

# Functions

- ▶ Function
- ▶ Input/output parameters
- ▶ Call by value / call by reference
- ▶ return
- ▶ void

# Functions

- ▶ **Function** = callable group of statements that together perform a task
  - `output = function(input)`
    - \* Input parameter `input`
    - \* Output parameter (return value) `output`
- ▶ Why functions?
  - Decomposition of a large problem into manageable small problems
  - Structured programming (levels of abstraction)
  - Reuse of program code
- ▶ A function consists of **signature** and **body**
  - **Signature** = name & input/output parameters
    - \* Number & ordering are important!
  - **Body** = Implementation of the function

## Name convention

- ▶ Local variables `lowercase_with_underscores`
- ▶ Global variables `underscore_also_at_the_end_`
- ▶ Functions `firstWordLowercaseNoUnderscores`

# Functions in C

- ▶ In C functions are allowed to have
  - more than one or no parameters
  - one or zero return value
- ▶ Return value must be an elementary data type
  - \* e.g., `double`, `int`
- ▶ The signature has the following form  
`<type of return value> <function name>(parameters)`
  - Function without return value:
    - \* `<type of return value> = void`
  - Else: `<type of return value> = data type`
  - `parameters` = list of input parameters
    - \* separated by commas
    - \* specify data type *before* each parameter
    - \* *no* parameter  $\Rightarrow$  empty brackets `()`
- ▶ The body is a block
  - Go back to the main program either with `return` or, for functions without return value (`void`), at the end of the function block
  - Go back to the main program with `return output`, if the variable `output` should be returned
  - **Common mistake: forget return**
    - \* **Then, return value is random**
    - \* **Chaos (= runtime error)**

## Variables

- ▶ All variables declared throughout a function block are local
- ▶ All elementary variables declared in the signature are local
- ▶ Functions receive input parameters as values, recall type casting!

## Call by value

- ▶ **Call by value** = When the function is called, the values of the input parameters are copied into local variables used inside the function
  - New storage locations are allocated and the values of the input parameters are copied
  - Changes made inside the function have no effect on the input parameters

## Example: squaring

```
1 #include <stdio.h>
2
3 double square(double x) {
4     return x*x;
5 }
6
7 main() {
8     double x = 0;
9     printf("Input x = ");
10    scanf("%lf",&x);
11    printf("%f^2 = %f\n",x,square(x));
12 }
```

- ▶ Compiler must know the function **before** calling it
  - Define a function before its first call
- ▶ Execution always starts with **main()**
- ▶ The variable **x** in the function square and the variable **x** in the function main are different!
- ▶ Giving 5 as input value yields the output

Input x = 5

5^2 = 25.000000

## Example: Minimum of two numbers

```
1 #include <stdio.h>
2
3 double min(double x, double y) {
4     if (x > y) {
5         return y;
6     }
7     else {
8         return x;
9     }
10 }
11
12 main() {
13     double x = 0;
14     double y = 0;
15
16     printf("Input x = ");
17     scanf("%lf",&x);
18     printf("Input y = ");
19     scanf("%lf",&y);
20     printf("min(x,y) = %f\n",min(x,y));
21 }
```

- ▶ Input of 10 and 2 yields the output

Input x = 10

Input y = 2

min(x,y) = 2.000000

- ▶ Typical structure of a program in exercises:

- Function with a specific functionality
- Main program which
  - \* reads the input parameters from the keyboard
  - \* calls the function
  - \* prints the output to the screen

# Declaration of functions

```
1 #include <stdio.h>
2
3 double min(double, double);
4
5 main() {
6     double x = 0;
7     double y = 0;
8
9     printf("Input x = ");
10    scanf("%lf",&x);
11    printf("Input y = ");
12    scanf("%lf",&y);
13    printf("min(x,y) = %f\n",min(x,y));
14 }
15
16 double min(double x, double y) {
17     if (x > y) {
18         return y;
19     }
20     else {
21         return x;
22     }
23 }
```

- ▶ Too many functions might make the code heavy
  - Declare all functions at the beginning, see line 3
    - \* Compiler knows how the function operates
  - Full code of the function follows, see lines 16–23
- ▶ Alternative declaration = Function code without body
  - `double min(double x, double y);`  
see lines 3 and 16
- ▶ Keywords: *forward declaration* and *prototype*

## Call by value

```
1 #include <stdio.h>
2
3 void test(int x) {
4     printf("a) x=%d\n", x);
5     x = 43;
6     printf("b) x=%d\n", x);
7 }
8
9
10 main() {
11     int x = 12;
12     printf("c) x=%d\n", x);
13     test(x);
14     printf("d) x=%d\n", x);
15 }
```

► Output:

```
c) x=12
a) x=12
b) x=43
d) x=12
```



# Call by reference

- ▶ In other programming languages, it is not the value of a variable that is passed to a function as input parameter, but rather its memory address (**call by reference**)
  - In this way, changes in the variable can be also seen outside of the function

```
1 void test(int y) {
2     printf("a) y=%d\n", y);
3     y = 43;
4     printf("b) y=%d\n", y);
5 }
6
7
8 main() {
9     int x = 12;
10    printf("c) x=%d\n", x);
11    test(x);
12    printf("d) x=%d\n", x);
13 }
```

- ▶ This source code is **not** a C code!
  - Just to explain the concept!
- ▶ *Call by reference* **would** yield the following output:
  - c) x=12
  - a) y=12
  - b) y=43
  - d) x=43
- ▶ Call by reference in C realized with **pointers** (more details later!)

## Type casting & call by value

```
1 #include <stdio.h>
2
3 double divide(double, double);
4
5 main() {
6     int int1 = 2;
7     int int2 = 3;
8
9     printf("a) %f\n", int1 / int2 );
10    printf("b) %f\n", divide(int1,int2));
11 }
12
13 double divide(double dbl1, double dbl2) {
14     return(dbl1 / dbl2);
15 }
```

▶ Type casting from int to double in the function

▶ Output:

a) 0.000000

b) 0.666667

## Type casting (negative example!)

```
1 #include <stdio.h>
2
3 int isEqual(int, int);
4
5 main() {
6     double x = 4.1;
7     double y = 4.9;
8
9     if (isEqual(x,y)) {
10         printf("x == y\n");
11     }
12     else {
13         printf("x != y\n");
14     }
15 }
16
17 int isEqual(int x, int y) {
18     if (x == y) {
19         return 1;
20     }
21     else {
22         return 0;
23     }
24 }
```

► Output:

x == y

► But actually  $x \neq y$ !

- Implicit type casting from double to int via truncation, because input parameters are int

► Pay attention to type casting while dealing with functions

# Recursion

- ▶ What is a recursive function?
- ▶ Example: Factorial
- ▶ Example: Bisection method

## Recursive function

- ▶ A function is **recursive**, if it calls itself
- ▶ Natural concept in mathematics:
  - $n! = n \cdot (n - 1)!$
- ▶ Philosophy: Reduce a problem to a 'smaller' (= easier) problem of the same type
- ▶ Be careful!
  - Recursion must end
  - **Termination condition** is important
  - e.g.,  $1! = 1$
- ▶ Often recursion can be replaced by loops (more details later!)
  - usually recursion more elegant
  - usually loops more efficient

## Example: Factorial

```
1 #include <stdio.h>
2
3 int factorial(int n) {
4     if (n <= -1) {
5         return -1;
6     }
7     else {
8         if (n > 1) {
9             return n*factorial(n-1);
10        }
11        else {
12            return 1;
13        }
14    }
15 }
16
17 main() {
18     int n = 0;
19     int nfac = 0;
20     printf("n=");
21     scanf("%d",&n);
22     nfac = factorial(n);
23     if (nfac <= 0) {
24         printf("Wrong input!\n");
25     }
26     else {
27         printf("%d!=%d\n",n,nfac);
28     }
29 }
```

# Bisection method

## ► Input

- Continuous function  $f : [a, b] \rightarrow \mathbb{R}$  satisfying  $f(a)f(b) \leq 0$
- Tolerance  $\tau > 0$

## ► Intermediate value theorem

- There exists  $x \in [a, b]$  with  $f(x) = 0$

## ► Task

- Find approximation of a zero of  $f$
- i.e., find  $x_0 \in [a, b]$  with the following property:  
 $\exists x \in [a, b]$  such that  $f(x) = 0$  and  $|x - x_0| \leq \tau$

## ► Bisection method = Interval halving method

- As long as  $|b - a| > 2\tau$ 
  - \* Compute midpoint  $m$  of  $[a, b]$  and  $f(m)$
  - \* If  $f(a)f(m) \leq 0$ , consider  $[a, m]$
  - \* Otherwise consider  $[m, b]$
- $x_0 := m$  is the desired approximation

## ► The method terminates after a finite number of steps

## ► Convergence towards $x \in [a, b]$ with $f(x) = 0$ as $\tau \rightarrow 0$

## Example: Bisection method

```
1 #include <stdio.h>
2
3 double f(double x) {
4     return x*x + 1/(2 + x) - 2;
5 }
6
7 double bisection(double a, double b, double tol){
8     double m = 0.5*(a+b);
9     if ( b - a <= 2*tol ) {
10         return m;
11     }
12     else {
13         if ( f(a)*f(m) <= 0 ) {
14             return bisection(a,m,tol);
15         }
16         else {
17             return bisection(m,b,tol);
18         }
19     }
20 }
21
22 main() {
23     double a = 0;
24     double b = 10;
25     double tol = 1e-12;
26     double x = bisection(a,b,tol);
27
28     printf("Approximate zero x=%g\n",x);
29     printf("Function value f(x)=%g\n",f(x));
30 }
```

► Placeholder for **double** in **printf**

- **%f** fixed-point number representation **1.30278**
- **%e** exponential representation **-5.64659e-13**
- **%g** most appropriate between **%f** and **%e**



# Mathematical functions

- ▶ Compilation process
- ▶ Object code
- ▶ Libraries
- ▶ Mathematical functions

▶ `#define`

▶ `#include`

# Compilation process

- ▶ Compilers convert a C program into an executable
- ▶ Compilation process consists of four steps
  - Preprocessing
  - Compiling
  - Assembling
  - Linking

## Preprocessing

- ▶ Removes comments
- ▶ Expands macros and included files
- ▶ Preprocessor commands *always* start with **#** and *never* end with semicolon, e.g.,
  - **#define** text replacement
    - \* In all successive lines of code **text** is replaced by **replacement**
    - \* Useful to define constants
    - \* **Convention:** UPPERCASE\_WITH\_UNDERSCORES
  - **#include** file
    - \* Includes the file **file**

# Compiling & Assembling

- ▶ Compiler translates preprocessed (source) code into **assembly code**
- ▶ Assembler translates assembly code into **object code**
- ▶ Object code = Machine code, where symbolic names (e.g., function names) are still available

## Linking

- ▶ **Linker** includes further object code
  - e.g., libraries (= collection of functions)
- ▶ Symbolic names in object code are replaced by addresses
- ▶ Creation of executable program

## If you are curious...

- ▶ Compile code with **gcc -save-temps filename.c**
  - **filename.i** = Output of preprocessor
  - **filename.s** = Output of compiler
  - **filename.o** = Output of assembler (object code)

## Libraries & Header files

- ▶ **Libraries** (e.g., mathematical functions) always consists of 2 files
  - Object code
  - Associated header file
- ▶ Header file contains declaration of all functions available in the library
- ▶ If you want to use a library, you must include the corresponding header file in your source code
  - **#include <header>** includes the header file **header** from the standard folder **/usr/include/**
    - \* e.g., **math.h** (header file for math. library)
  - **#include "file"** the header file **file** from the *current* folder (e.g., downloads from internet)
- ▶ Moreover, object code of the library must be **linked**
  - Its location must be told to **gcc** with the option **-l** (and **-L**)
  - e.g., **gcc file.c -lm** links the math. library
  - Standard libraries automatically linked  
e.g., no additional option needed for **stdio**

# Mathematical functions

- ▶ Declaration of math. functions in `math.h`
  - Function input and output are of type `double`
- ▶ If you need a function of the math. library
  - In source code: `#include <math.h>`
  - Compile source code with linker option `-lm` to create the executable `output`, i.e.,  
`gcc file.c -o output -lm`
- ▶ Among others, this library provides
  - Trigonometric functions
    - \* `cos`, `sin`, `tan`, `acos`, `asin`, `atan`,  
`cosh`, `sinh`, `tanh`
  - Exponential and logarithm
    - \* `exp`, `log`, `log10`
  - Power and root functions
    - \* `pow`, `sqrt` (where  $x^y = \text{pow}(x, y)$ )
    - \* **NOT**  $x^3$  via `pow`, **BUT** `x*x*x`
    - \* **NOT**  $(-1)^n$  via `pow`, **BUT** ...
  - Absolute value `fabs`
  - Rounding to integers: `round`, `floor`, `ceil`
- ▶ **Be careful:** In the library `stdlib.h` there is `abs`
  - `abs` is absolute value for `int`
  - `fabs` is absolute value for `double`

## Elementary example

```
1 #include <stdio.h>
2 #include <math.h>
3
4 main() {
5     double x = 2.;
6     double y = sqrt(x);
7     printf("sqrt(%f)=%f\n",x,y);
8 }
```

- ▶ Precompiler commands in lines 1–2  
(without semicolon)
- ▶ Compile with `gcc sqrt.c -lm`
- ▶ If you forget `-lm` ⇒ Error message from linker  
In function 'main'  
sqrt.c:(.text+0x24): undefined reference to 'sqrt'  
collect2: ld returned 1 exit status
- ▶ Output:  
sqrt(2.000000)=1.414214

# Arrays

- ▶ Vectors & Matrices
- ▶ Operator `[...]`
- ▶ Matrix-vector multiplication
- ▶ Linear system of equations

# Vectors

- ▶ Declaration of a vector  $x = (x_0, \dots, x_{N-1}) \in \mathbb{R}^N$ :
  - `double x[N];` declares a double-vector `x`
- ▶ Access to the coefficients
  - `x[j]` refers to  $x_j$
  - Each `x[j]` is of type double
- ▶ Analogous declaration for other data types
  - `int y[N];` declares a int-vector `y`
- ▶ Watch out for the coefficient indexing!
  - In C the indices are  $0, \dots, N-1$
  - The indices are not  $1, \dots, N$
  - Indexing with  $1, \dots, N$  is used, e.g., in
    - \* Mathematics
    - \* Other programming languages (e.g., Matlab)
    - \* **NOT** in C!
- ▶ Simultaneous initialization & declaration possible
  - `double x[3] = {1,2,3};`  $\rightarrow x = (1, 2, 3) \in \mathbb{R}^3$
  - Vector initialization allowed only together with declaration
  - Otherwise must be done componentwise
    - \* i.e., `x[0] = 1; x[1] = 2; x[2] = 3;` is OK
    - \* `x = {1,2,3}` is not allowed



## Example: Reading a vector

```
1 #include <stdio.h>
2
3 main() {
4     double x[3] = {0,0,0};
5
6     printf("Input of a vector in R^3:\n");
7     printf("x_0 = ");
8     scanf("%lf",&x[0]);
9     printf("x_1 = ");
10    scanf("%lf",&x[1]);
11    printf("x_2 = ");
12    scanf("%lf",&x[2]);
13
14    printf("x = (%f, %f, %f)\n",x[0],x[1],x[2]);
15 }
```

- ▶ Printing double via **printf** with placeholder **%f**
- ▶ Reading double via **scanf** with placeholder **%lf**

## Static arrays

- ▶ Array lengths are static
  - Cannot be changed during program execution
    - \* e.g.,  $x \in \mathbb{R}^3$  cannot be changed to  $x \in \mathbb{R}^5$
- ▶ Programs cannot determine array sizes
  - During the execution, a program does not know that a vector  $x \in \mathbb{R}^3$  has length 3
  - Task of the programmer!
- ▶ Watch out for the coefficient indexing!
  - In C the indices are  $0, \dots, N - 1$
  - A program does not know if  $x[j]$  is defined
    - \*  $x$  must have at least length  $j + 1$
    - \* Wrong indexing is not a syntax error (= runtime error)
- ▶ Arrays cannot be the output of a function
- ▶ Arrays are passed to functions via call by reference
- ▶ The same holds for matrices or general arrays

## Arrays & Call by reference

```
1 #include <stdio.h>
2
3 void callByReference(double y[3]) {
4     printf("a) y = (%f, %f, %f)\n",y[0],y[1],y[2]);
5     y[0] = 1;
6     y[1] = 2;
7     y[2] = 3;
8     printf("b) y = (%f, %f, %f)\n",y[0],y[1],y[2]);
9 }
10
11 main() {
12     double x[3] = {0,0,0};
13
14     printf("c) x = (%f, %f, %f)\n",x[0],x[1],x[2]);
15     callByReference(x);
16     printf("d) x = (%f, %f, %f)\n",x[0],x[1],x[2]);
17 }
```

### ► Output:

```
c) x = (0.000000, 0.000000, 0.000000)
a) y = (0.000000, 0.000000, 0.000000)
b) y = (1.000000, 2.000000, 3.000000)
d) x = (1.000000, 2.000000, 3.000000)
```

### ► Call by reference for vectors!

### ► Explanation follows later (→ pointers)

# Wrong indexing for vectors

```
1 #include <stdio.h>
2 #define WRONG 1000
3
4 main() {
5     int x[3] = {0,1,2};
6
7     x[WRONG] = 43;
8
9     printf("x = (%d, %d, %d), x[%d] = %d\n",
10           x[0],x[1],x[2],WRONG,x[WRONG]);
11 }
```

- ▶ Line 2 defines the constant **WRONG**
  - **Convention:** Constants are **UPPERCASE\_WITH\_UNDERSCORES**
- ▶ Lines 7, 9–10: Wrong access to vector **x**
  - Nevertheless neither error message nor warning from the compiler
  - Correct indexing is a task of the programmer!
- ▶ Output:  
x = (0, 1, 2), x[1000] = 43
- ▶ Runtime error
  - **WRONG** small ⇒ No error message
  - **WRONG** suff. large ⇒ Maybe **segmentation fault**
    - \* Attempt to access a forbidden memory location

# Matrices

- ▶ Matrix  $A \in \mathbb{R}^{M \times N}$  is a rectangular structure

$$A = \begin{pmatrix} A_{00} & A_{01} & A_{02} & \dots & A_{0,N-1} \\ A_{10} & A_{11} & A_{12} & \dots & A_{1,N-1} \\ A_{20} & A_{21} & A_{22} & \dots & A_{2,N-1} \\ \vdots & \vdots & \vdots & & \vdots \\ A_{M-1,0} & A_{M-1,1} & A_{M-1,2} & \dots & A_{M-1,N-1} \end{pmatrix}$$

with coefficients  $A_{jk} \in \mathbb{R}$

- ▶ Fundamental objects in linear algebra
- ▶ Declaration of a matrix  $A \in \mathbb{R}^{M \times N}$ :
  - `double A[M][N];` declares a double-matrix **A**
- ▶ Access to the coefficients
  - `A[j][k]` refers to  $A_{jk}$
  - Each `A[j][k]` is of type double
- ▶ Row-wise initialization together with declaration
  - `double A[2][3] = {{1,2,3},{4,5,6}};`  
declares and initializes  $A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$
  - Only possible for simultaneous declaration  
(the same as for vectors)

## General arrays

- ▶ Vectors are 1-dimensional arrays
- ▶ Matrices are 2-dimensional arrays
- ▶ In general, given a data type `type`,
  - `type x[N];` declares a vector of length  $N$ , where each `x[j]` is a variable of type `type`
  - `type x[M][N];` declares a  $M \times N$  matrix, where `x[j]` is a vector of type `type` (with length  $N$ ), while each `x[j][k]` is a variable of type `type`
  - `type x[M][N][P];` declares a 3-dimensional array, where `x[j]` is a  $N \times P$  matrix of type `type`, `x[j][k]` is a vector of type `type` (with length  $P$ ), while each `x[j][k][p]` is a variable of type `type`
  - ...