$\mathrm{E}\{Z\} ext{-}\mathsf{Kriging}$ Exploring the World of Ordinary Kriging

Dennis J. J. Walvoort

Wageningen University & Research Center Wageningen, The Netherlands

July 2004 (version 0.2)

What is $E\{Z\}$ -Kriging?

- a computer program for exploring ordinary kriging;
- interactive, self-explanatory, and easy to use.
 Hence, 'easy kriging'
- and last but not least: it's freeware

What is $E\{Z\}$ -Kriging?

- a computer program for exploring ordinary kriging;
- interactive, self-explanatory, and easy to use. Hence, 'easy kriging'
- and last but not least: it's freeware!

What is $E\{Z\}$ -Kriging?

- a computer program for exploring ordinary kriging;
- interactive, self-explanatory, and easy to use.
 Hence, 'easy kriging'
- and last but not least: it's freeware!

Who may benefit from it?

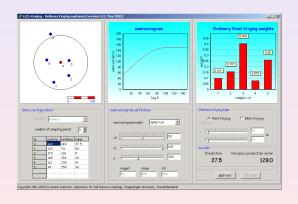
- Students, who need to understand those 'mysterious' kriging equations;
- 2 Lecturers, who want to explain kriging in an intuitive way;
- Others, who just want to know what they are doing when using geostatistical software.

Who may benefit from it?

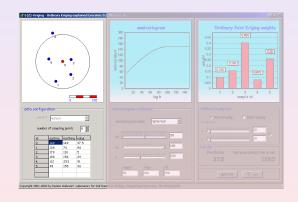
- Students, who need to understand those 'mysterious' kriging equations;
- Lecturers, who want to explain kriging in an intuitive way;
- Others, who just want to know what they are doing when using geostatistical software.

Who may benefit from it?

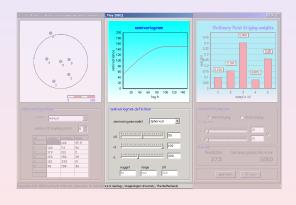
- Students, who need to understand those 'mysterious' kriging equations;
- Lecturers, who want to explain kriging in an intuitive way;
- Others, who just want to know what they are doing when using geostatistical software.



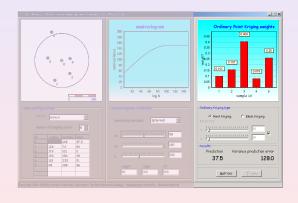
- data configuration panel
- 2 semivariogram panel
- kriging pane



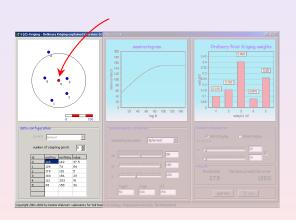
- data configuration panel
- 2 semivariogram panel
- 6 kriging pane



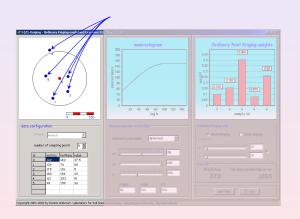
- data configuration panel
- 2 semivariogram panel
- kriging panel



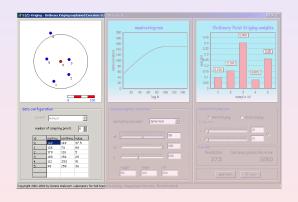
- data configuration panel
- 2 semivariogram panel
- 6 kriging panel



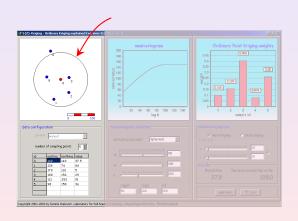
The prediction point is red and labelled 0.



The *n* sampling points are blue and labelled from 1 to *n*.

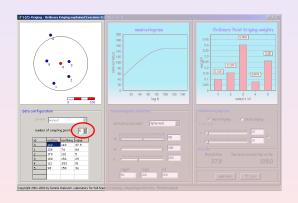


The configuration of points can be changed by means of the mouse (*drag 'n' drop*).

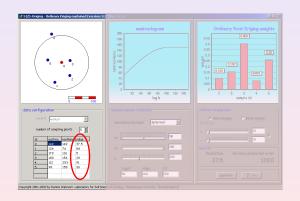


The range is represented by a solid circle. A dashed circle represents the *practical* range.

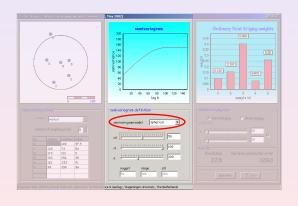
▶ definition



The number of sampling points has to be specified here (see ellipse).



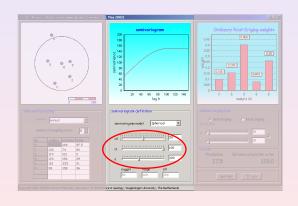
The values at the sampling locations have to be entered here.



The following semivariogram models can be selected:

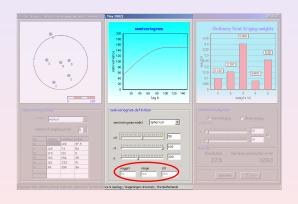
- Spherical model
- Exponential modeldetails
- Gaussian model

▶ details

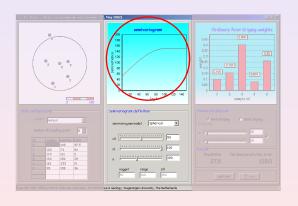


Use the sliders to set the semivariogram parameters:

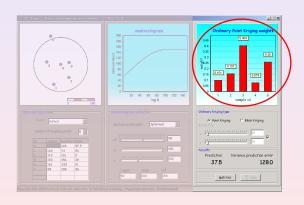
- nugget (*c*₀)
- partial sill (c₁)
- range parameter (a)



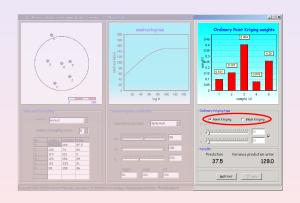
This section gives the nugget variance, the (practical) range and the sill variance $(c_0 + c_1)$.



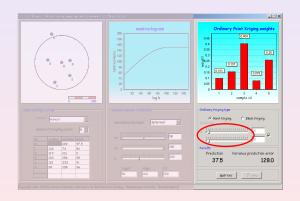
The resulting semivariogram will be shown here.



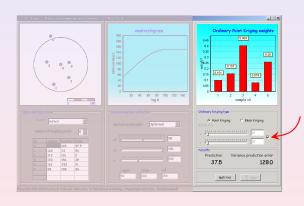
The ordinary kriging weights are shown as bars. Click on the bars for numerical values.



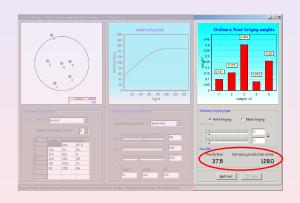
Use the radiobuttons to switch between ordinary point kriging and ordinary block kriging.



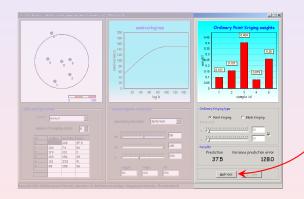
The block size can be set by means of the sliders.



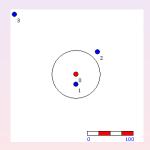
Check this checkbox to enforce *square* prediction blocks.



The ordinary kriging prediction and the associated variance of the prediction error are given here.

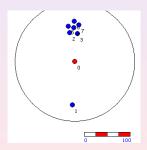


Press this button to get a glimpse of the underlying maths.



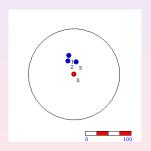
Distance effect

Discover that points outside the range affect predictions differently than points within the range (cf. inverse squared distance interpolation).



Declustering effect

Discover how ordinary kriging reduces the influence of clustered sampling points (cf. inverse squared distance interpolation).



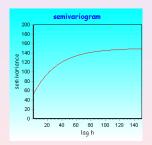
Screening effect

Recall that ordinary kriging is a non-convex interpolator, *i.e.*, its predictions can be outside the data range. Explore data configurations and semivariogram settings that enhance this effect.

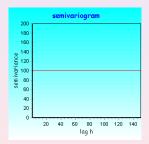


Effect of data values

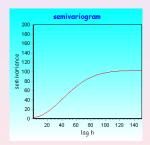
Discover how data values affect the weights, the prediction and the variance of the prediction error.



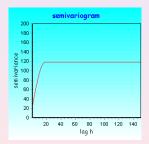
Effect of semivariogram model



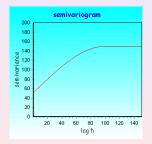
Effect of semivariogram model



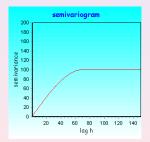
Effect of semivariogram model



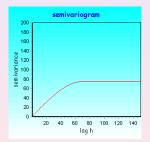
Effect of semivariogram model



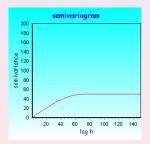
Effect of semivariogram model



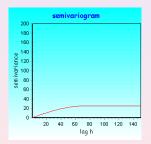
Effect of semivariogram scale



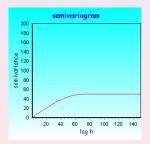
Effect of semivariogram scale



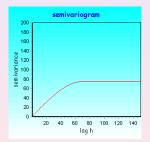
Effect of semivariogram scale



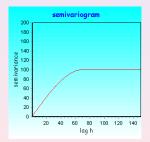
Effect of semivariogram scale



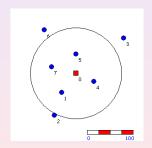
Effect of semivariogram scale



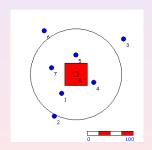
Effect of semivariogram scale



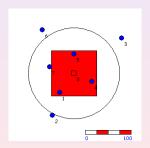
Effect of semivariogram scale



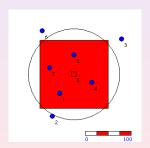
Effect of aggregation



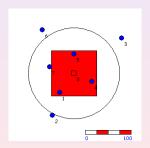
Effect of aggregation



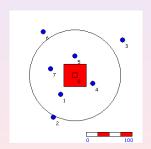
Effect of aggregation



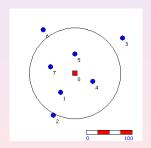
Effect of aggregation



Effect of aggregation



Effect of aggregation



Effect of aggregation

Suggestions for further reading

E.H. Isaaks and R.M. Srivastava. An Introduction to Applied Geostatistics. Oxford University Press, New York, 1989.

P. Goovaerts. Geostatistics for Natural Resources Evaluation. Oxford University Press, New York, 1997.

Geostatistical software

- Vesper (www.usyd.edu.au/su/agric/acpa/vesper/vesper.html)
- GStat (www.gstat.org),
 GStat is also available as R-package (www.r-project.org)







License

 $E\{Z\}$ -Kriging is freeware and provided *as is* without warranty of any kind, either express or implied.

Enjoy $\mathbb{E}\{Z\}$ -Kriging!

Spherical model

$$\gamma_{s}(h) = \begin{cases} \frac{3h}{2a} - \frac{1}{2} \left(\frac{h}{a}\right)^{3} & \forall h < a \\ 1 & \forall h \ge a \end{cases}$$

$$\gamma(h) = c_0 + c_1 \gamma_s(h)$$

where:

a: range parameter

c₀: nugget variance

 c_1 : partial sill variance

h : lag distance

 γ_s standardised semivariance

 γ semivariance

Return



Exponential model

$$\gamma_s(h) = 1 - \exp\left(-\frac{h}{a}\right)$$

$$\gamma(h) = c_0 + c_1 \gamma_s(h)$$

where:

a: range parameter

c₀: nugget variance

 c_1 : partial sill variance

h : lag distance

 γ_s standardised semivariance

 γ semivariance

◆ Return



Gaussian model

$$\gamma_s(h) = 1 - \exp\left(-\frac{h^2}{a^2}\right)$$

$$\gamma(h) = c_0 + c_1 \gamma_s(h)$$

where:

a: range parameter

 c_0 : nugget variance

 c_1 : partial sill variance

h : lag distance

 γ_s standardised semivariance

 γ semivariance

Return



Practical range

Lag h for which $\gamma(h) = 0.95\gamma(\infty)$, i.e., that distance at which the semivariance is 95% of the sill.

∢ Return