Towards reproducible Jupyter notebooks

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Jupyter = reproducible science

Jupyter = reproducible science?

```
In [1]: %matplotlib inline
        from matplotlib import pyplot as plt
        from matplotlib import style
        import random
        x = random.sample(range(1, 5000), 1000)
        num bins = 100
        n, bins, patches = plt.hist(x, num bins, facecolor='green', alpha=0.5)
        plt.title('Histogram Example')
        plt.xlabel('Values')
        plt.xlabel('Counts')
        plt.show()
```



Daniel S. Katz

@danielskatz

Follow

When I see a jupyter notebook that starts with pip install I get a little scared

6:37 AM - 15 Jul 2019



Luis Pedro Coelho @luispedrocoelho · Jan 22

Me, 6 months ago: I am going to save this conda environment with all the versions of all the packages so it can be recreated later; this is Reproducible Science!

conda, today: these versions don't work together, lol.

○ 3 1 3



Turn a Git repo into a collection of interactive notebooks

Have a repository full of Jupyter notebooks? With Binder, open those notebooks in an executable environment, making your code immediately reproducible by anyone, anywhere.

- environment.yml Install a Python environment • Pipfile and/or Pipfile.lock - Install a Python environment
- requirements.txt Install a Python environment
- setup.pv Install Python packages
- Project.toml Install a Julia environment • **REOUIRE** - Install a Julia environment (legacy)
- install.R Install an R/RStudio environment
- apt.txt Install packages with apt-get
- **DESCRIPTION** Install an R package manifest.xml - Install Stencila
- postBuild Run code after installing the environment
- start Run code before the user sessions starts
- runtime.txt Specifying runtimes
- default.nix the nix package manager • Dockerfile - Advanced environments

What if notebooks were

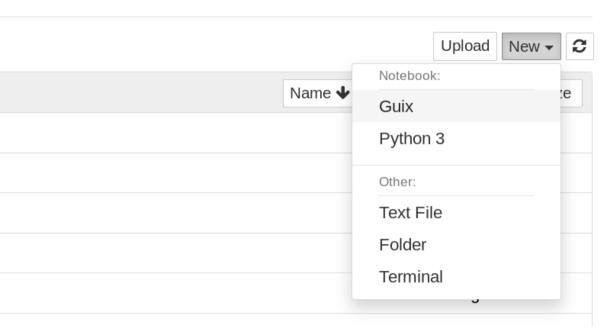
self-contained,

"deployment-aware"?

```
$ guix environment --ad-hoc \
         python python-numpy python-scipy \
         -- python3
```







```
In [4]: ;;quix environment matplotlib-env <- python-ipykernel python-ipywidgets python-matplotlib
Out[4]:
        Preparing environment matplotlib-env with these packages:
          • python-ipykernel 5.1.1
          • pvthon-ipvwidgets 5.2.2
          • python-matplotlib 3.1.1
Out[3]: Running Python 3 kernel.
In [1]: %matplotlib inline
        from matplotlib import pyplot as plt
        from matplotlib import style
        import random
        x = random.sample(range(1, 5000), 1000)
        num bins = 100
        n, bins, patches = plt.hist(x, num bins, facecolor='green', alpha=0.5)
        plt.title('Histogram Example')
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```

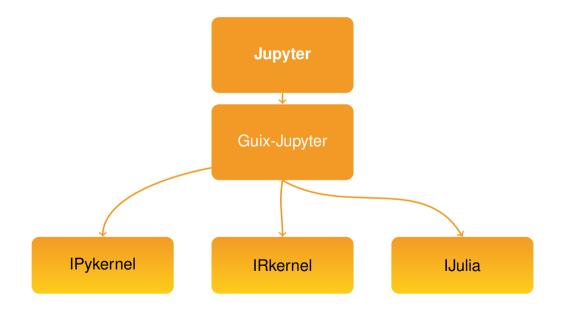


First, jump back to Guix as it existed in January 2019:

Out [1]: Switched to these Guix channels:

In [1]: ;; guix pin 0791437f972caa7e48de91ad5cb150a614f617c2

quix 0791437f972caa7e48de91ad5cb150a614f617c2



```
In [6]: import os
        os.getcwd()
Out[6]: '/home/jupyter'
In [7]: os.getuid()
Out[7]: 1000
In [8]: os.getpid()
Out[8]: 1
In [9]: os.listdir('.')
Out[9]: ['.ipython']
```



Imposing a Memory Management Discipline on Software Deployment

Eelco Dolstra, Eelco Visser and Merijn de Jonge Utrecht University, P.O. Box 80089, 3508 TB Utrecht, The Netherlands {eelco, visser, mdejonge}@cs.uu.nl

Abstract

The deployment of software components frequently fails because dependencies on other components are not declared explicitly or are declared imprecisely. This results in an incomplete reproduction of the environment necessary for proper operation, or in interference between incompatible variants. In this paper we show that these deployment hazards are similar to pointer hazards in memory models of programming languages and can be countered by imposing a memory management discipline on software deployment.

cies between the components being deployed. Dependencies on other components are not declared explicitly, causing an incomplete reproduction of the environment necessary for proper operation of the components. Furthermore, dependency information that is declared, is often not precise enough, allowing incompatible variants of a component to be used, or causing interference between such variants.

In this paper, we present a simple and effective solution to such deployment problems. In Section 2 we analyse the problems that occur in software deployment. We then show

Wrap-up.

Open issues

- how can we improve the user interface?
- should deployment be built into Jupyter?
- what about interoperability?
- **...**

Guix-Jupyter =

- self-contained notebooks
- automatic & reproducible deployment
- code runs in isolated environment



https://hpc.guix.info

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Delegant land and land in the Control of the Contro

DeLorean time machine picture © 2014 Oto Godfrey and Justin Morton, CC-BY-SA 4.0, https://commons.wikimedia.org/wiki/File:TeamTimeCar.com-BTTF_DeLorean_Time_Machine-OtoGodfrey.com-

JMortonPhoto.com-07.jpg.

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