Andrew Guo

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EDUCATION

University of Toronto

2024 - 2025

Master of Science - Computer Science

- Research stream, directly transitions to PhD
- Advisors: Prof. David Lindell, Prof. Kyros Kutulakos
- Focus on deep learning, artificial intelligence, computer vision, neural rendering

University of Waterloo

2019 - 2024

Honours Bachelor of Software Engineering

- Dean's Honour List, Cumulative Avg: 92%, awarded \$44,000 in scholarships
- Completed 40 months of full-time work experience in industry, double the requirement for co-op program

EXPERIENCE

Research Engineering Intern

Sept. 2022 - Apr. 2024

Nvidia

Toronto, ON

- Researched 3D reconstruction, neural scene representations, LiDAR novel view synthesis, and pose estimation
- Created automated 6D pose annotation pipeline for data collection in the wild, conference paper in IROS 2023
- Advisors: Dr. Stan Birchfield, Dr. Liila Torabi, Dr. Hammad Mazhar

Simulation Software Engineering Intern

May 2022 - Aug. 2022

Nvidia

Toronto, ON

- Designed synthetic data generation pipeline for 6D Pose Estimation, beat benchmarks in original paper
- Created custom annotator to capture semantic information from simulation to generate ground truth for training
- Sped up data generation by 150% by asynchronously writing to $\mathbf{s3}$ bucket with multiprocessing

Machine Learning Intern

Sept. 2021 - Dec. 2021

Nvidia

Santa Clara, CA

- Created features for driver-safety system: developer.nvidia.com/drive/drive-ix
- Optimized 11 convolutional neural networks (CNNs) using TensorRT to run inference on limited hardware
- Transitioned team's entire SDK to new version of Nvidia's DRIVE OS to support integration of new camera

Software Engineering Intern

May 2021 – Aug. 2021

Canoo

Torrance, CA

- Created integrated calibration framework in C to update ECU calibration without recompiling main application
- Saved company \$30,000 in annual licensing fees by creating Python module to generate .a2l description files

Autonomous Vehicle Software Intern

Jan. 2021 – Apr. 2021

WAT onomous

 $Waterloo,\ ON$

- Created localization pipeline to match camera and LiDAR images with a priori map to navigate car without GPS
- Achieved 3x speed up using multi-processing in C++ with OpenMP and lane line matching with KD-trees
- Utilized Carla for autonomous driving simulations when access to vehicle was not possible

Software Engineering Intern

May 2020 - Aug. 2020

AMD

Toronto, ON

- · Automated analysis of memory dumps and sped up debugging by detecting anomalies and key metrics
- Created register save/restore tools that interfaced with low-level drivers for power-saving features on graphics chips

Publications

HANDAL: A Dataset of Real-World Manipulable Object Categories with Pose Annotations, Affordances, and Reconstructions

Andrew Guo, Bowen Wen, Jianhe Yuan, Jonathan Tremblay, Stephen Tyree, Jeffrey Smith, Stan Birchfield IROS 2023 - Paper Link - Project Page