

Connection guide for Raspberry Pi and Arduino

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BETTER FINISH IT BEFORE CHRISTMAS

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1 Motor

1.1 Connection with Raspberry Pi

1.1.1 Material

Motor, Raspberry Pi, motor driver L298N and GPIO cables.

L298N Pinout:

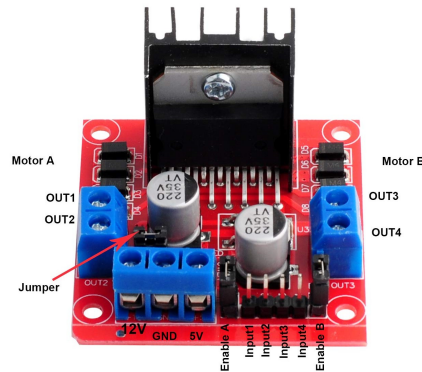


Figure 1: L298N Pin Layout

Input1 controls OUT1 and so on. Control by H-bridge:

Low	Low	Stop
High	Low	Clockwise/Anti-Clockwise
High	Low	Clockwise/Anti-Clockwise
High	High	Brake

1.1.2 Connection scheme

The connection scheme to connect motor to rbp using l298n

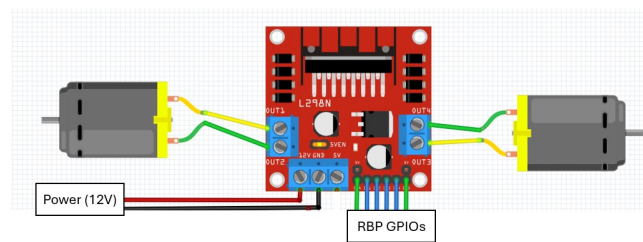


Figure 2: Connection scheme

1.1.3 Real image

The image of real connection

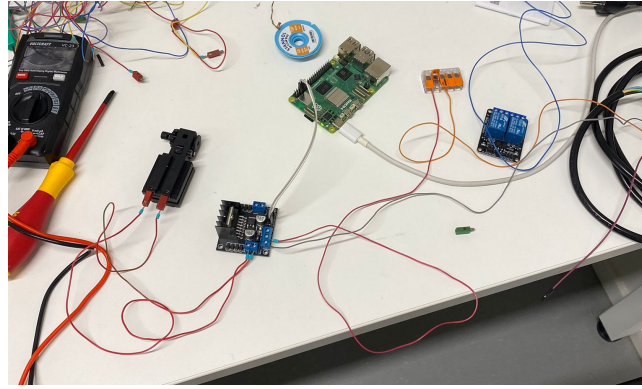


Figure 3: Real connection image

1.1.4 Remark

Some remark about the connection:

- 1 L298N can controll maximum 2 independent motors.
- 1 L298N occupys at least 4 GPIOs on RBP (for 2 motors).
- L298N can be powered by RBP or external power source.

1.2 Connection with Arduino

2 NFC Reader(PN532 V3)

3 Sensor

4 Compressor