Parallel & Distributed Computing (WQD7008)

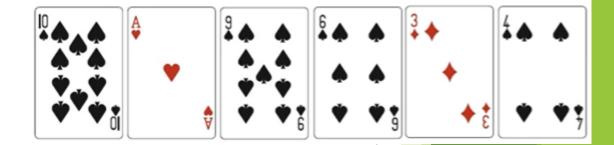
Week 11

Sorting Algorithms

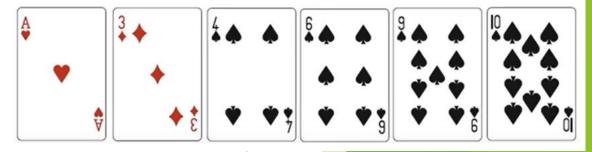
2019/2020 Semester 1

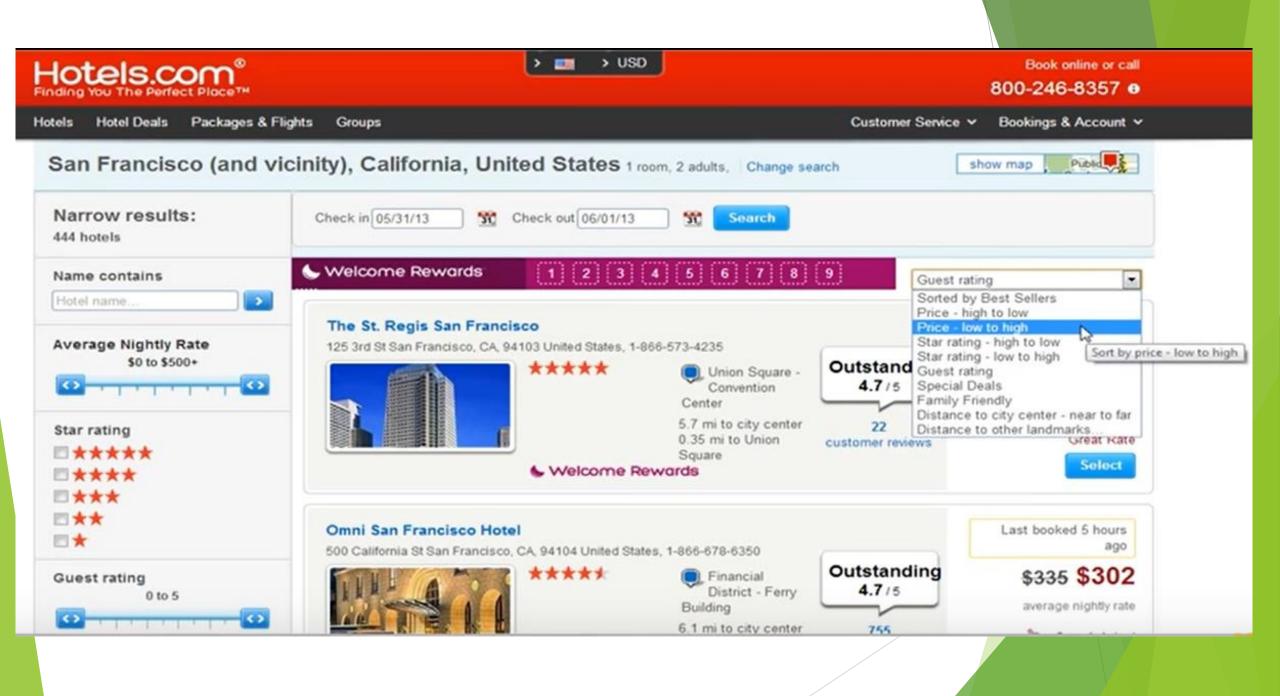
Dr. Hamid Tahaei

- Practical application
 - ▶ People by last name
 - Gaming
 - Countries by population
 - ► Search engine results by relevance
 - ...
- Fundamental to other algorithms









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2012 Summer Olympics medal table [15]

Rank 🔺	NOC \$	Gold ¢	Silver ♦	Bronze \$	Total ♦
1	United States (USA)	46	29	29	104
2	China (CHN)	38	27	23	88
3	Great Britain (GBR)*	29	17	19	65
4	Russia (RUS)	24	26	32	82
5	South Korea (KOR)	13	8	7	28
6	Germany (GER)	11	19	14	44
7	France (FRA)	11	11	12	34
8	Italy (ITA)	8	9	11	28
9	Hungary (HUN)	8	4	6	18
10	Australia (AUS)	7	16	12	35
11	Japan (JPN)	7	14	17	38
12	Kazakhstan (KAZ)	7	1	5	13
13	Netherlands (NED)	6	6	8	20
14	Ukraine (UKR)	6	5	9	20

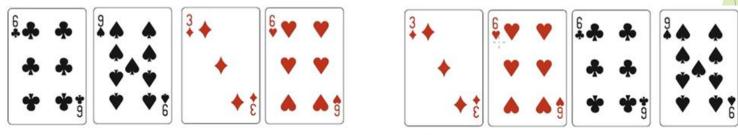
- Sorting is arranging the elements in a list or collection in increasing or decreasing order of some property
- ► Homogeneous (the same type)
- 2,3,9,4,6
- ▶ 2, 3, 4, 6, 9 (increasing order of value)
- ▶ 9, 6, 4, 3, 2 (decreasing order of value)
- "fork", "knife", "mouse", "screen", "key"
- "fork", "key", knife", "mouse", "screen"

Sorting algorithms

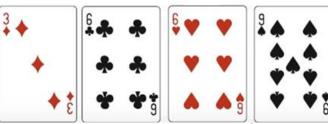
- ► Bubble sort
- Selection sort
- ► Insertion sort
- Merge sort
- Quick sort
- ► Radix sort
- ...

Classification

- ► Time complexity
 - Measure of rate of growth of time taken by an algorithm with respect to input size
- Space complexity or memory usage
 - In-place constant memory
 - Extra memory Memory usage growth with input-size
- Stability



Insertion sort,
Merge Sort,
Bubble Sort, etc
are stable by
nature

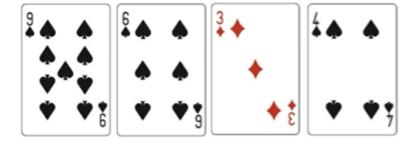


like Heap Sort, Quick Sort, etc not stable

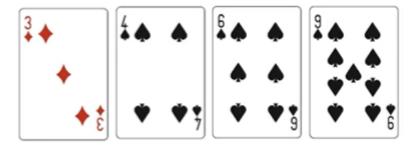
Classification (continued)

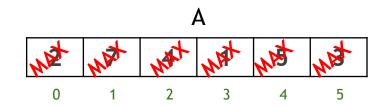
- Internal sort vs external sort
 - ► Internal → all the records are in main memory (RAM)
 - External → records on auxiliary store (disk/tapes)
- Recursive vs non-recursive
 - ► Recursive → quick sort, merge sort
 - Non-recursive → insertion sort, selection sort

Lest hand - unsorted



Right hand - sorted





• Find the minimum and put it in array B $_{\mbox{\footnotesize B}}$

1	2	3	4	5	7
0	1	2	3	4	5

Not In place

n-place sorting algorithm takes constant amount of extra memory

In-place selection sorting algorithm

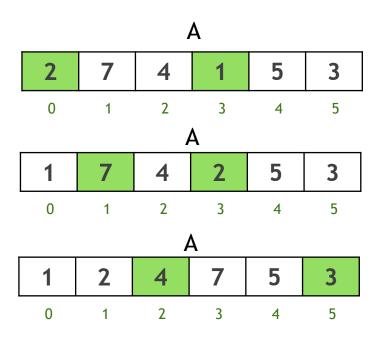
Find the least(or greatest) value in the array, swap it into the leftmost(or rightmost) component, and then forget the leftmost component, Do this repeatedly.

swap (element[min], element[i])

	2	7	4	1	5	3
	0	1	2	3	4	5
	1	7	4	2	5	3
	0	1	2	3	4	5
	1	2	4	7	5	3
	0	1	2	3	4	5
	1	2	3	7	5	4
	0	1	2	3	4	5
_						
	1	2	3	4	5	7

► In-place selection sorting algorithm

```
void SelectionSort(int A[],int n)
    for(int i = 0;i< n-1;i++)
        int iMin = i;
        for(int j = i+1;j<n;j++)</pre>
             if(A[j] < A[iMin])</pre>
                 iMin = j;
        int temp = A[i];
        A[i] = A[iMin];
        A[iMin] = temp;
```



- Time Complexity
 - ► Inner loop executes (n-1) times when i=0, (n-2) times when i=1 and so on:
 - c_2 = (n-1) + (n-2) + (n-3) + +2+1 = $\frac{n(n-1)}{2}$
 - ightharpoonup Time complexity = $c_1 + c_2 + c_3$ =

(n-1)
$$c_1 + \frac{n(n-1)}{2}$$
. $c_2 + (n-1)$ $c_3 = O(n^2)$

- Space Complexity
 - Since no extra space beside n variables is needed for sorting so:

```
O(n)
```

```
void SelectionSort(int A[],int n)
       for(int i = 0;i< n-1;i++)
      c<sub>1</sub> { int iMin = i;
n-1 for(int j = i+1;j<n;j++)</pre>
     c<sub>3</sub>
n-1

int temp = A[i];
A[i] = A[iMin];
A[iMin] = temp;
```

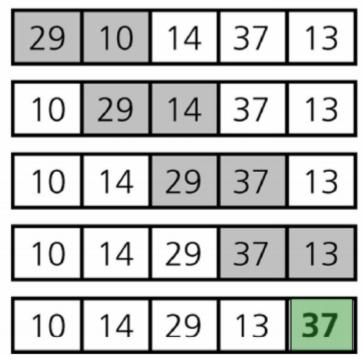
Bubble sort

Given an array of n items

- Compare pair of adjacent items
- Swap if the items are out of order
- Repeat until the end of array
 - ► The largest item will be at the last position
- Reduce n by 1 and go to Step 1
- Analogy
 - ▶ Large item is like "bubble" that floats to the end of the array

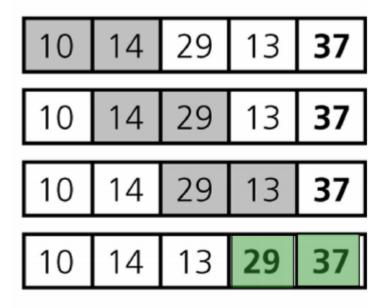
Bubble sort

(a) Pass 1



At the end of Pass 1, the largest item 37 is at the last position.

(b) Pass 2



At the end of Pass 2, the second largest item 29 is at the second last position.



Sorted Item



Pair of items under comparison

Bubble sort

- Time Complexity
 - $c_1 = n-1$

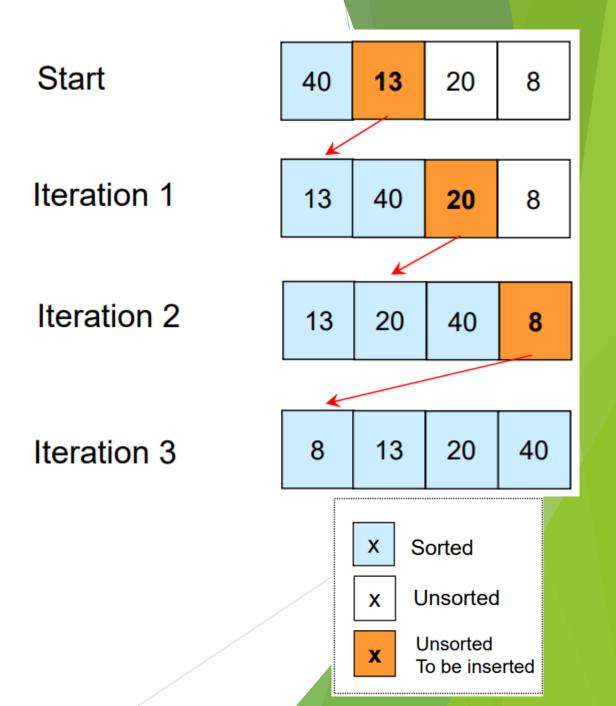
 - ► Time complexity = $c_1 + c_2 =$ (n-1) $c_1 + \frac{n(n-1)}{2}$. $c_2 =$

$$O(n^2)$$

- Worst Case Time Complexity [Big-O]: O(n²)
- Best Case Time Complexity [Bigomega]: O(n)
- Average Time Complexity [Big-theta]: O(n²)
- Space Complexity: O(1)

Insertion sort

- One of the most straight forward sorting algorithm
- Similar to how most people arrange a hand of poker cards
- Start with one card in your hand
- Pick the next card and insert it into its proper sorted order
- Repeat previous step for all cards



Insertion sort

- ▶ Outer-loop executes (n-1) times
- Number of times inner-loop is executed depends on the input
- Best-case: the array is already sorted and (a[j] > next) is always false
- No shifting of data is necessary
- Worst-case: the array is reversely sorted and (a[j] > next) is always true
- Insertion always occur at the front
- Therefore, the best-case time is O(n)
- And the worst-case time is $O(n^2)$

```
for i : 1 to length(A) -1
  j = i
  while j > 0 and A[j-1] > A[j]
  swap A[j] and A[j-1]
  j = j - 1
```

- Suppose we only know how to merge two sorted sets of elements into one
- ► Merge $\{1, 5, 9\}$ with $\{2, 11\} \rightarrow \{1, 2, 5, 9, 11\}$

Question

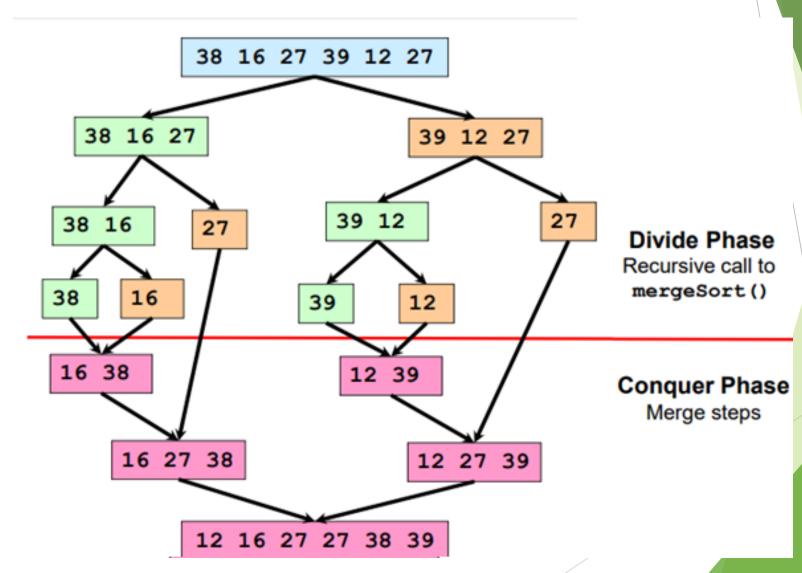
- Where do we get the two sorted sets in the first place?
- Idea (use merge to sort n items)
- Merge each pair of elements into sets of 2
- Merge each pair of sets of 2 into sets of 4
- Repeat previous step for sets of 4 ...
- Final step: merge 2 sets of n/2 elements to obtain a fully sorted set

Divide-and-Conquer Method

- A powerful problem solving technique
- Divide-and-conquer method solves problem in the following steps
- Divide step
 - Divide the large problem into smaller problems
 - Recursively solve the smaller problems
- Conquer step
 - Combine the results of the smaller problems to produce the result of the larger problem

Divide-and-Conquer: Merge Sort

- Merge Sort is a divide-and-conquer sorting algorithm
- Divide step
 - ▶ Divide the array into two (equal) halves
 - Recursively sort the two halves
- Conquer step
 - Merge the two halves to form a sorted array



```
if ( n == 1 )
    return a

arrayOne = a[0] ... a[n/2]
    arrayTwo = a[n/2+1] ... a[n]

arrayOne = mergesort ( arrayOne )
    arrayTwo = mergesort ( arrayTwo )
```

time complexity O(nlogn)

```
merge ( array a, array b )
     array c
     while ( a and b have elements )
        if (a[0] > b[0])
          add b[0] to the end of c
           remove b[0] from b
        else
          add a[0] to the end of c
           remove a[0] from a
     // At this point either a or b is empty
     while ( a has elements )
        add a[0] to the end of c
        remove a[0] from a
     while (b has elements)
        add b[0] to the end of c
        remove b[0] from b
     return c
```

Pros

- The performance is guaranteed, i.e. unaffected by original ordering of the input
- Suitable for extremely large number of inputs
- Can operate on the input portion by portion

Cons

- Not easy to implement
- Requires additional storage during merging operation
- O(n) extra memory storage needed
- Not In-place algorithm

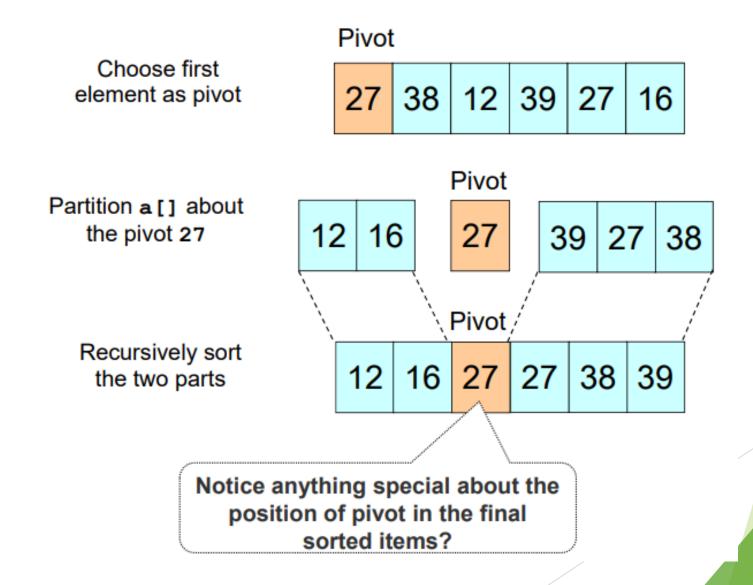
Quick sort

Quick Sort is a divide-and-conquer algorithm

- Divide step
 - Choose an item Choose an item p (known as (known as pivot) and partition the) and partition the items of a[i...j] into two parts
 - ▶ Items that are smaller than p
 - Items that are greater than or equal to p
 - Recursively sort the two parts
- Conquer step
 - Do nothing!

In comparison, Merge Sort spends most of the time in conquer step but very little time in divide step

Quick sort: Divide Step



Quick sort

Example:

7	2	1	6	8	5	3	4
---	---	---	---	---	---	---	---

Average case: O(nlogn)

Worst case: $O(n^2)$

In-place algorithm

Radix sort

- Treats each data to be sorted as a character string
- ▶ It is not using comparison, i.e. no comparison between the data is needed
- In each iteration
- Organize the data into groups according to the next character in each data
- ► The groups are then "concatenated" for next iteration

Radix sort

Original Integer

53 89 150 36 366 233

Grouped by the third digit

150 **5**3 **633 233 36 89**

Grouped by the second digit

 633
 233
 36
 150
 53
 89

Grouped by the first digit

36 53 89 150 233 633

Radix sort

- For each iteration
- We go through each item once to place them into group
- Then go through them again to concatenate the groups
- Complexity is O(n)
- Number of iterations is d, the maximum number of digits (or maximum number of characters)
- Complexity is thus O(dn)
- Radix sort is an In-place and stable sorting algorithm

Time complexities: Summary

	Worst Case	Best Case	In-place?	Stable?
Selection Sort	O(n ²)	O(n ²)	Yes	No
Insertion Sort	O(n ²)	O(n)	Yes	Yes
Bubble Sort	O(n ²)	O(n ²)	Yes	Yes
Bubble Sort 2	O(n ²)	O(n)	Yes	Yes
Merge Sort	O(n lg n)	O(n lg n)	No	Yes
Quick Sort	O(n²)	O(n lg n)	Yes	No
Radix sort	O(dn)	O(dn)	No	yes

Summary

Comparison-Based Sorting Algorithms

- Iterative Sorting
 - Selection Sort
 - Bubble Sort
 - Insertion Sort
- Recursive Sorting
 - Merge Sort
 - Quick Sort

Non-Comparison Comparison-Based Sorting Algorithms Based Sorting Algorithms

Radix Sort

Properties of Sorting Algorithms

- ► In-Place
- Stable

Parallel sort

Parallel Sorts

Odd-Even Transposition Sort

Odd-Even Transposition Sort is a parallel version of bubble sort

9	7	3	8	5	6	4	1	Phase 1(Odd)
7	9	3	8	5	6	1	4	Phase 2(Even)
7	3	9	5	8	1	6	4	Phase 3(Odd)
3	7	5	9	1	8	4	6	Phase 4(Even)
3	5	7	1	9	4	8	6	Phase 5(Odd)
3	5	1	7	4	9	6	8	Phase 6(Even)
3	1	5	4	7	6	9	8	Phase 7(Odd)
1	3	4	5	6	7	8	9	

Odd-Even Transposition Sort

Time Complexity

 \bigcirc $O(n^2)$

```
void oddEvenSort(int arr[], int n)
    bool isSorted = false; // Initially array is unsorted
   while (!isSorted) {
       isSorted = true;
        // Perform Bubble sort on odd indexed element
        for (int i = 1; i <= n - 2; i = i + 2) {
            if (arr[i] > arr[i + 1]) {
                swap(arr[i], arr[i + 1]);
               isSorted = false;
        // Perform Bubble sort on even indexed element
       for (int i = 0; i <= n - 2; i = i + 2) {
            if (arr[i] > arr[i + 1]) {
                swap(arr[i], arr[i + 1]);
               isSorted = false;
    return;
```

Bitonic Sort

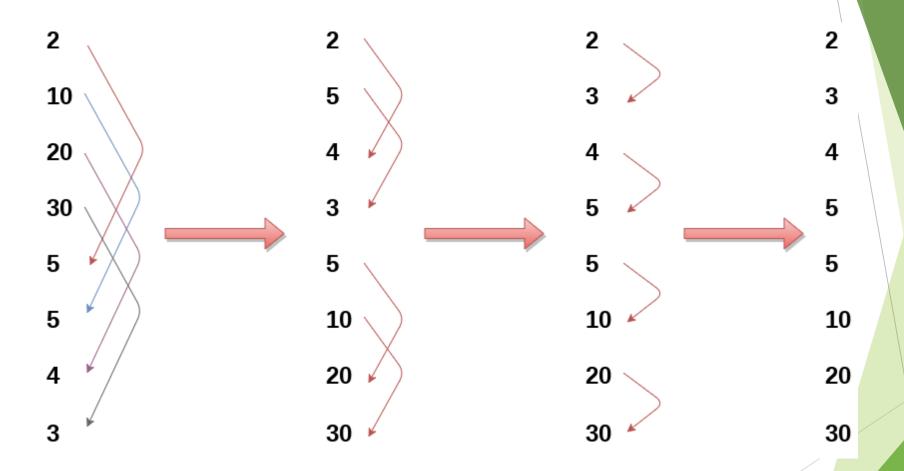
- ► A parallel sorting algorithm which performs O(n2 log n) comparisons.
- ▶ It performs better for the parallel implementation because elements are compared in predefined sequence which must not be depended upon the data being sorted.
- The predefined sequence is called Bitonic sequence

to understand Bitonic sort

Bitonic sequence is the one in which, the elements first comes in increasing order then start decreasing after some particular index. An array A[0... i ... n-1] is calle(A[0] < A[1] < A[2] A[i-1] < A[i] > A[i+1] > A[i+2] > A[i+3] > ... > A[n-1]



Bitonic Sort



Complexity	Best Case	Average Case	Worst Case
Time Complexity	O(log ² n)	O(log ² n)	O(log ² n)

Thank you for your patience