

# Microcontrollers

Andrew Sampson  
2012-12-13

# Introduction

This presentation is a brief overview of microcontroller software development, with a focus on the Atmel line of MCUs. I'll cover:

- how development for these devices differs from traditional desktop PC development
- the rules for our programming contest

I'll wrap up by handing out some development kits.

# Microcontrollers

Microcontrollers (MCUs) are very low-end, inexpensive CPUs.

- They're used in all kinds of electronics products, and they're usually used in unglamorous, low-visibility roles.
- It's big business: wikipedia says that "About 55% of all CPUs sold in the world are 8-bit microcontrollers and microprocessors."

# Microcontrollers

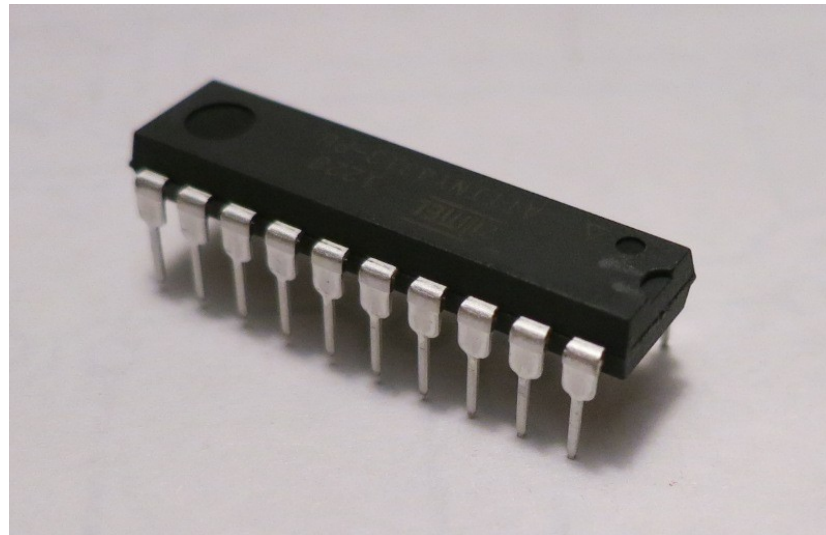
- Trends in MCUs have focused on consolidating more and more functionality in a single chip.
- While MCUs can't really compare with a desktop in performance, they do incorporate everything needed to run a simple program in a single chip:
  - CPU
  - RAM
  - storage
  - serial UART
  - USB and CAN interfaces
  - timers

# Microcontrollers

Given the intended role of MCUs, and the fact that they don't depend on external chips, most of the pins on MCUs are "general-purpose". Here, this means that a pin's voltage state (high or low) can be *controlled directly* by the software running on the MCU. This is very different from how, say, a desktop PC CPU operates.

# What's it like to write software for an MCU?

We're using an Atmel ATtiny2313  
It has 2 kilobytes of (flash) program memory  
It has 128 bytes of RAM  
It has 128 bytes of EEPROM



# What's it like to write software for an MCU?

Despite these severe limitations, programming the ATtiny2313 isn't really uncomfortable. You can use C. The biggest differences between programming this MCU and a desktop system are:

- There's no OS: no file system, no memory protection, etc
- There is a libc, but it's very basic
- malloc() doesn't really make sense here (128 bytes, remember)
- The stack is very short
- There's no FPU
- The ALU has no multiply or divide instructions
- The native integer length is 8 bits

# Word length

The Atmel AVR<sup>s</sup> are 8-bit systems. For efficiency, you should stick with 8-bit data types as much as possible. However, the `avr-gcc` compiler does a good job of hiding the ugly if you need to use longer data types.

Learn to love the `stdint.h` data types, i.e. `uint8_t`, `int16_t`, etc.

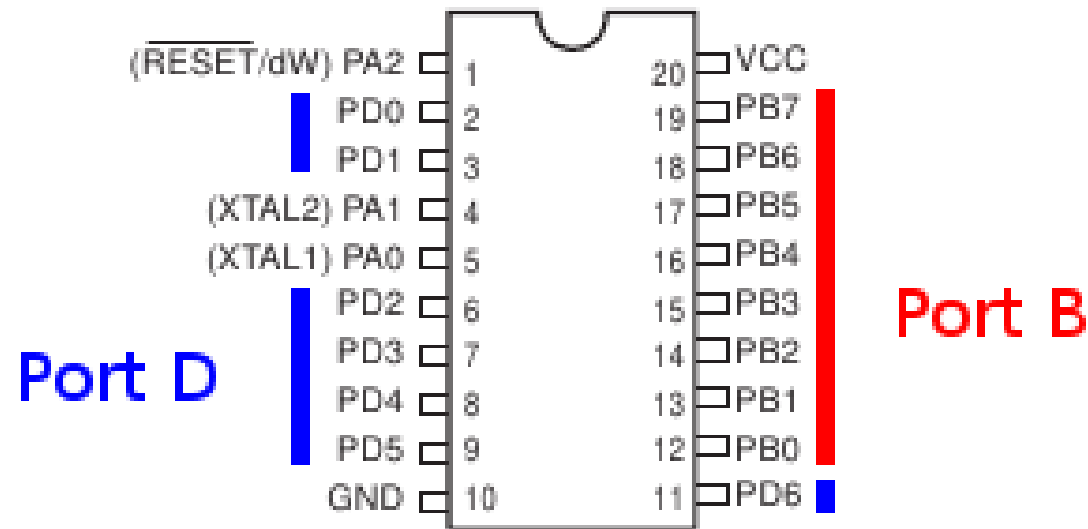


# Memory

- The AVR<sup>s</sup> follow the Harvard architecture, with separate memory spaces for instructions (flash) and data (RAM).
- The instruction memory is much larger than the data memory for these devices.
- It is preferable that large constants (strings, arrays) remain in flash, and not be copied to the stack.
- There are functions and macros – “PROGMEM” – for forcing a constant to remain in flash, and for accessing such a constant. See the links slide for details.

# Pins

For Atmel MCUs, the pins are logically (and sometimes physically) organized into groups of 8 (called "ports").



# Pins

Ports appear in software as special memory locations. Changing the high/low states of the pins is as simple as assigning a value to the memory location. Reading the state of the pins is equally simple.

Setting pin 5 on port D high:

```
PORTD |= (1 << 5);
```

Setting all pins on port D high:

```
PORTD = 0b11111111;
```

Setting pin 5 on port D low:

```
PORTD &= ~(1 << 5);
```

Reading all pins on port B:

```
uint8_t blah = PINB;
```

# Configuring pins

Pins can be either inputs or outputs, but not both at the same time. You can set the input/output state of a pin by (you guessed it) writing to a memory location.

Set pin 5 of port D to be an output:

```
DDRD |= (1 << 5);
```

Set pin 5 of port D to be an input:

```
DDRD &= ~(1 << 5);
```

Set all pins of port B to be outputs:

```
DDRB = 0b11111111;
```

# Configuring pins

Pins are configured as inputs by default. It's good practice to configure your pins to known input/output states at the beginning of your program. Also, because the pin I/O state is global, you need to manage it carefully (esp. when it comes to functions).

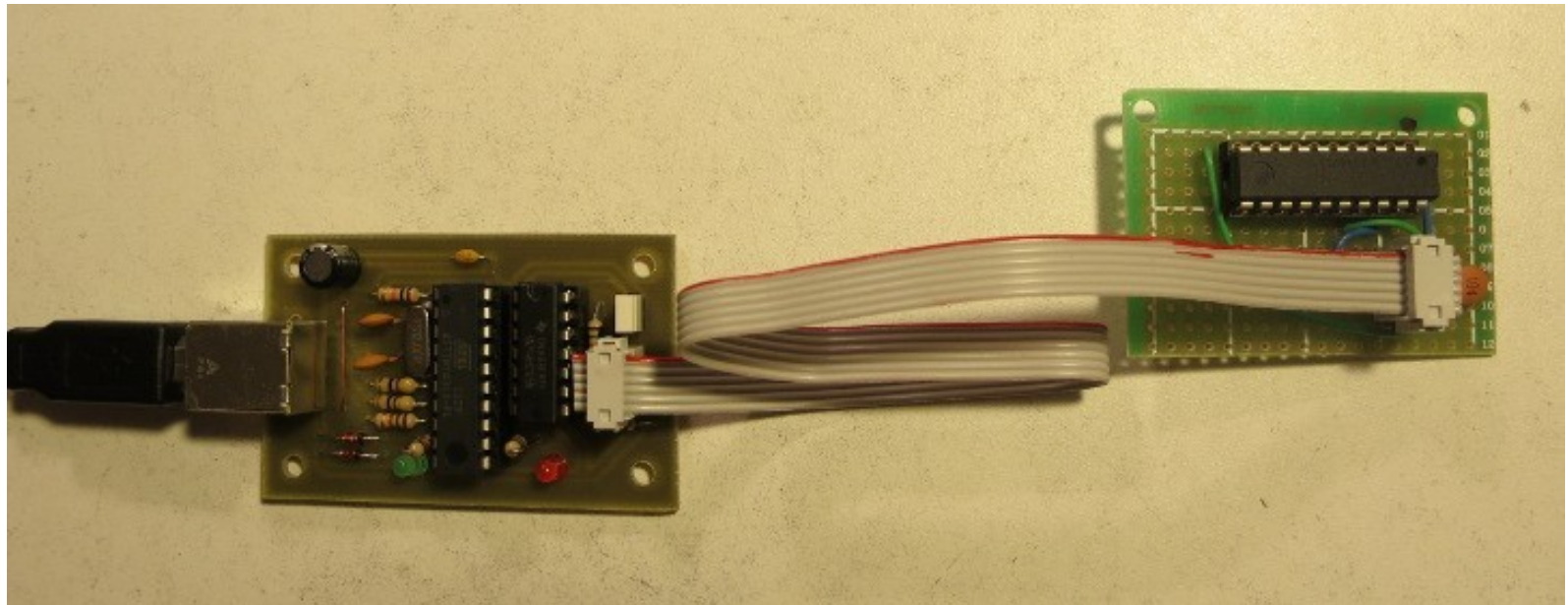
# Workflow: Compiler

The preferred compiler for AVR is `avr-gcc`. The input is your C code and the output is a `.hex` file, which contains the compiled firmware.

- Main page:
  - <http://www.nongnu.org/avr-libc/>
- Linux users have it easy:
  - `sudo apt-get install gcc-avr binutils-avr avr-libc`
- Windows users can play too:
  - <http://winavr.sourceforge.net/>
- Mac users might start here:
  - <http://www.ladyada.net/learn/avr/setup-mac.html>

# Workflow: Connections

- Remove the MCU from your keypad
- Insert the MCU into the programmer break-out board (note pin 1!)
- Connect the 6-pin ribbon cable (note pin 1 on each end!)
- Connect the programmer to your computer



# Workflow: Flash programmer

The USBtinyISP programmer works with the avrdude firmware uploader. This software reads in your .hex file and sends it to the flash programmer.

- Main page:
  - <http://www.nongnu.org/avrdude/>
- Linux users have it easy:
  - `sudo apt-get install avrdude`
- Windows users can play too:
  - <http://winavr.sourceforge.net/> (avrdude seems to be included)
- Mac users might start here:
  - <http://www.ladyada.net/learn/avr/setup-mac.html> (there's some info here)



# Dev kit

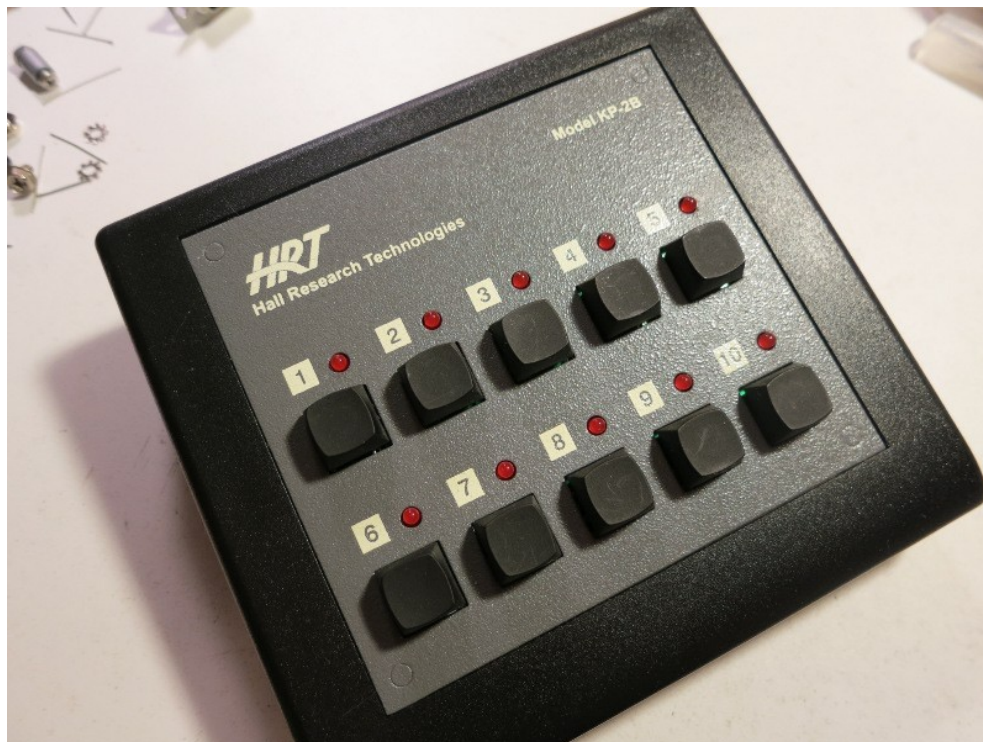
To help get people started in microcontroller development, I've put together some development kits. Here's what's included:

- Keypad
- Flash programmer
- “Target” board
- High tech power supply

# Dev kit: The keypad

We found a bunch of these keypads in the trash. They've got a microcontroller, 10 buttons, 10 LEDs, and a serial interface. I've replaced the microcontrollers with Atmel ATtiny2313s.

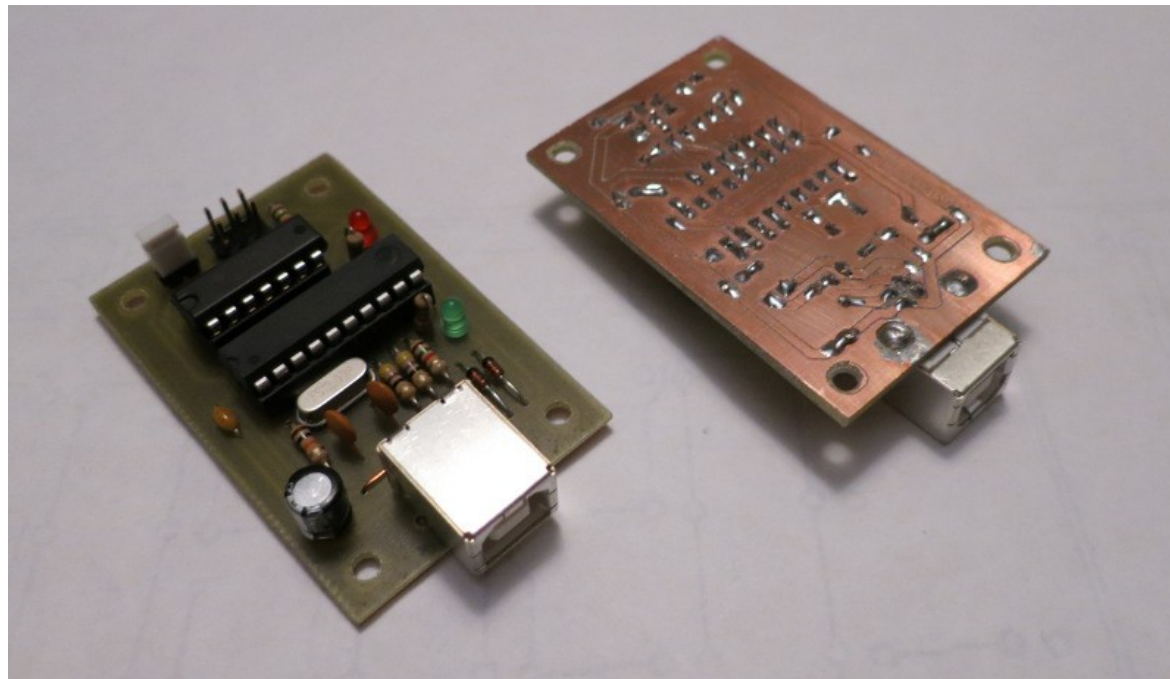
<http://www.hallresearch.com/page/Products/KP-2B>



# Dev kit: The programmer

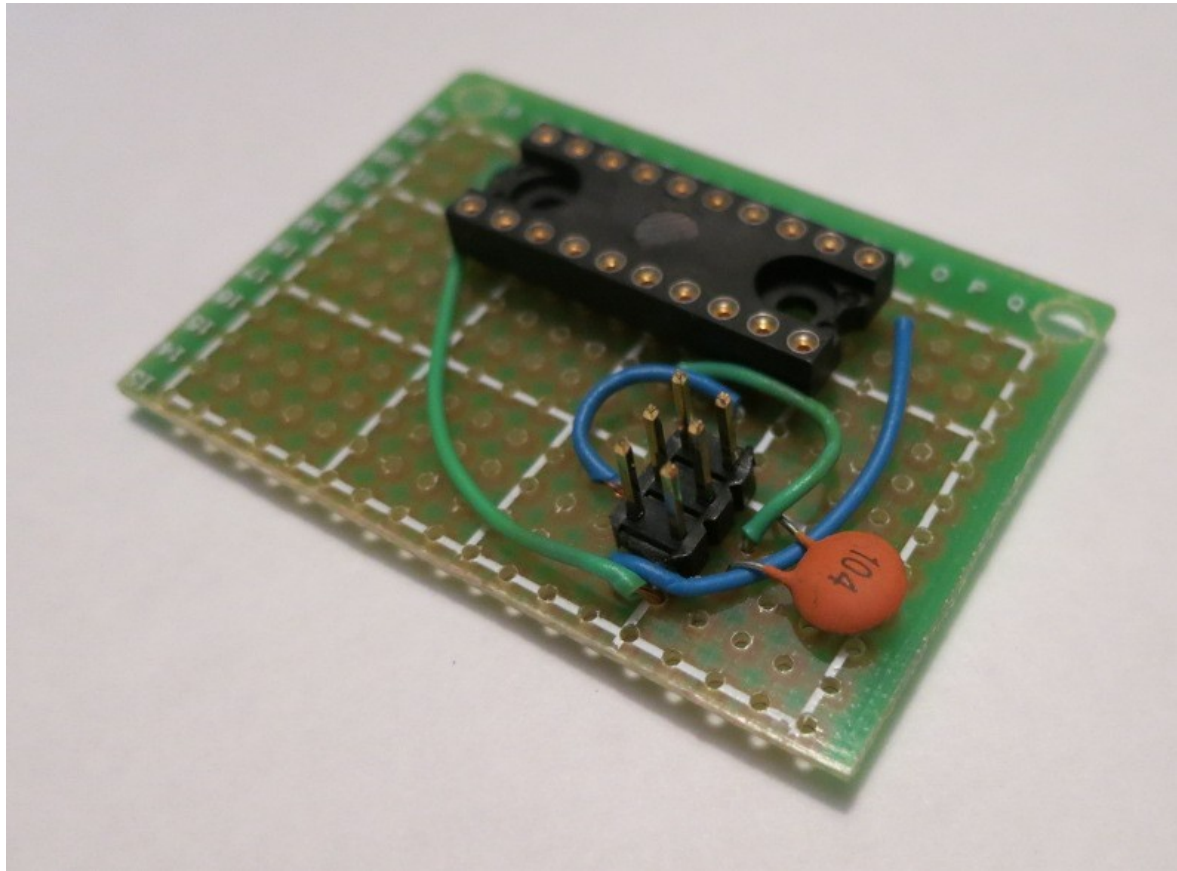
I made a bunch of flash programmers. They're based on the USBtinyISP. They allow you to write compiled software to the microcontroller.

<http://www.ladyada.net/make/usbtinyisp/>



# Dev kit: The target board

Nathan made a bunch of break-out boards. They connect your MCU to your flash programmer. Ordinarily, this feature is built in to the board you're developing for; in the case of the keypads, it is not built in.

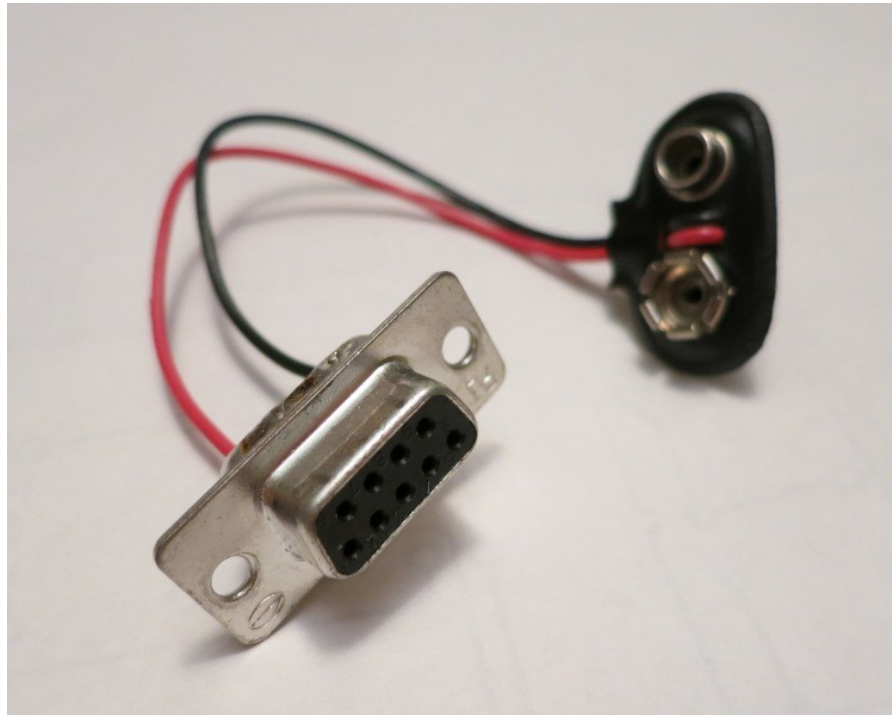




# Dev kit: High tech power supply

The keypad, in its original application, was powered via one of the data lines on the serial port. This space-age contraption allows you to power your keypad without tethering it to a computer.

Warning: Do not plug the high tech power supply into your computer or something. Doing so will surely create a black hole and destroy the Earth.



# Shopping list

Here's what you need to complete your dev kit:

- USB A to B cable
  - This cable connects your programmer board to your computer.



Image courtesy of <http://en.wikipedia.org/wiki/USB>

# Shopping list

- Chip puller
  - This tool aids extracting ICs from their sockets. Without one, your fingers will slip and you'll bend all the pins.

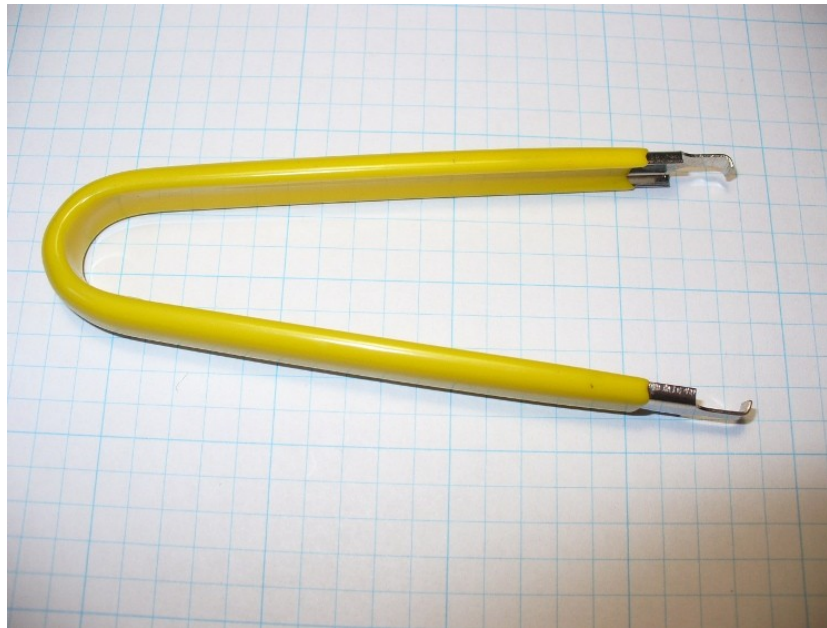


Image courtesy of <http://tronixstuff.files.wordpress.com/2010/06/>

# Shopping list

- 9V battery
  - You need one of these in order to power your keypad.





# Shopping list

- Optional: A case for your programmer
  - The programmer boards are vulnerable to corrosion from fingerprints and to metal bits shorting the pins on the bottom. You can buy cases for your programmers from here:
  - [http://dangerousprototypes.com/docs/Sick\\_of\\_Beige\\_compa](http://dangerousprototypes.com/docs/Sick_of_Beige_compa)

# Contest rules

- Write an interesting game for your keypad
- Entries must be open-sourced
- Deadline is January 14, 2013
- Submit your entries by forking my project on github and posting your code there.
- Prizes:
  - Everyone who submits an actual entry gets to keep the keypad and programmer. If you take a development kit today but don't produce anything by the deadline, I ask that you return the kit.
  - Grand prize: [TBD]
- Everyone who submits an actual entry gets to vote for the winner of the grand prize.

# Example code

- I've reverse-engineered the keypad and written a demo app for it. The demo shows how to write to the LEDs and read from the switches.
- The example makefile contains examples of how to invoke gcc-avr and avrdude.
- The C files contain reusable functions for setting the LEDs and reading the switches.
- The project is hosted on GitHub. See <http://github.com/andrewsampson>
- Grab the code like so:
  - `git clone [fixme]`

# Things I'm skipping

- Fuses
- The external crystal
- UART
- Timers
- EEPROM

# Additional resources

Nathan offers the following additional AVR references.

- Basic:
  - Bit manipulation: <http://www.avrfreaks.net/index.php?name=PNphpBB2&file=viewtopic&t=37871>
  - I/O operations: <http://iamsuhasm.wordpress.com/tutsproj/avr-gcc-tutorial/>
  - Storing constants in flash: <http://www.avrfreaks.net/index.php?name=PNphpBB2&file=viewtopic&t=38003>
- Intermediate:
  - Efficient AVR C coding: <http://www.atmel.com/Images/doc1497.pdf> (syntax differences from GCC)
  - EEPROM: <http://www.avrfreaks.net/index.php?name=PNphpBB2&file=viewtopic&t=38417>
  - Timers: <http://www.avrfreaks.net/index.php?name=PNphpBB2&file=viewtopic&t=50106>
- Advanced?:
  - Interrupts: <http://www.avrfreaks.net/index.php?name=PNphpBB2&file=viewtopic&t=89843>
  - Inline assembly: [http://www.nongnu.org/avr-libc/user-manual/inline\\_asm.html](http://www.nongnu.org/avr-libc/user-manual/inline_asm.html)
  - Multitasking: <http://www.avrfreaks.net/index.php?name=PNphpBB2&file=viewtopic&t=95490>
- Misc/Resources:
  - ATtiny2313/4313 datasheet: <http://www.atmel.com/images/doc8246.pdf>
  - AVR forum with active community: <http://www.avrfreaks.net/index.php?name=PNphpBB2&file=index>
  - avr-libc FAQ: <http://www.nongnu.org/avr-libc/user-manual/FAQ.html>
  - RS232 transceiver datasheet: <http://www.datasheetcatalog.org/datasheet/sipex/SP3232.pdf>
- Tips/gotchas:
  - Use the smallest-sized data type that you need.
  - Don't change the fuses!
  - When changing fuses, don't change the reset disable fuse or the clock source fuses!
  - If using interrupts understand the concept of "atomicity" and when to use the keyword "volatile".
  - Don't use floating point math!
  - Don't divide!
  - If dividing by a constant, do it by multiplying by its reciprocal (google "binary scaling"--also used for multiplying by non-integer).
  - Need some extra speed? Look up "OSCCAL" in the attiny2313/4313 datasheet.