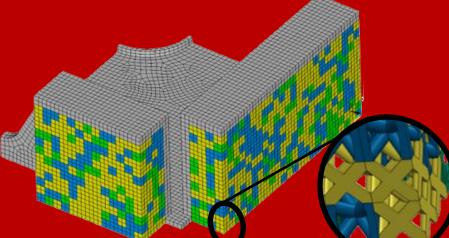
2. Establishing a method to incorporate both **thermal and structural** simulation-informed evaluations for lattice support structures

3. Developing an approach to broaden the application of lattice support structure to **complex geometries**

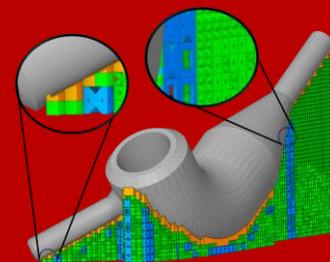
Objective 1



Objective 2



Objective 3

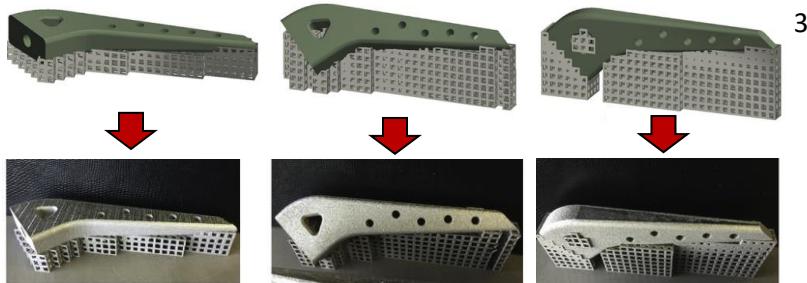


Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Future Work

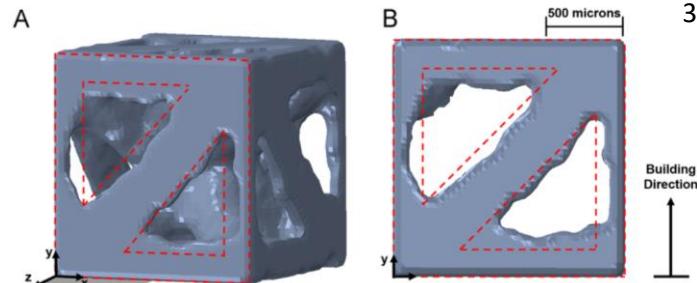
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Physical Structure Validation



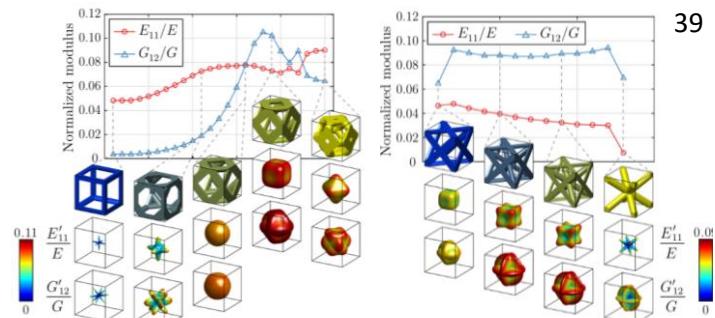
3

Evaluating Lattice Printability



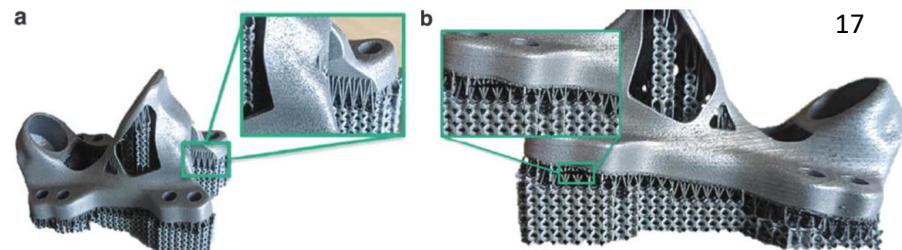
38

Guidelines for choosing pre-defined unit cells



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Parameterizing Transition Subdomain



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Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Acknowledgements

Supported by:



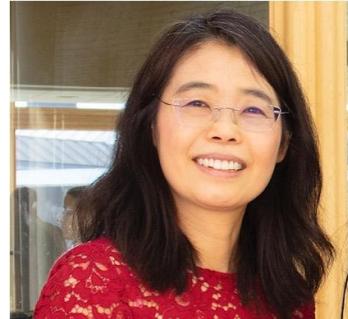
Integrated
Design
Innovation
Group

Carnegie Mellon University
Computational Bio-Modeling Lab

Committee:



Prof. Cagan



Prof. Zhang



Prof. Rollett



Dr. Zhang

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Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		
									42

**Thank you
Questions?**



Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

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Conference Papers

1. White, L., Liang, X., Zhang, G., Cagan, J., and Zhang, Y. J. "Coupling Simulated Annealing and Homogenization to Design Thermally Conductive Hybrid Lattice Support Structures for LPBF". Accepted in Proceedings of the ASME 2024 International Design Engineering Technical Conferences & Computers and Information in Engineering Conference, Boston, Massachusetts, 2023.
2. X. Liang, L. White, J. Cagan, A. D. Rollett, Y. J. Zhang. Design and Printability Evaluation of Heat Exchangers for Laser Powder Bed Fusion Process. ASME International Design Engineering Technical Conference & Computers and Information in Engineering Conference (IDETC/CIE). St. Louis, MI. Aug 14-17, 2022.

Journal Papers

1. White, L., Liang, X., Zhang, G., Cagan, J., and Zhang, Y. J. "A Modified Simulated Annealing-Based Method for Hybrid Lattice Support Structure Design in LPBF Additive Manufacturing". *Under review for Journal of Computing and Information Science in Engineering*, 2023.
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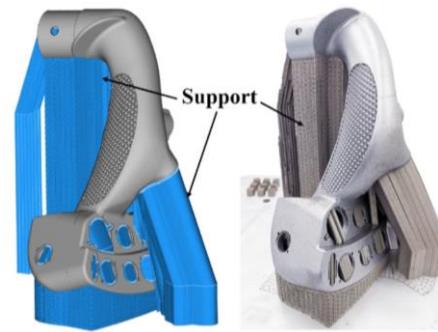
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Manufacturing of Metal Components^a

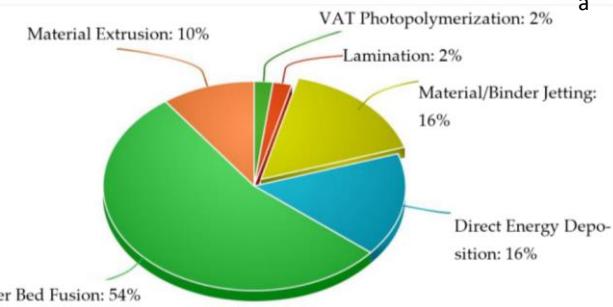
Manufacturing Method	Pros	Cons	Examples
Conventional Manufacturing (Subtractive in nature)	<ul style="list-style-type: none"> ✓ Mass Manufacturing ✓ Mature 	<ul style="list-style-type: none"> - Simple geometry - High material waste - Specialized tooling 	<ul style="list-style-type: none"> • Milling • Die-casting • Laser cutting
Additive Manufacturing (Additive in nature)	<ul style="list-style-type: none"> ✓ Complex geometry ✓ Reduced delivery costs ✓ Inventory stock reduction ✓ Mass customization ✓ No specialized tooling 	<ul style="list-style-type: none"> - Initial start-up costs - Limited materials - Slow build time 	<ul style="list-style-type: none"> • Directed Energy Deposition • Material Extrusion • Powder Bed Fusion



b



c



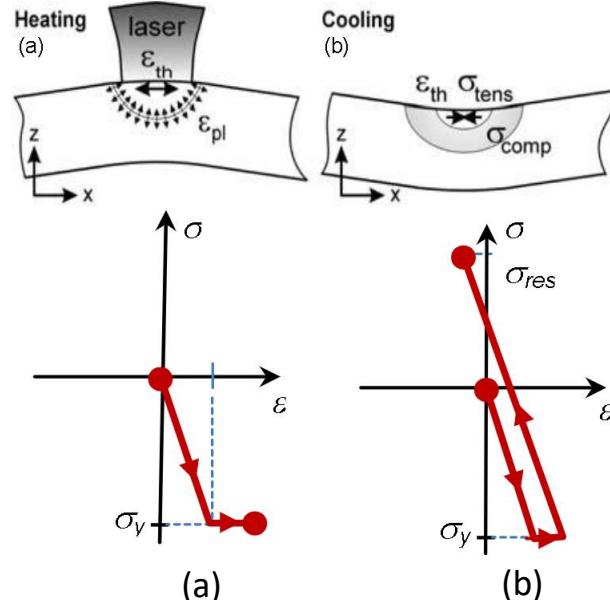
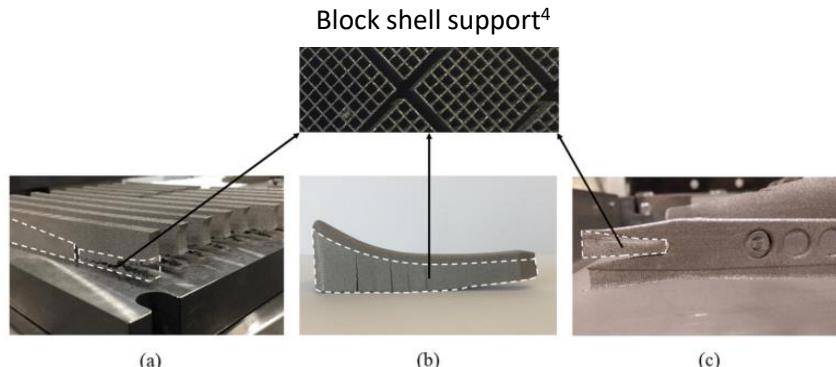
a

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Geometric Inaccuracy: Residual Stress

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- Thermal Cycle³
 - Rapid heating with steep gradients
 - Rapid solidification with high cooling
 - Melt-back involving simultaneous melting and remelting



Model of one layer of stress for laser powder bed fusion (a) Heating phase and (b) cooling phase³

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Support Structures

49

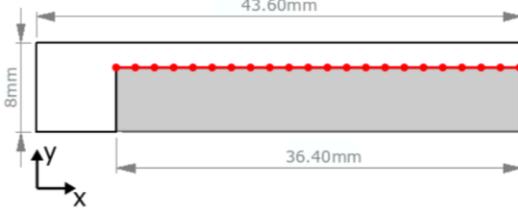
Purpose^{5,9}:

- **Dissipate Heat**^{6,9,10}
- Maintenance of structural integrity^{4,7,11}

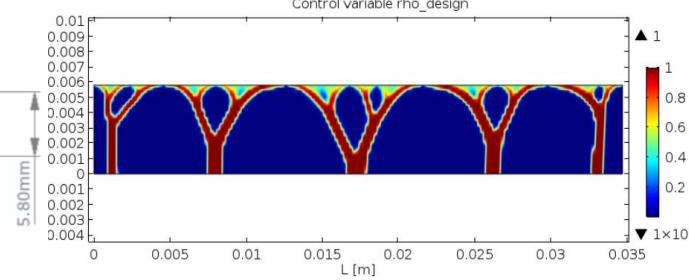
Methods to generate Support structures

- Topology Optimization for arbitrary states^{6,7,11}
- Lattice Structures^{5,8-10}

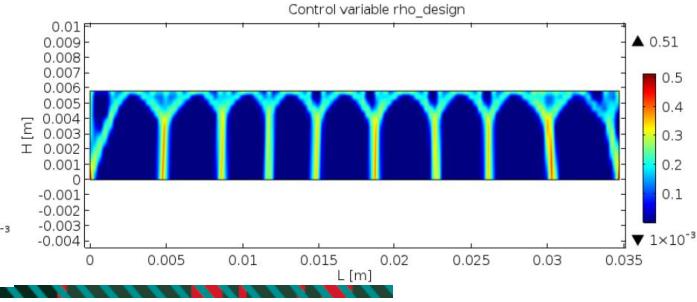
Cantilever Beam^{6,7}



Design for heat dissipation⁶



Design for structural compliance⁷



Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3			Conclusions
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2	Obj. 3.3	

Gradient-Based Optimizers

50

Pros:

- Faster convergence
- Local solution search

Cons:

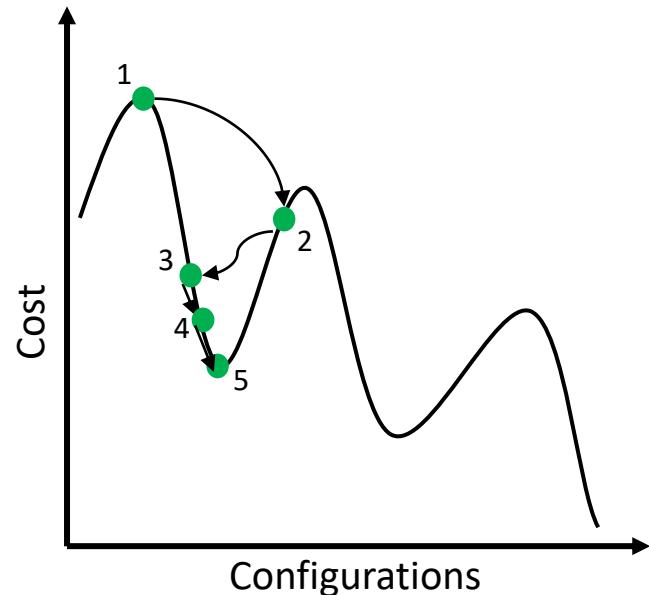
- More likely to get in a local optima
- Require differentiable design variables

Examples:

- Gradient Descent
- Method of Moving Asymptotes

Applications in Lattice Support Structure Design :

- Minimizing compliance
- Minimizing mean temperature
- Minimizing temperature gradient



Non-Gradient-Based Optimizers

Pros:

- Do not require differentiable design variables
- Ideally a global solution search

Cons:

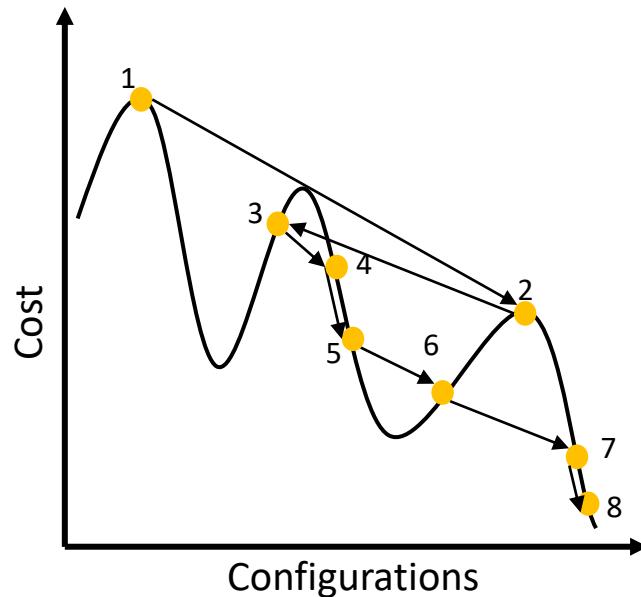
- Computationally expensive

Examples:

- Genetic Algorithms
- Simulated Annealing

Applications in Lattice Support Structure Design :

- Minimizing compliance



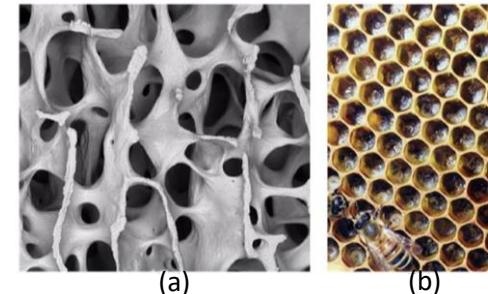
Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Lattices

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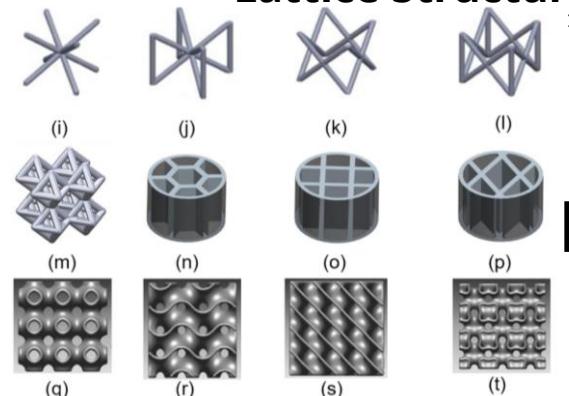
Artificial microscopic structures with strategically designed geometry to control properties on the macroscopic level^{12,13}

Lattice Structures in Nature¹²

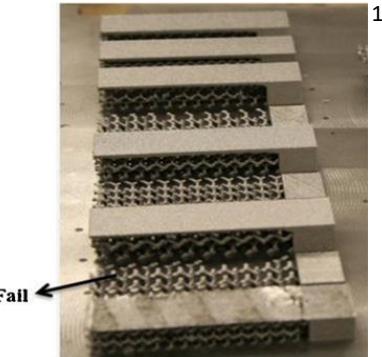


Lattice Support Structures¹²⁻¹⁴

- Self-supporting structure
- Light-weight design
- Tailorable physical properties
- Ease of powder removal

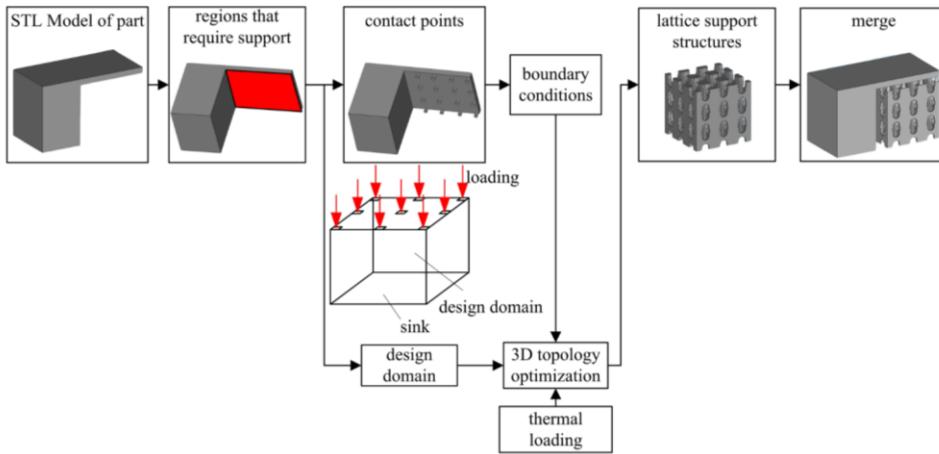


Lattice Structures for AM¹²



Existing Gradient-Based-Optimizers

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Optimizer: Method of Moving Asymptotes

Problem

Minimize thermal compliance w.r.t material elements

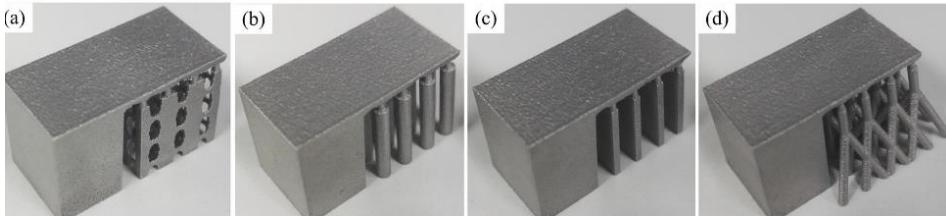
s.t. volume

Advantages:

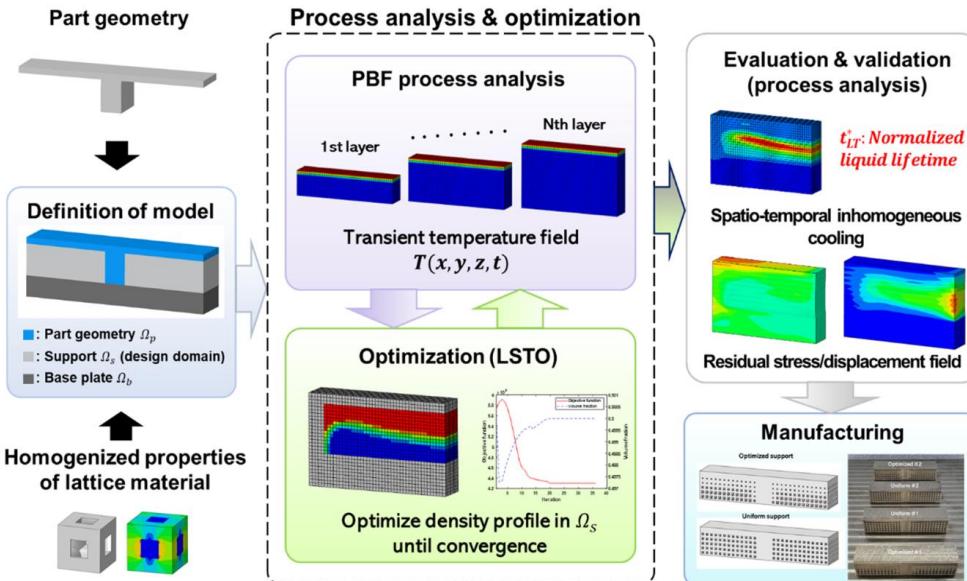
- Fast evaluation using homogenization approximation
- Least amount of vertical warpage than the standard designs (b-d)

Disadvantages:

- Does not consider spatio-temporal inhomogenization



Existing Gradient-Based-Optimizers



Optimizer: Method of Moving Asymptotes

Problem:

Minimize temperature gradient w.r.t cell density
s.t. volume

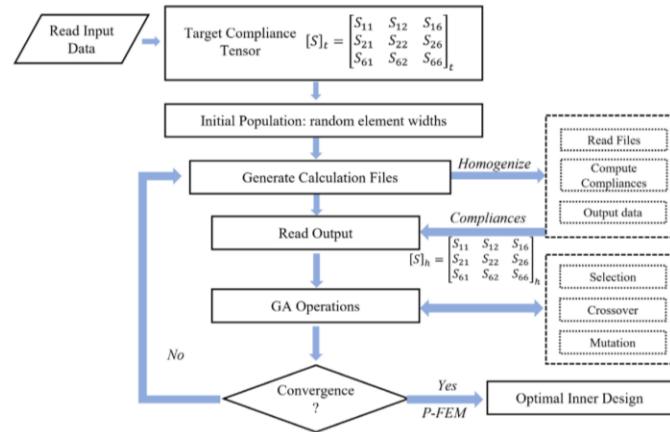
Advantages:

- Fast evaluation using homogenization approximation
- Captures spatio-temporal homogenization
- 47% reduced stress

Disadvantages:

- Sensitivity Analysis Approximations
- Demonstrated only on simple geometry
- Limited consideration of Design Constraints

Existing Non-Gradient-Based Optimizers



Optimizer: Genetic Algorithm

Problem:

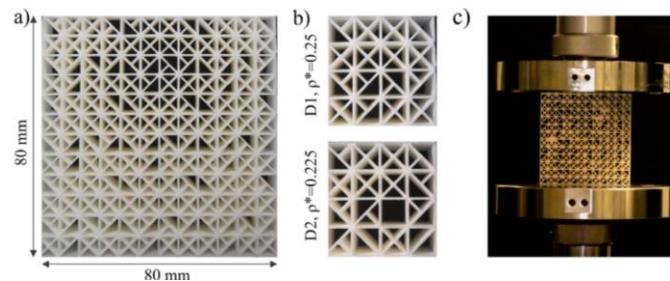
Minimize structural compliance w.r.t cell geometry
s.t. volume

Advantages:

- Fast evaluation using homogenization approximation
- Hybrid lattice structures

Disadvantages:

- Only planar optimization
- Does not consider use as metal support structure

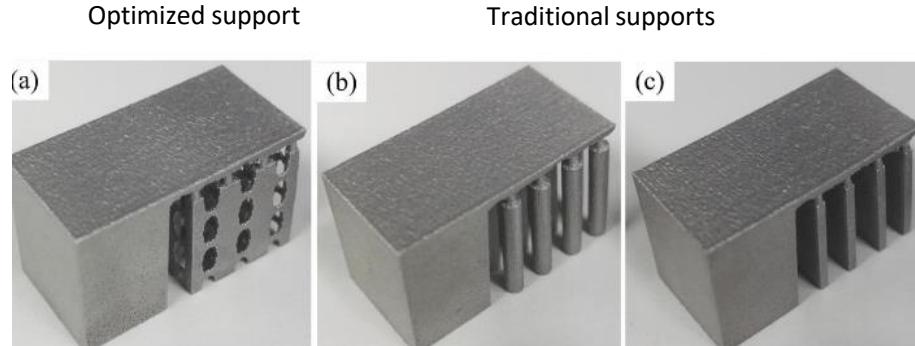


Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Existing Optimizer Method to Design Heat Dissipating Lattice Support Structures

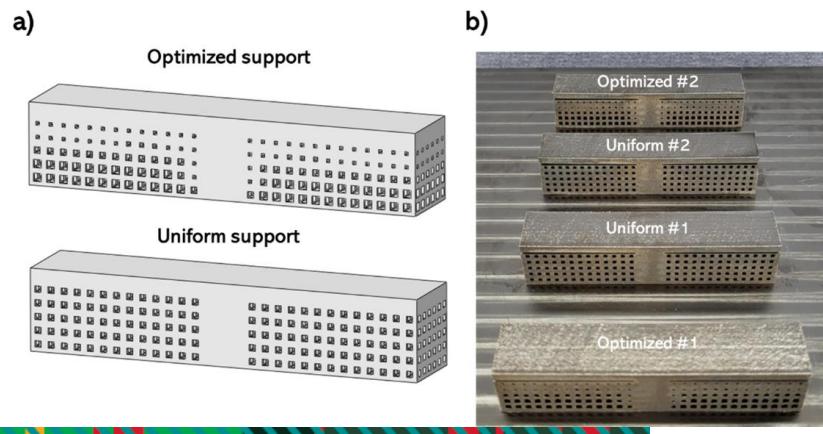
Optimize periodic unit cell^{9,14}

- Minimize thermal compliance⁹
 - Did not consider non-uniform heat distribution

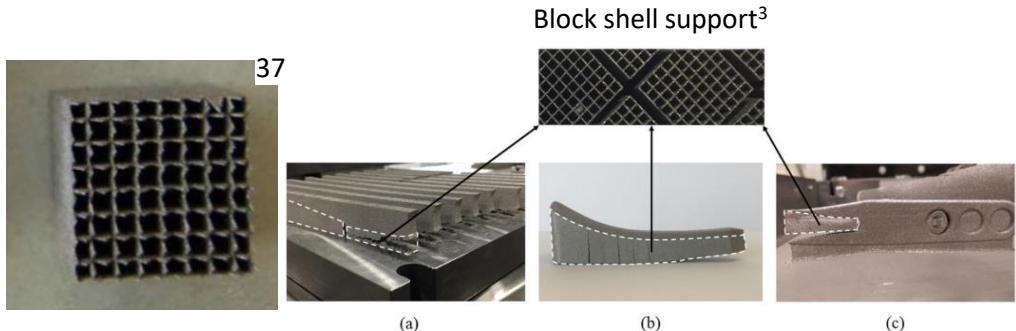


Optimize density distribution^{4,10,11,19}

- Minimize thermal gradient w.r.t density¹⁷
 - Accumulated error from approximations
 - Limited AM constraints

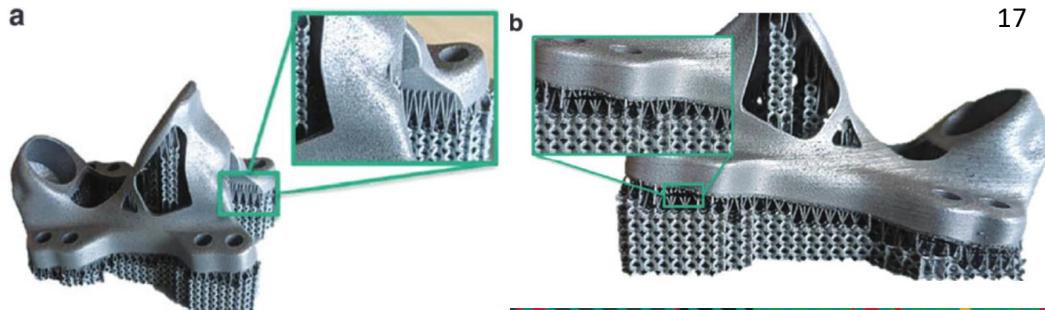


Existing Designs for Lattice Support Structures Connection to Complex Geometries



Non-Solid Connections

- ✓ Reduced material cost
 - ✓ Easily removable
 - ✓ Found in commercial software
 - Poor for large overhangs
 - Trap unused powder



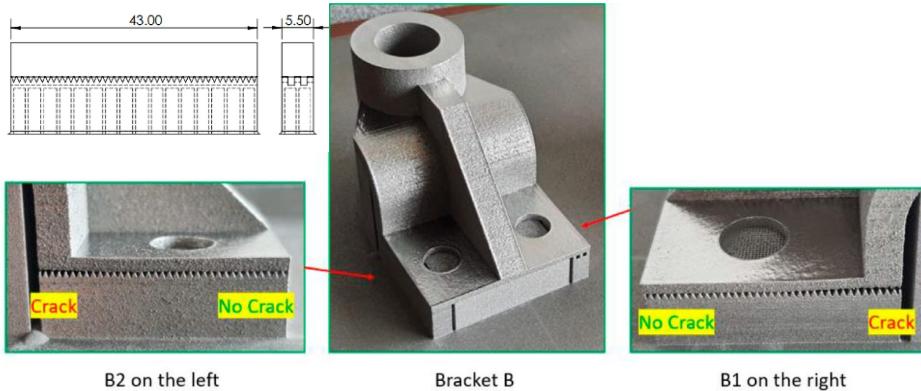
Pin Connections

- ✓ Increased connection to part
 - ✓ Simple geometry
 - High computational cost to optimize

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Existing Designs for Lattice Support Structures Connection to Flat Geometries

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Tooth Connections

- ✓ Reduced material cost
- ✓ Easily removable
- Reduced flexibility on spacing
- Not shown to work with hybrid lattices

Research Gaps

1. Restricting types of manufacturable unit cells limits the types of AM constraints that can be considered, such as using a varying density of a simple cubic cell
2. Nondifferentiable lattices make it difficult for gradient-based optimizers to fully explore the design space and can lead to inaccuracies due to accumulating approximations.
3. High computation time is a major limitation for using non-gradient-based optimizers, particularly with powerful methods such as simulated annealing (SA).



Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3			Conclusions
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2	Obj. 3.3	

Defining Constraints

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Volume

Material Waste

- Support structure is sacrificial for LPBF
- Cost of powder

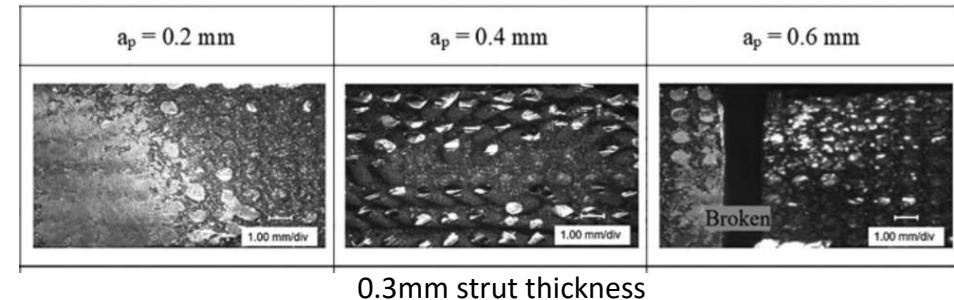
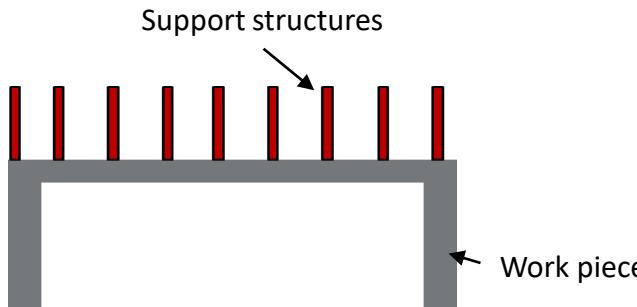
Build time

- Laser scanning

Interfacial area

- Post-processing costs
 - Existing methods
- Surface roughness
 - cost
- Thin features

Removal of support structure by depth of cut (a_p)^k:



Equivalent Flash Heating Method

Heating

$$\begin{cases} \rho c \frac{dT_i(t, x)}{dt} = \nabla \cdot (k \nabla T_i(t, x)) + q(x) \\ - (k \nabla T_i(t, x)) \cdot n = h \nabla T_i(t, x) \\ T_i(t, x) = T_{base} \\ T = T_{powder} \end{cases}$$

in $(0, t_h) \times \Omega_A$
 on $(0, t_h) \times \Omega_A / \Omega$
 on $(0, t_h) \times \Omega_b$
 In φ_A

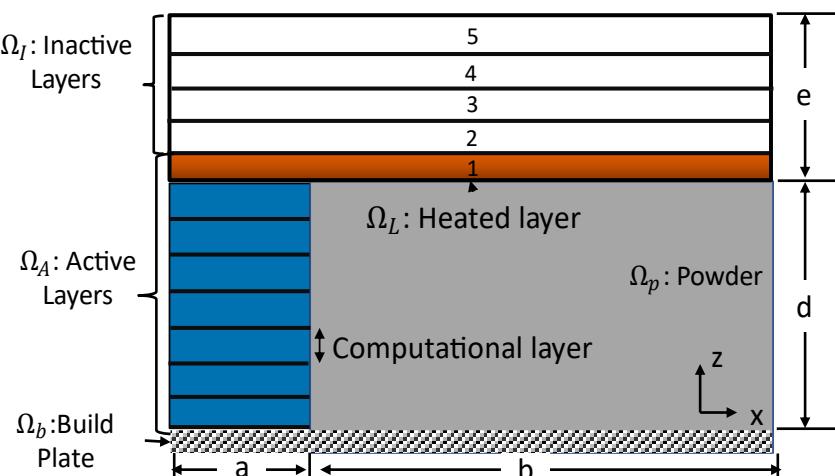
Ω_I : Inactive
Layers

Cooling

$$\begin{cases} \rho c \frac{dT_i(t, x)}{dt} = \nabla \cdot (k \nabla T_i(t, x)) + q(x) \\ - (k \nabla T_i(t, x)) \cdot n = h \nabla T_i(t, x) \\ T_i(t, x) = T_{base} \\ T = T_{powder} \end{cases}$$

in $(0, t_c) \times \Omega_A$
 on $(0, t_c) \times \Omega_A / \Omega_b$
 on $(0, t_c) \times \Omega_A / \Omega_b$
 in $(0, t_c) \times \Omega_A$

$$q(x) = \begin{cases} q & \text{for } x \in \Omega_I \\ 0 & \text{otherwise} \end{cases}$$

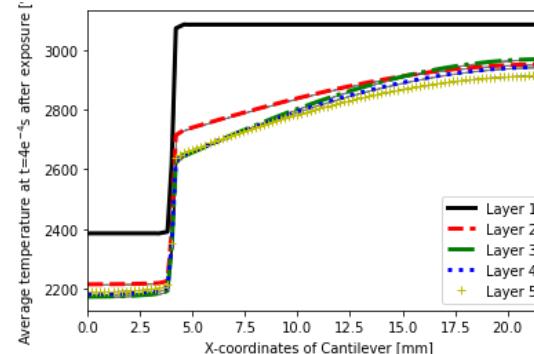


Equivalent Flash Heating Method

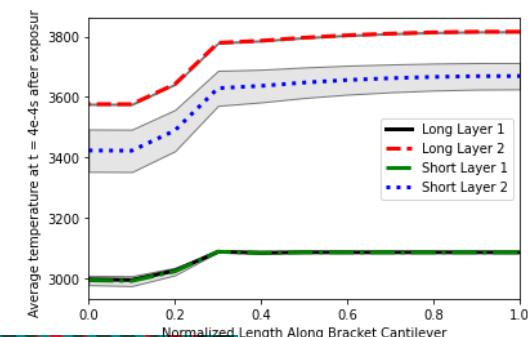
62

Process Parameter	Value
Volume heat flux, $q [W/m^3]$	1.96×10^{13}
Convection Coefficient for heat loss to environment, $h_{side} [W/m^2\text{°C}]$	100
Convection Coefficient for heat loss to build plate, $h_{plate} [W/m^2\text{°C}]$	8000
Heating time per layer, $t_h [\text{s}]$	4×10^{-4}
Cooling time per layer, $t_c [\text{s}]$	5
Build plate temperature, $T_{amb} [\text{°C}]$	20
Inherent strain vector in x, y, z	-0.016,-0.016, 0.014

Cantilever Beam

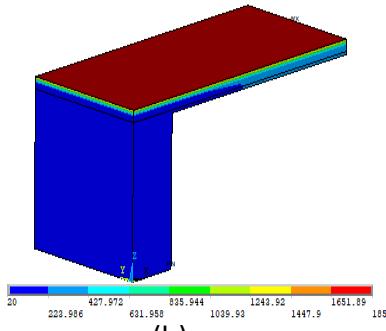
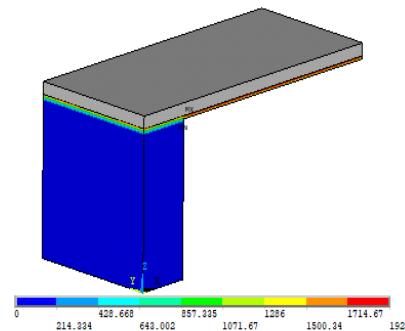


Aerospace Bracket

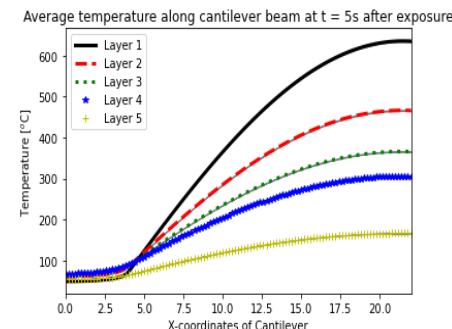
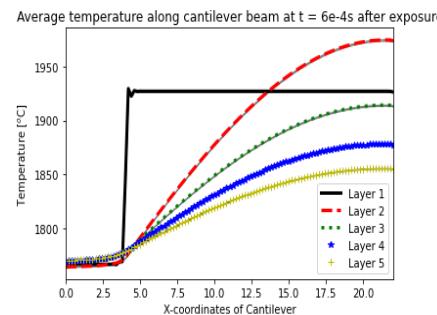
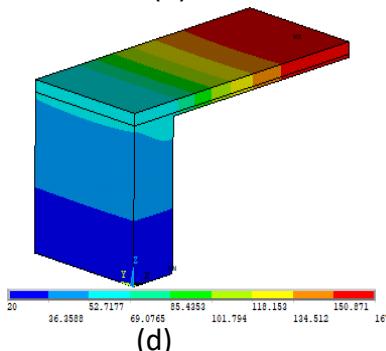
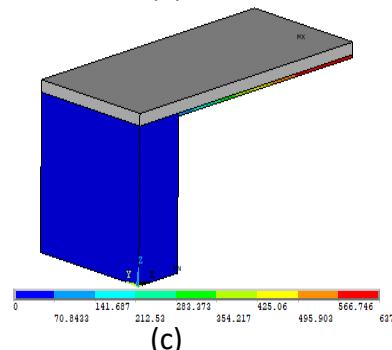


Equivalent Flash Heating Method

Heating



Cooling

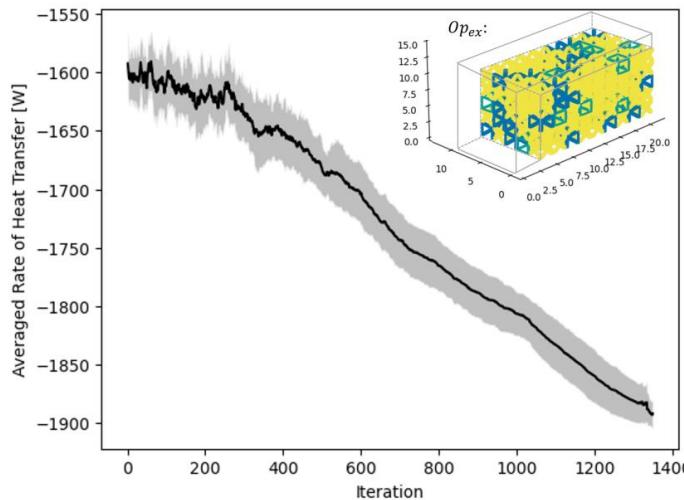


Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Case Study of Cantilever Beam: Validation

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Iteration History of 30 runs



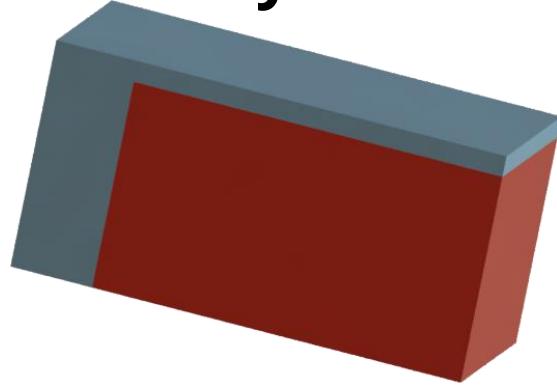
Op_{ex} : Objective = -1,900 W, Volume = 615 mm³,
Area = 106 mm².

Stages	Traditional SA	M-SAM
Exploration	1	Total
Intermediate	1	Total/100
Fine-Tuning	1	Total/200

Analysis Model	Simulation	SC Only	BV Only	FC Only	Op_{ex}
Steady-state	$Q_{in,h}[W]$	-1,196	-1,607	-2,124	-1,608
	$Q_{in,exact}[W]$	-1,198	-1,605	-2,132	-1,647
Transient	$t_s[s]$	3.25	2.18	1.38	1.45

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Case Study of Cantilever Beam



Design variables: 225

possible configurations: 3^{225}

Evaluation time per iteration: ~3s

SA Hyperparameters: $T_0 = 50$; $\alpha = 0.5$

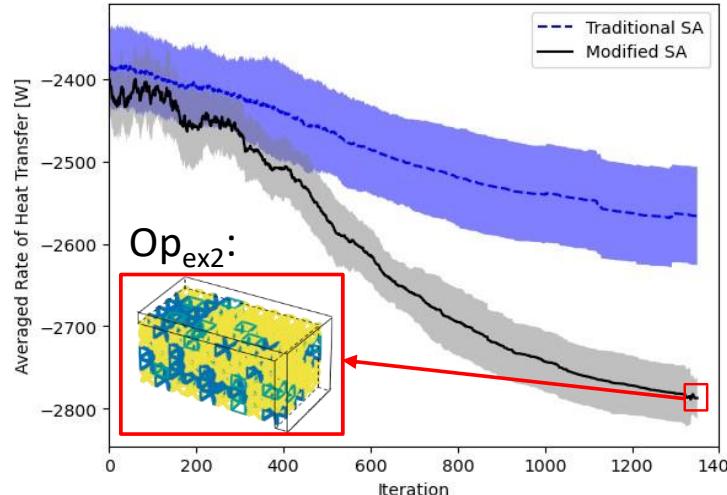
$$V_{\max} = 0.4 * V_{\text{solid}} \approx 750 \text{ mm}^3$$

$$A_{\max} = 0.55 * A_{\text{solid}} \approx 140 \text{ mm}^2$$

$$\sigma_{\text{Max}}^{\text{PN}} = 1/1.5 = 0.66$$

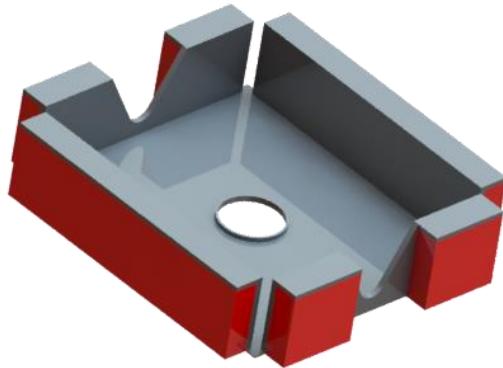
$$U_{z,\max} = \text{Layer}/\rho_{\text{shr}} = 32 \mu\text{m}$$

Iteration History of 30 runs



Stages	Traditional SA	M-SAM
Exploration	1	Total
Intermediate	1	Total/100
Fine-Tuning	1	Total/200

Case Study of Aerospace Bracket



Design variables: 1,776

possible configurations: $3^{1,776}$

Evaluation time per iteration: ~3s

SA Hyperparameters: $T_0 = 50$; $\alpha = 0.5$

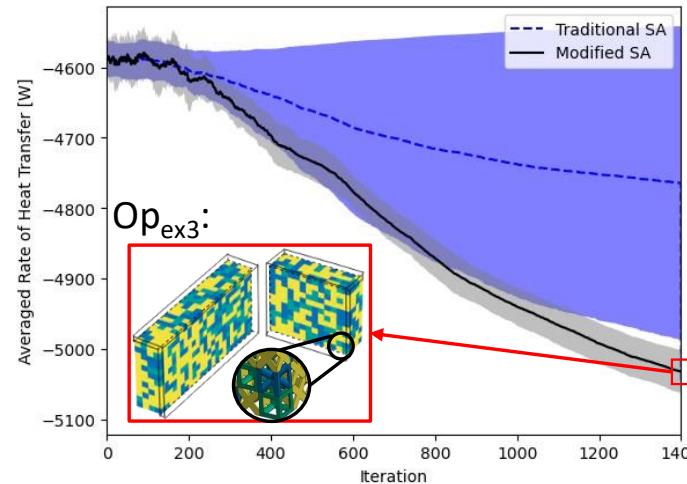
$$V_{\max} = 0.4 * V_{\text{solid}} \approx 5,900 \text{ mm}^3$$

$$A_{\max} = 0.55 * A_{\text{solid}} \approx 1360 \text{ mm}^2$$

$$\sigma_{\text{Max}}^{\text{PN}} = 1/1.5 = 0.66$$

$$U_{z,\max} = \text{Layer}/\rho_{\text{shr}} = 76 \mu\text{m}$$

Iteration History of 30 runs

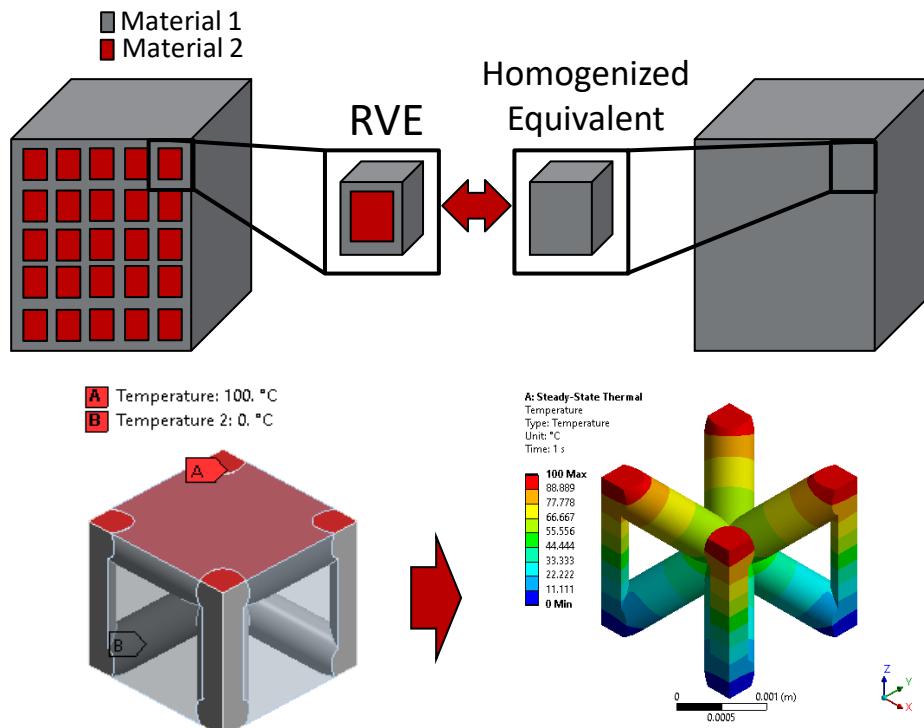


Stages	Traditional SA	M-SAM
Exploration	17	Total
Intermediate	17	Total/100
Fine-Tuning	17	Total/200

Motivation	Purpose/ Aims	Objective 1	Objective 2	Objective 3	Conclusions				
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2	Obj. 3.3	

Asymptotic Homogenization

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Let $y=x/\beta$

Double-scale asymptotic expansion

$$T(x, y) = \underbrace{T_0(x, y)}_{\text{Exact Solution}} + \underbrace{\beta T_1(x, y)}_{\text{Average}} + \underbrace{\beta^2 T_2(x, y)}_{\text{Perturbations from microstructure}} + \dots$$

Governing equations:

$$\begin{cases} k\nabla^2 T(x, y) + f = 0 & \text{(Steady-state heat)} \\ q(x, y) = -k\nabla T(x, y) & \text{(Fourier's Law)} \end{cases}$$

Effective thermal conductivity (K_{ijkl}^{eff})

$$K_{ijkl}^{eff} = \frac{1}{V_{RVE}} \int_{V_{RVE}} K_{ijmn} M_{mnkl} d$$

Conductivity of unit cell (K_{ijmn})

Structure Tensor (M_{mnkl})

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3			Conclusions
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2	Obj. 3.3	

P-Norm Stress

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$$\sigma_j^{PN}(x) = \left(\frac{1}{N_j} \sum_{a \in \Omega_j} (\sigma_a^{vM}(x))^p \right)^{\frac{1}{p}}$$

- Minimizes stress concentrations
- Global and local search
- Stress-level technique
- $\sigma_j^{PN} > \sigma_y$:= plastic deformation
- $\sigma_j^{PN} < \sigma_y$:= elastic deformation

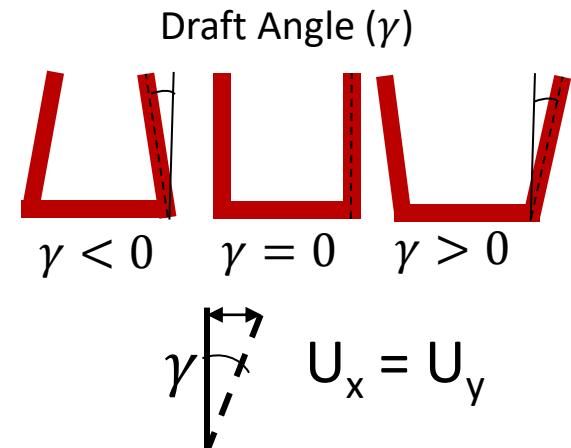
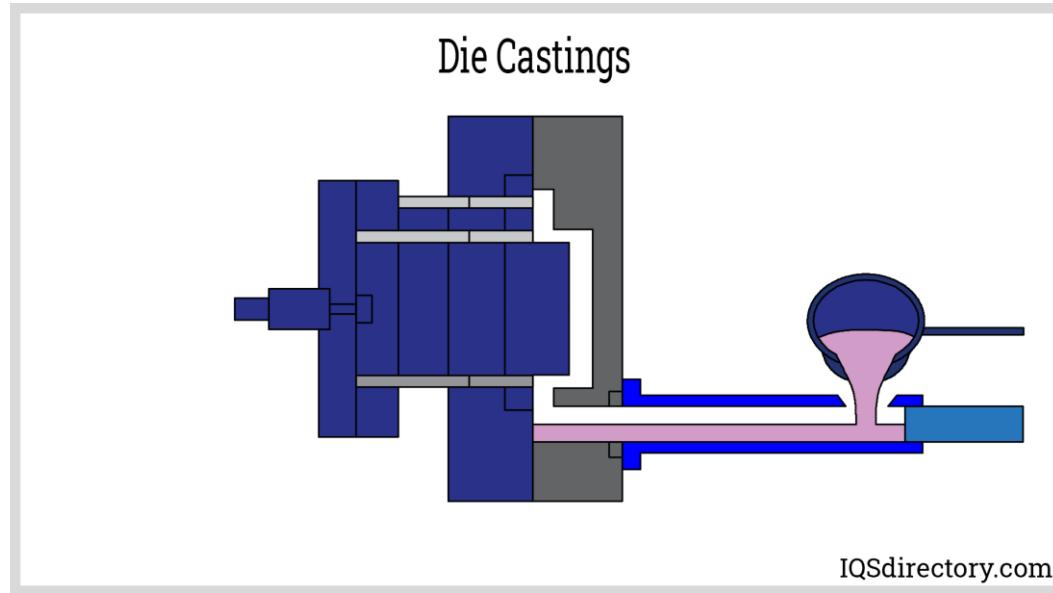
$$\begin{array}{ccc} \text{Cluster 1} & \text{Cluster 2} & \text{Cluster } n_c \\ \overbrace{\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_{\frac{n_e}{n_c}}}^{} \geq \dots \geq \overbrace{\sigma_{\frac{2n_e}{n_c}} \geq \dots \geq \sigma_{\frac{n_e}{n_c}}}^{} \end{array}$$



Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3			Conclusions
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2	Obj. 3.3	

Die Casting

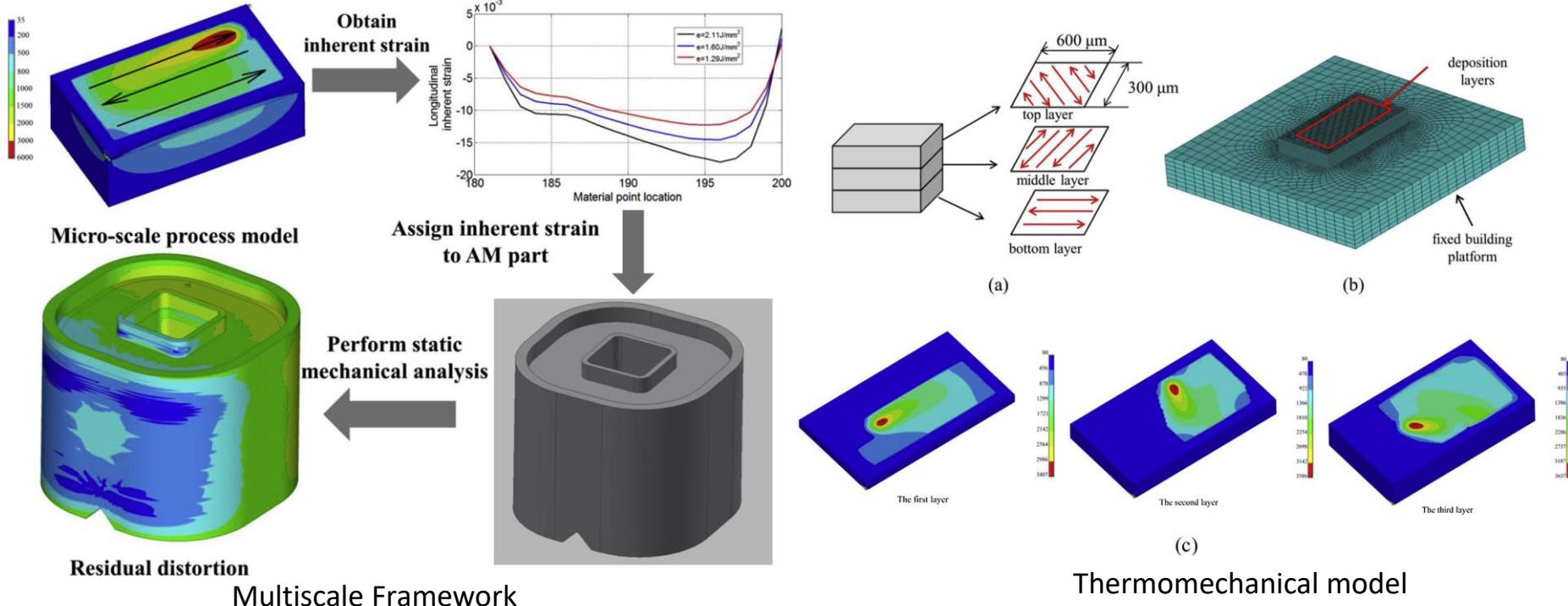
69



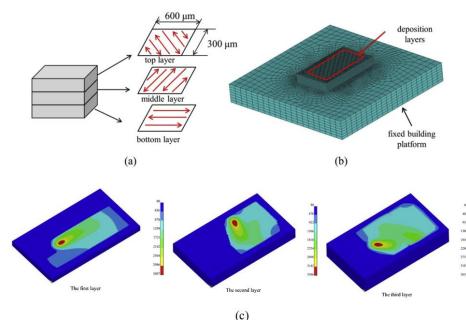
Motivation	Purpose/ Aims	Objective 1	Objective 2	Objective 3	Conclusions				
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2	Obj. 3.3	

Inherent Strain Method (ISM)

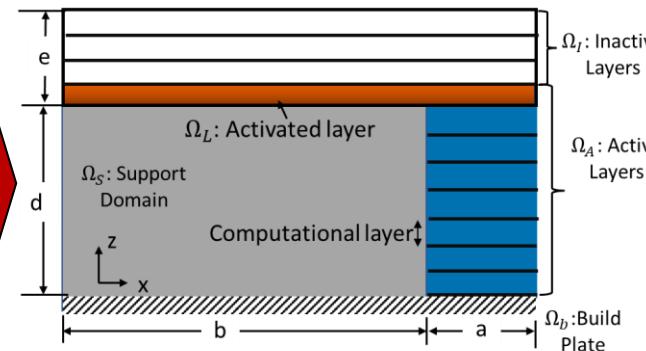
70



Inherent Strain Method (ISM)



$$\varepsilon^{inh} = \begin{cases} \varepsilon_{xx} \\ \varepsilon_{yy} \\ \varepsilon_{zz} \end{cases}$$



Governing equation:

$$\left\{ \begin{array}{l} \nabla \cdot \sigma_i = 0 \\ \sigma_i = C \varepsilon_e^i \\ \varepsilon_{tot}^i = \varepsilon_e^i + \varepsilon_p^i + \varepsilon_{in}^i \end{array} \right.$$

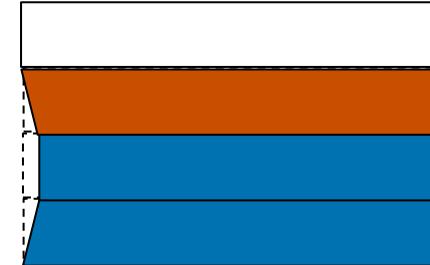
Inherent
Strain
Method



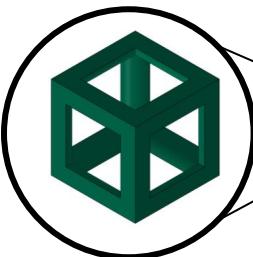
i=2



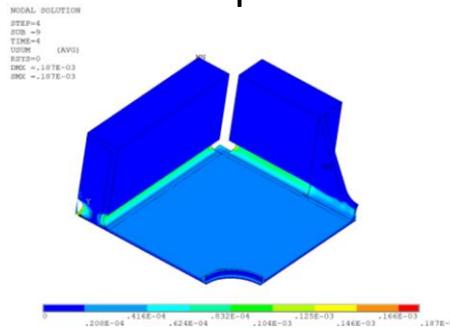
i=3



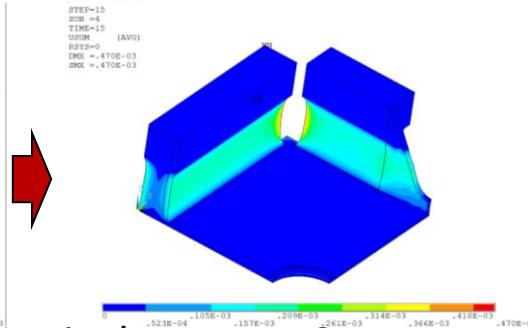
ISM of Bracket



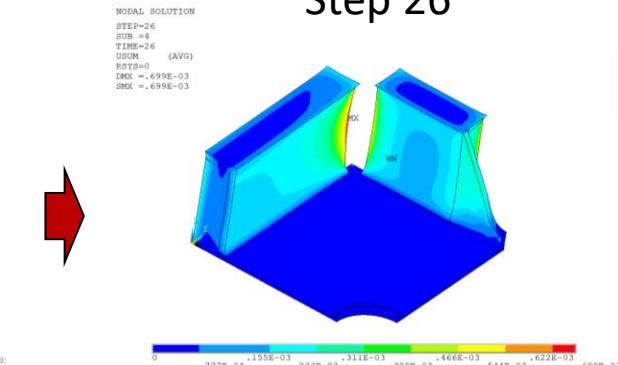
Step 4



Step 15



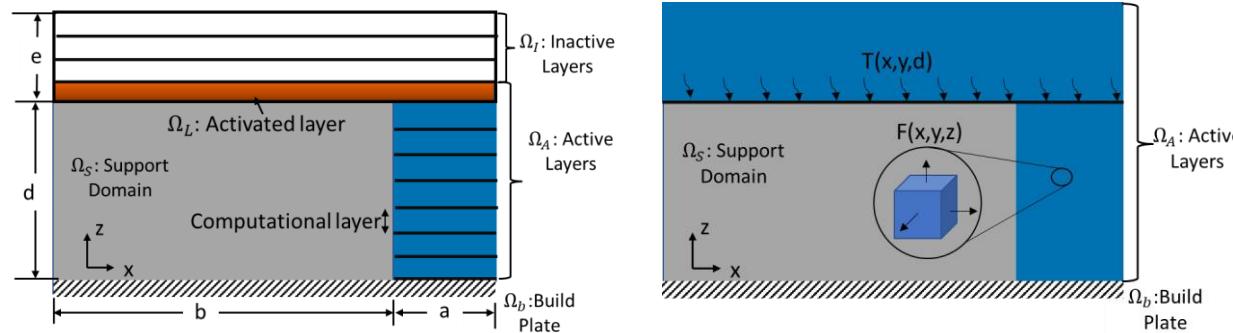
Step 26



Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3			Conclusions
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2	Obj. 3.3	

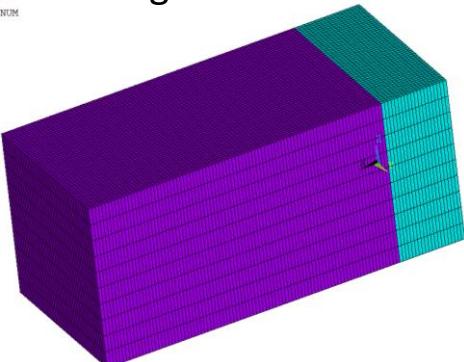
Equivalent Static Load Sub-models

73



Part

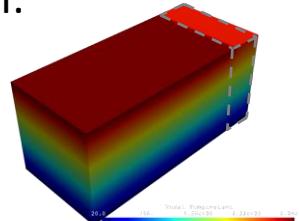
Design Domain



Steady-State Thermal

Governing equation:

$$\left\{ \begin{array}{l} \nabla \cdot (K \nabla T) + q = 0 \\ T(x, y, 0) = T_{base} \\ T(x, y, d) = T_{source} \end{array} \right.$$

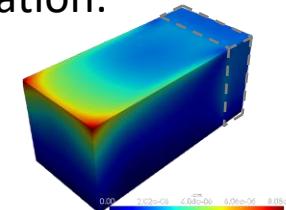


Example Temperature
Results

Static Structural

Governing equation:

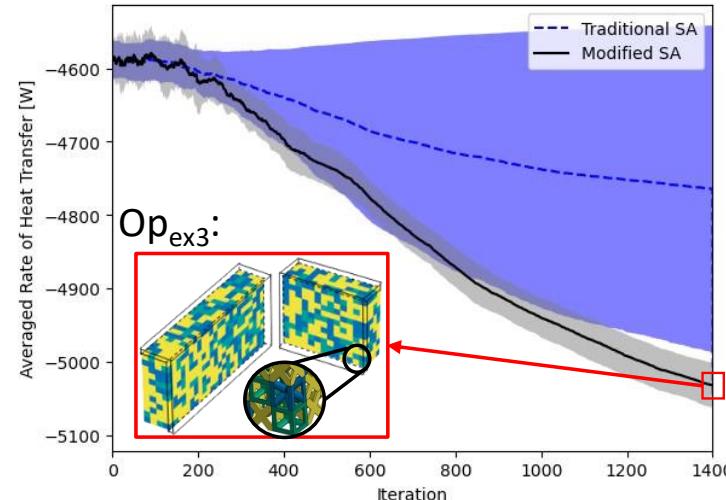
$$\left\{ \begin{array}{l} \nabla \cdot \sigma + F = 0 \\ U(x, y, 0) = 0 \end{array} \right.$$



Example Displacement
Results

Case Study of Aerospace Bracket

Iteration History of 30 runs



Objective = -5,039 W, Volume = 5,481 mm³,
 Area = 1,243 mm², p-Norm = 0.648, U_{sum} = 69.7
 mm

Comparison of support designs*

Q _{in}	V(x)	A(x)	P-norm Stress	Max(U _{sum}) [μm]	SC/BV/FC	V(x) < 5,900 A(x) < 1,360 P-norm < 0.66 Max(U _{sum}) < 76
Solid	12,479	14,208	2,368	0.609	14	--
SC Only	3,524	3,232	1,367	0.648	96.0	1,776/0/0
BV Only	4,624	5,008	66	0.648	97.5	0/1,776/0
FC Only	6,004	6,553	1,568	0.637	74.7	0/0/1,776
Op _{avg,3}	4,902 (29.4)	5,315 (36.2)	1,222 (13.7)	0.643 (0.0037)	72.8 (2.3)	388/589/799 (16/20/30)

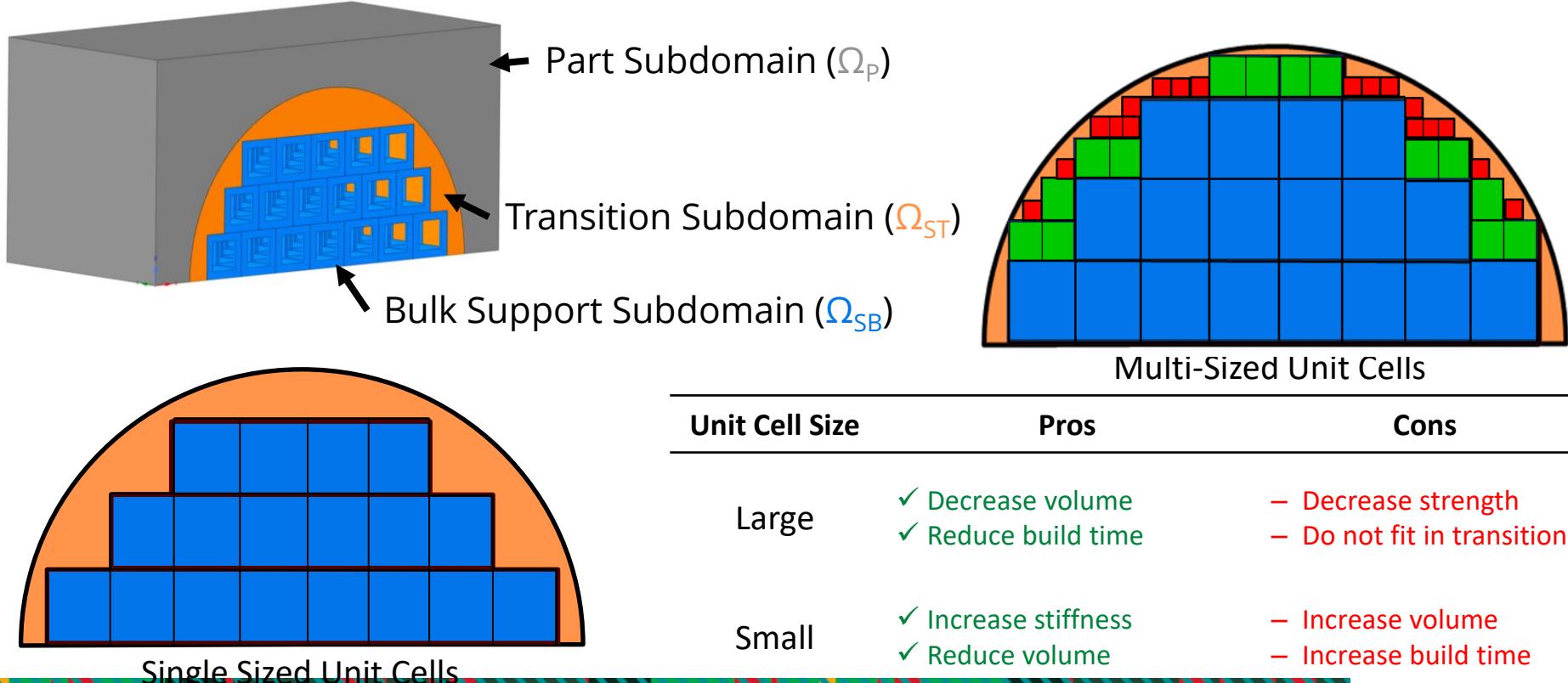
*standard deviation in ()

Cost Comparison
 Cost of Haynes 282³⁹: \$145/kg
 $\rho_{\text{Haynes282}}: 8.29 \text{ g/cm}^3$
 Cost Savings
 (Solid Support)
\$13,527*

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Reducing Material Waste using Multi-Sized Unit Cells

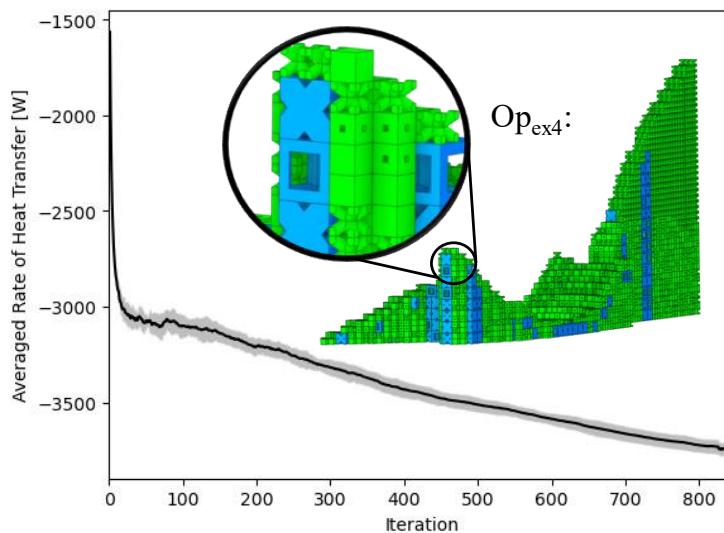
75



Case Study of Heat Exchanger Adapter

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Iteration History of 30 runs



Objective = -3,742 W, Volume = 3,807mm³,
 p -Norm = 0.08, U_{sum} = 18.24 mm

Comparison of support designs*

	$ Q_{in} $	$V(x)$	P-norm Stress	$\text{Max}(U_z)$ [μm]	SC/TR/FC sc/bv/sol	$V(x) < 3,808$ P -norm < 0.66 $\text{Max}(U_z) < 40$
Solid	6,470	7,617	0.053	4.6	--	No
SC Only	3,182	3,711	0.166	19.45	631/0/0 0/0/2,563 0/63/0	Yes
TR Only	3,756	4,468	0.108	13.0	0/0/2,562 0/0/1,776 0/0/2,563	No
FC Only	4,775	4,891	0.072	8.08	0/0/2,563	No
$Op_{avg,4}$	3,734 (37)	3,801 (9.6)	0.087 (0.004)	16.0 (0.53)	151/185/295 645/1,228/689 (6/12/11/18/16/21)	Yes

*standard deviation in ()

Cost Comparison
 Cost of Haynes 282³⁹: \$145/kg Cost Savings
 $\rho_{\text{Haynes282}}$: 8.29 g/cm³ (Solid Support)
\$1,301*

Reducing Size + Forced Flat Domain

3 sizes:

10 mm

- Low volume
- Low compliance

5 mm

2.5 mm

- High volume
- High compliance

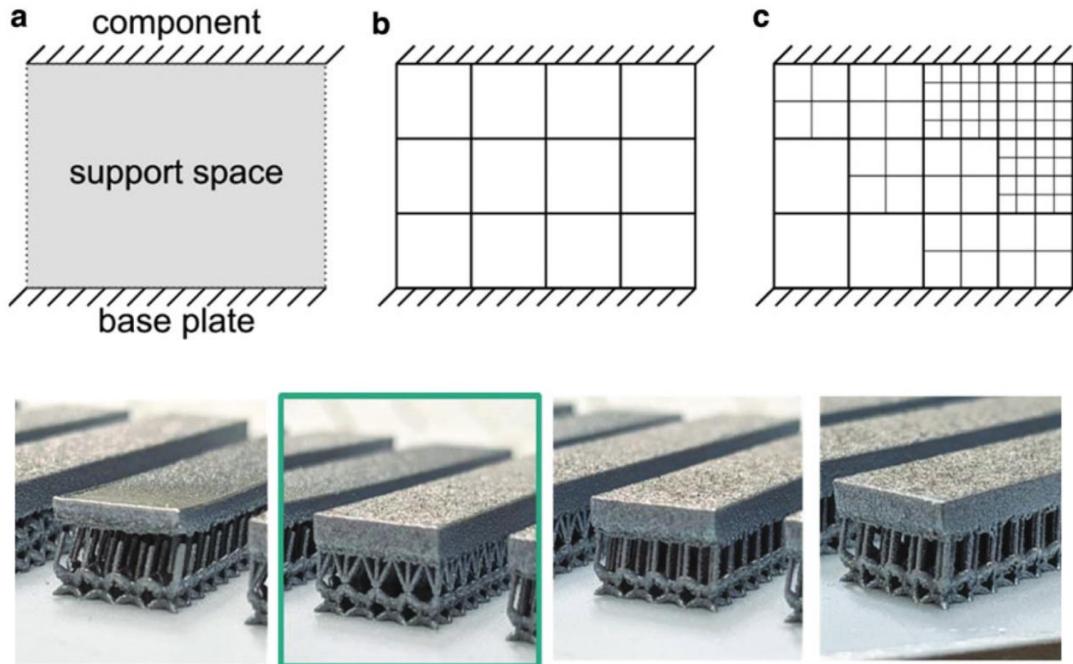
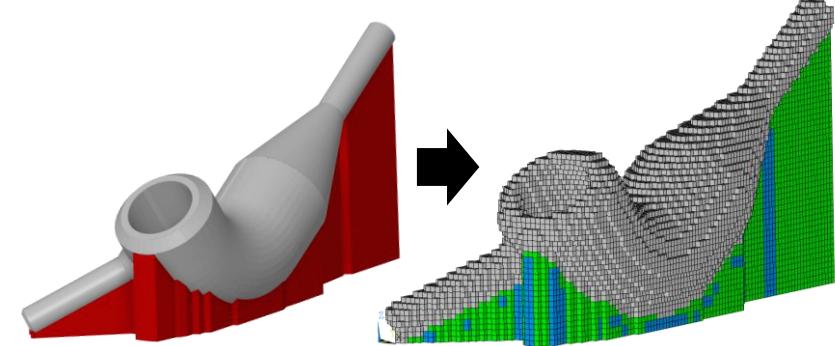


FIG. 5. Printed cantilever geometries to identify the required distribution of connection structures between unit cells and solids. The structure used for further design is highlighted green.

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Case Study of Heat Exchanger Adapter

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Design variables: 3,194 (631 2mm; 2,563 1mm)

possible configurations: $3^{631} \times 3^{2,563}$

Evaluation time per iteration: ~3s

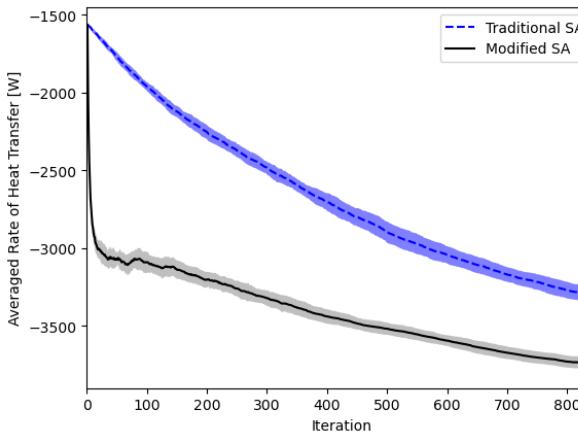
SA Hyperparameters: $T_0 = 50$; $\alpha = 0.5$

$$V_{\max} = 0.5 * V_{\text{solid}} = 3,808 \text{ mm}^3$$

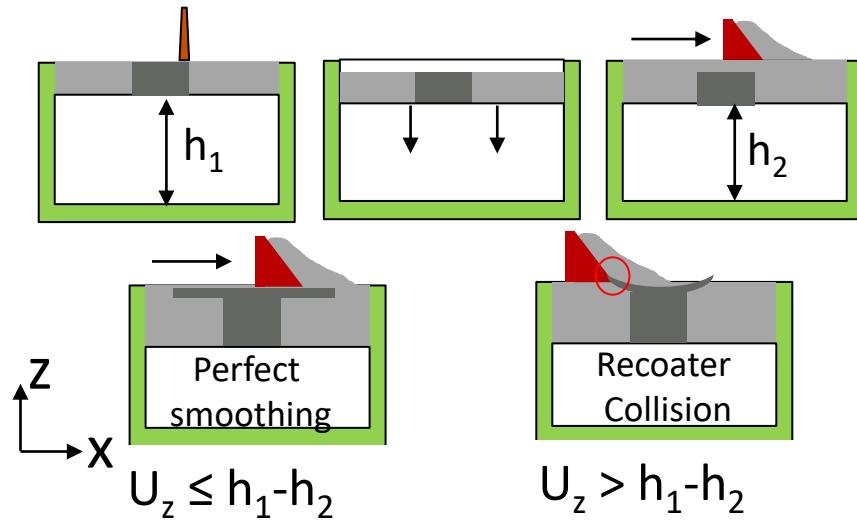
$$\sigma_{\text{Max}}^{\text{PN}} = 1/1.5 = 0.66$$

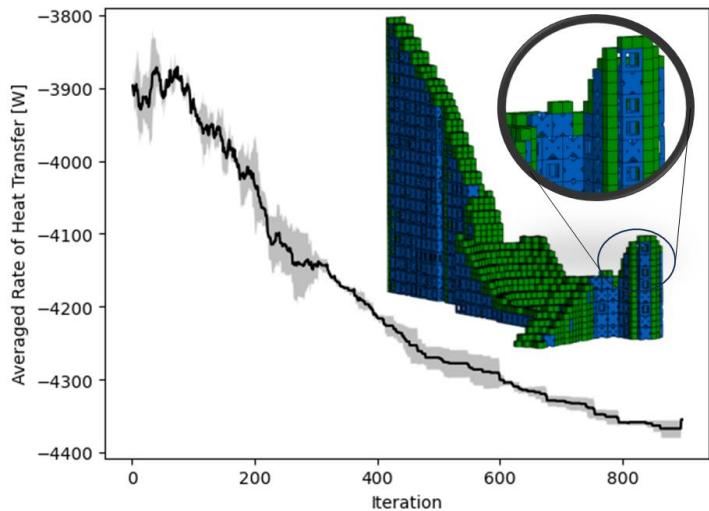
$$U_{z,\max} = \text{Layer} = 40 \mu\text{m}$$

Iteration History of 30 runs (M-SAM) and 12 runs (TSA)



Stages	Traditional SA	M-SAM
Exploration	Total/400	Total/4
Intermediate	Total/400	Total/40
Fine-Tuning	Total/400	Total/400



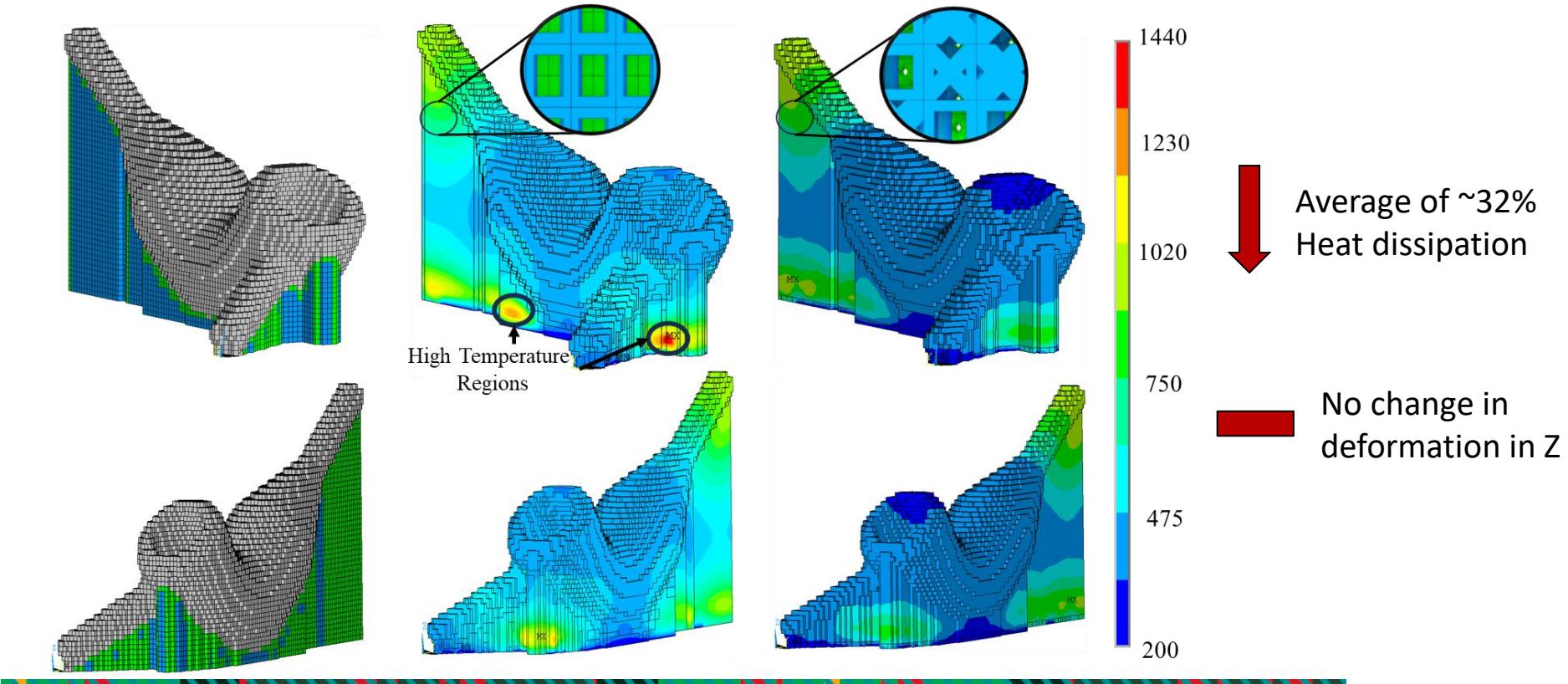


	$ Q_{out} $	$V(x)$	P-norm Stress	$\text{Max}(U_z)$ [μm]	SC/TR/FC	$V(x) < 4570$ P-norm < 0.66 $\text{Max}(U_z) < 66$
Solid SC	6470	7617	0.053	4.6	--	No
Only TR	3182	3711	0.166	19.45	631/0/0	No
Only FC	3756	4468	0.108	13.07	0/631/0	No
Only Op _{avg,3}	4775	4891	0.072	8.08	0/0/631	No
	4365	4481	0.11	12.95	175/197/259	
	(10.5)	(11.2)	(0.00094)	(0.226)	(29.3/14.8/37.8)	Yes

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Case Study of Heat Exchanger Adapter: Validation

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Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Future Work

Evaluating Other Priority Factors

Lattice Printability

- Defects
- Transition

Time

- Dissipation Time
- Build time

Guidelines for User-Defined Constraints

Pre-defined unit cell library

Stage-dependent annealing swapping strategy

Additional Validation

Computational

- Gradient Based Optimizers
- Non-Gradient based optimizers

Physical Structure

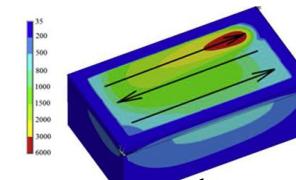
- Calibrating ISM

Physical Validation: Calibration

Haynes 282³⁴

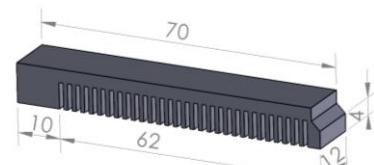
- Nickel-based superalloy
 - High strength
 - Resistance to corrosion and oxidation
 - Good creep and fatigue performance
- Applications
 - Industrial gas turbines
 - Powerplant parts

Thermo-mechanical Model³³



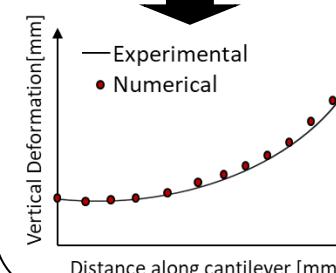
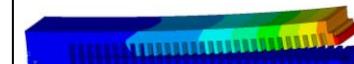
$$\varepsilon_0^{inh} = \begin{cases} \varepsilon_{xx} \\ \varepsilon_{yy} \\ \varepsilon_{zz} \end{cases}$$

Experimental Results*^{35,36}



*Performed by Rollett Research Lab

Regression Model³⁴

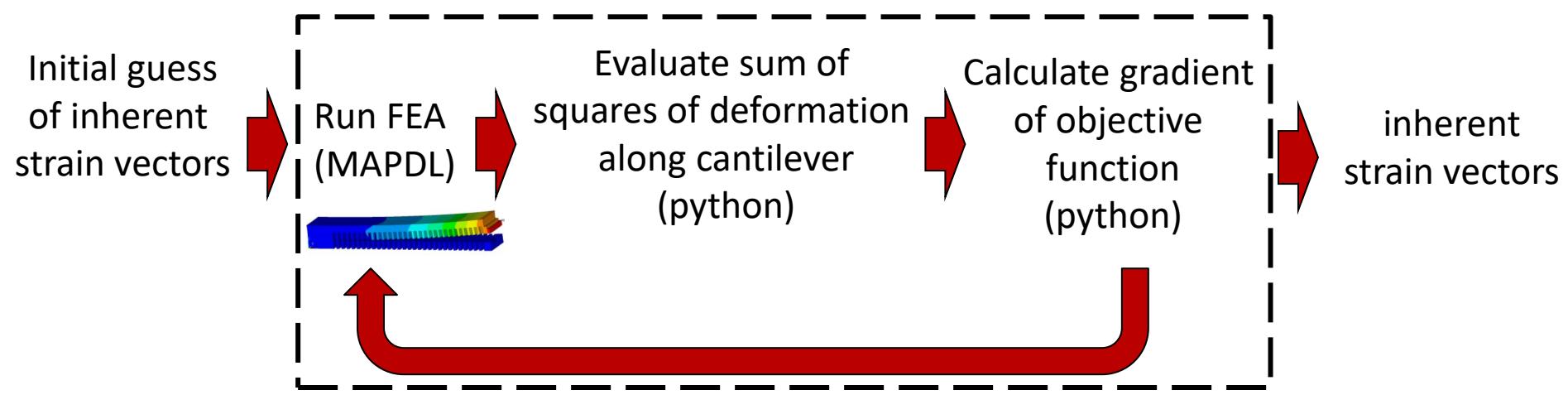


$$\varepsilon^{inh} = \begin{cases} \varepsilon_{xx} \\ \varepsilon_{yy} \\ \varepsilon_{zz} \end{cases}$$

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Curve Fitting Regression Model Flowchart

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Mechanical Ansys Parametric Design Language (MAPDL)

- Scripting language used to interact with the ANSYS mechanical solver

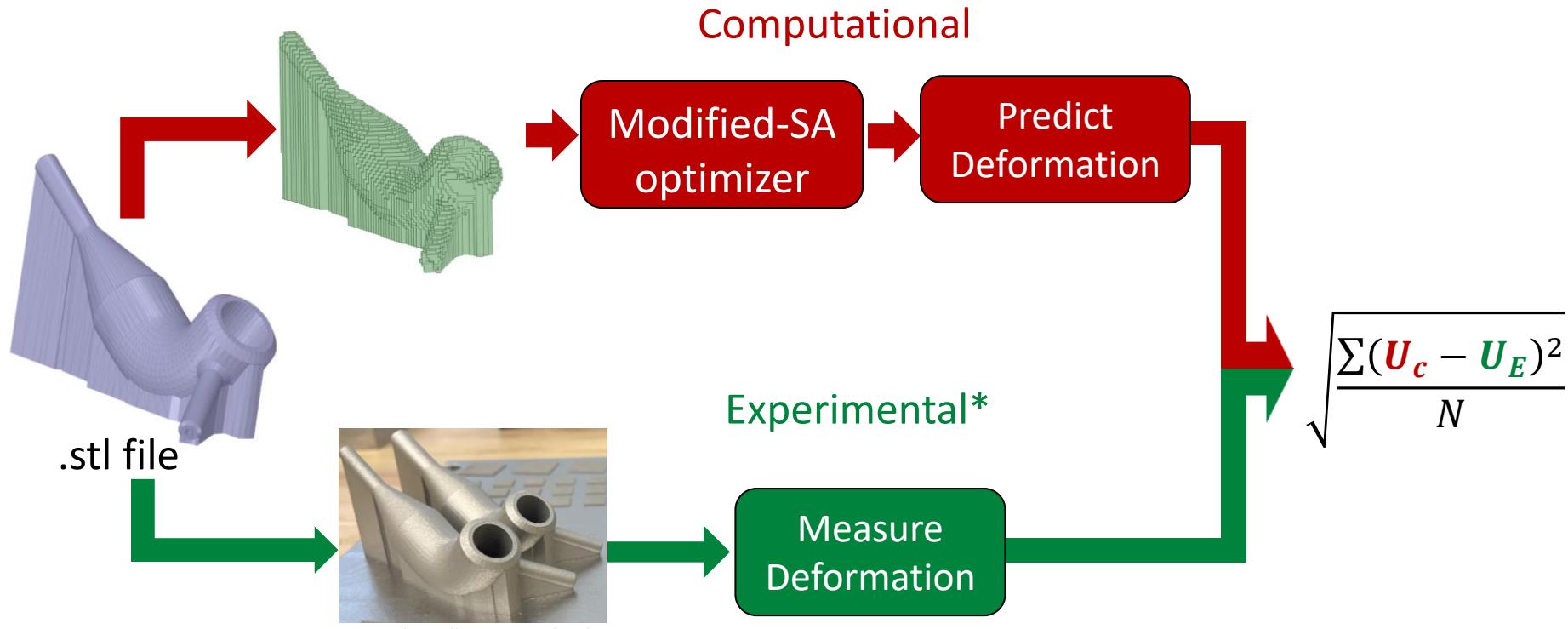
Python code: `scipy.optimize.least_squares`

- Solves a nonlinear least-squares problem with bounds on the variables

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Physical Validation

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*Performed by Rollett Research Lab

Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

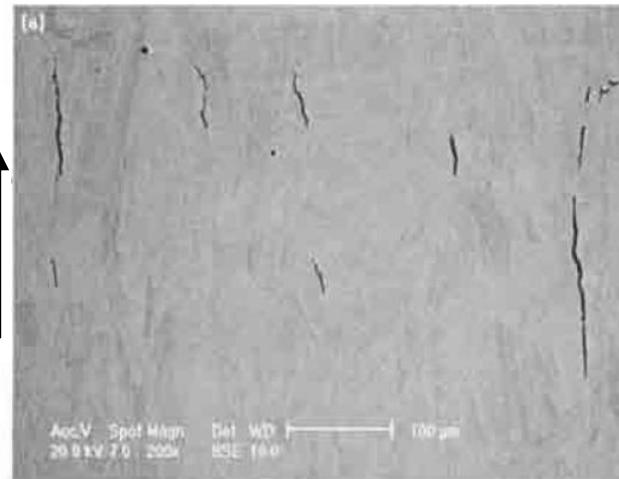
Printability of Lattice Structure [22]

86

Material Dependency

- Porosity
- Residual stress

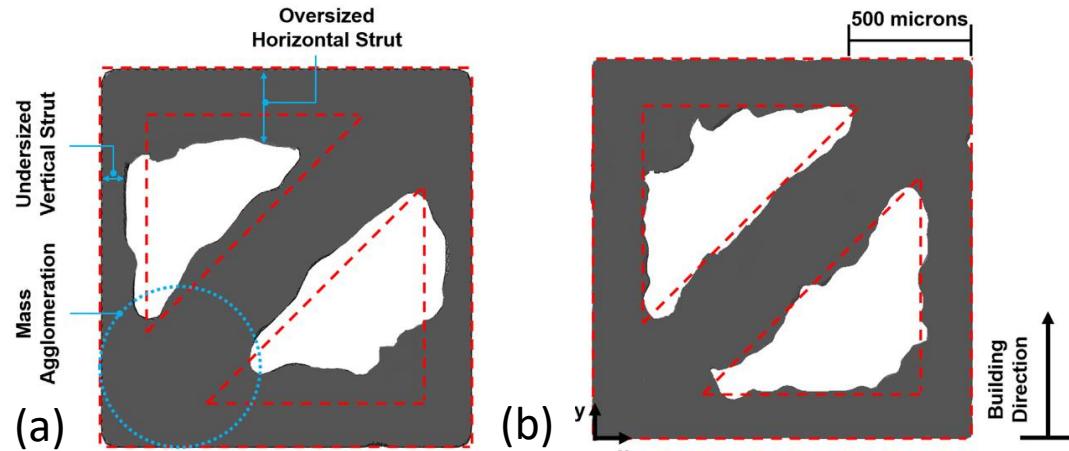
Build Direction



Cracking found in nickel-based superalloy [34]

Geometric Dependency

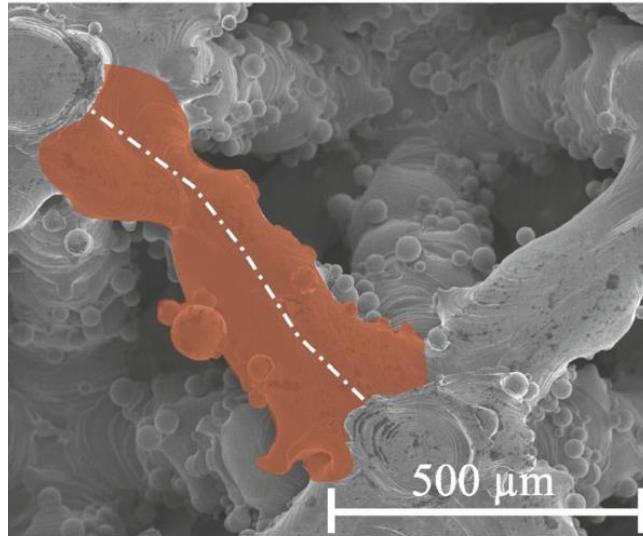
- Strut Diameter
- Strut Orientation



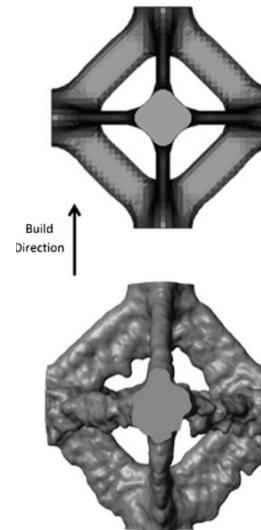
2D reconstruction of initial design of unit cell (dashed lines) with (a) as-printed and (b) compensation [35]

Printability of Lattice Structure: Defects²²

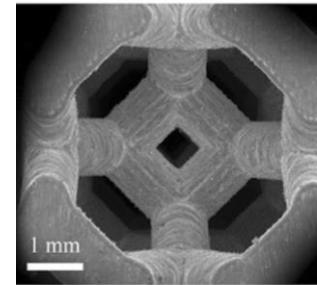
87



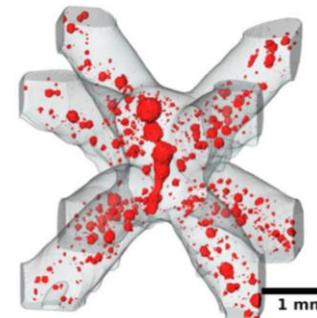
Surface roughness



Upskin vs
Downskin



Stair-stepping



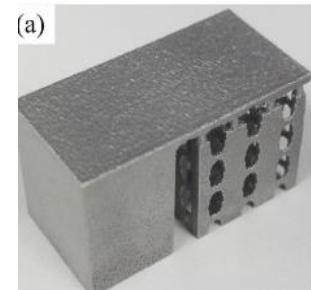
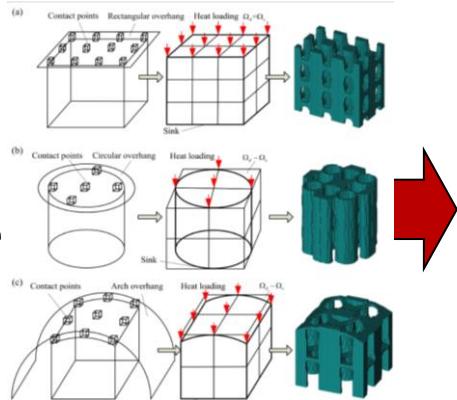
Porosity

Parameterizing Transition Subdomain

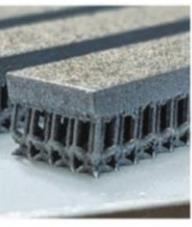
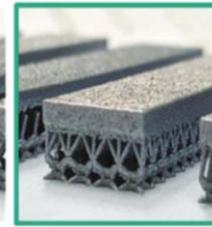
88

17

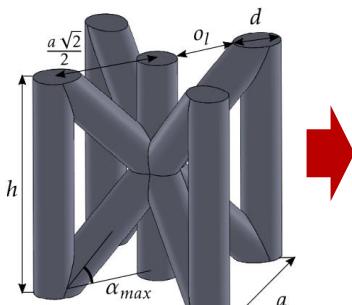
Fixed
Pin Size



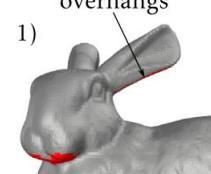
5



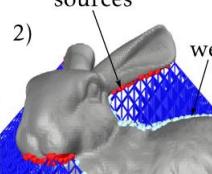
Variable
Pin Size



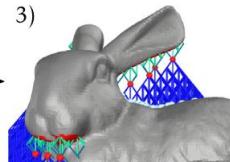
overhangs

Oriented
part

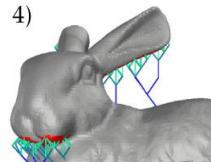
sources

Pre-processed initial
lattice (wireframe)

3)

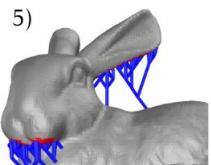
Pre-optimized
lattice (wireframe)

4)

Optimized
supports (wireframe)

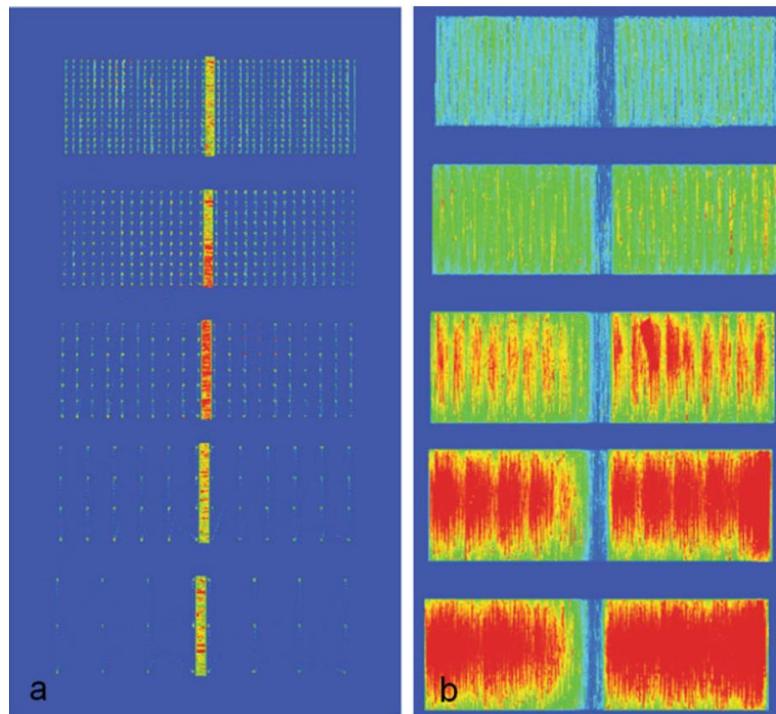
50

5)

Post-processed
supports (volume)

Parameterizing Transition Subdomain

Effect of support structure on temperature distribution^{zz}



Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3			Conclusions
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2	Obj. 3.3	

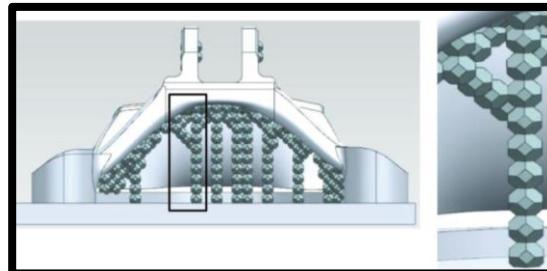
Incorporating complex, curved structures for lattice support generation

90

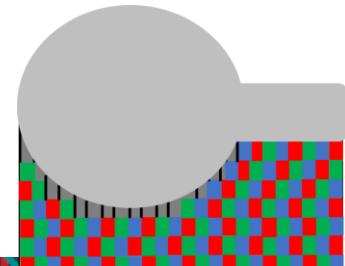
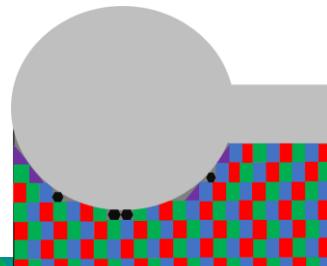
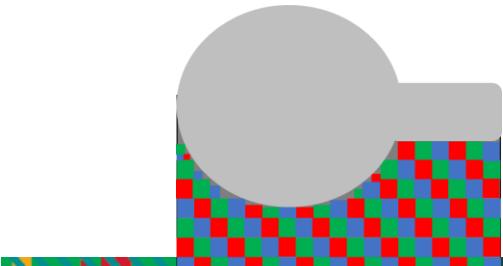
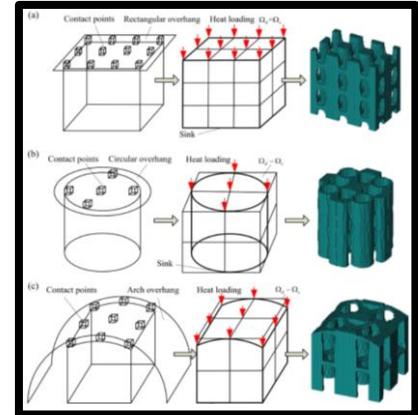
1. Multisize unit cells³⁷



2. Extended unit cell library³⁸



3. Forced flat domain^{9,20,36}



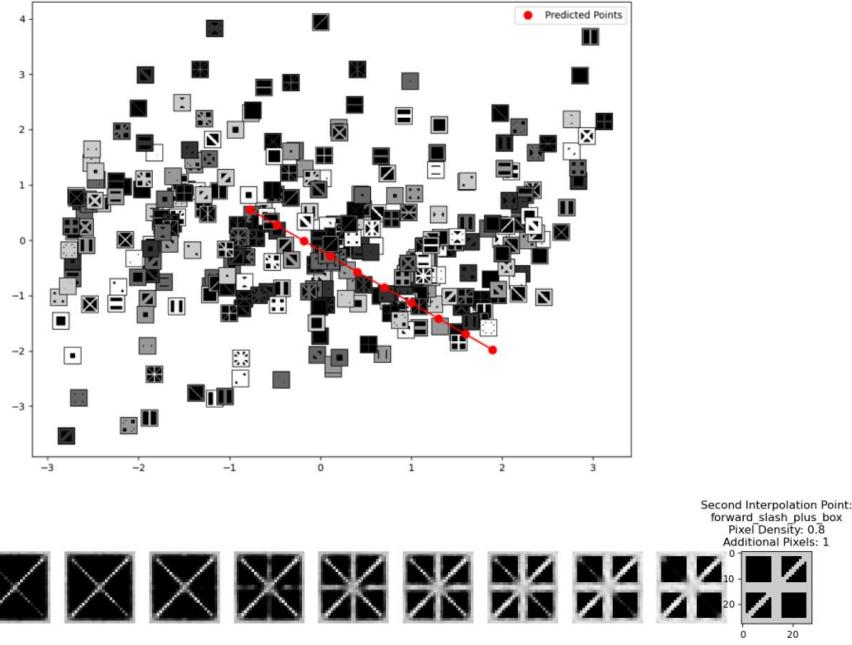
Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

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Guidelines for Unit Cell Library: Selection

Considerations:

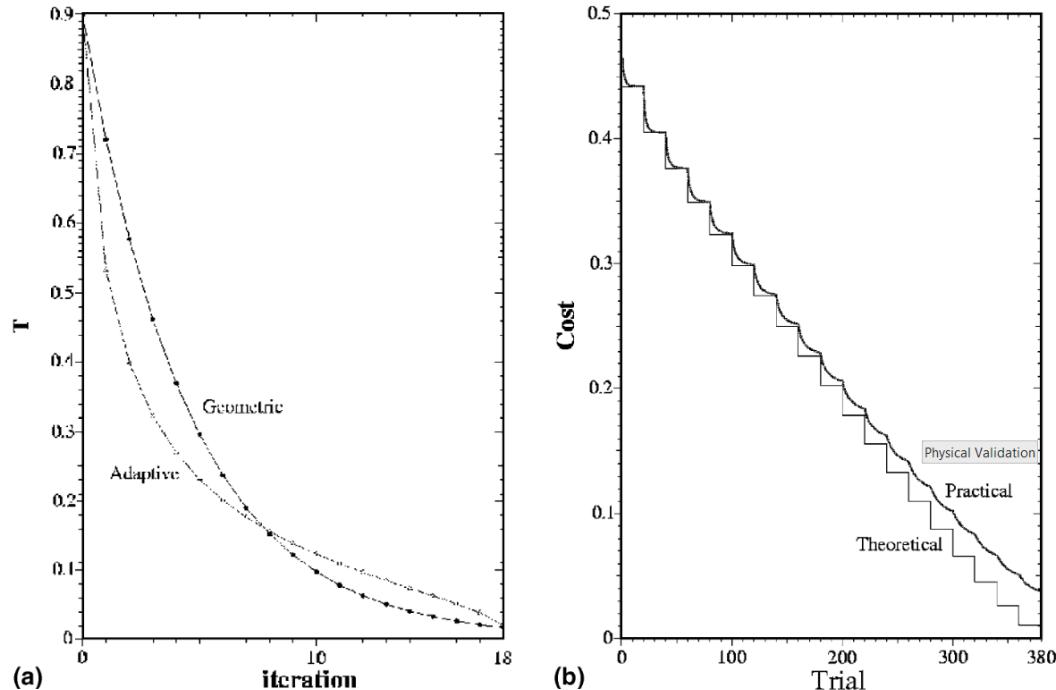
- Connection (including Intracellular stress)
- Increased design exploration
- Priority factors
- Printing parameters



Motivation	Purpose/ Aims	Objective 1		Objective 2		Objective 3		Conclusions	Future Work
		Obj. 1.1	Obj. 1.2	Obj. 2.1	Obj. 2.2	Obj. 3.1	Obj. 3.2		

Guidelines for Stage-dependent Annealing Swapping Strategy

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Geometric cooling schedule

$$T_{k+1} = \alpha * T'_k$$

Adaptive Cooling Schedule⁵¹

$$T'_{k+1} = T'_k \cdot \left(1 - T'_k \left(\frac{\Delta}{\sigma^2(T'_k)} \right) \right)$$