```
/* Moves motor 1 or 2 at a certain speed. Accepts 1 or 2 for
motor, 0-255 for speed. */
void setSpeed(int motor, int motorSpeed){}
/* Sets the direction of motor 1 or 2 forward. */
void forward(int motor){}
/* Sets the direction of motor 1 or 2 backward. */
void backward(int motor) { }
/* Returns true if there is more light than turn on time by
LIGHT DIFFERENCE. */
boolean moreLight(){}
/* Returns true if there is less light than turn on time by
LIGHT DIFFERENCE. */
boolean lessLight(){}
/* Returns true if line detected */
boolean line(int sensorNum){}
/* Delay for x milliseconds */
void delay(int x)
```