



# **Replace the real-time clock battery**

## **ONTAP Systems**

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# Replace the real-time clock battery

You replace the real-time clock (RTC) battery in the controller module so that your system's services and applications that depend on accurate time synchronization continue to function.

- You can use this procedure with all versions of ONTAP supported by your system
- All other components in the system must be functioning properly; if not, you must contact technical support.

## Step 1: Shut down the impaired controller

To shut down the impaired node, you must determine the status of the node and, if necessary, take over the node so that the healthy node continues to serve data from the impaired node storage.

### About this task

If you have a cluster with more than two nodes, it must be in quorum. If the cluster is not in quorum or a healthy node shows false for eligibility and health, you must correct the issue before shutting down the impaired node.

[ONTAP 9 System Administration Reference](#)

### Steps

1. If AutoSupport is enabled, suppress automatic case creation by invoking an AutoSupport message:

```
system node autosupport invoke -node * -type all -message  
MAINT=number_of_hours_downh
```

The following AutoSupport message suppresses automatic case creation for two hours: `cluster1:*>`

```
system node autosupport invoke -node * -type all -message MAINT=2h
```

2. Disable automatic giveback from the console of the healthy node: `storage failover modify -node local -auto-giveback false`
3. Take the impaired node to the LOADER prompt:

If the impaired node is displaying...	Then...
The LOADER prompt	Go to the next step.
Waiting for giveback...	Press Ctrl-C, and then respond <code>y</code> when prompted.
System prompt or password prompt (enter system password)	<p>Take over or halt the impaired node:</p> <ul style="list-style-type: none"><li>• For an HA pair, take over the impaired node from the healthy node: <code>storage failover takeover -ofnode <i>impaired_node_name</i></code></li></ul> <p>When the impaired node shows Waiting for giveback..., press Ctrl-C, and then respond <code>y</code>.</p>

# Step 2: Remove the controller module

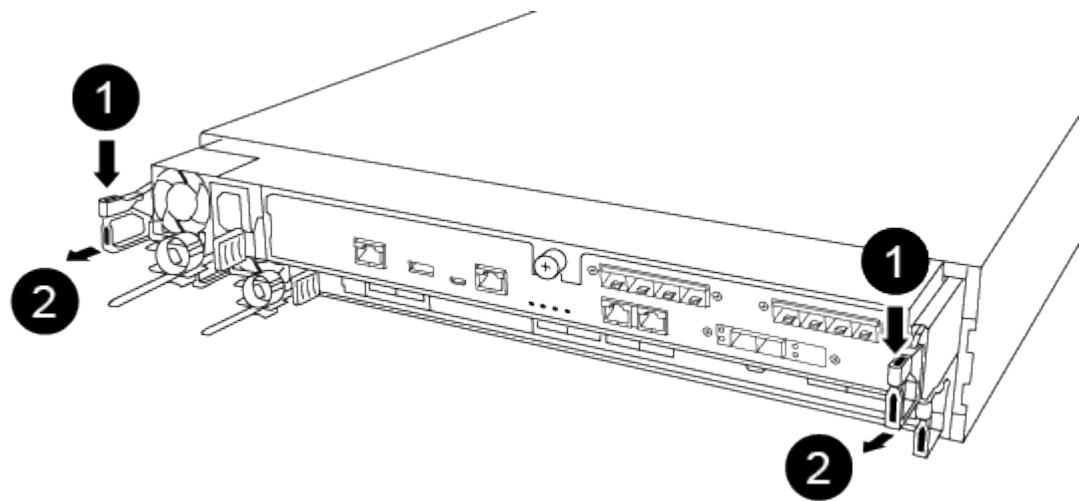
You must remove the controller module from the chassis when you replace a component inside the controller module.

Make sure that you label the cables so that you know where they came from.

- 1. If you are not already grounded, properly ground yourself.
- 2. Unplug the controller module power supplies from the source.
- 3. Release the power cable retainers, and then unplug the cables from the power supplies.
- 4. Insert your forefinger into the latching mechanism on either side of the controller module, press the lever with your thumb, and gently pull the controller a few inches out of the chassis.



If you have difficulty removing the controller module, place your index fingers through the finger holes from the inside (by crossing your arms)



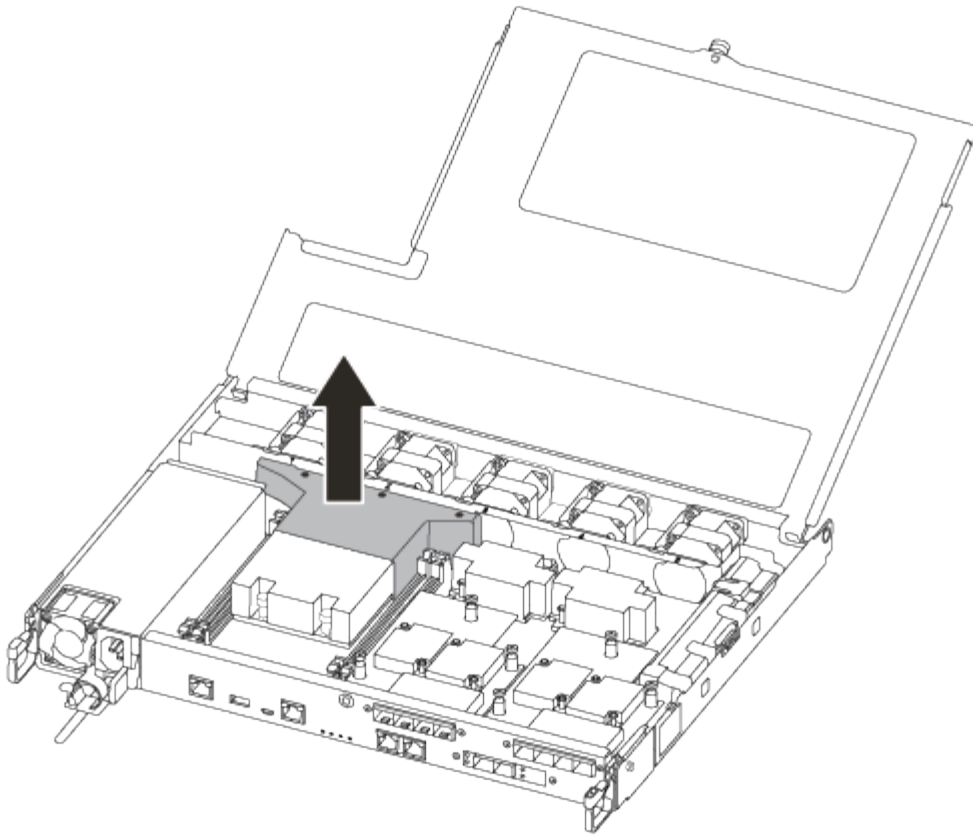
1	Lever
2	Latching mechanism

- 5. Using both hands, grasp the controller module sides and gently pull it out of the chassis and set it on a flat, stable surface.
- 6. Turn the thumbscrew on the front of the controller module anti-clockwise and open the controller module cover.



1	Thumbscrew
2	Controller module cover.

7. Lift out the air duct cover.



## Step 3: Replace the RTC battery

To replace the RTC battery, locate it inside the controller and follow the specific sequence of steps.

You can use the following video or the tabulated steps to replace the RTC battery:

### [Replacing the RTC battery](#)

1. Locate the RTC battery between the heatsink and the midplane and remove it exactly as shown in the graphic.



1	<p>Gently pull tab away from the battery housing.</p> <p>NOTE: Pulling it away aggressively might displace the tab.</p>
2	<p>Lift the battery up.</p> <div data-bbox="873 1255 928 1318"> <p>i</p> </div> <p>Make a note of the polarity of the battery.</p>
3	<p>The battery should eject out.</p>

The battery will be ejected out.

2. Remove the replacement battery from the antistatic shipping bag.
3. Locate the RTC battery holder between the heatsink and the midplane and insert it exactly as shown in the graphic.



1	With positive polarity face up, slide the battery under the tab of the battery housing.
2	<p>Push the battery gently into place and make sure the tab secures it to the housing.</p> <p><b>Attention:</b> Pushing it in aggressively might cause the battery to eject out again.</p>

4. Visually inspect the battery to make sure that it is completely installed into the holder and that the polarity is correct.

## Step 4: Reinstall the controller module and set time/date after RTC battery replacement

After you replace a component within the controller module, you must reinstall the controller module in the system chassis, reset the time and date on the controller, and then boot it.

### Steps

1. If you have not already done so, close the air duct or controller module cover.
2. Align the end of the controller module with the opening in the chassis, and then gently push the controller module halfway into the system.



Do not completely insert the controller module in the chassis until instructed to do so.

3. Recable the system, as needed.

If you removed the media converters (QSFPs or SFPs), remember to reinstall them if you are using fiber optic cables.

4. If the power supplies were unplugged, plug them back in and reinstall the power cable retainers.

5. Insert the controller module into the chassis:

- a. Ensure the latching mechanism arms are locked in the fully extended position.
- b. Using both hands, align and gently slide the controller module into the latching mechanism arms until it stops.
- c. Place your index fingers through the finger holes from the inside of the latching mechanism.
- d. Press your thumbs down on the orange tabs on top of the latching mechanism and gently push the controller module over the stop.
- e. Release your thumbs from the top of the latching mechanisms and continue pushing until the latching mechanisms snap into place.

The controller module begins to boot as soon as it is fully seated in the chassis. Be prepared to interrupt the boot process.

- f. Halt the controller at the `LOADER` prompt.

The controller module should be fully inserted and flush with the edges of the chassis.

6. Reset the time and date on the controller:

- a. Check the date and time on the healthy node with the `show date` command.
- b. At the `LOADER` prompt on the target node, check the time and date.
- c. If necessary, modify the date with the `set date mm/dd/yyyy` command.
- d. If necessary, set the time, in GMT, using the `set time hh:mm:ss` command.
- e. Confirm the date and time on the target node.

7. At the `LOADER` prompt, enter `bye` to reinitialize the PCIe cards and other components and let the node reboot.

8. Return the node to normal operation by giving back its storage: `storage failover giveback -ofnode impaired_node_name`

9. If automatic giveback was disabled, reenable it: `storage failover modify -node local -auto-giveback true`

## Step 5: Complete the replacement process

After you replace the part, you can return the failed part to NetApp, as described in the RMA instructions shipped with the kit. Contact technical support at [NetApp Support](#), 888-463-8277 (North America), 00-800-44-638277 (Europe), or +800-800-80-800 (Asia/Pacific) if you need the RMA number or additional help with the replacement procedure.

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