"DeepLearning.AI TensorFlow Developer" Specialization

Andrii X

1 C1: Introduction to TensorFlow for AI, ML, and DL

1.1 Week 1: First NN

```
• Simple example aka "Hello, World!":
 Define NN (1 layer with 1 neuron):
 # Build a simple Sequential model
 model = tf.keras.Sequential(
 [keras.layers.Dense(units=1, input_shape=[1])]
 Compile the model:
 model.compile(optimizer='sgd', loss='mean_squared_error')
 Provide the data:
 # Declare model inputs and outputs for training
 xs = np.array([-1.0, 0.0, 1.0, 2.0, 3.0, 4.0], dtype=float)
 ys = np.array([-3.0, -1.0, 1.0, 3.0, 5.0, 7.0], dtype=float)
 Train the NN:
 # Train the model
 model.fit(xs, ys, epochs=500)
 Use trained NN for new data:
 # Make a prediction
 print(model.predict([10.0]))
```

1.2 Week 2: Intro to CV

• A Computer Vision Example: Fashion MNIST dataset

The Fashion MNIST dataset is a collection of grayscale 28x28 pixel clothing images.

1) Load the Fashion MNIST dataset:

```
fmnist = tf.keras.datasets.fashion_mnist
```

2) Load the training and test split of the Fashion MNIST dataset:

```
(training_images, training_labels),
(test_images, test_labels) = fmnist.load_data()
```

3) Normalize the pixel values of the train and test images:

```
training_images = training_images / 255.0
test_images = test_images / 255.0
```

4) Build the classification model:

```
model = tf.keras.models.Sequential([
tf.keras.layers.Flatten(),
tf.keras.layers.Dense(128, activation=tf.nn.relu),
tf.keras.layers.Dense(10, activation=tf.nn.softmax)])
```

Sequential - defines a sequence of layers in the neural network.

Flatten - converts a 28x28 matrix into a 1-D array.

Dense - adds a layer of neurons. Activation function **relu** passes values greater than 0 to the next layer.

Softmax takes a list of values and scales these so the sum of all elements will be equal to 1. When applied to model outputs, you can think of the scaled values as the probability for that class.

5) Compile and train the model:

```
model.compile(optimizer = tf.optimizers.Adam(),
loss = 'sparse_categorical_crossentropy',
metrics=['accuracy'])
```

```
model.fit(training_images, training_labels, epochs=5)
```

6) Evaluate the model on unseen data

```
model.evaluate(test_images, test_labels)
```

$Exploration\ Exercises$

ex1: the below code creates a set of classifications for each of the test images, and then prints the first entry in the classifications.

```
classifications = model.predict(test_images)
print(classifications[0])
# The output of the model is a list of 10 numbers.
# These numbers are a probability that the value
# being classified is the corresponding value
```

ex2: adding more Neurons we have to do more calculations, slowing down the process, but in this case they have a good impact — we do get more accurate. That doesn't mean it's always a case of 'more is better', you can hit the law of diminishing returns very quickly!

ex3: it may seem vague right now, but it reinforces the rule of thumb that the first layer in your network should be the same shape as your data. Right now our data is 28x28 images, and 28 layers of 28 neurons would be infeasible, so it makes more sense to 'flatten' that 28,28 into a 784x1.

ex4: **another rule of thumb** – the number of neurons in the last layer should match the number of classes you are classifying for.

ex5: consider the effects of additional layers in the network. There isn't a significant impact – because this is relatively simple data. For far more complex data (including color images to be classified as flowers that you'll see in the next lesson), extra layers are often necessary.

ex6: consider the impact of training for more or less epochs. Try 15 epochs – you'll probably get a model with a much better loss than the one with 5. Try 30 epochs – you might see the loss value decrease more slowly, and sometimes increases. This is a side effect of something called 'overfitting'.

ex7: If you try to train the model without normalizing the data, you might find that the model takes longer to train, or that it's unable to learn effectively from the training data, leading to poorer performance on the test data. The reason you get different results with and without normalization is because the scale of the inputs can significantly impact the gradient of the loss function, and hence the updates to the weights during training. Normalization ensures that the scale of the inputs is consistent, which can make the training process more stable and efficient. ex8: 'wouldn't it be nice if I could stop the training when I reach a desired value?' – i.e. 85% accuracy might be enough for you, and if you reach that after 3 epochs, why sit around waiting for it to finish a lot more epochs.... you have callbacks!

```
class myCallback(tf.keras.callbacks.Callback):
def on_epoch_end(self, epoch, logs={}):
if logs.get('accuracy') is not None
and logs.get('accuracy') > 0.60:
print("\nReached 60% accuracy so cancelling training!")
self.model.stop_training = True

callbacks = myCallback()
```

```
fmnist = tf.keras.datasets.fashion_mnist
(training_images, training_labels) ,
(test_images, test_labels) = fmnist.load_data()

training_images=training_images/255.0

test_images=test_images/255.0

model = tf.keras.models.Sequential([
tf.keras.layers.Flatten(),
tf.keras.layers.Dense(128, activation=tf.nn.relu),
tf.keras.layers.Dense(10, activation=tf.nn.softmax)
])

model.compile(optimizer='adam',
loss='sparse_categorical_crossentropy', metrics=['accuracy'])
# model fitting with callback
model.fit(training_images, training_labels,
epochs=5, callbacks=[callbacks])
```

1.3 Week 3: Convolutional NN

• Improving Computer Vision Accuracy using Convolutions

A neural network containing three layers — the input layer (in the shape of the data), the output layer (in the shape of the desired output) and only one hidden layer gives accuracy about 89% on training and 87% on validation. How does one make that even better? One way is to use something called convolutions. The ultimate concept is that they narrow down the content of the image to focus on specific parts and this will likely improve the model accuracy. This is perfect for computer vision because it often highlights features that distinguish one item from another. Moreover, the amount of information needed is then much less because one will just train on the highlighted features. That's the concept of Convolutional Neural Networks.

```
# Define the model
model = tf.keras.models.Sequential([

# Add convolutions and max pooling
tf.keras.layers.Conv2D(32, (3,3), activation='relu',
input_shape=(28, 28, 1)),
tf.keras.layers.MaxPooling2D(2, 2),
tf.keras.layers.Conv2D(32, (3,3), activation='relu'),
tf.keras.layers.MaxPooling2D(2,2),

# Add the same layers as before
tf.keras.layers.Flatten(),
tf.keras.layers.Dense(128, activation='relu'),
```

```
tf.keras.layers.Dense(10, activation='softmax')
 ])
  # Print the model summary
 model.summary()
 # Use same settings
 model.compile(optimizer='adam',
 loss='sparse_categorical_crossentropy', metrics=['accuracy'])
 # Train the model
 print(f'\nMODEL TRAINING:')
 model.fit(training_images, training_labels, epochs=5)
 # Evaluate on the test set
 print(f'\nMODEL EVALUATION:')
 test_loss = model.evaluate(test_images, test_labels)
• Lab:
 import os
 import numpy as np
 import tensorflow as tf
 from tensorflow import keras
 # Load the data
  # Get current working directory
 current_dir = os.getcwd()
  # Append data/mnist.npz to the previous path to get
  # the full path
 data_path = os.path.join(current_dir, "data/mnist.npz")
  # Get only training set
  (training_images, training_labels), _ =
 tf.keras.datasets.mnist.load_data(path=data_path)
```

Pre-processing the data:

- Reshape the data so that it has an extra dimension. The reason for this is that commonly you will use 3-dimensional arrays (without counting the batch dimension) to represent image data. The third dimension represents the color using RGB values. This data might be in black and white format so the third dimension doesn't really add any additional information for the classification process but it is a good practice regardless.
- Normalize the pixel values so that these are values between 0 and 1. You can achieve this by dividing every value in the array by the maximum.

```
def reshape_and_normalize(images):
### START CODE HERE
```

```
# Reshape the images to add an extra dimension
images = images.reshape(images.shape[0],
images.shape[1],
images.shape[2],
1)
# Normalize pixel values
images = images / 255.0
### END CODE HERE
return images
# rest of the code like previously
```

1.4 Week 4: Usage of real-world images

• Lab 1: Training with ImageDataGenerator: Building a Small Model from Scratch

```
import tensorflow as tf
model = tf.keras.models.Sequential([
# Note the input shape is the desired size of the
#image 300x300 with 3 bytes color
# This is the first convolution
tf.keras.layers.Conv2D(16, (3,3), activation='relu',
input_shape=(300, 300, 3)),
tf.keras.layers.MaxPooling2D(2, 2),
# The second convolution
tf.keras.layers.Conv2D(32, (3,3), activation='relu'),
tf.keras.layers.MaxPooling2D(2,2),
# The third convolution
tf.keras.layers.Conv2D(64, (3,3), activation='relu'),
tf.keras.layers.MaxPooling2D(2,2),
# The fourth convolution
tf.keras.layers.Conv2D(64, (3,3), activation='relu'),
tf.keras.layers.MaxPooling2D(2,2),
# The fifth convolution
tf.keras.layers.Conv2D(64, (3,3), activation='relu'),
tf.keras.layers.MaxPooling2D(2,2),
# Flatten the results to feed into a DNN
tf.keras.layers.Flatten(),
# 512 neuron hidden layer
tf.keras.layers.Dense(512, activation='relu'),
# Only 1 output neuron. It will contain a value
# from O-1 where O for 1 class ('horses') and 1 for
# the other ('humans')
tf.keras.layers.Dense(1, activation='sigmoid')
```

])

The increasing number of filters in deeper layers allows the network to capture a hierarchy of features, from simple to complex, which is essential for the network to understand and classify intricate patterns in images.

```
from tensorflow.keras.optimizers import RMSprop
model.compile(loss='binary_crossentropy',
optimizer=RMSprop(learning_rate=0.001),
metrics=['accuracy'])
```

In this case, using the **RMSprop optimization algorithm** is preferable to stochastic gradient descent (SGD), because **RMSprop automates** learning-rate tuning for us. (Other optimizers, such as Adam and Adagrad, also automatically adapt the learning rate during training, and would work equally well here.)

Data Preprocessing

Next step is to set up the data generators that will read pictures in the source folders, convert them to float32 tensors, and feed them (with their labels) to the model.

```
from tensorflow.keras.preprocessing.image import ImageDataGenerator

# All images will be rescaled by 1./255
train_datagen = ImageDataGenerator(rescale=1/255)

# Flow training images in batches of 128 using train_datagen generator
train_generator = train_datagen.flow_from_directory(
'./horse-or-human/', # This is the source directory for training images
target_size=(300, 300), # All images will be resized to 300x300
batch_size=128,
# Since we use binary_crossentropy loss, we need binary labels
class_mode='binary')
Training

history = model.fit(train_generator,
steps_per_epoch=8, epochs=15, verbose=1)
As a result, a convnet processes images by transforming pixels through
```

As a result, a **convnet** processes images by transforming pixels through layers into abstract representations, **emphasizing key features** and achieving representation sparsity, which refines information about the image's class.

• Lab 2: ImageDataGenerator with a Validation Set Building a Small Model from Scratch

```
# the same model architecture as before
# in previous lab 1
# the same compile settings as before
```

Data Preprocessing

It will mostly be the same as last time but notice the additional code to also prepare the validation data.

from tensorflow.keras.preprocessing.image import ImageDataGenerator

```
# All images will be rescaled by 1./255
train_datagen = ImageDataGenerator(rescale=1/255)
validation_datagen = ImageDataGenerator(rescale=1/255)
# Flow training images in batches of 128 using train_datagen generator
train_generator = train_datagen.flow_from_directory(
'./horse-or-human/', # This is the source directory for training images
target_size=(300, 300), # All images will be resized to 300x300
batch_size=128,
# Since you use binary_crossentropy loss, you need binary labels
class_mode='binary')
# Flow validation images in batches of 128 using validation_datagen generator
validation_generator = validation_datagen.flow_from_directory(
'./validation-horse-or-human/', # This is the source directory for validation images
target_size=(300, 300), # All images will be resized to 300x300
batch_size=32,
# Since you use binary_crossentropy loss, you need binary labels
class_mode='binary')
```

Training

Notice that as you train with more epochs, your training accuracy might go up but your validation accuracy goes down. This can be a sign of overfitting and you need to prevent your model from reaching this point.

```
history = model.fit(
train_generator,
steps_per_epoch=8,
epochs=15,
verbose=1,
validation_data = validation_generator,
validation_steps=8)
```

• Final Assignment: Happy or Sad

The happy or sad dataset, which contains 80 images of emoji-like faces, 40 happy and 40 sad.

The task is to create a convolutional neural network that trains to 99.9%

accuracy on these images, which cancels training upon hitting this training accuracy threshold.

```
# IMPORTS
import matplotlib.pyplot as plt
import tensorflow as tf
import numpy as np
import os
# LOAD AND EXPLORE THE DATA
from tensorflow.keras.preprocessing.image import load_img
from tensorflow.keras.preprocessing.image import img_to_array
base dir = "./data/"
happy_dir = os.path.join(base_dir, "happy/")
sad_dir = os.path.join(base_dir, "sad/")
print("Sample happy image:")
plt.imshow(load_img(f"{os.path.join(happy_dir, os.listdir(happy_dir)[0])}"))
plt.show()
print("\nSample sad image:")
plt.imshow(load_img(f"{os.path.join(sad_dir, os.listdir(sad_dir)[0])}"))
plt.show()
# Load the first example of a happy face
sample_image = load_img(f"{os.path.join(happy_dir, os.listdir(happy_dir)[0])}")
# Convert the image into its numpy array representation
sample_array = img_to_array(sample_image)
print(f"Each image has shape: {sample_array.shape}")
print(f"The maximum pixel value used is: {np.max(sample_array)}")
Defining the callback
The EarlyStopping callback will monitor the validation loss (val loss)
by default. If the validation loss does not improve for a specified
number of epochs (defined by the patience parameter), the training will
stop, and the best weights (from the epoch with the lowest validation
loss) will be restored to the model.
Note: To use the EarlyStopping callback effectively, you should have a
validation set defined when calling model.fit().
from tensorflow.keras.callbacks import EarlyStopping
# Define the EarlyStopping callback
early_stopping = EarlyStopping(monitor='val_loss', # or 'val_accuracy' depending
# on what you want to monitor
patience=10, # Number of epochs with no improvement after which training will
```

```
# be stopped
verbose=1,
restore_best_weights=True) # Restore model weights from the
# epoch with the best value of the monitored quantity.
# Now, when you fit the model, you can use this callback:
# model.fit(..., callbacks=[early_stopping])
class myCallback(tf.keras.callbacks.Callback):
def on_epoch_end(self, epoch, logs={}):
if logs.get('accuracy') is not None and logs.get('accuracy') > 0.999:
print("\nReached 99.9% accuracy so cancelling training!")
self.model.stop_training = True
Pre-processing the data:
from tensorflow.keras.preprocessing.image import ImageDataGenerator
def image_generator():
        \# Instantiate the ImageDataGenerator class.
        train_datagen = ImageDataGenerator(rescale=1/255.0)
        train_generator = train_datagen.flow_from_directory(directory=base_dir,
        target_size=(150, 150),
        batch_size=10,
        class_mode='binary')
        return train_generator
gen = image_generator()
Creating and training your model:
from tensorflow.keras import optimizers, losses
def train_happy_sad_model(train_generator):
        # Instantiate the callback
        callbacks = myCallback()
        # Define the model
        model = tf.keras.models.Sequential([
        # This is the first convolution
        tf.keras.layers.Conv2D(16, (3,3), activation='relu', input_shape=(150, 150, 3))
        tf.keras.layers.MaxPooling2D(2, 2),
        # The second convolution
        tf.keras.layers.Conv2D(32, (3,3), activation='relu'),
        tf.keras.layers.MaxPooling2D(2,2),
```

```
# The third convolution
        tf.keras.layers.Conv2D(32, (3,3), activation='relu'),
        tf.keras.layers.MaxPooling2D(2,2),
        tf.keras.layers.Flatten(),
        tf.keras.layers.Dense(256, activation = 'relu'),
        tf.keras.layers.Dense(1, activation = 'sigmoid')
        ])
        # Compile the model
        model.compile(loss='binary_crossentropy',
                optimizer=optimizers.RMSprop(learning_rate=0.001),
                metrics=['accuracy'])
        # Train the model
        history = model.fit(x=train_generator,
        epochs=20,
        callbacks=[callbacks]
        return history
hist = train_happy_sad_model(gen)
```

*Congratulations on finishing the last assignment of this course!

2 C2: Convolutional Neural Networks in TensorFlow

2.1 Week 1: Larger Dataset

• Lab: More sophisticated images with CNN

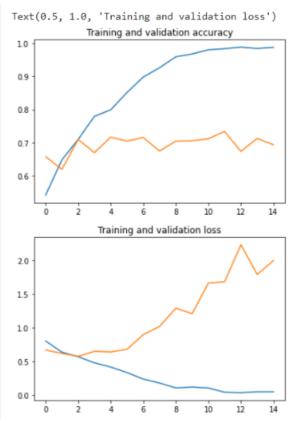
```
# -> Download the dataset
# !wget --no-check-certificate https://storage.googleapis.com/mledu-datasets/cats_and_c
# -> Unzip it
import zipfile
# Unzip the archive
local_zip = './cats_and_dogs_filtered.zip'
zip_ref = zipfile.ZipFile(local_zip, 'r')
zip_ref.extractall()
zip_ref.close()
# -> Subdirectories
import os
base_dir = 'cats_and_dogs_filtered'
```

```
print("Contents of base directory:")
print(os.listdir(base_dir))
print("\nContents of train directory:")
print(os.listdir(f'{base_dir}/train'))
print("\nContents of validation directory:")
print(os.listdir(f'{base_dir}/validation'))
# -> Assign each of these directories to a variable
import os
train_dir = os.path.join(base_dir, 'train')
validation_dir = os.path.join(base_dir, 'validation')
# Directory with training cat/dog pictures
train_cats_dir = os.path.join(train_dir, 'cats')
train_dogs_dir = os.path.join(train_dir, 'dogs')
# Directory with validation cat/dog pictures
validation_cats_dir = os.path.join(validation_dir, 'cats')
validation_dogs_dir = os.path.join(validation_dir, 'dogs')
# -> Filenames
train_cat_fnames = os.listdir( train_cats_dir )
train_dog_fnames = os.listdir( train_dogs_dir )
print(train_cat_fnames[:10])
print(train_dog_fnames[:10])
# -> Total number of cat and dog images in the train
# and validation directories
print('total training cat images :', len(os.listdir(
                                                          train_cats_dir ) ))
print('total training dog images :', len(os.listdir(
                                                          train_dogs_dir ) ))
print('total validation cat images :', len(os.listdir( validation_cats_dir ) ))
print('total validation dog images :', len(os.listdir( validation_dogs_dir ) ))
# -> Building a Small Model from Scratch to get to ~72% Accuracy ->
import tensorflow as tf
model = tf.keras.models.Sequential([
        \# Note the input shape is the desired size of the image 150x150
        # with 3 bytes color
        tf.keras.layers.Conv2D(16, (3,3), activation='relu', input_shape=(150, 150, 3))
        tf.keras.layers.MaxPooling2D(2,2),
        tf.keras.layers.Conv2D(32, (3,3), activation='relu'),
        tf.keras.layers.MaxPooling2D(2,2),
        tf.keras.layers.Conv2D(64, (3,3), activation='relu'),
        tf.keras.layers.MaxPooling2D(2,2),
        # Flatten the results to feed into a DNN
        tf.keras.layers.Flatten(),
        # 512 neuron hidden layer
        tf.keras.layers.Dense(512, activation='relu'),
```

```
# Only 1 output neuron. It will contain a value from O-1
        # where 0 for 1 class ('cats') and 1 for the other ('dogs')
        tf.keras.layers.Dense(1, activation='sigmoid')
1)
model.summary()
# -> Model configuration
from tensorflow.keras.optimizers import RMSprop
model.compile(optimizer=RMSprop(learning_rate=0.001),
loss='binary_crossentropy',
metrics = ['accuracy'])
# -> Data Preprocessing
from tensorflow.keras.preprocessing.image import ImageDataGenerator
# All images will be rescaled by 1./255.
train_datagen = ImageDataGenerator( rescale = 1.0/255. )
test_datagen = ImageDataGenerator( rescale = 1.0/255. )
# -----
# Flow training images in batches of 20 using train_datagen generator
# -----
train_generator = train_datagen.flow_from_directory(train_dir,
       batch_size=20,
       class_mode='binary',
       target_size=(150, 150))
# Flow validation images in batches of 20 using test_datagen generator
# -----
validation_generator = test_datagen.flow_from_directory(validation_dir,
       batch_size=20,
       class_mode = 'binary',
       target_size = (150, 150))
# -> Training
history = model.fit(
        train_generator,
        epochs=15,
        validation_data=validation_generator,
        verbose=2
# -> Take a look at actually running a prediction using the model
import numpy as np
from google.colab import files
from tensorflow.keras.utils import load_img, img_to_array
uploaded=files.upload()
for fn in uploaded.keys():
```

```
# predicting images
path='/content/' + fn
img=load_img(path, target_size=(150, 150))
x=img_to_array(img)
x /= 255
x=np.expand_dims(x, axis=0)
images = np.vstack([x])
classes = model.predict(images, batch_size=10)
print(classes[0])
if classes[0]>0.5:
print(fn + " is a dog")
else:
print(fn + " is a cat")
# -> Visualizing Intermediate Representations
import numpy as np
import random
from tensorflow.keras.utils import img_to_array, load_img
# Define a new Model that will take an image as input, and will output
# intermediate representations for all layers in the previous model
successive_outputs = [layer.output for layer in model.layers]
visualization_model = tf.keras.models.Model(inputs = model.input, outputs = successive
# Prepare a random input image from the training set.
cat_img_files = [os.path.join(train_cats_dir, f) for f in train_cat_fnames]
dog_img_files = [os.path.join(train_dogs_dir, f) for f in train_dog_fnames]
img_path = random.choice(cat_img_files + dog_img_files)
img = load_img(img_path, target_size=(150, 150)) # this is a PIL image
                                                # Numpy array with shape (150, 150, 3
x = img_to_array(img)
x = x.reshape((1,) + x.shape)
                                                # Numpy array with shape (1, 150, 150
# Scale by 1/255
x /= 255.0
# Run the image through the network, thus obtaining all
# intermediate representations for this image.
successive_feature_maps = visualization_model.predict(x)
# These are the names of the layers, so you can have them as part of our plot
layer_names = [layer.name for layer in model.layers]
# Display the representations
for layer_name, feature_map in zip(layer_names, successive_feature_maps):
if len(feature_map.shape) == 4:
#-----
# Just do this for the conv / maxpool layers, not the fully-connected layers
#-----
n_features = feature_map.shape[-1] # number of features in the feature map
       = feature_map.shape[ 1] # feature map shape (1, size, size, n_features)
# Tile the images in this matrix
display_grid = np.zeros((size, size * n_features))
```

```
#-----
# Postprocess the feature to be visually palatable
#-----
for i in range(n_features):
x = feature_map[0, :, :, i]
x = x.mean()
x /= x.std()
x *= 64
x += 128
x = np.clip(x, 0, 255).astype('uint8')
display_grid[:, i * size : (i + 1) * size] = x # Tile each filter into a horizontal gra
#----
# Display the grid
#-----
scale = 20. / n_features
plt.figure( figsize=(scale * n_features, scale) )
plt.title ( layer_name )
plt.grid (False)
plt.imshow( display_grid, aspect='auto', cmap='viridis' )
# -> Evaluating Accuracy and Loss for the Model
#-----
# Retrieve a list of list results on training and test data
# sets for each training epoch
#-----
acc = history.history[ 'accuracy']
val_acc = history.history[ 'val_accuracy' ]
loss = history.history[ 'loss']
val_loss = history.history['val_loss']
epochs = range(len(acc)) # Get number of epochs
#-----
# Plot training and validation accuracy per epoch
#-----
plt.plot (epochs,
                acc )
plt.plot ( epochs, val_acc )
plt.title ('Training and validation accuracy')
plt.figure()
#-----
# Plot training and validation loss per epoch
#-----
plt.plot (epochs,
                 loss )
plt.plot ( epochs, val_loss )
plt.title ('Training and validation loss' )
```



The model is **overfitting** like it's getting out of fashion. The training accuracy (in blue) gets close to 100% while the validation accuracy (in orange) stalls as 70%. The validation loss reaches its minimum after only five epochs.

Since you have a relatively small number of training examples (2000), overfitting should be the number one concern. Overfitting happens when a model exposed to too few examples learns patterns that do not generalize to new data, i.e. when the model starts using irrelevant features for making predictions.

• Week 1 Assignment: Cats vs Dogs

```
import os
import zipfile
import random
import shutil
import tensorflow as tf
from tensorflow.keras.preprocessing.image import ImageDataGenerator
from shutil import copyfile
```

```
import matplotlib.pyplot as plt
# -> Download the dataset
!wget --no-check-certificate \
"https://download.microsoft.com/download/3/E/1/3E1C3F21-ECDB-4869-8368-6DEBA77B919F/kag
-0 "/tmp/cats-and-dogs.zip"
local_zip = '/tmp/cats-and-dogs.zip'
zip_ref = zipfile.ZipFile(local_zip, 'r')
zip_ref.extractall('/tmp')
zip_ref.close()
source_path = '/tmp/PetImages'
source_path_dogs = os.path.join(source_path, 'Dog')
source_path_cats = os.path.join(source_path, 'Cat')
# Deletes all non-image files (there are two .db files bundled into the dataset)
!find /tmp/PetImages/ -type f ! -name "*.jpg" -exec rm {} +
# os.listdir returns a list containing all files under the given path
print(f"There are {len(os.listdir(source_path_dogs))} images of dogs.")
print(f"There are {len(os.listdir(source_path_cats))} images of cats.")
# Define root directory
root_dir = '/tmp/cats-v-dogs'
# Empty directory to prevent FileExistsError is the function is run several times
if os.path.exists(root_dir):
shutil.rmtree(root_dir)
# -> GRADED FUNCTION: create_train_val_dirs
def create_train_val_dirs(root_path):
        Creates directories for the train and test sets
        root_path (string) - the base directory path to create subdirectories from
        Returns:
        None
        # Create training and validation directories
        training_dir = os.path.join(root_path, 'training')
        validation_dir = os.path.join(root_path, 'validation')
        # Create subdirectories for cats and dogs under training and validation director
        os.makedirs(os.path.join(training_dir, 'cats'))
        os.makedirs(os.path.join(training_dir, 'dogs'))
        os.makedirs(os.path.join(validation_dir, 'cats'))
        os.makedirs(os.path.join(validation_dir, 'dogs'))
try:
        create_train_val_dirs(root_path=root_dir)
except FileExistsError:
        print("You should not be seeing this since the upper directory is removed before
# Test your create_train_val_dirs function
```

```
for rootdir, dirs, files in os.walk(root_dir):
        for subdir in dirs:
                print(os.path.join(rootdir, subdir))
# -> GRADED FUNCTION: split_data
def split_data(SOURCE_DIR, TRAINING_DIR, VALIDATION_DIR, SPLIT_SIZE):
        Splits the data into train and test sets
        Aras:
        SOURCE_DIR (string): directory path containing the images
        TRAINING_DIR (string): directory path to be used for training
        VALIDATION_DIR (string): directory path to be used for validation
        SPLIT_SIZE (float): proportion of the dataset to be used for training
        Returns:
        None
        11 11 11
        files = os.listdir(SOURCE_DIR)
        # Filter out files with zero length
        files = [f for f in files if os.path.getsize(os.path.join(SOURCE_DIR, f)) > 0]
        # Shuffle the files
        random.shuffle(files)
        # Determine the split index
        split_idx = int(len(files) * SPLIT_SIZE)
        # Split the files into training and validation sets
        training_files = files[:split_idx]
        validation_files = files[split_idx:]
        # Copy the training files
        for file_name in training_files:
                source = os.path.join(SOURCE_DIR, file_name)
                destination = os.path.join(TRAINING_DIR, file_name)
                copyfile(source, destination)
        # Copy the validation files
        for file_name in validation_files:
                source = os.path.join(SOURCE_DIR, file_name)
                destination = os.path.join(VALIDATION_DIR, file_name)
                copyfile(source, destination)
# Test your split_data function
# Define paths
CAT_SOURCE_DIR = "/tmp/PetImages/Cat/"
DOG_SOURCE_DIR = "/tmp/PetImages/Dog/"
TRAINING_DIR = "/tmp/cats-v-dogs/training/"
VALIDATION_DIR = "/tmp/cats-v-dogs/validation/"
TRAINING_CATS_DIR = os.path.join(TRAINING_DIR, "cats/")
VALIDATION_CATS_DIR = os.path.join(VALIDATION_DIR, "cats/")
TRAINING_DOGS_DIR = os.path.join(TRAINING_DIR, "dogs/")
VALIDATION_DOGS_DIR = os.path.join(VALIDATION_DIR, "dogs/")
```

```
# Empty directories in case you run this cell multiple times
if len(os.listdir(TRAINING_CATS_DIR)) > 0:
        for file in os.scandir(TRAINING CATS DIR):
                os.remove(file.path)
if len(os.listdir(TRAINING_DOGS_DIR)) > 0:
        for file in os.scandir(TRAINING_DOGS_DIR):
                os.remove(file.path)
if len(os.listdir(VALIDATION_CATS_DIR)) > 0:
        for file in os.scandir(VALIDATION_CATS_DIR):
                os.remove(file.path)
if len(os.listdir(VALIDATION_DOGS_DIR)) > 0:
        for file in os.scandir(VALIDATION_DOGS_DIR):
                os.remove(file.path)
# Define proportion of images used for training
split_size = .9
# Run the function
# NOTE: Messages about zero length images should be printed out
split_data(CAT_SOURCE_DIR, TRAINING_CATS_DIR, VALIDATION_CATS_DIR, split_size)
split_data(DOG_SOURCE_DIR, TRAINING_DOGS_DIR, VALIDATION_DOGS_DIR, split_size)
# Check that the number of images matches the expected output
# Function should perform copies rather than moving images so original directories show
print(f"\n\n0riginal cat's directory has {len(os.listdir(CAT_SOURCE_DIR))} images")
print(f"Original dog's directory has {len(os.listdir(DOG_SOURCE_DIR))} images\n")
# Training and validation splits
print(f"There are {len(os.listdir(TRAINING_CATS_DIR))} images of cats for training")
print(f"There are {len(os.listdir(TRAINING_DOGS_DIR))} images of dogs for training")
print(f"There are {len(os.listdir(VALIDATION_CATS_DIR))} images of cats for validation'
print(f"There are {len(os.listdir(VALIDATION_DOGS_DIR))} images of dogs for validation'
# -> GRADED FUNCTION: train_val_generators
def train_val_generators(TRAINING_DIR, VALIDATION_DIR):
        Creates the training and validation data generators
        TRAINING_DIR (string): directory path containing the training images
        VALIDATION_DIR (string): directory path containing the testing/validation image
        train_qenerator, validation_qenerator - tuple containing the generators
        # Instantiate the ImageDataGenerator class
        train_datagen = ImageDataGenerator(rescale=1.0/255.)
        # Pass in the appropriate arguments to the flow_from_directory method
        train_generator = train_datagen.flow_from_directory(directory=TRAINING_DIR,
                batch_size=20,
                class_mode='binary',
```

```
target_size=(150, 150))
        \# Instantiate the ImageDataGenerator class
        validation_datagen = ImageDataGenerator(rescale=1.0/255.)
        # Pass in the appropriate arguments to the flow_from_directory method
        validation_generator = validation_datagen.flow_from_directory(directory=VALIDAT
                batch_size=20,
                class_mode='binary',
                target_size=(150, 150))
        return train_generator, validation_generator
# Test generators
train_generator, validation_generator = train_val_generators(TRAINING_DIR, VALIDATION_I
# -> GRADED FUNCTION: create_model
def create_model():
        from tensorflow.keras.optimizers import RMSprop
        model = tf.keras.models.Sequential([
                tf.keras.layers.Conv2D(16, (3,3), activation='relu', input_shape=(150,
                tf.keras.layers.MaxPooling2D(2,2),
                tf.keras.layers.Conv2D(32, (3,3), activation='relu'),
                tf.keras.layers.MaxPooling2D(2,2),
                tf.keras.layers.Conv2D(64, (3,3), activation='relu'),
                tf.keras.layers.MaxPooling2D(2,2),
                # Flatten the results to feed into a DNN
                tf.keras.layers.Flatten(),
                # 512 neuron hidden layer
                tf.keras.layers.Dense(512, activation='relu'),
                # Only 1 output neuron
                tf.keras.layers.Dense(1, activation='sigmoid')
        ])
        model.compile(optimizer=RMSprop(learning_rate=0.001),
                loss='binary_crossentropy',
                metrics=['accuracy'])
        return model
# Get the untrained model
model = create_model()
# Train the model
# Note that this may take some time.
history = model.fit(train_generator,
        epochs=15,
        verbose=1,
        validation_data=validation_generator)
# Retrieve a list of list results on training and test data
# sets for each training epoch
```

```
acc=history.history['accuracy']
val_acc=history.history['val_accuracy']
loss=history.history['loss']
val_loss=history.history['val_loss']
epochs=range(len(acc)) # Get number of epochs
#-----
# Plot training and validation accuracy per epoch
#-----
plt.plot(epochs, acc, 'r', "Training Accuracy")
plt.plot(epochs, val_acc, 'b', "Validation Accuracy")
plt.title('Training and validation accuracy')
plt.show()
print("")
# Plot training and validation loss per epoch
#-----
plt.plot(epochs, loss, 'r', "Training Loss")
plt.plot(epochs, val_loss, 'b', "Validation Loss")
plt.show()
```

2.2 Week 2: Tackle Overfitting with Data Augmentation

• Image augmentation is a technique used to artificially increase the size of a training dataset by applying various transformations to the original images. This helps in making the model more robust and capable of generalizing well to unseen data.

TensorFlow provides the **ImageDataGenerator** class, which offers a wide range of image augmentation techniques. It can be used to preprocess images, augment them with various transformations, and feed them into a neural network.

An instance of ${\bf ImageDataGenerator}$ can be created with desired augmentations as follows:

from tensorflow.keras.preprocessing.image import ImageDataGenerator

```
train_datagen = ImageDataGenerator(
    rescale=1./255,
    rotation_range=40,
    width_shift_range=0.2,
    height_shift_range=0.2,
    shear_range=0.2,
    zoom_range=0.2,
    horizontal_flip=True,
    fill_mode='nearest'
)
```

The model is **overfitting**.

Here's a brief description of some common parameters:

- rotation range: Degree range for random rotations.
- width_shift_range, height_shift_range: Range for random horizontal and vertical shifts.
- shear _range: Shear intensity (shear angle in counter-clockwise direction).
- **zoom** range: Range for random zoom.
- horizontal_flip: Boolean for randomly flipping half of the images horizontally.
- fill mode: Points outside the boundaries are filled according to the given mode ('nearest', 'reflect', etc.).
- Week assignment: The famous <u>cats vs dogs</u> dataset to train a model that can classify images of dogs from images of cats. Create a Convolutional Neural Network in Tensorflow and leverage Keras' image preprocessing utilities, more so this time around since Keras provides excellent support for augmenting image data.

```
"""
Should be done!!!
```

C2W2 notebook for week's assignment.

2.3 Week 3: Transfer Learning

- Transfer Learning: A powerful technique in deep learning, allowing the use of pre-trained models to accelerate training. TensorFlow simplifies this process.
- Lab 1: Transfer Learning

Next code demonstrates the implementation of **transfer learning** using TensorFlow and the **InceptionV3** pre-trained model to classify images of cats and dogs.

Initially, the pre-trained InceptionV3 model is loaded without the top (fully connected) layer and its weights are set from a downloaded file. The convolutional layers of the model are frozen to retain the pre-trained features, and a custom dense network is appended to the base model. This includes a Flatten layer, a Dense layer with 1024 hidden units and ReLU activation, a **Dropout layer** with a rate of 0.2 to prevent overfitting, and a final sigmoid activation layer for binary classification.

The model is compiled with the RMSprop optimizer and binary crossentropy loss function. The dataset of cats and dogs is downloaded and preprocessed with data augmentation techniques for the training set, including rescaling, rotation, width and height shifting, shear transformation, zooming, and horizontal flipping. The validation data is only rescaled. The model is then trained for 20 epochs with a batch size of 20, using the augmented training data and validation data. Finally, the training and validation accuracy are plotted to visualize the model's performance. The entire code leverages the concept of transfer learning by utilizing a pretrained model's knowledge and fine-tuning it for a specific task, in this case, classifying cats and dogs, leading to faster training and potentially better performance.

```
# -> Setup the pretrained model
# Download the pre-trained weights. No top means it excludes the fully connected layer
!wget --no-check-certificate \
https://storage.googleapis.com/mledu-datasets/inception_v3_weights_tf_dim_ordering_tf_k
-0 /tmp/inception_v3_weights_tf_dim_ordering_tf_kernels_notop.h5
from tensorflow.keras.applications.inception_v3 import InceptionV3
from tensorflow.keras import layers
# Set the weights file you downloaded into a variable
local_weights_file = '/tmp/inception_v3_weights_tf_dim_ordering_tf_kernels_notop.h5'
# Initialize the base model.
# Set the input shape and remove the dense layers.
pre_trained_model = InceptionV3(input_shape = (150, 150, 3),
        include_top = False,
        weights = None)
# Load the pre-trained weights you downloaded.
pre_trained_model.load_weights(local_weights_file)
# Freeze the weights of the layers.
for layer in pre_trained_model.layers:
layer.trainable = False
# -> Choose `mixed7` as the last layer of your base model
last_layer = pre_trained_model.get_layer('mixed7')
print('last layer output shape: ', last_layer.output_shape)
last_output = last_layer.output
# -> Add dense layers for your classifier
from tensorflow.keras.optimizers import RMSprop
from tensorflow.keras import Model
# Flatten the output layer to 1 dimension
x = layers.Flatten()(last_output)
# Add a fully connected layer with 1,024 hidden units and ReLU activation
x = layers.Dense(1024, activation='relu')(x)
# Add a dropout rate of 0.2
x = layers.Dropout(0.2)(x)
```

```
# Add a final sigmoid layer for classification
x = layers.Dense (1, activation='sigmoid')(x)
# Append the dense network to the base model
model = Model(pre_trained_model.input, x)
# Print the model summary. See your dense network connected at the end.
model.summary()
# -> Set the training parameters
model.compile(optimizer = RMSprop(learning_rate=0.0001),
        loss = 'binary_crossentropy',
        metrics = ['accuracy'])
# -> Prepare the dataset
# Download the dataset
wget https://storage.googleapis.com/tensorflow-1-public/course2/cats_and_dogs_filtered
import os
import zipfile
from tensorflow.keras.preprocessing.image import ImageDataGenerator
# Extract the archive
zip_ref = zipfile.ZipFile("./cats_and_dogs_filtered.zip", 'r')
zip_ref.extractall("tmp/")
zip_ref.close()
# Define our example directories and files
base_dir = 'tmp/cats_and_dogs_filtered'
train_dir = os.path.join( base_dir, 'train')
validation_dir = os.path.join( base_dir, 'validation')
# Directory with training cat pictures
train_cats_dir = os.path.join(train_dir, 'cats')
# Directory with training dog pictures
train_dogs_dir = os.path.join(train_dir, 'dogs')
# Directory with validation cat pictures
validation_cats_dir = os.path.join(validation_dir, 'cats')
# Directory with validation dog pictures
validation_dogs_dir = os.path.join(validation_dir, 'dogs')
# Add our data-augmentation parameters to ImageDataGenerator
train_datagen = ImageDataGenerator(rescale = 1./255.,
rotation_range = 40,
width_shift_range = 0.2,
height_shift_range = 0.2,
shear_range = 0.2,
zoom_range = 0.2,
horizontal_flip = True)
# Note that the validation data should not be augmented!
test_datagen = ImageDataGenerator( rescale = 1.0/255. )
# Flow training images in batches of 20 using train_datagen generator
train_generator = train_datagen.flow_from_directory(train_dir,
```

```
batch_size = 20,
class_mode = 'binary',
target_size = (150, 150))
# Flow validation images in batches of 20 using test_datagen generator
validation_generator = test_datagen.flow_from_directory( validation_dir,
batch_size = 20,
class_mode = 'binary',
target_size = (150, 150))
# -> Train the model
# Train the model.
history = model.fit(
        train_generator,
        validation_data = validation_generator,
        steps_per_epoch = 100,
        epochs = 20,
        validation_steps = 50,
        verbose = 2)
# -> Evaluate the results
import matplotlib.pyplot as plt
acc = history.history['accuracy']
val_acc = history.history['val_accuracy']
loss = history.history['loss']
val_loss = history.history['val_loss']
epochs = range(len(acc))
plt.plot(epochs, acc, 'r', label='Training accuracy')
plt.plot(epochs, val_acc, 'b', label='Validation accuracy')
plt.title('Training and validation accuracy')
plt.legend(loc=0)
plt.figure()
plt.show()
```

• Week's assignment:

Transfer Learning to see if you can increase training accuracy for Horses v Humans.

Should be done!!!

C2W3 notebook for week's assignment.

2.4 Week 4: Multiclass Classifications

• The **key change** here is the loss function. Whereas before you were using binary crossentropy for 2 classes, you will change it to **categori**-

```
cal crossentropy to extend it to more classes.
 model.compile(
          loss = 'categorical_crossentropy',
          optimizer='rmsprop',
          metrics=['accuracy']
 )
 Prepare the ImageDataGenerator:
 from tensorflow.keras.preprocessing.image import ImageDataGenerator
 TRAINING_DIR = "tmp/rps-train/rps"
 training_datagen = ImageDataGenerator(
         rescale = 1./255,
          rotation_range=40,
          width_shift_range=0.2,
          height_shift_range=0.2,
          shear_range=0.2,
          zoom_range=0.2,
          horizontal_flip=True,
          fill_mode='nearest')
 VALIDATION_DIR = "tmp/rps-test/rps-test-set"
 validation_datagen = ImageDataGenerator(rescale = 1./255)
 train_generator = training_datagen.flow_from_directory(
          TRAINING_DIR,
          target_size=(150,150),
          class_mode='categorical',
          batch_size=126
 )
 validation_generator = validation_datagen.flow_from_directory(
          VALIDATION_DIR,
          target_size=(150,150),
          class_mode='categorical',
          batch_size=126
• Week's assignment:
 Multi-class classification problem using the Sign Language MNIST
 dataset.
                  11 11 11
                  Should be done!!!
```

C2W4 notebook for week's assignment.

3 C3: Natural Language Processing in TensorFlow

3.1 Week 1: Intro to NLP

• Lab 1: Tokenizer Basics Generating the vocabulary

```
from tensorflow.keras.preprocessing.text import Tokenizer
 # Define input sentences
 sentences = [
 'i love my dog',
 'I, love my cat'
 # Initialize the Tokenizer class
 tokenizer = Tokenizer(num_words = 100)
 # Generate indices for each word in the corpus
 tokenizer.fit_on_texts(sentences)
 # Get the indices and print it
 word_index = tokenizer.word_index
 print(word_index)
• Lab 2: Sequences and Padding
 Text to sequences of tokens
 from tensorflow.keras.preprocessing.text import Tokenizer
 from tensorflow.keras.preprocessing.sequence import pad_sequences
 # Define your input texts
 sentences = [
         'I love my dog',
         'I love my cat',
         'You love my dog!',
         'Do you think my dog is amazing?'
 ]
 # Initialize the Tokenizer class
 tokenizer = Tokenizer(num_words = 100, oov_token="<00V>")
 # Tokenize the input sentences
 tokenizer.fit_on_texts(sentences)
 # Get the word index dictionary
 word_index = tokenizer.word_index
```

```
# Generate list of token sequences
 sequences = tokenizer.texts_to_sequences(sentences)
 # Print the result
 print("\nWord Index = " , word_index)
 print("\nSequences = " , sequences)
 Pad the sequences into a uniform length
 # Pad the sequences to a uniform length
 padded = pad_sequences(sequences, maxlen=5, padding='post', truncating='post')
 # Print the result
 print("\nPadded Sequences:")
 print(padded)
• Lab 3: Tokenizing the Sarcasm Dataset
 Load JSON file into my workplace
 import json
 # Load the JSON file
 with open("./sarcasm.json", 'r') as f:
          datastore = json.load(f)
 Collect all urls, headlines, and labels for easier processing
 # Initialize lists
 sentences = []
 labels = []
 urls = []
 # Append elements in the dictionaries into each list
 for item in datastore:
          sentences.append(item['headline'])
          labels.append(item['is_sarcastic'])
          urls.append(item['article_link'])
 Preprocessing the headlines
 from tensorflow.keras.preprocessing.text import Tokenizer
 from tensorflow.keras.preprocessing.sequence import pad_sequences
 # Initialize the Tokenizer class
 tokenizer = Tokenizer(oov_token="<00V>")
 # Generate the word index dictionary
 tokenizer.fit_on_texts(sentences)
```

```
# Print the length of the word index
word index = tokenizer.word index
print(f'number of words in word_index: {len(word_index)}')
# Print the word index
print(f'word_index: {word_index}')
print()
# Generate and pad the sequences
sequences = tokenizer.texts_to_sequences(sentences)
padded = pad_sequences(sequences, padding='post')
# Print a sample headline
index = 2
print(f'sample headline: {sentences[index]}')
print(f'padded sequence: {padded[index]}')
print()
# Print dimensions of padded sequences
print(f'shape of padded sequences: {padded.shape}')
```

• Week's assignment:

Work with a variation of the **BBC News Classification Dataset**, which contains 2225 examples of news articles with their respective categories (labels).

"""
Should be done!!!

C3W1 notebook for week's assignment.

3.2 Week 2: Word Embeddings

• Lab 1: Training a binary classifier with the IMDB

```
import tensorflow_datasets as tfds

# -> Load the IMDB Reviews dataset
imdb, info = tfds.load("imdb_reviews", with_info=True, as_supervised=True)

# -> Split the dataset
import numpy as np
# Get the train and test sets
train_data, test_data = imdb['train'], imdb['test']
```

```
# Initialize sentences and labels lists
training_sentences = []
training_labels = []
testing_sentences = []
testing_labels = []
# Loop over all training examples and save the sentences and labels
for s,l in train_data:
        training_sentences.append(s.numpy().decode('utf8'))
        training_labels.append(l.numpy())
# Loop over all test examples and save the sentences and labels
for s,l in test_data:
        testing_sentences.append(s.numpy().decode('utf8'))
        testing_labels.append(l.numpy())
# Convert labels lists to numpy array
training_labels_final = np.array(training_labels)
testing_labels_final = np.array(testing_labels)
# -> Generate Padded Sequences
# Parameters
vocab_size = 10000
max_length = 120
embedding_dim = 16
trunc_type='post'
oov_tok = "<00V>"
from tensorflow.keras.preprocessing.text import Tokenizer
from tensorflow.keras.preprocessing.sequence import pad_sequences
# Initialize the Tokenizer class
tokenizer = Tokenizer(num_words = vocab_size, oov_token=oov_tok)
# Generate the word index dictionary for the training sentences
tokenizer.fit_on_texts(training_sentences)
word_index = tokenizer.word_index
# Generate and pad the training sequences
sequences = tokenizer.texts_to_sequences(training_sentences)
padded = pad_sequences(sequences,maxlen=max_length, truncating=trunc_type)
# Generate and pad the test sequences
testing_sequences = tokenizer.texts_to_sequences(testing_sentences)
testing_padded = pad_sequences(testing_sequences, maxlen=max_length, truncating=trunc_ty
# -> Build and Compile the Model
import tensorflow as tf
# Build the model
model = tf.keras.Sequential([
        tf.keras.layers.Embedding(vocab_size, embedding_dim, input_length=max_length),
        tf.keras.layers.Flatten(),
        tf.keras.layers.Dense(6, activation='relu'),
```

```
tf.keras.layers.Dense(1, activation='sigmoid')
])
# Setup the training parameters
model.compile(loss='binary_crossentropy',optimizer='adam',metrics=['accuracy'])
# Print the model summary
model.summary()
# -> Train the Model
num_epochs = 10
# Train the model
model.fit(padded, training_labels_final, epochs=num_epochs, validation_data=(testing_padded)
# -> Visualize Word Embeddings
# Get the embedding layer from the model (i.e. first layer)
embedding_layer = model.layers[0]
# Get the weights of the embedding layer
embedding_weights = embedding_layer.get_weights()[0]
# Print the shape. Expected is (vocab_size, embedding_dim)
print(embedding_weights.shape)
# Get the index-word dictionary
reverse_word_index = tokenizer.index_word
# loop to generate the files. You will loop vocab_size-1 times, skipping the O key become
import io
# Open writeable files
out_v = io.open('vecs.tsv', 'w', encoding='utf-8')
out_m = io.open('meta.tsv', 'w', encoding='utf-8')
# Initialize the loop. Start counting at `1` because `0` is just for the padding
for word_num in range(1, vocab_size):
        # Get the word associated at the current index
        word_name = reverse_word_index[word_num]
        # Get the embedding weights associated with the current index
        word_embedding = embedding_weights[word_num]
        # Write the word name
        out_m.write(word_name + "\n")
        # Write the word embedding
        out_v.write('\t'.join([str(x) for x in word_embedding]) + "\n")
# Close the files
out_v.close()
out m.close()
# Now you can go to the Tensorflow Embedding Projector and load the two files
# you downloaded to see the visualization. You can search for words like worst and
# fantastic and see the other words closely located to these.
```

• Training a binary classifier with the Sarcasm Dataset

```
# -> Download dataset
import json
```

```
# Load the JSON file
with open("./sarcasm.json", 'r') as f:
datastore = json.load(f)
# Initialize the lists
sentences = []
labels = []
# Collect sentences and labels into the lists
for item in datastore:
        sentences.append(item['headline'])
        labels.append(item['is_sarcastic'])
# -> Hyperparameters
# Number of examples to use for training
training_size = 20000
# Vocabulary size of the tokenizer
vocab_size = 10000
# Maximum length of the padded sequences
max_length = 32
# Output dimensions of the Embedding layer
embedding_dim = 16
# -> Split the dataset
# Split the sentences
training_sentences = sentences[0:training_size]
testing_sentences = sentences[training_size:]
# Split the labels
training_labels = labels[0:training_size]
testing_labels = labels[training_size:]
# -> Preprocessing the train and test sets
import numpy as np
from tensorflow.keras.preprocessing.text import Tokenizer
from tensorflow.keras.preprocessing.sequence import pad_sequences
# Parameters for padding and OOV tokens
trunc_type='post'
padding_type='post'
oov_tok = "<00V>"
# Initialize the Tokenizer class
tokenizer = Tokenizer(num_words=vocab_size, oov_token=oov_tok)
# Generate the word index dictionary
tokenizer.fit_on_texts(training_sentences)
word_index = tokenizer.word_index
# Generate and pad the training sequences
training_sequences = tokenizer.texts_to_sequences(training_sentences)
training_padded = pad_sequences(training_sequences, maxlen=max_length, padding=padding_
# Generate and pad the testing sequences
```

```
testing_sequences = tokenizer.texts_to_sequences(testing_sentences)
testing_padded = pad_sequences(testing_sequences, maxlen=max_length, padding=padding_ty
# Convert the labels lists into numpy arrays
training_labels = np.array(training_labels)
testing_labels = np.array(testing_labels)
# -> Build and Compile the Model
import tensorflow as tf
# Initialize a GlobalAveragePooling1D (GAP1D) layer
gap1d_layer = tf.keras.layers.GlobalAveragePooling1D()
# Define sample array
sample_array = np.array([[[10,2],[1,3],[1,1]]])
# Print shape and contents of sample array
print(f'shape of sample_array = {sample_array.shape}')
print(f'sample array: {sample_array}')
# Pass the sample array to the GAP1D layer
output = gap1d_layer(sample_array)
# Print shape and contents of the GAP1D output array
print(f'output shape of gap1d_layer: {output.shape}')
print(f'output array of gap1d_layer: {output.numpy()}')
# Build the model
model = tf.keras.Sequential([
tf.keras.layers.Embedding(vocab_size, embedding_dim, input_length=max_length),
tf.keras.layers.GlobalAveragePooling1D(),
tf.keras.layers.Dense(24, activation='relu'),
tf.keras.layers.Dense(1, activation='sigmoid')
# Print the model summary
model.summary()
# Compile the model
model.compile(loss='binary_crossentropy',optimizer='adam',metrics=['accuracy'])
# -> Train the Model
num_epochs = 30
# Train the model
history = model.fit(training_padded, training_labels, epochs=num_epochs, validation_dat
# -> Visualize the Results
import matplotlib.pyplot as plt
# Plot utility
def plot_graphs(history, string):
plt.plot(history.history[string])
plt.plot(history.history['val_'+string])
plt.xlabel("Epochs")
```

```
plt.legend([string, 'val_'+string])
plt.show()
# Plot the accuracy and loss
plot_graphs(history, "accuracy")
plot_graphs(history, "loss")
  1.00
  0.95
  0.90
 o.es
  0.80
   0.75
                                     accuracy
   0.70
                                     val_accuracy
                         15
                                     25
                       Epochs
         loss
        val_loss
  1.50
   1.25
s 1.00
   0.75
   0.50
   0.00
                   10
                               20
                       Epochs
# -> Visualize Word Embeddings
# using the Tensorflow Embedding Projector
# Get the index-word dictionary
reverse_word_index = tokenizer.index_word
# Get the embedding layer from the model (i.e. first layer)
embedding_layer = model.layers[0]
# Get the weights of the embedding layer
embedding_weights = embedding_layer.get_weights()[0]
# Print the shape. Expected is (vocab_size, embedding_dim)
print(embedding_weights.shape)
```

plt.ylabel(string)

```
import io
# Open writeable files
out_v = io.open('vecs.tsv', 'w', encoding='utf-8')
out_m = io.open('meta.tsv', 'w', encoding='utf-8')
# Initialize the loop. Start counting at `1` because `0` is just for the padding
for word_num in range(1, vocab_size):
# Get the word associated at the current index
word_name = reverse_word_index[word_num]
# Get the embedding weights associated with the current index
word_embedding = embedding_weights[word_num]
# Write the word name
out_m.write(word_name + "\n")
# Write the word embedding
out_v.write('\t'.join([str(x) for x in word_embedding]) + "\n")
# Close the files
out_v.close()
out_m.close()
# Download the files (???)
files.download('vecs.tsv')
files.download('meta.tsv')
```

So far, tokenizing datasets from scratch we treating the **vocab size as a hyperparameter**. Furthermore, we're tokenizing the texts by building a vocabulary of full words. In the next lab, we will make use of a **pretokenized dataset** that uses a vocabulary of subwords.

• *