

INF5620 - Compulsory project 1

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Exercise 2.2

Want to discretize the equation (1):

$$\frac{\partial^2 u}{\partial t^2} + b \frac{\partial u}{\partial t} = \frac{\partial}{\partial x} (q(x, y) \frac{\partial u}{\partial x}) + \frac{\partial}{\partial y} (q(x, y) \frac{\partial u}{\partial y}) + f(x, y, t)$$

on the domain $\Omega = [0, L_x] \times [0, L_y]$, and time in $t \in [0, T]$.

Discretize domain

Divide $[0, L_x]$ into N_x intervals $[x_i, x_{i+1}]$, with $i \in \{0, \dots, N_x - 1\}$, with $x_0 = 0$ and $x_{N_x} = L_x$. Do the same for $[0, L_y]$, so you get $\{y_j\}_{j=0}^{N_y}$, and $[0, T]$ so you get $\{t_n\}_{n=0}^{N_t}$. From now on let $u(x_i, y_j, t_n) = u_{i,j}^n$.

Discretize equation for inner points

I discretize with finite differences term by term. For $\frac{\partial^2 u}{\partial t^2}$ I use centred difference:

$$\frac{\partial^2 u}{\partial t^2}(x_i, y_j, t_n) \approx \frac{u_{i,j}^{n+1} - 2u_{i,j}^n + u_{i,j}^{n-1}}{\Delta t^2}$$

For $b \frac{\partial u}{\partial t}$ I use forward difference:

$$b \frac{\partial u}{\partial t}(x_i, y_j, t_n) \approx b \frac{u_{i,j}^{n+1} - u_{i,j}^n}{\Delta t}$$

For $\frac{\partial}{\partial x} (q(x, y) \frac{\partial u}{\partial x})$ and $\frac{\partial}{\partial y} (q(x, y) \frac{\partial u}{\partial y})$ I use the normal centred difference for variable coefficient:

$$\frac{\partial}{\partial x} (q(x, y) \frac{\partial u}{\partial x})(x_i, y_j, t_n) \approx \frac{1}{\Delta x^2} (q_{i+\frac{1}{2},j} (u_{i+1,j}^n - u_{i,j}^n) - q_{i-\frac{1}{2},j} (u_{i,j}^n - u_{i-1,j}^n))$$

$$\frac{\partial}{\partial y} (q(x, y) \frac{\partial u}{\partial y})(x_i, y_j, t_n) \approx \frac{1}{\Delta y^2} (q_{i,j+\frac{1}{2}} (u_{i,j+1}^n - u_{i,j}^n) - q_{i,j-\frac{1}{2}} (u_{i,j}^n - u_{i,j-1}^n))$$

Want to find expression for $u_{i,j}^{n+1}$, for calculating inner points. Set $C = \frac{\partial}{\partial x} (q(x, y) \frac{\partial u}{\partial x}) + \frac{\partial}{\partial y} (q(x, y) \frac{\partial u}{\partial y}) + f(x, y, t)$. Then :

$$\frac{u_{i,j}^{n+1} - 2u_{i,j}^n + u_{i,j}^{n-1}}{\Delta t^2} + b \frac{u_{i,j}^{n+1} - u_{i,j}^n}{\Delta t} = C$$

$$\iff u_{i,j}^{n+1} - 2u_{i,j}^n + u_{i,j}^{n-1} + \Delta t b (u_{i,j}^{n+1} - u_{i,j}^n) = \Delta t^2 C$$

$$\begin{aligned}\Leftrightarrow u_{i,j}^{n+1}(1 + \Delta tb) &= u_{i,j}^n(2 + \Delta tb) - u_{i,j}^{n-1} + \Delta t^2 C \\ \Leftrightarrow u_{i,j}^{n+1} &= \frac{u_{i,j}^n(2 + \Delta tb) - u_{i,j}^{n-1} + \Delta t^2 C}{(1 + \Delta tb)}\end{aligned}$$

If we set in expression for C we get (2):

$$\begin{aligned}u_{i,j}^{n+1} &= \frac{u_{i,j}^n(2 + \Delta tb) - u_{i,j}^{n-1} + \Delta t^2 f_{i,j}^n}{(1 + \Delta tb)} \\ &+ \frac{\Delta t^2 (q_{i+\frac{1}{2},j}(u_{i+1,j}^n - u_{i,j}^n) - q_{i-\frac{1}{2},j}(u_{i,j}^n - u_{i-1,j}^n))}{\Delta x^2 (1 + \Delta tb)} \\ &+ \frac{\Delta t^2 (q_{i,j+\frac{1}{2}}(u_{i,j+1}^n - u_{i,j}^n) - q_{i,j-\frac{1}{2}}(u_{i,j}^n - u_{i,j-1}^n))}{\Delta y^2 (1 + \Delta tb)}\end{aligned}$$

Discretize first step

For the first step we do not know $u_{i,j}^{-1}$, but the initial condition $u(x, y, 0) = I(x, y)$ gives us $u_{i,j}^0$. The second initial condition is $u_t(x, y, 0) = V(x, y)$. To find an expression for $u_{i,j}^{-1}$, we discretize $u_t(x, y, 0) = V(x, y)$:

$$u_t(x_i, y_j, 0) \approx \frac{u_{i,j}^1 - u_{i,j}^{-1}}{2\Delta t}$$

Set this equal to $V_{i,j}$, and we get an expression for $u_{i,j}^{-1}$:

$$\frac{u_{i,j}^1 - u_{i,j}^{-1}}{2\Delta t} = V_{i,j} \Leftrightarrow u_{i,j}^{-1} = u_{i,j}^1 - 2\Delta t V_{i,j}$$

Set this into the above result for inner points we get:

$$\begin{aligned}u_{i,j}^1(1 + \Delta tb) &= u_{i,j}^0(2 + \Delta tb) - u_{i,j}^{-1} + 2\Delta t V_{i,j} + \Delta t^2 C \\ \Leftrightarrow u_{i,j}^1(2 + \Delta tb) &= u_{i,j}^0(2 + \Delta tb) + 2\Delta t V_{i,j} + \Delta t^2 C \\ \Leftrightarrow u_{i,j}^1 &= \frac{u_{i,j}^0(2 + \Delta tb) + 2\Delta t V_{i,j} + \Delta t^2 C}{2 + \Delta tb}\end{aligned}$$

Here C is the discrete version of:

$$C = \frac{\partial}{\partial x}(q(x_i, y_j) \frac{\partial u(x_i, y_j, 0)}{\partial x}) + \frac{\partial}{\partial y}(q(x_i, y_j) \frac{\partial u(x_i, y_j, 0)}{\partial y}) + f(x_i, y_j, 0)$$

Discretize Neumann conditions

Lastly we need to handle the boundary, with homogeneous Neumann conditions. There are three cases:

(i): $(x_i, y_j) \in (0, L_x) \times \{0\} \cup (0, L_x) \times \{L_y\}$.

(ii): $(x_i, y_j) \in \{0\} \times (0, L_y) \cup \{L_x\} \times (0, L_y)$.

(iii): $(x_i, y_j) \in \{(0, 0), (0, L_y), (L_x, 0), (L_x, L_y)\}$.

For case (i) I only look at points (x_i, y_0) . The Neumann condition gives us $u_y(x_i, y_0, t_n) = 0$. With the normal discretization of this we get:

$$\frac{u_{i,1}^n - u_{i,-1}^n}{2\Delta y} = 0 \iff u_{i,-1}^n = u_{i,1}^n$$

The only part of the scheme that is affected is $\frac{\partial}{\partial y}(q(x, y) \frac{\partial u}{\partial y})$, we get:

$$\begin{aligned} \frac{1}{\Delta y^2} (q_{i,\frac{1}{2}}(u_{i,1}^n - u_{i,0}^n) - q_{i,-\frac{1}{2}}(u_{i,0}^n - u_{i,-1}^n)) &= \frac{1}{\Delta y^2} (q_{i,\frac{1}{2}}(u_{i,1}^n - u_{i,0}^n) + q_{i,-\frac{1}{2}}(u_{i,1}^n - u_{i,0}^n)) \\ &= \frac{1}{\Delta y^2} (u_{i,1}^n - u_{i,0}^n)(q_{i,\frac{1}{2}} + q_{i,-\frac{1}{2}}) \end{aligned}$$

Since $q_{i,-\frac{1}{2}}$ is evaluating q outside of our domain, we make the following ansatz: $q_{i,-\frac{1}{2}} \approx q_{i,\frac{1}{2}} \approx q_{i,0}$. This gives:

$$\frac{\partial}{\partial y}(q(x_i, 0) \frac{\partial u(x_i, 0, t_n)}{\partial y}) \approx \frac{2(u_{i,1}^n - u_{i,0}^n)q_{i,0}}{\Delta y^2}$$

For $y = L_y$, we get the following by same arguments:

$$\frac{\partial}{\partial y}(q(x_i, L_y) \frac{\partial u(x_i, y_{N_y}, t_n)}{\partial y}) \approx \frac{2(u_{i,N_y-1}^n - u_{i,N_y}^n)q_{i,N_y}}{\Delta y^2}$$

For case (ii), we get the same, but now we have:

$$u_x(x_0, y_j, t_n) = u_x(x_{N_x}, y_j, t_n) = 0$$

By the same approach as for case (i), we get

$$\frac{\partial}{\partial x}(q(0, y_j) \frac{\partial u(0, y_j, t_n)}{\partial x}) \approx \frac{2(u_{1,j}^n - u_{0,j}^n)q_{0,j}}{\Delta x^2}$$

and

$$\frac{\partial}{\partial x}(q(L_x, y_j) \frac{\partial u(x_{N_x}, y_j, t_n)}{\partial x}) \approx \frac{2(u_{N_x-1,j}^n - u_{N_x,j}^n)q_{N_x,j}}{\Delta x^2}$$

For case (iii), we get both case (i) and (ii). This means we already have the expressions needed to explicitly find u for points in (iii). If you want the

formulas for the boundary points, you need to substitute the expressions for the x and y derivatives in (2) with the ones we have found above.

Exercise 3.1

Want to prove that a constant solution also solves the discrete equation:

$$\begin{aligned} & \frac{u_{i,j}^{n+1} - 2u_{i,j}^n + u_{i,j}^{n-1}}{\Delta t^2} + b \frac{u_{i,j}^{n+1} - u_{i,j}^n}{\Delta t} \\ &= \frac{1}{\Delta x^2} (q_{i+\frac{1}{2},j} (u_{i+1,j}^n - u_{i,j}^n) - q_{i-\frac{1}{2},j} (u_{i,j}^n - u_{i-1,j}^n)) \\ &+ \frac{1}{\Delta y^2} (q_{i,j+\frac{1}{2}} (u_{i,j+1}^n - u_{i,j}^n) - q_{i,j-\frac{1}{2}} (u_{i,j}^n - u_{i,j-1}^n)) \end{aligned}$$

A constant solution $u(x, y, t) = c$ means that $u_{i,j}^n = c$. This means that

$$\frac{u_{i,j}^{n+1} - 2u_{i,j}^n + u_{i,j}^{n-1}}{\Delta t^2} + b \frac{u_{i,j}^{n+1} - u_{i,j}^n}{\Delta t} = \frac{c - 2c + c}{\Delta t^2} + b \frac{c - c}{\Delta t} = 0$$

and:

$$\begin{aligned} & \frac{1}{\Delta x^2} (q_{i+\frac{1}{2},j} (u_{i+1,j}^n - u_{i,j}^n) - q_{i-\frac{1}{2},j} (u_{i,j}^n - u_{i-1,j}^n)) \\ &= \frac{1}{\Delta x^2} (q_{i+\frac{1}{2},j} (c - c) - q_{i-\frac{1}{2},j} (c - c)) = 0 \end{aligned}$$

and:

$$\frac{1}{\Delta y^2} (q_{i,j+\frac{1}{2}} (u_{i,j+1}^n - u_{i,j}^n) - q_{i,j-\frac{1}{2}} (u_{i,j}^n - u_{i,j-1}^n)) = 0$$

This means that the discrete equation is satisfied when u is constant.

Exercise 3.1.4: Making bugs

To make it simple, all my bugs are made in the first step, and are shown in the code.

(1): The first bug is to not implement the initial condition correctly. This causes errors.

(2): The second bug, is to change a sign in the scheme. This does not cause errors, since the terms I subtract are both zero.

(3): The third bug is also a changed sign, but this time the two non-zero terms are added instead of subtracted, and we therefore get errors.

(4): The fourth bug is changing the q function in the in the scheme. This does not create errors, since the constant solution does not depend on q because q is multiplied by zero.

(5): Use current timestep to calculate one of the boarders instead of the previous one. This also causes no error.

Exercise 3.3: Plug wave solution

When I tested that i should get exact solution, I made sure that the wave did not hit the boundary at the end time. This means that the exact solution at time t is given by Dalambert formula $u(x, y, t) = \frac{1}{2}(I(x - t, y) + I(x + t, y))$. To check that I got exact solution look in code.

Exercise 3.4: Standing undamped waves

Everything is in the code.

Exercise 3.6: Manufactured solution

Everything in code. Used sympy to find sorce-term. Did not get exactly 2 in convergence rate, but closer to 2 than 1.