An Introduction to Estimating Monte Carlo Standard Errors with R Package mcmcse

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August 19, 2021

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1 Introduction

The R package mcmcse provides estimates of Monte Carlo standard errors for Markov chain Monte Carlo (MCMC) when estimating means or quantiles of functions of the MCMC output. In addition to MCMC output, the package can be used for time series and other correlated processes.

The package is predominantly useful after MCMC output has been obtained by the user. In addition to estimating the Monte Carlo standard errors, the package also provides univariate and multivariate estimates of effective sample size and tools to determine whether enough Monte Carlo samples have been obtained. The package also samples a stationary Markov chain from a bivariate normal target. There are also some graphical tools to ascertain the behavior of the Monte Carlo estimates.

2 An MCMC Example

To illustrate the use of our package, we consider sampling from a bivariate normal distribution using a Gibbs sampler. For $\omega_1, \omega_2 > 0$ and ρ such that $\rho^2 < \omega_1 \omega_2$, the target distribution is

$$\begin{pmatrix} X_1 \\ X_2 \end{pmatrix} \sim N \begin{pmatrix} \begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix}, \begin{pmatrix} \omega_1 & \rho \\ \rho & \omega_2 \end{pmatrix} \end{pmatrix} .$$

The Gibbs sampler updates the Markov chain by using the following full conditional distributions transition equations:

$$X_1 \mid X_2 \sim N\left(\mu_1 + \frac{\rho}{\omega_2} (X_2 - \mu_2), \omega_1 - \frac{\rho^2}{\omega_2}\right),$$

$$X_2 \mid X_1 \sim N\left(\mu_2 + \frac{\rho}{\omega_1} (X_1 - \mu_1), \omega_2 - \frac{\rho^2}{\omega_1}\right)$$
.

The function BVN_Gibbs in the package draws samples from the above model.

```
#library(mcmcse)
mu = c(2, 50)
sigma = matrix(c(1, 0.5, 0.5, 1), nrow = 2)

# Monte Carlo sample size is N
N <- 5e3
set.seed(100)
chain <- BVN_Gibbs(n = N, mu = mu, sigma = sigma)</pre>
```

For using the mcmcse package the rows of the MCMC output should store each iteration of the algorithm and so the output should have n rows and p columns. We will denote each row i of the output as $y_i = (y_i^{(1)}, y_i^{(2)})$.

```
#Rows has observations (samples) and each comlumn is a component.
head(chain)

## Y1 Y2

## [1,] 1.497808 49.86281

## [2,] 1.863062 50.69951

## [3,] 2.451055 50.50147

## [4,] 1.746889 50.49225

## [5,] 1.531428 49.45406

## [6,] 1.804876 49.98581
```

This vignette will discuss estimating two sets of features of interest of F.

• $E_F y$: For estimating $\mu = E_F y$, the estimator is the Monte Carlo sample mean

$$\mu_n = \frac{1}{n} \sum_{t=1}^n y_t.$$

In R, μ_n is obtained using the usual colMeans function. If p=1, then use mean instead of colMeans.

```
colMeans(chain)
## Y1 Y2
## 2.006982 50.006033
```

• $E_F(y^{(1)2}+y^{(2)2})$: When interested in estimating the sum of the second moments of each component of y, define the function $g:\mathbb{R}^2\to\mathbb{R}$ as $g(x_1,x_2)=x_1^2+x_2^2$. This is defined in R by creating a function that implements the function g, row-wise.

```
g <- function(x)
{
   return(sum(x^2))
}</pre>
```

The Monte Carlo estimator for g is

$$\mu_{g,n} = \frac{1}{n} \sum_{t=1}^{n} g(y_t),$$

```
# Apply the function g to each row
gofy <- apply(chain, 1, g)

# Monte Carlo estimate
mean(gofy)

## [1] 2506.55</pre>
```

Thus, to obtain Monte Carlo estimates from MCMC output, the base package is sufficient (generally). However, Monte Carlo estimates must be reported with Monte Carlo standard error. That is, if the following central limit theorems hold

$$\sqrt{n}(\mu_n - \mathcal{E}_F y) \stackrel{d}{\to} N_p(0, \Sigma) ,$$
 (1)

and

$$\sqrt{n}(\mu_{g,n} - \mathcal{E}_F[||y||^2]) \stackrel{d}{\to} N_p(0, \Sigma_g), \qquad (2)$$

then estimates of Σ and Σ_g must be reported, directly or indirectly. Since the samples obtained are correlated, these quantities require more sophisticated tools than usual sample estimators. (Note that a Markov chain CLT is not always guaranteed to hold. In fact, it depends on the rate of convergence of the Markov chain. Most of the functions in this package assume that a Markov chain CLT holds. Such an assumption is also made when using many of the convergence diagnostics).

3 Estimating Monte Carlo Standard Error

In this package, the functions mcse, mcse.mat, mcse.multi, and mcse.initseq estimate the Monte Carlo standard error of μ_n (or $\mu_{g,n}$).

- mcse: consistent estimates of $\sqrt{\Sigma/n}$ (standard error) when Σ is 1×1 .
- mcse.mat: consistent estimates of the square root of the diagonals of Σ/n .

- mcse.multi: consistent estimates of Σ .
- mcse.initseq: asymptotically conservative estimates of Σ using initial sequence estimators.

Using the mcmcse package we can estimate Σ in (1) with the mcse.multi and mcse.initseq function.

```
# Batch means estimator
mcerror_bm <- mcse.multi(x = chain, method = "bm", r = 1,</pre>
                          size = NULL, g = NULL, adjust = TRUE,
                          blather = TRUE)
# Overlapping batch means estimator
mcerror_obm <- mcse.multi(x = chain, method = "obm", r = 1,</pre>
                          size = NULL, g = NULL, adjust = TRUE,
                          blather = TRUE)
# Spectral variance estimator with Bartlett window
mcerror_bart <- mcse.multi(x = chain, method = "bartlett", r = 1,</pre>
                            size = NULL, g = NULL, adjust = TRUE,
                            blather = TRUE)
# Spectral variance estimator with Tukey window
mcerror_tuk <- mcse.multi(x = chain, method = "tukey", r = 1,</pre>
                           size = NULL, g = NULL, adjust = TRUE,
                           blather = TRUE)
# Initial sequence estimator, unadjusted
mcerror_is <- mcse.initseq(x = chain, g = NULL,</pre>
                            adjust = FALSE, blather = TRUE)
# Initial sequence estimator, adjusted
mcerror_isadj <- mcse.initseq(x = chain, g = NULL,</pre>
                               adjust = TRUE, blather = TRUE)
```

• \mathbf{x} takes the $n \times p$ MCMC data. \mathbf{x} can take only numeric entries in the form of a matrix or data frame. The rows of \mathbf{x} are the iterations of the MCMC.

- method = bm, obm, bartlett, tukey calculates the estimate using the batch means method and spectral variance methods with the modified-Bartlett and Tukey-Hanning windows.
- r is the lugsail parameter that indicates how much to "lift" the lag window (this also applies to bm and obm). Higher values will increasingly remove underestimation of Σ but may yield more variable estimators. Values more than 5 are not advised and negative values are not allowed. Reasonable choices are r=1,2,3, where r=3 yields the lugsail estimator, r=2 is the flat-top estimator, and r=1 is the vanilla estimator.
- size is the batch size for the bm method and the truncation point for tukey and bartlett methods. Default batch size is calulcated using the exported batchSize function. Other accepted values are size = sqroot, which sets the size as $\lfloor \sqrt{n} \rfloor$ and size = cuberoot which sets it at $\lfloor n^{1/3} \rfloor$. An integer value of size less than n is also valid as long as n/size > 1.

For reference on bm (batch means estimators) see Jones et al. (2006) and Vats et al. (2019).

For reference on bartlett and tukey (spectral variance estimators)see Flegal et al. (2010) and Vats et al. (2018).

For reference on lugsail estimation see Liu and Flegal (2018) and Vats and Flegal (2018).

- g is a function that is applied to each row of x and represents the features of interest of the process. Since here we are interested in only means, g is NULL. g will be explained in later examples.
- adjust is a logical argument indicating whether the resulting matrix should be adjusted in order to retain positive-definiteness. By default this is set to be TRUE.
- blather when TRUE outputs under the hood information about the estimation process. The default is set to FALSE since most users should be interested in only cov and est.

For reference on mcse.initseq (initial sequence estimators) see Dai and Jones (2017).

mcse.multi and mcse.initseq return an S3 class with multiple components. When blather = FALSE, cov stores the estimate of Σ obtained using the method chosen, est stores the estimate of the mean of g applied on the Markov chain. In addition, nsim stores the no. of Markov chain samples, eigen-values stores the eigen values of the estimated Σ and cov.adj stores the adjusted covariance matrix if adjust = TRUE (see mcse.multi for more details). When blather = TRUE the following are returned in addition to the above: size which indicates the size of batches/truncation, method used, Adjustment-used indicating whether an adjusted estimator was used (adjust) and message containing additional information about the estimation process (like the numerical adjustments possibly made to keep the estimate mathematically consistent).

Note: The Monte Carlo estimates of μ are not affected by the choice of the method.

Note: For consistent estimation, the batch means estimators are significantly faster to calculate than the spectral variance estimators. The user is advised to use the default method = "bm" for large input matrices.

Note: cov returns an estimate of Σ and not Σ/n .

If the diagonals of Σ are σ_{ii}^2 , the function mcse and mcse.mat returns σ_{ii}/\sqrt{n} . mcse does it for one component and mcse.mat does it for all diagonals.

```
mcse(x = chain[,1], method = "bm", g = NULL)

## $est
## [1] 2.006982
##

## $se
## [1] 0.01792272
##

## $nsim
## [1] 5000

mcse.mat(x = chain, method = "bm", g = NULL)

## est se
## Y1 2.006982 0.01792272
## Y2 50.006033 0.01814934
```

In order to estimate $\mu_{n,g}$ and Σ_g as in (2), we use the R function g we had defined before. Recall that g should be a function that takes vector inputs.

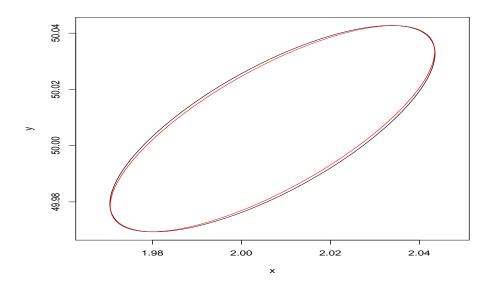
```
g
## function(x)
## {
##
     return(sum(x^2))
## }
## <bytecode: 0x000002b5849bcba0>
mcerror_g_bm <- mcse.multi(x = chain, g = g, blather = TRUE)</pre>
mcerror_g_is <- mcse.initseq(x = chain, g = g, blather = TRUE)</pre>
mcerror_g_bm$cov
             [,1]
## [1,] 17464.29
# Initial Sequence error is larger than batch means, as expected.
mcerror_g_is$cov
##
             [,1]
## [1,] 16091.86
# Returned value is asymptotic variance.
# So we calculate the standard error here.
sqrt(mcerror_g_bm$cov/N)
             [,1]
## [1,] 1.868919
sqrt(mcerror_g_is$cov/N)
             [,1]
## [1,] 1.793982
```

4 Confidence Regions

Using the function confRegion in the package, the user can create joint confidence regions for two parameters. The input for this function is the output

list from the mcse.multi or mcse.initseq function. The function uses the attributes cov, est, and nsim from the output list. If the mcse.initseq is input and adjust = TRUE had been used, then cov.adj is used instead of cov. mcse.multi also uses the attribute size.

```
plot(confRegion(mcerror_bm, which = c(1,2), level = .90), type = 'l', asp = 1) lines(confRegion(mcerror_bart, which = c(1,2), level = .90), col = "red")
```



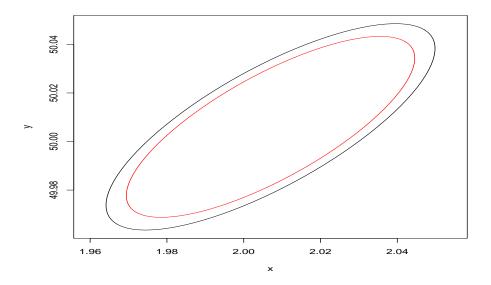
- which should be a vector of size 2 that indicates the two components for which the confidence ellipse is to be constructed.
- \bullet level is the confidence level of the confidence region. The default is .95

NOTE: confRegion calls on the function ellipse in package ellipse to draw the ellipse.

NOTE: Since the confidence region is created for two parameters only, the size of the ellipse is determined by setting p=2 irrespective of the original dimension of the problem.

To determine the effect of the confidence level, we draw two regions with different confidence levels. We use mcse.initseq this time.

```
plot(confRegion(mcerror_is, which = c(1,2), level = .95), type = 'l', asp = 1)
lines(confRegion(mcerror_is, which = c(1,2), level = .90), col = "red")
```



5 Effective Sample Size

Reporting $p \times p$ covariance matrix estimates is impractical and uninterpretable. The motivation of estimating Monte Carlo standard error is to ensure that said error is small. This is essentially the idea behind estimating effective sample size and ensuring that the estimated effective sample size is larger than a prespecified lower bound.

Before sampling the Markov chain, the user is advised to use the function minESS to ascertain what is the minimum effective sample size needed for stable analysis. See Vats et al. (2019) for theoretical details.

```
# For mu
minESS(p = 2, alpha = .05, eps = .05)
## minESS
## 7529
#For mu_g
minESS(p = 1, alpha = .05, eps = .05)
## minESS
## 6146
```

- p is the dimension of the estimation problem.
- alpha is the confidence level
- eps is the tolerance level. Default is .05. Reasonable levels are anywhere from .01 to .05. The smaller the tolerance, the larger the minimum effective samples. eps represents a tolerance level relative to the variability in the target distribution. It is akin to the idea of margin-of-error.

minESS is independent of the Markov chain or process, and is only a function of p, α , and ϵ . The user should find minESS and then sample their process until the required minimum samples are achieved.

Alternatively, we often don't have the luxury of obtaining a lot of samples, and reaching a minimum effective sample size is not possible. In such a scenario, it is useful to know the ϵ tolerance level the number of estimated effective samples correspond to. So if we can only obtain 1000 effective samples,

```
# For mu
minESS(p = 2, alpha = .05, ess = 1000)

## Epsilon
## 0.137196

#For mu_g
minESS(p = 1, alpha = .05, ess = 1000)

## Epsilon
## 0.123959
```

Thus, if you obtained a sample with estimated effective sample size equaling 1000 for estimating μ_g and $\mu_{n,g}$, then the precision level of your estimate is $\epsilon = .137$ and $\epsilon = .124$, respectively. multiESS and ess are two functions that calculate the effective sample size of a correlated sample. ess calculations are based on Gong and Flegal (2016) and is component-wise, and multiESS utilizes the multivariate nature of the problem.

Since ess produces a different estimate for each component, conservative practice dictates choosing the smallest of the values. multiESS returns one estimate of the effective sample size based on the whole sample. The function calls mcse.multi function to obtain a batch means estimate of Σ . The user can provide another estimate of Σ using the covmat argument.

```
multiESS(chain)
## [1] 4024.471

# Using spectral variance estimators
multiESS(chain, covmat = mcerror_bart$cov)

## [1] 4377.303

# Using initial sequence estimators
# Since this is a conservative estimator, ess will be smaller
multiESS(chain, covmat = mcerror_is$cov)

## [1] 4263.715
```

Since the effective sample size is less than the minimum effective samples, we should simulate more. Looking at the formula of ESS, we might need around 10,000 Monte Carlo samples.

```
set.seed(100)
chain <- BVN_Gibbs(1e4, mu, sigma)

# larger than 7529
multiESS(chain)

## [1] 9203.001

# larger than 7529
multiESS(chain, covmat = mcerror_bart$cov)

## [1] 8847.715

# larger than 7529
multiESS(chain, covmat = mcerror_is$cov)

## [1] 8618.124</pre>
```

So no matter which estimator we choose for the Monte Carlo standard error, 10,000 Monte Carlo samples are sufficient to have $\epsilon = .05$ relative tolerance.

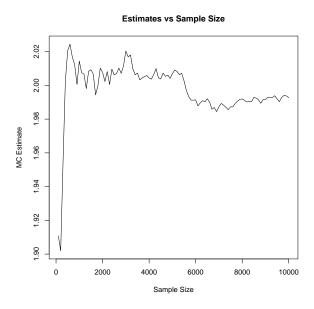
NOTE: Ideally, we want to get more samples using the last iteration of the previous Markov chain. However, BVN_Gibbs does not allow user specified

starting values and starts from stationarity itself, so to demonstrate the use of minESS and multiESS, we get a new sample altogether.

6 Graphical Diagnostics

The function estvssamp plots the Monte Carlo estimates versus the sample size for a component of the MCMC output. This plot indicates whether the Monte Carlo estimate has stabilized.

estvssamp(chain[,1])



References

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