Advanced indexing techniques

Knowledge Objectives

- Explain which index suits best depending on the selectivity of the selection predicate, the kind of comparison and the volatility of the table
- Name three situation where an index is useless
- 3. Explain what a bitmap index is
- 4. Explain the conditions where a bitmap suits better than a B+ index and vice-versa
- 5. Explain what a join-index is
- Explain the benefit of bitmap-join-indexes in multidimensional queries
- 7. Explain what makes the difference between a join-index and a clustered structure, from the query time point of view

Understanding Objectives

- Know the factors involved in the choice between rebuilding an index or making individual insertions in the case of massive insertions
- 2. Calculate the approximate size of a bitmap index
- 3. Estimate the cost of a selection with a complex predicate using a bitmap index
- 4. Estimate the cost of a join (or semi-join) operation using a join index (either bitmap, B+, hash or cluster)
- 5. Given a simple query (not mixing selection and join operations) and the structures of the tables, decide whether it can be solved by accessing only the indexes
- 6. Given the attributes in a multi-attribute index and a complex selection predicate, decide whether the index can be used to solve the query or not

Insertion of values with an index

- a) Individual insertions
 - Create the index over the table and insert the tuples one by one
- b) Massive insertions
 - Fill the table and create the index
 - Remove the index, insert tuples and rebuild the index

Algorithm to build a B-tree

- Create a file with the entries [value, RID]
- 2. Sort the file by value
- Build the leaves (filling them to the desired load)
- 4. Build the internal nodes (filling them to the desired load)
- 5. Save it to disk

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Order = 2Load = 75%

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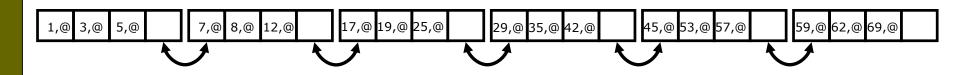
Order = 2Load = 75%

- 1. Create a file with entries [value,RID]
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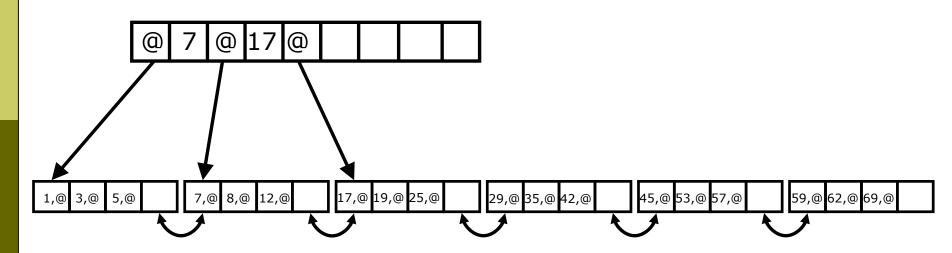
- 1. Create a file with entries [value,RID]
- 2. Sort the file by value
- 3. Build the leaves (filling them to the desired load)
- 4. Build the internal nodes (filling them to the desired load)
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Order = 2Load = 75%



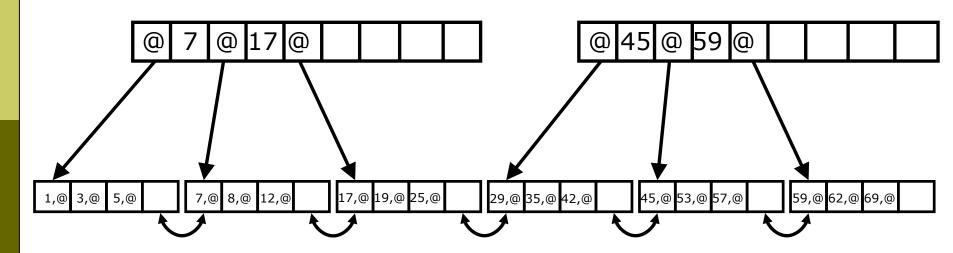
- 1. Create a file with entries [value,RID]
- 2. Sort the file by value
- 3. Build the leaves (filling them to the desired load)
- 4. Build the internal nodes (filling them to the desired load)
- 5. Save it to disk

Order = 2Load = 75%



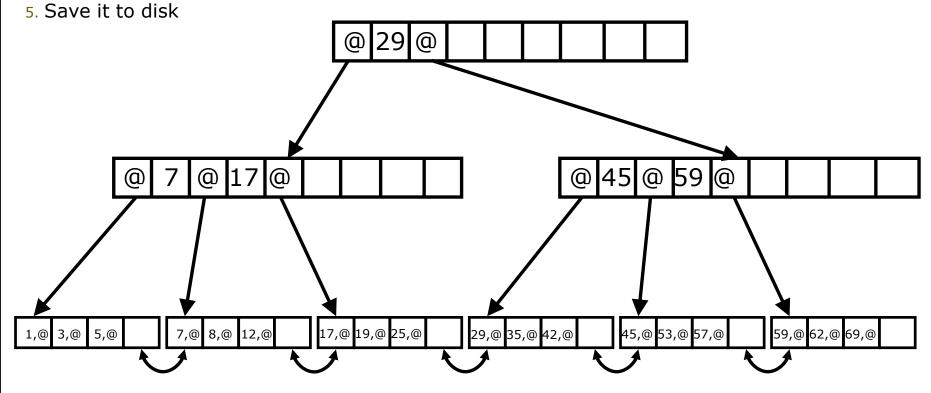
- 1. Create a file with entries [value,RID]
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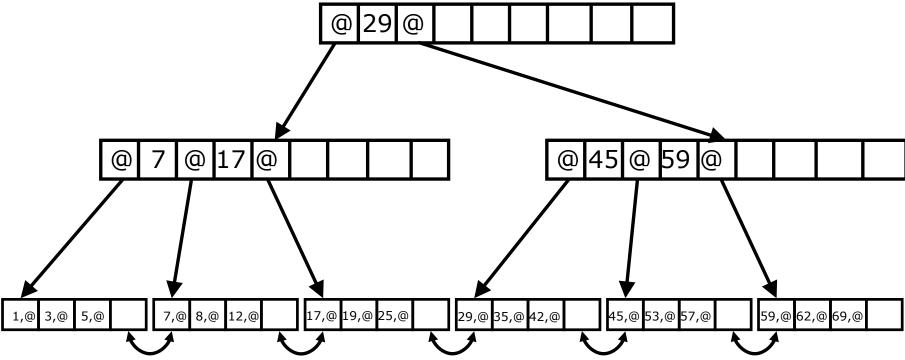
- 1. Create a file with entries [value,RID]
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- 1. Create a file with entries [value,RID]
- 2. Sort the file by value
- 3. Build the leaves (filling them to the desired load)
- 4. Build the internal nodes (filling them to the desired load)
- 5. Save it to disk

Order = 2Load = 75%



Comparison

- A. Sequence of individual insertions
 - For each new tuple
 - 1. Insert it
 - 2. Find its place
 - 3. Write the leaf (Possible split)
- B. Rebuild an index
 - Remove the index
 - 2. Insert new tuples
 - 3. Read table (with new tuples)
 - 4. Write entries file
 - 5. Sort entries
 - 6. Write index

- Copy leaves to entries file
- 2. Remove the index
- Insert new tuples and entries
- 4. Sort entries
- 5. Write index

We should define an index ...

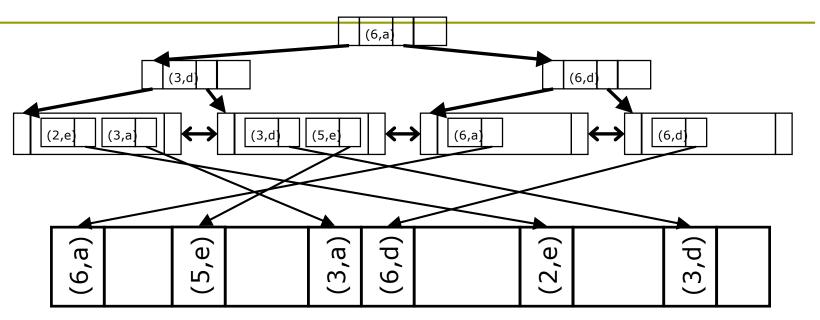
- B-tree:
 - There is a very selective condition
- Hash:
 - There is a very selective condition (with equality)
 - The table is not very volatile
 - The table is huge
- Clustered:
 - There is a little selective condition, or a GROUP BY or an ORDER BY or ...
 - The table is not very volatile

We should NOT define an index ...

- Processing is massive
 - Never one tuple at a time
- The table has few blocks
- The attribute has few values
 - Little selective conditions
- The attribute appears in the predicate inside a function (maybe DBMS allows function-based indexes)

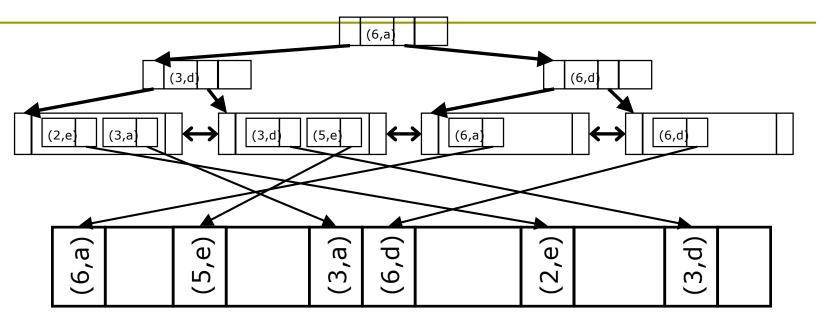
Usefulness of multi-attribute trees

- Need more space
 - For each tuple, keeps attributes A₁, ..., A_k
 - May result in more levels, worsening access time
- Modifications are more frequent
 - Every time one of the attributes in the index is modified
- It is much more efficient than intersecting RID lists (to evaluate conjunctions)
- Can be used to solve several kinds of queries
 - Equality of all first i attributes
 - Equality of all first i attributes and range of i+1
- The order of attributes in the index matters
 - We cannot evaluate condition over A_k , if there is no equality for $A_1, ..., A_{k-1}$



Queries:

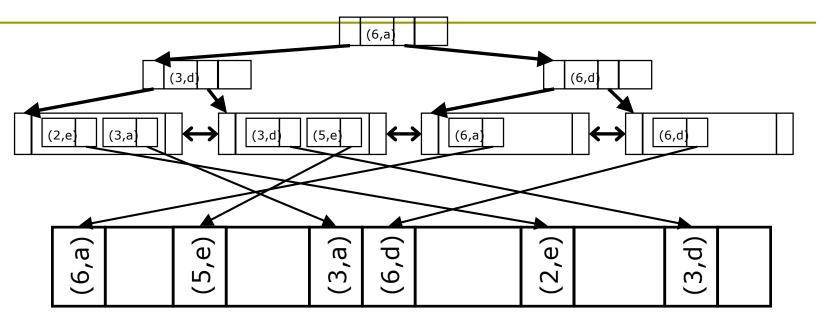
- Num='3' AND Let='d'
- Num='3' AND Let>'b'
- Num='3'
- Num>'3' AND Let='a'
- Num>'3' AND Let>'b'
- Num>'3'
- Let='e'
- Let>'b'
- Num='3' OR Let='a'



Queries:

- Num='3' AND Let='d'
- Num='3' AND Let>'b'
- Num='3'
- Num>'3' AND Let='a'
- Num>'3' AND Let>'b'
- Num>'3'
- Let='e'
- Let>'b'
- Num='3' OR Let='a'

YES

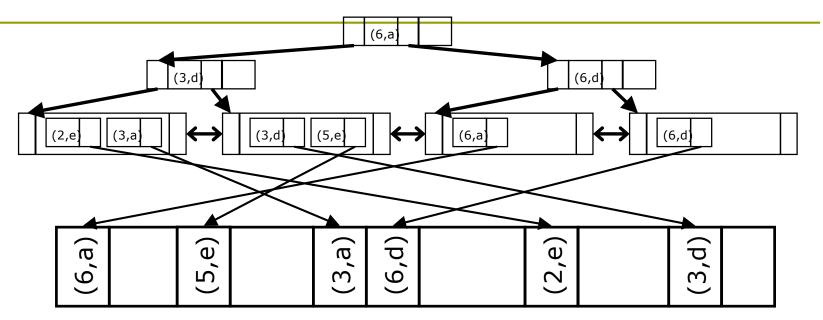


Queries:

- Num='3' AND Let='d'
- Num='3' AND Let>'b'
- Num='3'
- Num>'3' AND Let='a'
- Num>'3' AND Let>'b'
- Num>'3'
- Let='e'
- Let>'b'
- Num='3' OR Let='a'

YES

YES



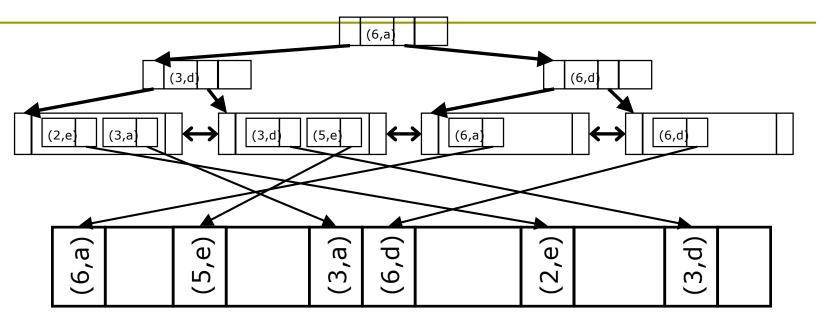
Queries:

- Num='3' AND Let='d'
- Num='3' AND Let>'b'
- Num='3'
- Num>'3' AND Let='a'
- Num>'3' AND Let>'b'
- Num>'3'
- Let='e'
- Let>'b'
- Num='3' OR Let='a'

YES

YES

YES



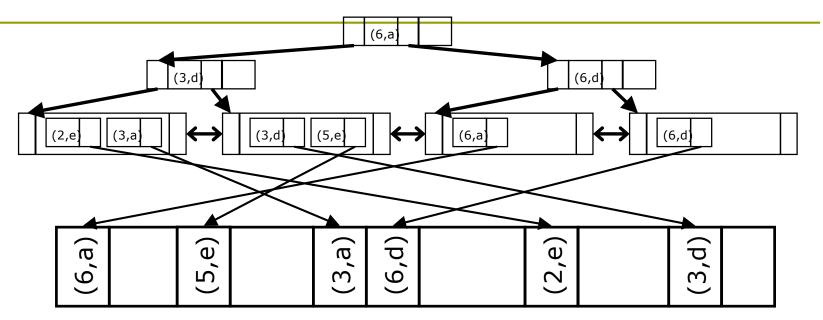
Queries:

- Num='3' AND Let='d'
- Num='3' AND Let>'b'
- Num='3'
- Num>'3' AND Let='a'
- Num>'3' AND Let>'b'
- Num>'3'
- Let='e'
- Let>'b'
- Num='3' OR Let='a'

YES

YES

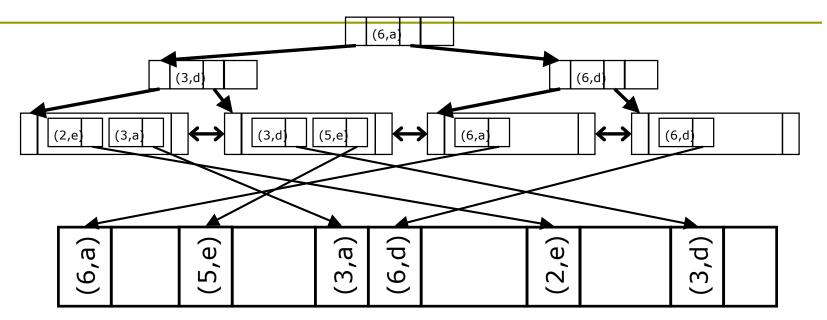
YES



Queries:

- Num='3' AND Let='d'
- Num='3' AND Let>'b'
- Num='3'
- Num>'3' AND Let='a'
- Num>'3' AND Let>'b'
- Num>'3'
- Let='e'
- Let>'b'
- Num='3' OR Let='a'

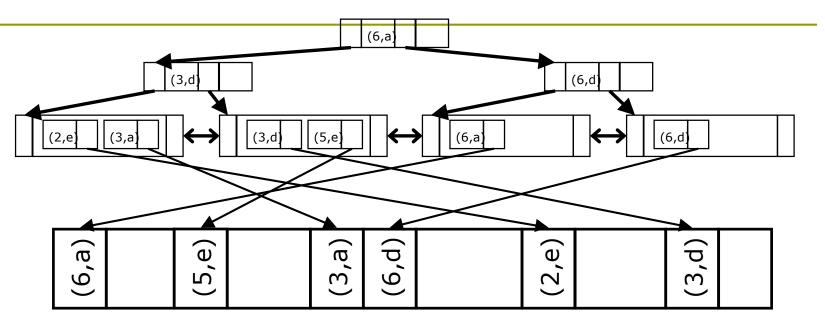
- YES
- YES
- YES
- NO
- NO



Queries:

- Num='3' AND Let='d'
- Num='3' AND Let>'b'
- Num='3'
- Num>'3' AND Let='a'
- Num>'3' AND Let>'b'
- Num>'3'
- Let='e'
- Let>'b'
- Num='3' OR Let='a'

- YES
- YES
- YES
- NO
- NO
- YES



Queries:

		Num=\3'	AND	l et='d'
--	--	---------	-----	----------

- Num='3' AND Let>'b'
- Num='3'
- Num>'3' AND Let='a'
- Num>'3' AND Let>'b'
- Num>'3'
- Let='e'
- Let>'b'
- Num='3' OR Let='a'

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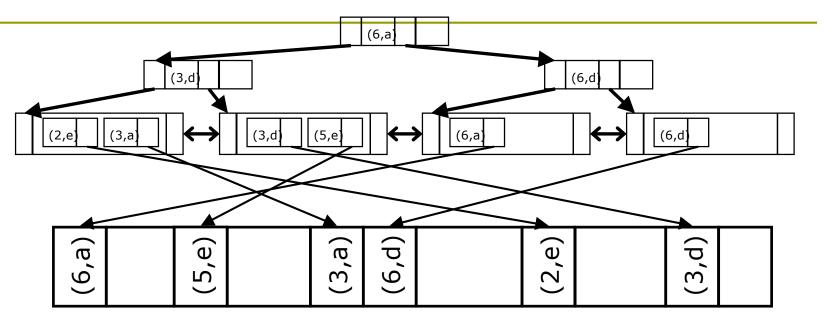
YES

YES

NO

NO

YES



Queries:

Num='3' AND Let>'b'

Num='3'

Num>'3' AND Let='a'

Num>'3' AND Let>'b'

Num>'3'

Let='e'

Let>'b'

Num='3' OR Let='a'

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YES

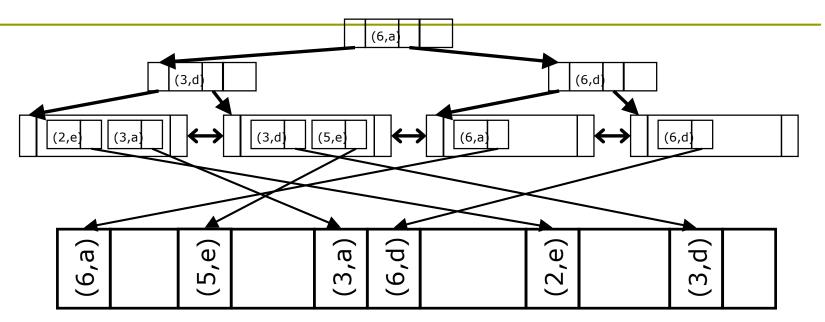
YES

NO

NO

YES

NO



Queries:

Num='3' AND Let='d'	
---------------------	--

Num='3' AND Let>'b'		Let>'h'	AND	Num='3'	
---------------------	--	---------	-----	---------	--

- Num>'3'
- Let='e'
- Let>'b'
- Num='3' OR Let='a'

YFS	

YES

YES

NO

NO

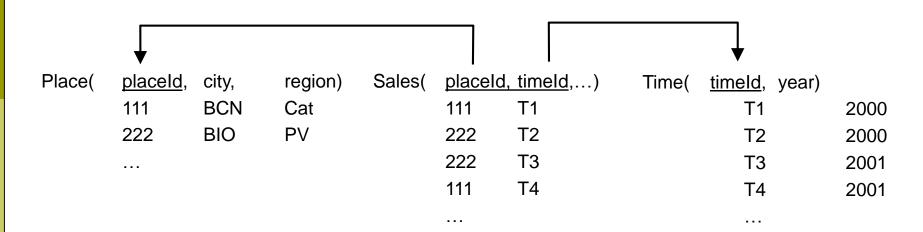
YES

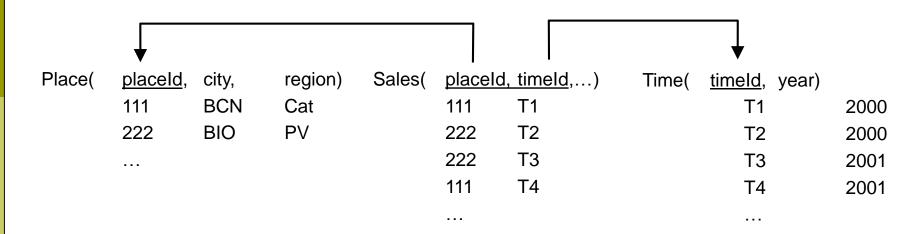
NO

NO

Multidimensional queries

SELECT d1.articleName, d2.region, d3.month, SUM(f.articles) FROM Sales f, Product d1, Place d2, Time d3 WHERE f.productId=d1.ID AND f.placeId=d2.ID AND f.timeId=d3.ID AND d1.articleName IN ('Ballpoint','Rubber') AND d2.region='Catalunya' AND d3.month IN ('January02', 'February02') GROUP BY ... **Product** Place Sales Time

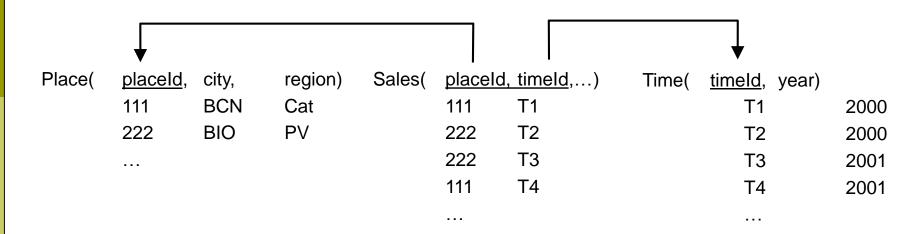




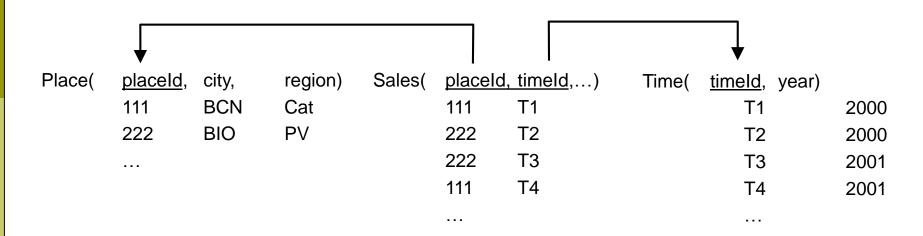
Join-index (one attribute)

Cat 1,4, ...

PV 2,3, ...



Join-ind	lex (one attribute)	Join-index (two attributes)			
Cat	1,4,	Cat	2000	1,	
PV	2,3,		2001	4,	
		PV	2000	2,	
			2001	3	



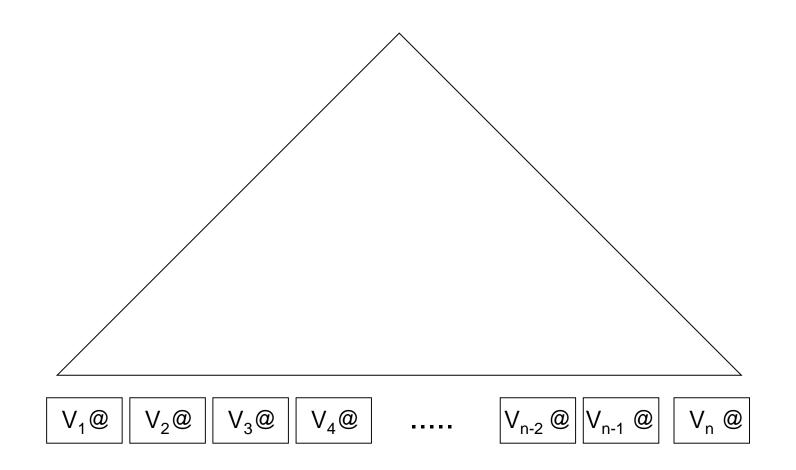
Join-ind	ex (one attribute)	Join-ind	lex (two attril	outes)	Join-ind	ex (two attr	ibutes)
Cat	1,4,	Cat	2000	1,	2000	Cat	1,
PV	2,3,		2001	4,		PV	2,
		PV	2000	2,	2001	Cat	4,
			2001	3,		PV	3,

- The algorithm is the one inside the loop in Row Nested Loops
- The saving in multidimensional queries is
 - Dimension tables do not need to be accessed
- Considerations
 - It is really useful if there is a join-index over the selection attribute of R
 - It may be useful even if there is a join-index over the join attribute of R
 - A hash index can only be used for equi-join
 - We cannot use this algorithm if we already performed another operation over the table (we could decide to change the syntactic tree)

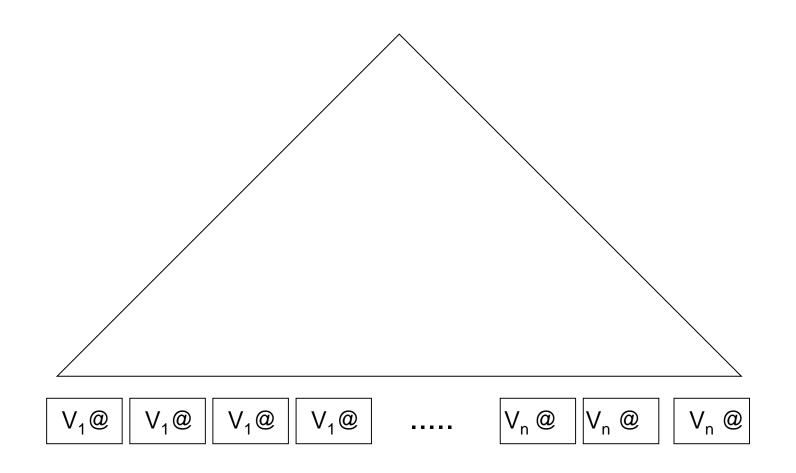
B-tree (I)

- Specially useful for simple queries
 - Without grouping, aggregations, or many joins
- Works better for very selective attributes (few repetitions per value)
 - Attributes in multidimensional queries are usually not very selective
- Order of attributes in the index is relevant
 - We can define as many indexes as we want
 - We can define only one Clustered index
 - For big tables, they may use too much space

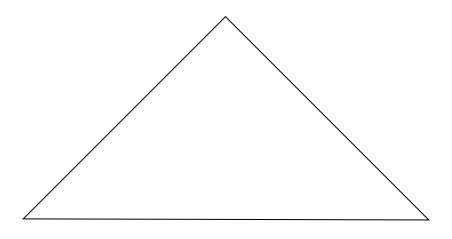
B-tree (II)



B-tree (II)



B-tree (II)



B-tree (II)

V₁@@...

V₂ @@...

V₃ @@...

V₄ @@...

Bitmap-index

Catalunya	León	o Madrid	Andalucía
1	0	0	0
1	0	0	0
0	0 0 0 1	0 0 1 0	1
0	0	1	0
0	1	0	0
1 0 0 0	0	0	0 0 0
0	0	0	1
0 0 1	0 1 0	0 0	1 0 0
1	0		0
1	0	0	0

Querying with bitmaps

SELECT COUNT(*)

. . .

WHERE articleName IN ['Ballpoint', 'Pencil'] AND region='Catalunya'

Ballpoint	F	Penci	1		Cata	alur	nya		
1 0 0 0 0 1 0 0 0	OR	0 0 1 0 0 0 0 0		1 0 1 0 1 0 0	AND	1 0 0 1 0 1 1	=	1 0 0 0 1 0 0	

- Two cases of insertion:
 - Without domain expansion:
 - □ Add "1"
 - With domain expansion:
 - Add a new vector
- One case of deletion:
 - Change "1" for "0"

Catalunya León Madrid Andalucía

1	0	0	0
1	0	0	0
0	0	0	1
0	0	1	0
0	1	0	0
1	0	0	0
0	0	0	1
0	1	0	0
1	0	0	0
1	0	0	0

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Catalunya León Madrid Andalucía

1	0	0	0
1	0	0	0
0	0	0	1
0	0	1	0
0	1	0	0
1	0	0	0
0	0	0	1
0	1	0	0
1	0	0	0
1	0	0	0
0	0	1	0

- Two cases of insertion:
 - Without domain expansion:
 - □ Add "1"
 - With domain expansion:
 - Add a new vector
- One case of deletion:
 - Change "1" for "0"

Catalunya León Madrid Andalucía Euskadi

1	0	0	0	0
1	0	0	0	0
0	0	0	1	0
0	0	1	0	0
0	1	0	0	0
1	0	0	0	0
0	0	0	1	0
0	1	0	0	0
1	0	0	0	0
1	0	0	0	0
0	0	1	0	0
0	0	0	0	1

- Two cases of insertion:
 - Without domain expansion:
 - □ Add "1"
 - With domain expansion:
 - Add a new vector
- One case of deletion:
 - Change "1" for "0"

Catalunya León Madrid Andalucía Euskadi

0	0	0	0	0
1	0	0	0	0
0	0	0	1	0
0	0	1	0	0
0	1	0	0	0
1	0	0	0	0
0	0	0	1	0
0	1	0	0	0
1	0	0	0	0
1	0	0	0	0
0	0	1	0	0
0	0	0	0	1

Probabilities with a bitmap

- Probability of a tuple fulfilling PSF
- Probability of a tuple NOT fulfilling P1-SF
- □ Probability of none of the tuples in a block fulfilling P $(1-SF)\cdot(1-SF)\cdot...\cdot(1-SF) = (1-SF)^R$
- Probability of some tuple in a block fulfilling P
 1-(1-SF)^R

Cost of bitmap per operation

- Table scan
 - ndist·[|T|/bits]·D+B·D
- Search for some tuples
 - v· |T|/bits + (B·(1-(1-SF)^R))
 - Examples:
 - Search for one tuple
 - Search for several tuples (given one value)
 - \[|T|/bits\] · D+(B·(1-((ndist-1)/ndist)\]
 - Search for several tuples (given several values)
 - v·[|T|/bits]·D+(B·(1-((ndist-v)/ndist)^R))
- Insertion of one tuple (in the last table block)
 - Existing value: ndist·2+2
 - New value: ndist·2+2+ [|T|/bits]
- Deletion of all tuples with a given value
 - \[|T|/bits\] + \(B \cdot (1 ((ndist 1)/ndist)^R)) \cdot 2

bits: bits per index block

v: number of queried values

ndist: different values

Cost of bitmap per operation

- Table scan
 - Useless

bits: bits per index block ndist: different values v: number of queried values

- Search for some tuples
 - v· |T|/bits + (B·(1-(1-SF)^R))
 - Examples:
 - Search for one tuple
 - Search for several tuples (given one value)
 - \[|T|/bits\] · D+(B·(1-((ndist-1)/ndist)\]
 - Search for several tuples (given several values)
 - v·[|T|/bits]·D+(B·(1-((ndist-v)/ndist)^R))
- Insertion of one tuple (in the last table block)
 - Existing value: ndist·2+2
 - New value: ndist·2+2+ \[|T|/bits \]
- Deletion of all tuples with a given value
 - \[|T|/bits\] + \(B \cdot (1 ((ndist 1)/ndist)^R)) \cdot 2

Cost of bitmap per operation

- Table scan
 - Useless

bits: bits per index block ndist: different values v: number of queried values

- Search for some tuples
 - $\mathbf{v} \cdot [\mathsf{T}] + (\mathsf{B} \cdot (1 (1 \mathsf{SF})^\mathsf{R}))$
 - Examples:
 - Search for one tuple
 - Useless?
 - Search for several tuples (given one value)
 - [|T|/bits]·D+(B·(1-((ndist-1)/ndist)^R))
 - Search for several tuples (given several values)
 - $v \cdot \lceil |T| / bits \rceil \cdot D + (B \cdot (1 ((ndist v) / ndist)^R))$
- Insertion of one tuple (in the last table block)
 - Existing value: ndist·2+2
 - New value: ndist·2+2+ [|T|/bits]
- Deletion of all tuples with a given value
 - \[|T|/bits\] + \(B\cdot(1-((ndist-1)/ndist)\)\) \(2\)

Comparison

- Better than B-tree and hash for multi-value queries
- Optimum performance for several conditions over more than one attribute (each with a low selectivity)
- Orders of magnitude of improvement compared to a table scan (specially for SF<1%)</p>
- May be useful even for range queries
- Easy indexing of NULL values
- Useful for non-unique attributes (specially for ndist<|T|/100, i.e. hundreds of repetitions)</p>
- Bad performance for concurrent INSERT, UPDATE and DELETE
- Use more space than RID lists for domains of 32 values or more (may be better with compression), assuming uniform distribution and 4 bytes per RID

Bitmap indexes in Oracle 11g

```
CREATE
[{UNIQUE|BITMAP}] INDEX <name>
ON  (<column>[,column]*);
```

- Allowed even for unique attributes
- Does not allow to check uniqueness

Benefits of Bitmap-join-index

CREATE BITMAP INDEX salesRegion
ON Sales(Place.region)
FROM Sales, Place
WHERE Sales.placeId=Place.ID;

- The saving in multidimensional queries is
 - Bit operations substitute unions and intersections
- Comparison against Clustered Structure:
 - Space: Always better
 - Time: Better for several relatively selective conditions

Index-only query answering

ProjectionSELECT ageFROM people

SELECT DISTINCT age FROM people

- Attribute removal
 - B+
- 1.5(|T|/2d)·D
- Hash
 - 1.25(|T|/2d)·D
- Aggregates

SELECT MIN(age) FROM people

SELECT AVG(age) FROM people

SELECT age, COUNT(*) FROM people GROUP BY age;

Joins

SELECT p.name FROM people p, departaments d WHERE p.id=d.boss;

- Index Sort Match Join
- Index Block Nested Loops
- Index Row Nested Loops

Summary

- □ Algorithm for B-tree rebuilding
- We should/shouldn't define an index...
- Bitmap-index
- Multi-attribute index usage
- □ Join-index
- □ Index-only query answering

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