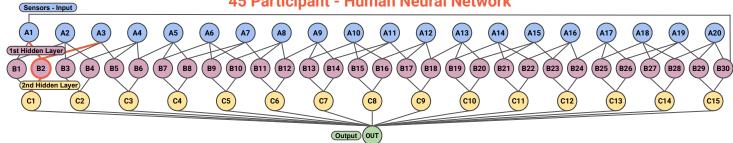
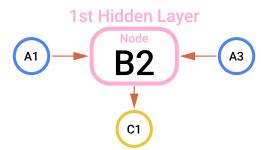
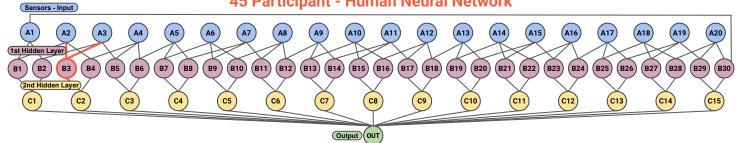


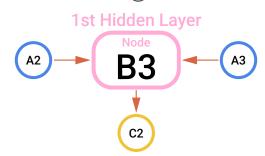
ITERATION	INF	PUT		PR	OBABIL	ITY			OUTPUT (me)	VERII	FICATIO	ON
#	Node A1	Node A2			oll the d				Node B1	Traffic Light	Is my corre	
1	RG	R	Node: A1	<u>A1</u> o o	<u>A1</u>	<u>A2</u>	<u>A2</u>	<u>A2</u>	RG	RG	O Yes	O No
2	RG	R	Node: O	© 0	© ₀	© 0 0 0	- 000 000		R	RG	O Yes	O No
3	RG	RG	Node:	© 0		- 0 0			RG	RG	O Yes	O No
4	RG	R	Node: O	©		- 0 0			RG	RG	O Yes	O No
5	RG	R	Node: O	©	© ₀	- 0 0			RG	RG	O Yes	O No
6	RG	RG	Node: O	© 0	© ₀	© 0 0			RG	RG	O Yes	O No



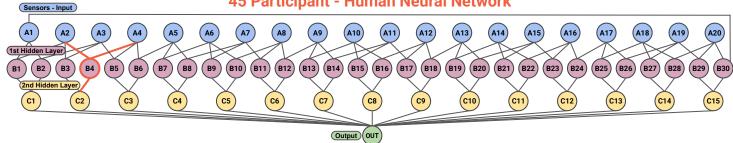


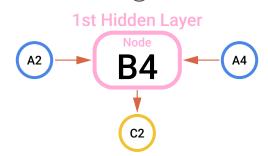
ITERATION	INF	PUT		PF	ROBABIL	ITY			OUTPUT (me)	VERII	FICATIO	ON
#	Node A1	Node A3		-	Roll the o				Node B2	Traffic Light	Is my corr	
1	RG	RG	Node: A1	<u>A1</u> O O	<u>A1</u>	A3	<u>A3</u>	<u>A3</u>	RG	RG	O Yes	O No
2	RG	R	Node: O	©		- 0 0 0	- 000 000		RG	RG	O Yes	O No
3	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
4	RG	R	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node:	©	© ₀ 0	- 0 0 0			R	RG	O Yes	O No
6	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No



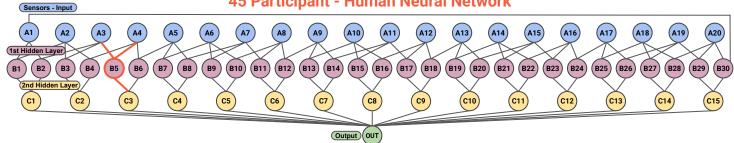


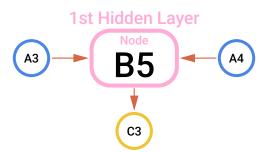
ITERATION	INF	PUT		PR	OBABIL	ITY			OUTPUT (me)	VERII	FICATIO	ON
#	Node A2	Node A3			oll the d	lie ed face			Node B3	Traffic Light	Is my corre	
1	RG	RG	Node: A2	<u>A2</u> o o	<u>A2</u>	<u>A3</u>	<u>A3</u>	<u>A3</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	© 0	© ₀ 0	© 0 0 0	000		RG	RG	O Yes	O No
3	RG	RG	Node: O	©	© ₀	© 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	©	000	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node: O	©	000	- 0 0 0			RG	RG	O Yes	O No
6	RG	RG	Node: O	· · ·		- 0 0 0			RG	RG	O Yes	O No



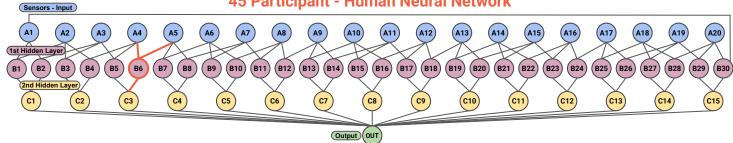


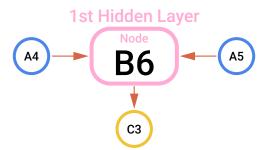
ITERATION	INF	PUT		PR	ROBABIL	ITY			OUTPUT (me)	VERI	FICATIO	ON
#	Node A2	Node A4			Roll the o	lie led face			Node B4	Traffic Light	Is my corr	
1	RG	RG	Node: A2	<u>A2</u>	<u>A2</u> O O O	A4	<u>A4</u>	<u>A4</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0	000		RG	RG	O Yes	O No
3	RG	RG	Node: O	©	© ₀ 0	© 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node: O	© 0	© ₀	- 0 0 0			RG	RG	O Yes	O No
6	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0	0000		RG	RG	O Yes	O No



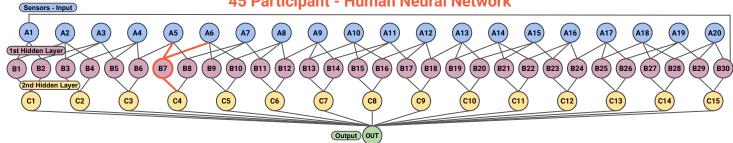


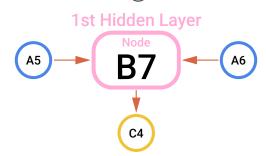
ITERATION	INF	PUT		PF	ROBABIL	ITY			OUTPUT (me)	VERII	FICATIO	ON
#	Node A3	Node A4		-	Roll the o				Node B5	Traffic Light	Is my corre	
1	RG	R	Node: A3	<u>A3</u>	<u>A3</u>	A4	<u>A4</u>	<u>A4</u>	RG	RG	O Yes	O No
2	RG	R	Node: O	© 0	© ₀ 0	- 0 0 0	000		RG	RG	O Yes	O No
3	RG	RG	Node:	©	© ₀ 0	© 0 0 0			RG	RG	O Yes	O No
4	RG	R	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
5	RG	R	Node:	©	© ₀ 0	- 0 0 0			R	RG	O Yes	O No
6	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No





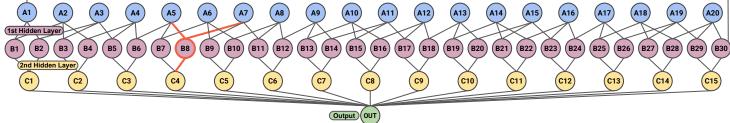
ITERATION	INF	PUT		PF	ROBABIL	.ITY			OUTPUT (me)	VERII	FICATIO	ON
#	Node A4	Node A5		-	Roll the o				Node B6	Traffic Light	Is my corre	
1	RG	R	Node: A4	<u>A4</u> O O	<u>A4</u> O _O O	<u>A5</u>	<u>A5</u>	<u>A5</u>	RG	RG	O Yes	O No
2	RG	R	Node: O	©		- 0 0 0	- 000 000		RG	RG	O Yes	O No
3	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
4	RG	R	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
5	RG	R	Node:	©	© ₀ 0	- 0 0 0			R	RG	O Yes	O No
6	RG	RG	Node: O	© 0	© ₀	- 0 0 0			RG	RG	O Yes	O No



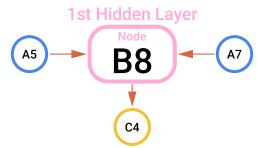


ITERATION	INF	PUT		PR	OBABIL	ITY			OUTPUT (me)	VERII	FICATIO	ON
#	Node A5	Node A6			oll the d	lie ed face			Node B7	Traffic Light	Is my corre	
1	RG	R	Node: A5	<u>A5</u> o o	<u>A5</u>	<u>A6</u>	<u>A6</u>	<u>A6</u>	RG	RG	O Yes	O No
2	RG	R	Node: O	© 0	© ₀ 0	© 0 0 0	000		RG	RG	O Yes	O No
3	RG	RG	Node:	©		- 0 0 0			RG	RG	O Yes	O No
4	RG	R	Node: O	©	000	- 0 0 0			RG	RG	O Yes	O No
5	RG	R	Node: O	©	000	- 0 0 0			RG	RG	O Yes	O No
6	RG	RG	Node: O	· · ·		- 0 0 0			RG	RG	O Yes	O No

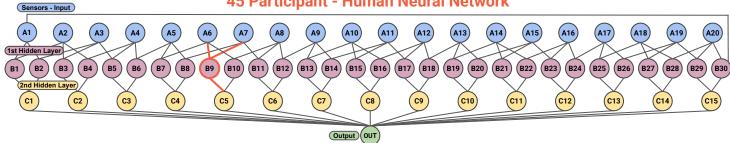
45 Participant - Human Neural Network (A15) (A16) (A18) (A3) (A6) (A12) (A13) (A17)

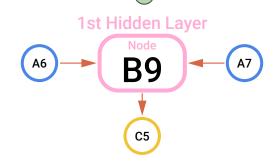


Sensors - Input

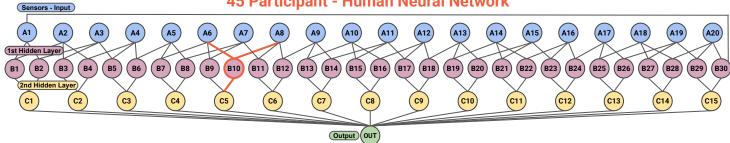


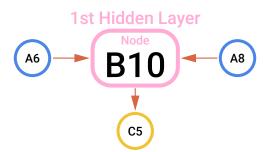
ITERATION	INF	PUT		PF	ROBABIL	ITY			OUTPUT (me)	VERII	FICATIO	ON
#	Node A5	Node A7		-	Roll the o				Node B8	Traffic Light	Is my corre	
1	RG	R	Node: A5	<u>A5</u>	<u>A5</u>	A7 (0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	<u>A7</u>	<u>A7</u>	RG	RG	O Yes	O No
2	RG	R	Node: O	©		- 0 0 0	000		RG	RG	O Yes	O No
3	RG	R	Node: O	© 0	© ₀	- 0 0 0			RG	RG	O Yes	O No
4	RG	R	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
6	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No



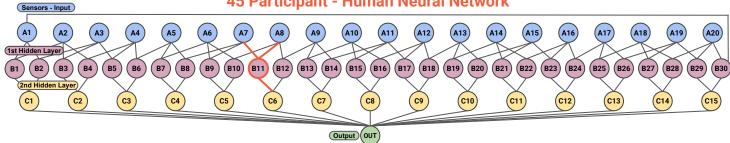


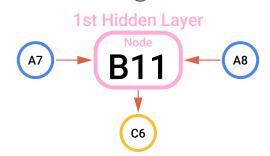
ITERATION	INF	PUT		PF	ROBABIL	.ITY			OUTPUT (me)	VERI	FICATIO	ON
#	Node A6	Node A7			Roll the c				Node B9	Traffic Light	Is my corre	
1	RG	RG	Node: A6	<u>A6</u> O O	<u>A6</u> O O O	A7 ○ ○ ○	<u>A7</u> ○○○ ○○	<u>A7</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0	- 000 000		RG	RG	O Yes	O No
3	RG	RG	Node:	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node:	©	© ₀ 0	- 0 0 0	- 000 000		R	RGG	O Yes	O No
6	RG	RG	Node: O	©	© ₀ 0	- 0 0 0			R	RG	O Yes	O No



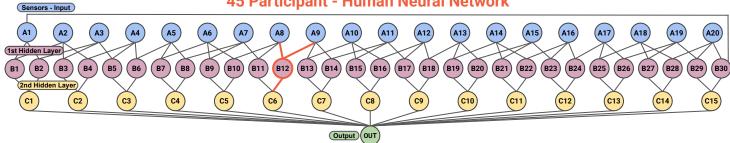


ITERATION	INF	PUT	PROBABILITY	OUTPUT (me)	VERI	FICATION
#	Node A6	Node A8	Roll the die Bubble the rolled face	Node B10	Traffic Light	Is my node correct?
1	RG	RG	Node: A6 A6 A6 A8 A8 A8 Rolled: O O O O O O O O O O O O O O O O O O O		R	O O Yes No
2	RG	RG	Node:	R	R	O O Yes No
3	RG	RG	Node:	R	RG	O O Yes No
4	RG	RG	Node:	R	R	O O Yes No
5	RG	RG	Node:	R	R	O O Yes No
6	RG	RG	Node:	R	R	O O Yes No



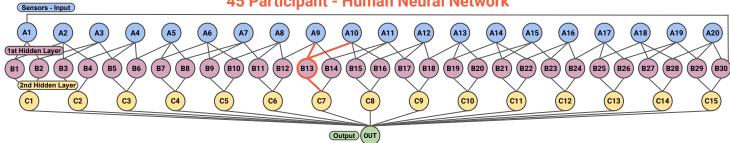


ITERATION	INF	PUT		PR	OBABIL	ITY			OUTPUT (me)	VERI	FICATIO	ON
#	Node A7	Node A8			oll the d	lie led face			Node B11	Traffic Light	ls my corre	
1	RG	RG	Node: A7	<u>A7</u> ○ ○	<u>A7</u>	<u>A8</u>	<u>A8</u>	<u>A8</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	© 0	<u> </u>	© 0 0 0	000		RG	RG	O Yes	O No
3	RG	RG	Node: O	© 0		- 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	©	© ₀	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node: O	©	© ₀	- 0 0 0	- 000 000		RG	RG	O Yes	O No
6	RG	RG	Node: O	· · ·	© ₀	- 0 0 0			RG	RG	O Yes	O No



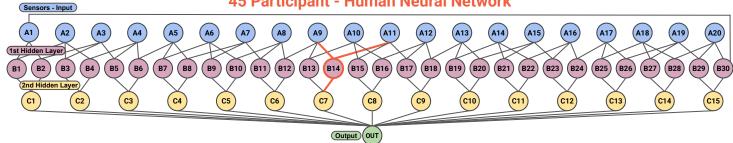
1st Hidden Layer Α8 C6

ITERATION	INF	PUT		PF	ROBABIL	.ITY			OUTPUT (me)	VERII	FICATIO	ON
#	Node A8	Node A9		-	Roll the o				Node B12	Traffic Light	ls my corr	
1	RG	RG	Node: A8	<u>A8</u>	<u>A8</u>	<u>A9</u>	<u>A9</u>	<u>A9</u>	RG	RG	O Yes	O No
2	RG	R	Node: O	©	© ₀ 0	- 0 0 0	- 000 000		RG	RG	O Yes	O No
3	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
4	RG	R	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node:	©	© ₀ 0	- 0 0 0			R	RG	O Yes	O No
6	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No



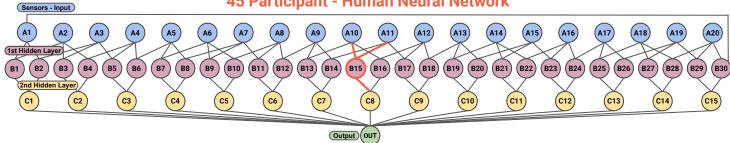
1st Hidden Layer A10 **C7**

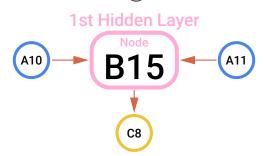
ITERATION	INI	PUT		PF	ROBABIL	.ITY			OUTPUT (me)	VERII	FICATIO	ON
#	Node A9	Node A10		-	Roll the o				Node B13	Traffic Light	Is my corr	
1	RG	RG	Node: A9	<u>A9</u>	<u>A9</u>	<u>A10</u>	<u>A10</u>	<u>A10</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	©	© ₀ 0	- 0 0 0	000		RG	RG	O Yes	O No
3	RG	RG	Node:	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node:	©	© ₀ 0	- 0 0 0			R	RG	O Yes	O No
6	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No



1st Hidden Layer **C7**

ITERATION	INI	PUT		PR	OBABIL	ITY			OUTPUT (me)	VERII	FICATIO	ON
#	Node A9	Node A11		-	oll the o	lie ed face			Node B14	Traffic Light	Is my corre	
1	RG	R	Node: A9	<u>A9</u>	<u>A9</u>	<u>A11</u>	<u>A11</u>	<u>A11</u>	RG	RG	O Yes	O No
2	RG	R	Node: O	<u> </u>	© ₀ 0	- 0 0 0	- 000 000		RG	RG	O Yes	O No
3	RG	RG	Node:	© 0	© ₀	- 0 0 0			RG	RG	O Yes	O No
4	RG	R	Node: O	© 0	© ₀	- 0 0 0			RG	RG	O Yes	O No
5	RG	R	Node:	©	© ₀	- 0 0 0			R	RG	O Yes	O No
6	RG	RG	Node: O	© 0		- 0 0			RG	RG	O Yes	O No





ITERATION	IN	PUT		PRO	BABIL	ITY			OUTPUT (me)	VERI	FICATIO	ON
#	Node A10	Node A11		Ro Bubble	oll the d				Node B15	Traffic Light	ls my corre	
1	RG	RG	Node: A10		<u>A10</u>	<u>A11</u>	<u>A11</u>	<u>A11</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	© (000	- 0 0 0			R	RG	O Yes	O No
3	RG	RG	Node:	© (- 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	<u> </u>		- 0 0			RG	RG	O Yes	O No
5	RG	RG	Node:	<u> </u>		- 0 0			RG	RG	O Yes	O No
6	RG	RG	Node: O	<u> </u>	0000	- 0 0 0			RG	RG	O Yes	O No

45 Participant - Human Neural Network Sensors - Input (A16) (A15) (A17) (A18) (A3) (A12) (A13) (A19) (A2) 1st Hidden Layer B1 B2 B3 B4 B5 B9 B10 B11 B12 B13 B14 B15 B16 B17 B18 B19 B20 B21 B22 B23 B24 B25 B26 B27 B28 B29 B7 B8 (B6)

(C8)

(C9)

(C10)

C11

(A1)

(C1)

C2

C3

C4

(A20)

C12

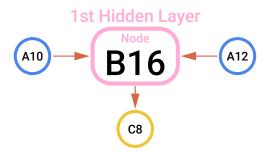
C13



(C7)

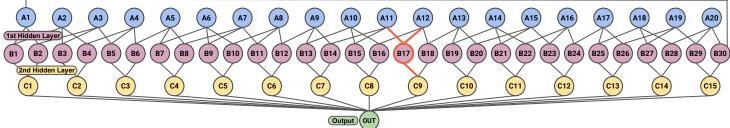
C6

C5

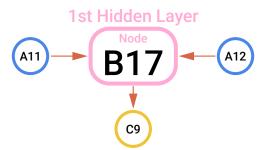


ITERATION	INF	PUT		PF	ROBABIL	.ITY			OUTPUT (me)	VERI	FICATIO	ON
#	Node A10	Node A12			Roll the o				Node B16	Traffic Light	Is my corr	
1	RG	RG	Node: A10	<u>A10</u> o o	<u>A10</u>	<u>A12</u>	<u>A12</u>	<u>A12</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0	000		RG	RG	O Yes	O No
3	RG	RG	Node: O	©	© ₀	© 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
6	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0	0000		RG	RG	O Yes	O No

45 Participant - Human Neural Network (A16) (A15) (A12) (A13)



Sensors - Input



ITERATION	INI	PUT		PR	ROBABIL	ITY			OUTPUT (me)	VERII	FICATIO	ON
#	Node A11	Node A12		-	Roll the o				Node B17	Traffic Light	Is my corr	
1	RG	RG	Node: A11	<u>A11</u>	<u>A11</u>	<u>A12</u>	<u>A12</u>	<u>A12</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	©	© ₀ 0	- 0 0 0	- 000 000		RG	RG	O Yes	O No
3	RG	RG	Node:	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node:	©	© ₀ 0	- 0 0 0			R	RG	O Yes	O No
6	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No

45 Participant - Human Neural Network Sensors - Input (A16) (A15) (A18) (A3) (A12) (A13) (A17) (A19) (A1) (A2) 1st Hidden Layer B1 B2 B3 B4 B5 B9 B10 B11 B12 B13 B14 B15 B16 B17 B18 B19 B20 B21 B22 B23 B24 B25 B26 B27 B28 B29 B7 B8 (B6)

(A20)

C12

C13

C14



(C8)

(C9)

(C10)

C11

C7

C6

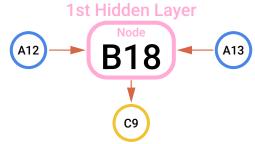
C5

(C1)

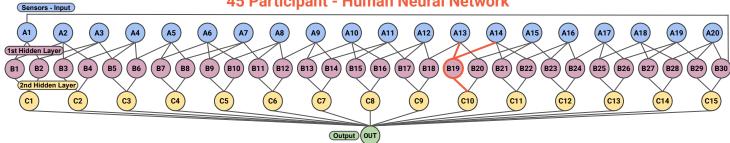
C2

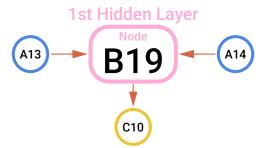
C3

C4



ITERATION	INI	PUT		PR	OBABIL	ITY			OUTPUT (me)	VERII	FICATIO	ON
#	Node A12	Node A13		-	oll the o	lie ed face			Node B18	Traffic Light	Is my corre	
1	RG	RG	Node: A12	<u>A12</u>	<u>A12</u>	<u>A13</u>	<u>A13</u>	<u>A13</u>	RG	RG	O Yes	O No
2	RG	R	Node: O	<u> </u>	© ₀ 0	- 0 0 0	- 000 000		RG	RG	O Yes	O No
3	RG	RG	Node:	© 0	© ₀	- 0 0 0			RG	RG	O Yes	O No
4	RG	R	Node: O	© 0	© ₀	- 0 0 0			RG	RG	O Yes	O No
5	RG	R	Node: O	©	© ₀	- 0 0 0			R	RG	O Yes	O No
6	RG	R	Node: O	· · ·	© ₀	- 0 0			RG	RG	O Yes	O No



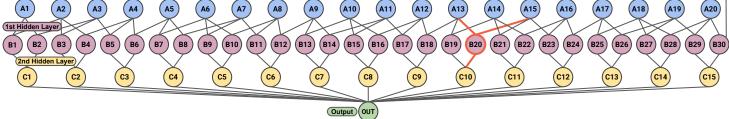


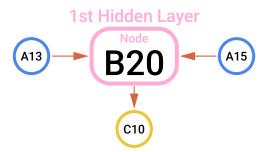
ITERATION	INF	PUT		PROB	ABILITY	Y			OUTPUT (me)	VERII	FICATIO	ON
#	Node A13	Node A14		Roll Bubble the	the die e rolled	face			Node B19	Traffic Light	ls my corre	
1	RG	RG	Node: A13			\14	<u>A14</u>	<u>A14</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O						RG	RG	O Yes	O No
3	RG	RG	Node: O	<u> </u>			0000		RG	RG	O Yes	O No
4	RG	RG	Node: O				0000		RG	RG	O Yes	O No
5	RG	RG	Node: O				0000		R	RG	O Yes	O No
6	RG	RG	Node: O				- 0000		RG	RG	O Yes	O No

45 Participant - Human Neural Network Sensors - Input (A15) (A16) (A17) (A18) (A3) (A12) (A13) (A14) (A2) 1st Hidden Layer

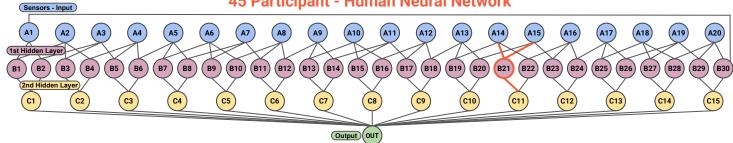
(A1)

(C1)





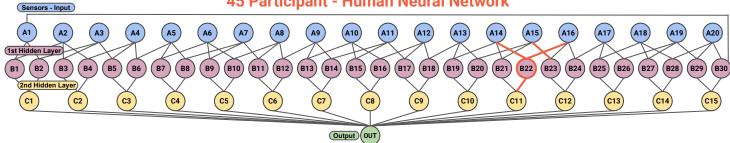
ITERATION	INF	PUT		PRO	OBABIL	ITY			OUTPUT (me)	VERII	FICATIO	ON
#	Node A13	Node A15		Ro Bubble	oll the d				Node B20	Traffic Light	Is my corre	
1	RG	RG	Node: A13	<u>A13</u>	<u>A13</u>	<u>A15</u>	<u>A15</u>	<u>A15</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	0		© 0 0 0			RG	RG	O Yes	O No
3	RG	RG	Node: O	000		- 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	© 0	© ₀	- 0 0	- 000 000		RG	RG	O Yes	O No
5	RG	RG	Node: O	000	© ₀	- 0 0	- 000 000		RG	RG	O Yes	O No
6	RG	RG	Node: O	· · ·	© ₀ 0	© 0 0			RG	RG	O Yes	O No

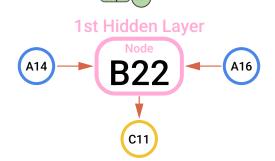


1st Hidden Layer C11

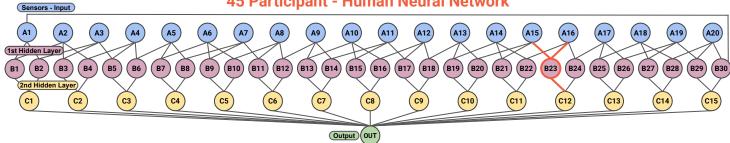
ITERATION	INF	PUT		PI	ROBABIL	.ITY			OUTPUT (me)	VERI	FICATI	ON
#	Node A14	Node A15			Roll the o				Node B21	Traffic Light	Is my	
1	RG	RG	Node: A14	A14	<u>A14</u>	<u>A15</u>	<u>A15</u>	<u>A15</u>	RG	RG	O Yes	O No
2	RG	RG	Node:		<u> </u>	- 0 0 0	- 000 000		RG	RG	O Yes	O No
3	RG	RG	Node:			- 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node:		<u> </u>	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node:		<u> </u>	- 0 0 0			RG	RG	O Yes	O No
6	RG	RG	Node:		<u> </u>				RG	RG	O Yes	O No

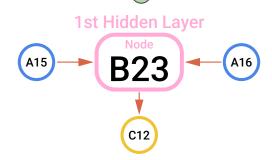
45 Participant - Human Neural Network (A15) (A16) (A17) (A12) (A13) (A14)





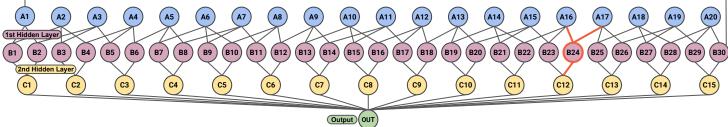
ITERATION	INF	PUT		PF	ROBABIL	.ITY			OUTPUT (me)	VERI	FICATION	ON
#	Node A14	Node A16			Roll the o	lie led face			Node B22	Traffic Light	Is my corre	
1	RG	RG	Node: A14	<u>A14</u>	<u>A14</u>	<u>A16</u>	<u>A16</u>	<u>A16</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0	000		RG	RG	O Yes	O No
3	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
6	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0	0000		RG	RG	O Yes	O No



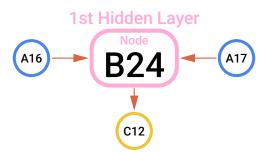


ITERATION	INF	PUT		PF	ROBABIL	.ITY			OUTPUT (me)	VERI	FICATIO	ON
#	Node A15	Node A16			Roll the d				Node B23	Traffic Light	Is my corre	
1	RG	RG	Node: A15	<u>A15</u>	<u>A15</u>	<u>A16</u>	<u>A16</u>	<u>A16</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0	000		RG	RG	O Yes	O No
3	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node: O	© 0	© ₀	- 0 0 0			RG	RG	O Yes	O No
6	RG	RG	Node: O	©	© ₀ 0				R	RG	O Yes	O No

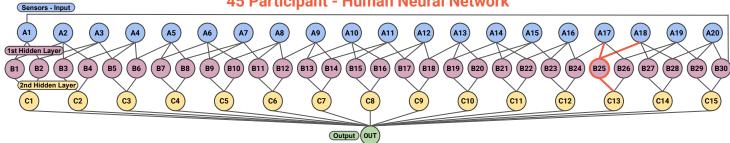
45 Participant - Human Neural Network (A15) (A16) (A12) (A13) (A17)

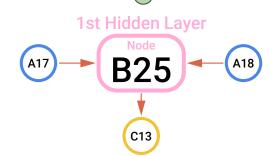


Sensors - Input



ITERATION	INF	PUT		PF	ROBABIL	ITY			OUTPUT (me)	VERII	FICATIO	ON
#	Node A16	Node A17		-	Roll the o				Node B24	Traffic Light	ls my corr	
1	RG	RG	Node: A16	<u>A16</u>	<u>A16</u>	<u>A17</u>	<u>A17</u>	<u>A17</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	©	© ₀ 0	- 0 0 0	- 000 000		RG	RG	O Yes	O No
3	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node:	©	© ₀ 0	- 0 0 0			R	RG	O Yes	O No
6	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No

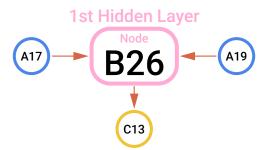




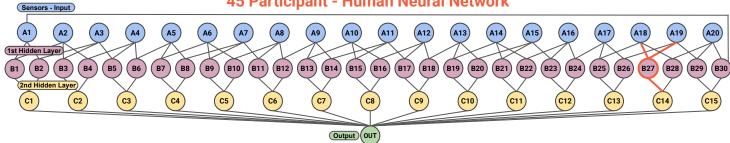
ITERATION	IN	PUT		PRO	BABIL	ITY			OUTPUT (me)	VERII	FICATION	
#	Node A17	Node A18	Roll the die Bubble the rolled face						Node B25	Traffic Light	Is my node correct?	
1	RG	RG	Node: A17		A17	<u>A18</u>	<u>A18</u>	<u>A18</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	© (0	- 0 0 0	- 000 000		R	RG	O Yes	O No
3	RG	RG	Node: O	© (0	- 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	© (0				RG	RG	O Yes	O No
5	RG	RG	Node: O	© (0				RG	RG	O Yes	O No
6	RG	RG	Node: O		000	- 0 0 0			RG	RG	O Yes	O No

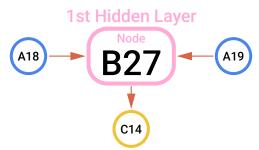
45 Participant - Human Neural Network Sensors - Input (A16) (A15) (A18) (A3) (A12) (A13) (A17) (A19) (A20) (A1) (A2) 1st Hidden Layer B1 B2 B3 B4 B5 B9 B10 B11 B12 B13 B14 B15 B16 B17 B18 B19 B20 B21 B22 B23 B24 B25 B26 B27 B28 B29 B7 B8 (B6) C6 C12 C13 (C1) C2 C3 C4 **C5** C7 (C9) (C10) C11 C14 (C8)

Output OUT



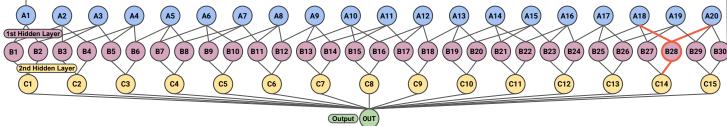
ITERATION	INI	PUT	PROBABILITY							VERII	RIFICATION	
#	Node A17	Node A19	Roll the die Bubble the rolled face						Node B26	Traffic Is my nod Light correct?		
1	RG	RG	Node: A17	<u>A17</u>	<u>A17</u>	<u>A19</u>	<u>A19</u>	<u>A19</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	<u> </u>	© ₀ 0	© 0 0 0	- 000 000		RG	RG	O Yes	O No
3	RG	RG	Node:	© 0	© ₀	- 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	© 0	© ₀	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node: O	©	© ₀	- 0 0 0	- 000 000		R	RG	O Yes	O No
6	RG	RG	Node: O	© 0	© ₀	- 0 0			RG	RG	O Yes	O No



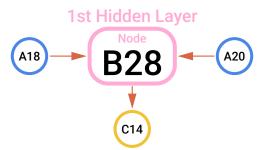


ITERATION	INI	PUT		OUTPUT (me)	VERII	RIFICATION						
#	Node A18	Node A19	Roll the die Bubble the rolled face						Node B27	Traffic Light	ls my corr	
1	RG	RG	Node: A18	<u>A18</u>	<u>A18</u>	<u>A19</u>	<u>A19</u>	<u>A19</u>	RG	RG	O Yes	O No
2	RG	R	Node: O	©	© ₀ 0	- 0 0 0	- 000 000		RG	RG	O Yes	O No
3	RG	RG	Node:	© 0	<u> </u>	- 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
5	RG	R	Node: O	©	© ₀ 0	- 0 0 0			R	RG	O Yes	O No
6	RG	R	Node: O	© 0	© ₀ 0				RG	RG	O Yes	O No

45 Participant - Human Neural Network (A16) (A15) (A12) (A17)

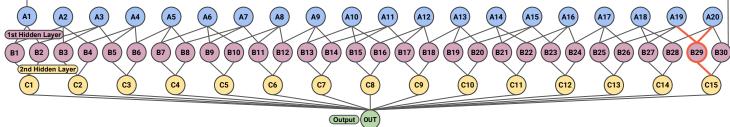


Sensors - Input

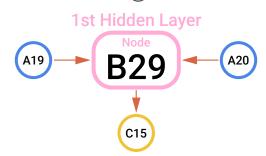


ITERATION	INF	PUT		OUTPUT (me)	VERI	FICATION						
#	Node A18	Node A20	Roll the die Bubble the rolled face						Node B28	Traffic Light	ls my corr	
1	RG	RG	Node: A18	<u>A18</u>	<u>A18</u>	<u>A20</u>	<u>A20</u>	<u>A20</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	©	© ₀	© 0 0 0	000		RG	RG	O Yes	O No
3	RG	RG	Node:	© 0	© ₀	- 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	© 0	© ₀	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node:	©	© ₀	- 0 0 0			RG	RG	O Yes	O No
6	RG	RG	Node: O	· · ·	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No

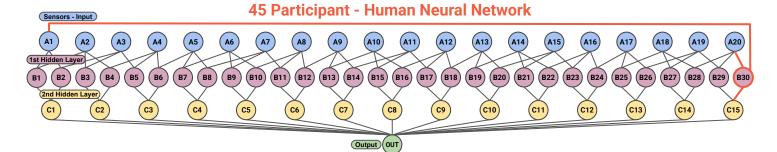
45 Participant - Human Neural Network (A15) (A16) (A17) (A12) (A13)

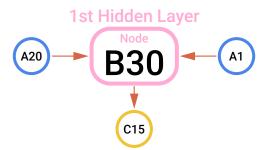


Sensors - Input



ITERATION	INF	PUT		PR	OBABIL	ITY			OUTPUT (me)	VERI	FICATION	
#	Node A19	Node A20	Roll the die Bubble the rolled face						Node B29	Traffic Light		
1	RG	RG	Node: A19	<u>A19</u>	<u>A19</u>	<u>A20</u>	<u>A20</u>	<u>A20</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	©	© ₀ 0	© 0 0 0			RG	RG	O Yes	O No
3	RG	RG	Node: O	© 0		- 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	© 0	© ₀	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node: O	©	000	- 0 0 0			RG	RG	O Yes	O No
6	RG	RG	Node: O	© 0		- 0 0 0 0			RG	RG	O Yes	O No





ITERATION	INF	PUT		PR	ROBABIL	ITY			OUTPUT (me)	VERI	IFICATION	
#	Node A20	Node A1	Roll the die Bubble the rolled face						Node B30	Traffic Light		
1	RG	RG	Node: A20	<u>A20</u> o o	<u>A20</u>	<u>A1</u>	<u>A1</u>	<u>A1</u>	RG	RG	O Yes	O No
2	RG	RG	Node: O	©	© ₀ 0	- 0 0 0	- 000 000		RG	RG	O Yes	O No
3	RG	RG	Node:	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
4	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
5	RG	RG	Node: O	© 0	© ₀ 0	- 0 0 0			RG	RG	O Yes	O No
6	RG	RG	Node: O	© 0	© ₀	- 0 0 0			RG	RG	O Yes	O No



1st Hidden Layer

You must also use the nodes in the second hidden layer