

Valent F(x) Logi Family

Mark 1 Starter Guide

A brief beginner's guide to the Mark 1 FPGA platform

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1. Forward

This tutorial is designed for beginners interested in getting started working with FPGA technology. FPGAs offer a very new and robust way to tackle digital system design. Unfortunately, their power and flexibility, coupled with their multidisciplinary nature, make them extremely complicated to work with. Consequently, the barrier to entry is quite a bit higher than your everyday microcontroller or discrete integrated circuit. An FPGA designer really needs to know a lot of information to make an FPGA do anything at all.

In an effort to ease this FPGA learning curve and get exposure to a wider audience of electronics practitioners, both hobbyist and professional alike, ValentF(X) has developed the Mark 1 FPGA board. It is a part of the Logi family of boards and is a fantastic platform to start out on for anyone who wants to learn about FPGA technology. It has many features that make it easy for beginners to dive quickly into FPGA development as well as IO capabilities and a form factor that a seasoned professional can even appreciate.

The primary goal of this guide is to take an absolute beginner from having a lifeless piece of hardware in front of them, to making it actually *do* something in a matter of hours. Therefore, the guide has also been designed to be a concise, goal oriented read. In areas where verbosity would slow the pace, there are many links to external content provided so you can explore and further your education on your own time.

Note, the part of this guide that actually takes the longest is downloading the FPGA development environment from Xilinx – the file is nearly **eight gigabytes**. If you're interested in completing this tutorial in an afternoon, start by getting the download going now! See the section called [Setup Your Development Environment](#) to start downloading the Xilinx "ISE" development software.

2. Background

[Field programmable gate arrays](#) (FPGAs) are unique [integrated circuits](#) (ICs) whose defining characteristic is that their internal logic can be reprogrammed indefinitely. They arrived on the scene around 1986 and have grown ever more sophisticated and capable over the years. Today they are found in many electronics devices such as networking equipment, electromechanical control equipment, cellular equipment as well as in simpler designs such as your car or maybe even your microwave.

At a fundamental level, the "program" running on an FPGA is actually a digital circuit whose wires are "executing" [combinatorial](#) and/or [sequential](#) logic. In FPGAs, the circuits consist of several to many millions of fundamental [logic gates](#) such as an [OR](#), [AND](#), [NOT](#) and [XOR](#) gate, just to name a few. An FPGA design typically has many inputs and outputs as well as [clock signals](#) to keep things synchronized.

It's really best to think about the logic on the FPGA's "fabric" as a physical circuit. In computing applications that run on processors, people are normally accustomed to thinking about their program as running in a sequential manner. The code executes from top to bottom right? Well, in FPGAs this is typically not the case. Everything is happening at once. There can be many parallel "logical flows" executing at the same time. Furthermore, parallel logical flows can interact with each other. In reality, you're building a circuit on the FPGA fabric, not a sequential processor. And, as in any circuit you are free to route any wire or "[net](#)," to any destination.

The reprogrammable internal logic found in FPGAs is an immensely powerful feature for many other reasons as well. For example, back in the days before FPGAs if you were designing a [printed circuit board](#) (PCB), the final design is what you were stuck with. And of course, if a mistake was made in the routing of the electrical signals you will have nearly irreversible problems.

Say some data signal from pin P73 of component U8 was wired to pin P27 of component U15 on the PCB; you would lay a copper trace on the PCB and then you are committed to that signal. If there was a mistake made on this trace or for some reason, after the PCB was manufactured the design no longer needed that signal, you have no option but to revise the board design and manufacture the board again. With an FPGA you might not need to do this depending on the circumstances. Component U8 and U15 might actually be in the FPGA fabric and therefore, all you would need to do is reprogram the FPGA to fix your mistake. Also, with an FPGA you could potentially add more functionality to the board's design after the PCB was made just by reprogramming the FPGA fabric!

At a higher level the reprogrammable, digital circuitry found in FPGAs allows designers to put much of the logic found in many discrete integrated circuits, onto one FPGA chip. This "part consolidation" feature makes for cheaper PCB designs and allows a greater margin of error in a PCB manufacturing. Imagine a PCB with 30, discrete integrated circuits on it. There would be a very large number of traces that need to be perfectly placed in order for the design to work. If you took the same design and consolidated the logic of 25 of these discrete integrated circuits onto the FPGA's fabric, the PCB would have far fewer traces that could go wrong.

Furthermore, because the FPGA's internal logic is reprogrammable; the FPGA designers can iterate their logical implementation of the 25 ICs as many times as they want without incurring any costs of "spinning" a new PCB – the only cost is the programmer's time. Also, designs based on FPGAs often have a much shorter time to market than a similar [ASIC](#) design and therefore are far more cost effective for smaller runs of complex custom hardware.

Indeed, the current trend in the electronics industry is moving toward more and more the part consolidation on circuit boards. This new breed of IC technology has been driven primarily by the mobile computing markets where size and power consumption are of primary importance. This has given rise to the concept of a [system on a chip](#) (or SoC) integrated circuit. Fortunately, the two major FPGA companies, Xilinx and Altera, offer sophisticated tools ([Vivado](#) and [Qsys](#) respectively) to help a designer efficiently make FPGAs into effective, reprogrammable SoCs.

The FPGA space is still quite new and the technology is evolving rapidly. Today we find FPGAs with ARM microprocessors in them which opens up a whole new world of possibilities. Most of all, FPGAs offer a unique and efficient way of solving very complex digital system design problems in an efficient, cost-effective manner. So why don't we dive in!

3. Getting Started

After taking the Mark 1 out of the box, take a moment to look carefully at the unit. You will see the board's dominant chip is a [Xilinx Spartan 6](#) FPGA. This is a relatively low cost and high performance device.

Your average electronics consumer will also spot two micro [USB](#) headers, some buttons, switches and a bank of small [LEDs](#). A more trained eye will see two [SATA](#) headers, a [JTAG](#) interface and even a small square [microcontroller](#) by [NPX Semiconductor](#).

You will notice a number of other [headers](#) on the board. The ones on top facing up arranged in a straight line can be used for [general purpose IO](#). The ones facing to the left, bent off the board at a right angle, are [Pmod](#) interfaces. Obviously, these bring huge device expandability to the Mark 1. The headers facing down are designed to fit into a host microcontroller or microcomputer platform such as the [BeagleBone](#), [Arduino](#) and even the [Raspberry Pi](#)! Integrating with these hosts significantly increases the overall system's capabilities. Sorry, using the Mark 1 to expand the functionality of one of these popular computing platforms is outside the scope of this document. There are so many possibilities this topic merits its own set of manuals!

Here is a useful component map of the device:

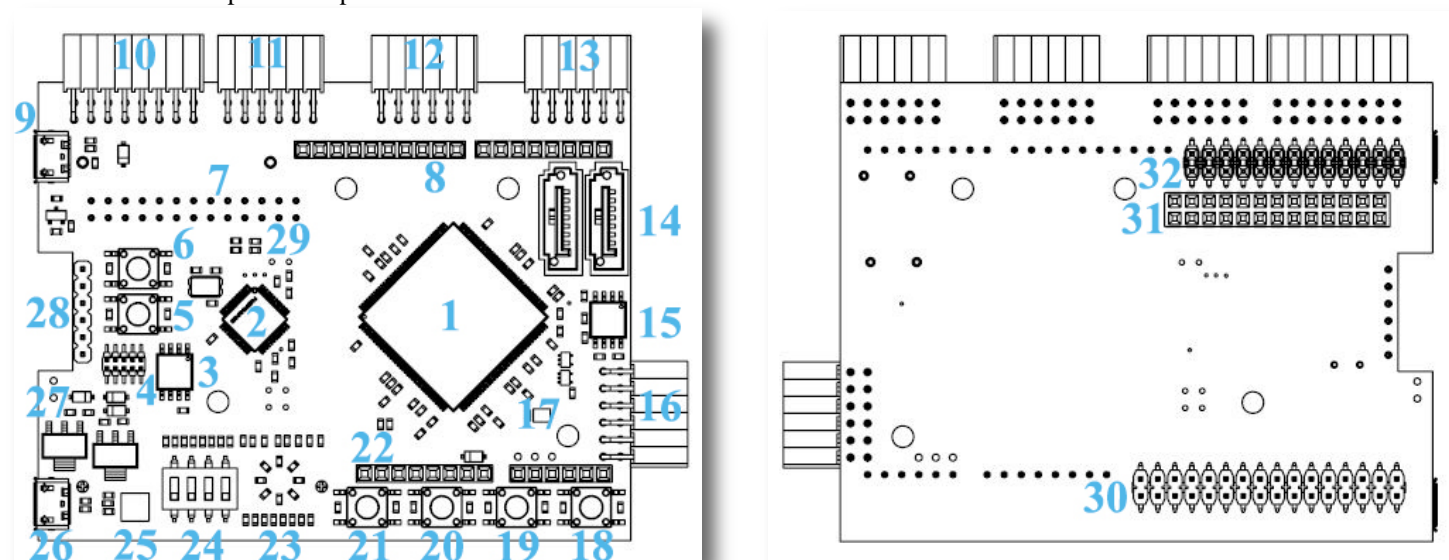


Figure 1 – Mark 1 Top and Bottom Component Map

1. U5 - Xilinx Spartan 6 - FPGA (XC6SLX9-3TQG144C)
2. U9 - NPX Semiconductor - Arm Cortex M3 Microcontroller (LPC1343FBD48)
3. U6 - Micron Technology Inc. - 16Mbit Serial Flash (M25PE16)
4. Spare Serial Wire JTAG Header
5. Push Button PB5
6. Push Button PB6
7. P6 Host Connector
8. P1D Arduino Uno Header
9. J11 Micro USB Connector 2
10. PMOD1 Header
11. PMOD2 Header
12. PMOD3 Header
13. PMOD4 Header
14. SATA Headers 1 and 2
15. U10 - Micron Technology Inc. - 16Mbit Serial Flash (M25PE16)
16. PMOD6 Header

17. U4 - Abracon Corporation - 50MHz Oscillator (ASDMB-50.000MHZ-LC-T)
18. Push Button PB0
19. Push Button PB1
20. Push Button PB2
21. Push Button PB3
22. PIC Arduino Uno Header
23. LEDs - LED0 through LED7
24. Switches - SW0 through SW4
25. U1 - Future Technology Devices International Ltd. - FTDI UART to USB (FT231XQ-R)
26. J1 Micro USB Connector 1
27. Power Regulation Circuitry
28. J7 - JTAG Header
29. LEDs DC17 and DC18 - power and configuration status
30. P28 Header - BeagleBone IO
31. P6 Header - Raspberry Pi IO
32. P29 Header – BeagleBone IO

3.1. Running a Pre-Compiled Design on the Mark 1

The Mark 1 ships with a great “LED counter” demo design that has already been [compiled](#) for you. If you’re interested in getting your hands dirty right away, you can run this program right out of the box! Otherwise, skip down to [Developing Your Own Design](#) to get started making your own FPGA design.

One difficulty with FPGAs is that their program or “configuration” is stored in a “[volatile](#) memory.” After the FPGA loses its power it also loses the program it was running. Some FPGAs can store their configuration in [non-volatile](#) memory in order to restore their program automatically on power up without any support circuitry. However, these devices are normally called [complex programmable logic devices](#) (or CPLDs). CPLDs differ in several other ways from FPGAs and are designed to do different things than FPGAs. Fundamentally both are [programmable logic devices](#).

The Mark 1 has a support microcontroller by NPX Semiconductor on it. This IC is used to configure the FPGA after power up. Using a microcontroller to assist in the configuration of the FPGA is one of the Mark 1’s best features. With this topology, the user can “drag and drop” a program onto the device. The device can then be rebooted by power cycling or pressing the PB5, Reset button. Then, on system reset, the NPX microcontroller’s [firmware](#) will load the program the user downloaded to it, onto the Spartan 6 FPGA. In this way, the NPX microcontroller makes “configuring” the FPGA very easy for the end user. If this topology wasn’t used, the user would need to purchase an extra programmer device to configure the FPGA after power up. This might, for example be a programmer connected to the board’s JTAG header. This procedure is much more tedious and would need to be performed every time the FPGA powers on.

Steps to set the Mark 1’s boot configuration file using the Windows “drag and drop” method:

1. Using a [micro USB to standard USB cable](#), plug the Mark 1 into your [Windows](#) based computer using the J11 mini USB header.

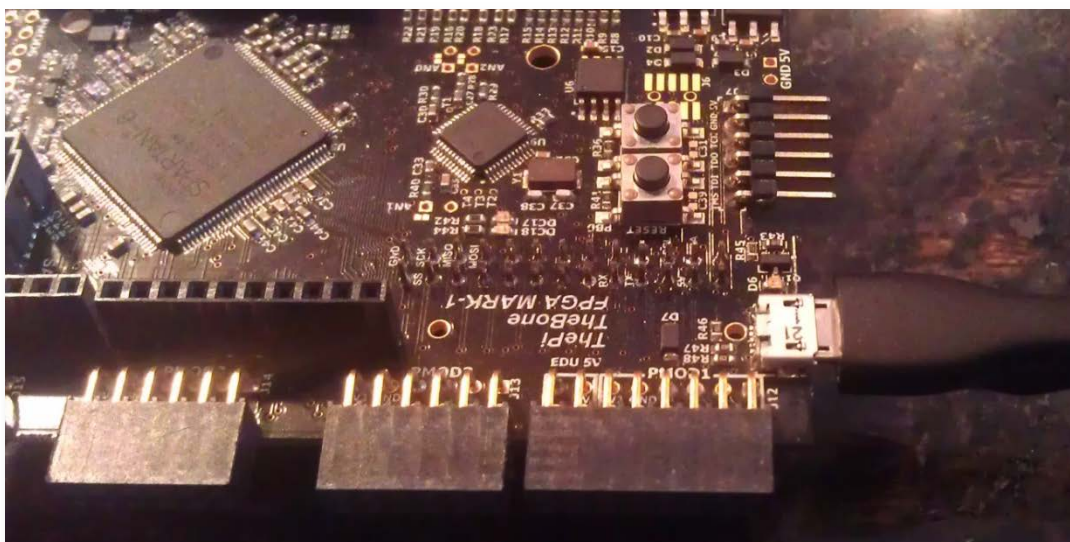


Figure 2 – Micro USB Connection on J11

- The board will come alive and you will see little green LEDs glowing on it. After a few seconds you will see LED DC17 start flashing if the board already has a configuration file setup on it. This means the NPX microcontroller is configuring the FPGA. Once the configuration is done you will see DC17 stop flashing and change to solid green. This means the FPGA is configured and running its program.
- Once the Mark 1 is connected to your computer Windows will try to install the appropriate device driver. This should succeed without any issues. When it does, you will see a new Removable Disk in Windows Explorer as shown in Figure 3.

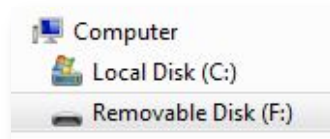


Figure 3 – New Device Appears in Windows Explorer

- On the removable disk you will see pre-compiled programs that come saved on the Mark 1's non-volatile memory.

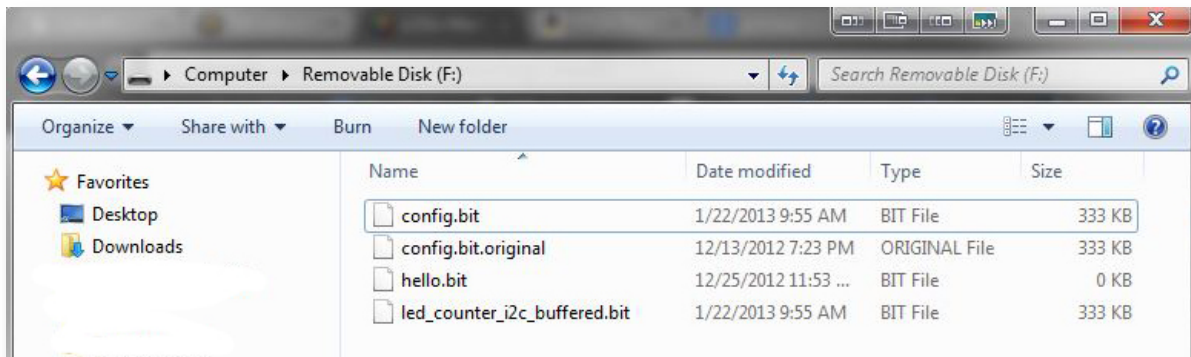


Figure 4 – Files Factory Preloaded Onto the Mark 1 Board as Shown in Windows Explorer

- The file "config.bit" is the file the NPX microcontroller is looking for to load onto the FPGA at boot time. "Config.bit.original" is a backup of the demo program shipped with the Mark 1.
- To make the system load a totally different FPGA configuration on boot up, simply delete the "config.bit" file and replace it with a .bit file of your choosing. Just make sure the file that is used for a replacement is named "config.bit." It's as simple as that. No special programmer hardware needed. Later in this guide we will show you how to make the Xilinx ISE generate a .bit file from your custom design.
- But, for demonstration purposes let's have the FPGA run a more interesting program. After deleting the "config.bit" file that is shipped with the board, use Windows Explorer to make a new copy of "led_counter_i2c_buffered.bit." If you're using Windows 7, highlighting the file and doing a Copy, Paste will generate a copy of the file called "led_counter_i2c_buffered - Copy.bit." Make a copy of the file before renaming it in the interest of preserving this example design for later use.
- Now rename "led_counter_i2c_buffered - Copy.bit." to "config.bit."
- The final step is to reset the board – just push button PB5.

On system reset you will see the NPX microcontroller start configuring the FPGA with the config.bit file you just chose. Once it's done configuring, you will immediately see LEDs 0 through 7 on the edge of the board start dancing wildly. Each LED represents a [bit](#). Because there are 8 LEDs total these LEDs can display 256 unique combinations. What they are actually doing is a very rapid [binary counting](#) sequence from 0 to 255 in about three seconds. When the sequence finishes it just starts over. Note that the [least significant bit](#) is LED 0 and the [most significant bit](#) is LED 7.

This demo is a very simple example of what's possible on this FPGA platform. With a little more learning and [HDL](#) code development, you can be on your way to blinking lights in your own sequence in no time! ...Or reading MP3s off your SATA connected, terabyte hard drive while playing the audio and displaying a visualizer! ...For example.

4. Developing Your Own Design

Now that you have a bit of FPGA background we will move on to the hands-on part of this instruction. In the following sections you will learn what is required to actually design and build your own FPGA configuration and then run it on the hardware. The example design given below is rather simple, but seeing the major FPGA software development concepts and workflows that are exposed through this tutorial will be instrumental in understanding the big picture.

4.1. Setup Your Development Environment

Software development for the Spartan 6 target is done in Xilinx's [ISE](#) development environment (ISE loosely means Integrated Software Environment). As of this writing, Xilinx is on ISE version 14.5. [Go here to start downloading it.](#) If you have a slow or unreliable connection you might want to download the file in parts. If you have a fast broadband connection, shoot the moon and go for the full DVD single file download – the full download can be found about half way down the page linked to above and it's 7.79GB – so get started. (Also note you want to install the Xilinx ISE for this tutorial, **not** Vivado which is Xilinx's SoC design tool.)

When the file is finally done downloading you will need to extract its contents to your hard drive as your download comes in a .tar archive format (That is, if you've downloaded the entire DVD in one file. Otherwise, follow the instruction on the website for how to reassemble a multi-part download). If you've never used .tar archives there is a pleasant little open source program you should have a look at, [7Zip](#). It's archiving software you can use to extract the files. Once you've extracted the contents of the .tar file you will see "xsetup.exe" under the extracted files' root folder. Run this installer program and follow the on screen instructions. A "typical" installation will suffice. This rather long document is the official [Xilinx Install Guide](#). Consult it if you have problems with the ISE installation.

When the installation completes, open the Xilinx ISE (you will most likely find it in your Start menu's All Programs list under "Xilinx Design Tools > ISE Design Suite 14.5 > ISE Design Tools > 32-bit Project Navigator"). The ISE download comes with the "full" version of the software. However, your computer will not have licenses to enable the various features Xilinx offers. Therefore, you need to get your own license file before you continuing.

Go to the [Xilinx website](#) and create a user account. Yes, needing a user account might seem like overkill if you're a beginner, but what you will find is your user account gives you access to many useful design resources. With a Xilinx user account you can watch training videos, use the forum, get updates and add-on software, and get license files – it's totally worth it.

Xilinx offers many different licensing tiers. We will be using the free "WebPack" license. This enables enough software features to get us started. The WebPack allows your software to compile and you can use most of the basic Xilinx development tools.

In the ISE, navigate to the "Help" toolbar on the top of the screen and choose "Manage License." This opens the Xilinx License Configuration Manager. Under the "Acquire License" tab, select the "Get Free ISE WebPack License" radio button and click Next:

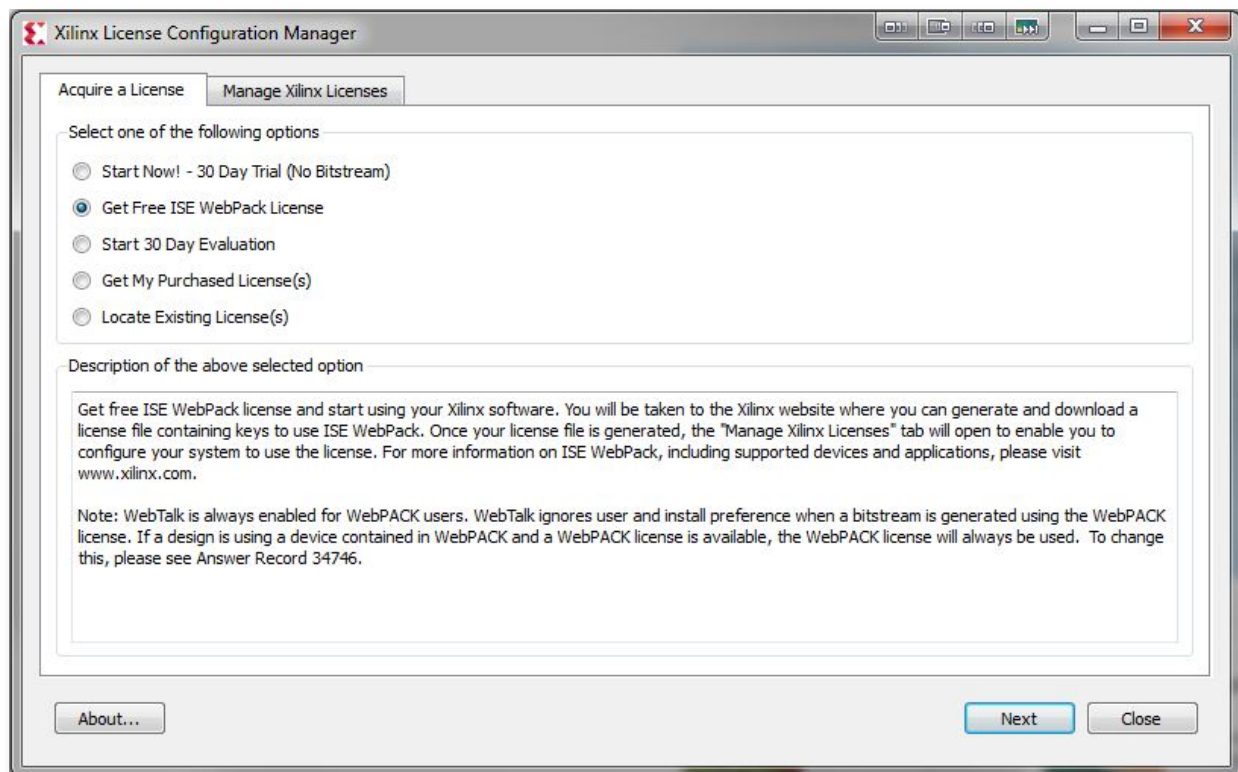


Figure 5 – Xilinx License Configuration Manager

The software will gather some unique information about your machine and then give you the option to "Connect Now." Click it:

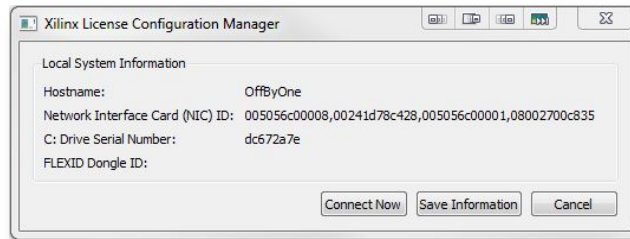


Figure 6 – Unique Computer Info Tied to WebPack License

At this point the software will open your web browser and bring you to the Xilinx site. It will ask you to login with your user account. Do it and follow the on screen instructions. Once you complete the on screen steps Xilinx will email you a license file with the file extension .lic. Save this .lic attachment somewhere safe. The ISE installation directory would suffice. The email also contains instructions on how to install the license.

Essentially all you need to do is open the Xilinx License Configuration Manager again, click the Manage Xilinx Licenses tab, and click Copy License. This will open a dialog that lets you find and select the .lic license file you downloaded from your email. Select it and click Ok. Under the Manage Xilinx Licenses tab the table should now be populated with details about what features of the software are enabled by your WebPack license. Congratulations, your software is setup and ready to go!

4.2. Create Your First Project

In this tutorial we will be using the Mark 1 hardware to create a working Verilog HDL design. We will keep the physical goals simple in order to demonstrate the basics. In the following example, the Mark 1's buttons will be used to turn on some of its LEDs. Thrilling! Absolutely yes, but it's an invaluable exercise none the less. Let's begin with creating our "Project" file in the ISE Project Navigator.

In the Xilinx ISE, like many other engineering programs, users create "Projects" to save all aspects of their design. FPGA designs often consist of many files of many different file types. The Project encapsulates everything and serves as a means to easily manage all the FPGA's design files. (ISE Project files contain references to many support files like the source code files and configuration files. They have a .xise file type.).

To create a project for this tutorial, open the Xilinx ISE Project Navigator. Under the File menu, choose New Project... you should see the New Project Wizard open. Choose some file paths and a name for your project (it is recommended each of your projects be put in its own folder to contain all the design files in one place):

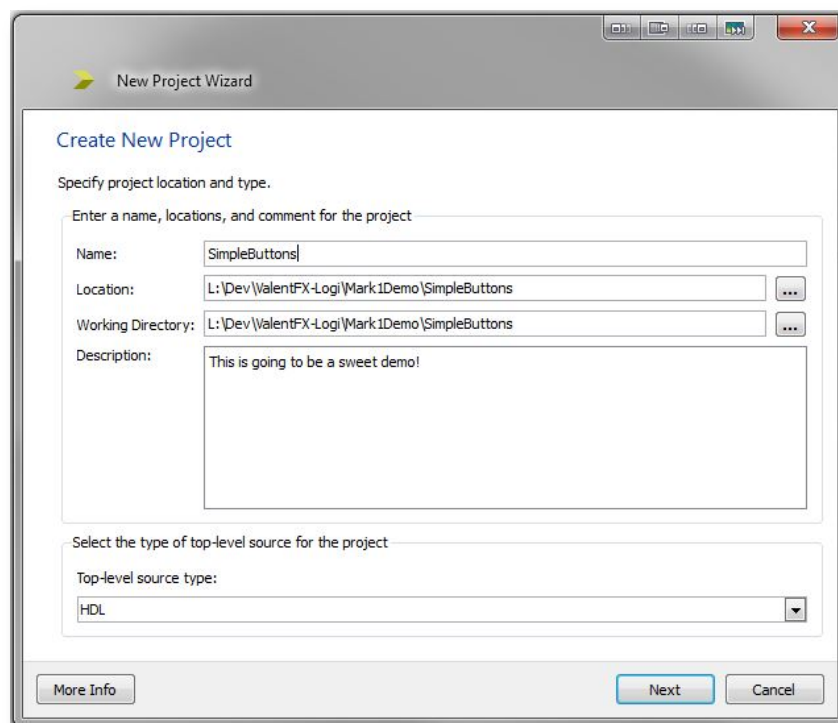
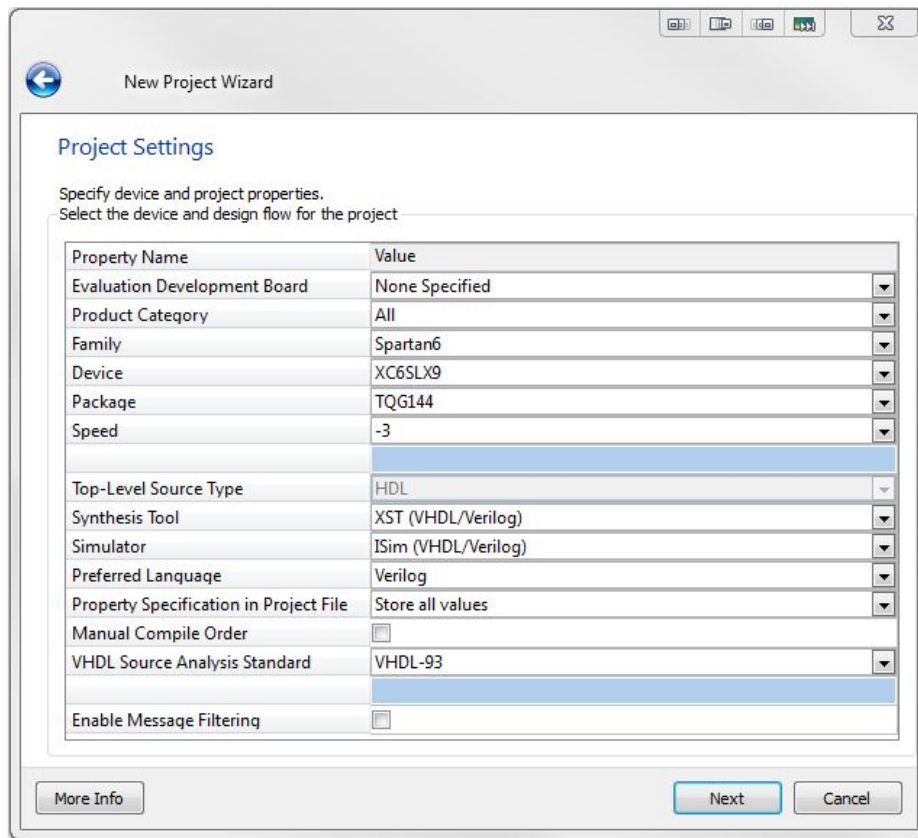


Figure 7 – The New Project Wizard

After clicking next you will find the project's settings page. You can use the settings shown below for the Mark 1 board. These settings can be changed at any time later on. This wizard page is designed to let you choose important software environment settings from lists of possibilities.

For example, it is on this dialog where you specify what chip you're designing for, the speed grade, and physical package. You also set which software [toolchain](#) and HDL language you prefer. We'll touch on what the common tools are and why they are used shortly.



Property Name	Value
Evaluation Development Board	None Specified
Product Category	All
Family	Spartan6
Device	XC6SLX9
Package	TQG144
Speed	-3
Top-Level Source Type	HDL
Synthesis Tool	XST (VHDL/Verilog)
Simulator	ISim (VHDL/Verilog)
Preferred Language	Verilog
Property Specification in Project File	Store all values
Manual Compile Order	<input type="checkbox"/>
VHDL Source Analysis Standard	VHDL-93
Enable Message Filtering	<input type="checkbox"/>

Figure 8 – Project Settings

The last page is a summary of your chosen settings displayed in plain text. Click Finish and you will be brought into the ISE Project Navigator development environment. You are now ready to add content to your design.

4.3. Add Some Logic to Your Project

Take some time to look around the software. The Project Navigator has a clean looking layout and there can be an enormous density of information displayed at once. Windows users will be familiar with the standard set of menu items located across the top of the screen; File, Edit, View, Project, Source, Process, Tools, Window, Layout and Help all contain items that fit their respective categories – as is tradition. The rearrangeable buttons across the top are concise and self-explanatory as well.

In the default workspace view, the top left pane shows the Project's "Hierarchy." This tree view shows the relationship between various HDL modules in the design. You can use this pane to add or remove HDL files from the project.

FPGA are often designed in a tree structure of "modules." Modules are blocks of logic that [encapsulate](#) some discrete, unique part of a design. The blue link describes encapsulation in the context of object-oriented programming but really the term is effective in a broader sense; HDL modules are can be thought of as "layers" that encapsulate the logic of some abstract but compartmentalized piece of circuitry. The "top level" module is the "root" of the tree of HDL modules. Although this design will not provide an example of how to add sub modules to the tree hierarchy, be aware that this is easily done and very common.

Let's start by adding your design's top level HDL file.

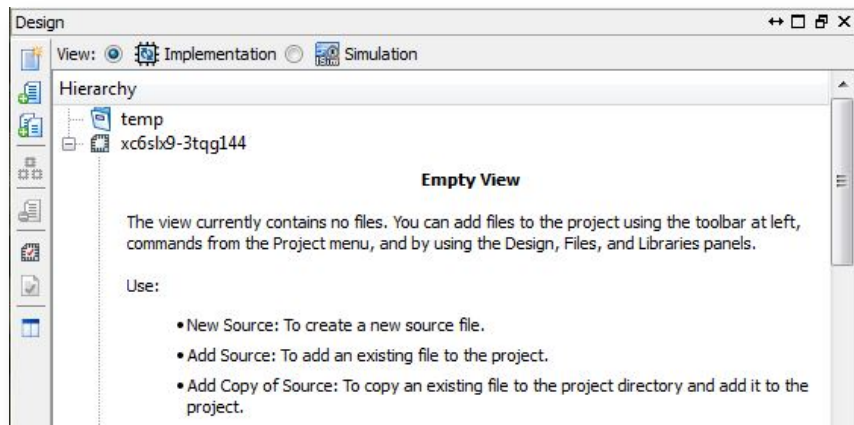


Figure 9 – An Empty Design in the Hierarchy View

To add a top level HDL file, right click the target chip in the Hierarchy view (denoted by the model, xc6slx9...) and choose New Source. This will bring up a view that allows you to add a design file to your project. There are many different types of files you can choose here but for this instruction we will have you load a new “Verilog Module.” Give it a name and click Next.

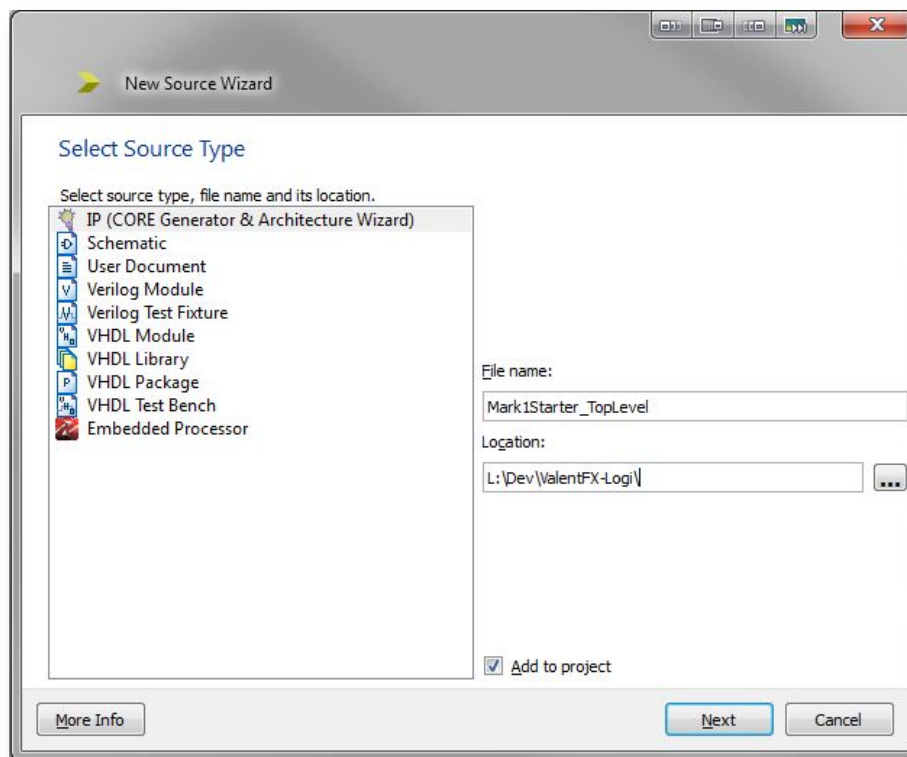


Figure 10 – New Source Wizard

On clicking next you are presented with a GUI that lets you define the module’s input and outputs. It’s convenient to think of Verilog HDL modules as chips on a circuit board. Typically a chip has a number of pins that are either inputs or outputs. This GUI lets the user specify names for the module’s IO, then, when the Verilog HDL file is generated and added to the project it will contain definitions for these IOs. Setup your Verilog module like the picture below. Note that you don’t need to specify these IO points as being “buses” or what their most or least significant bit is – all of these IO points are just one bit (or wire - depending on how you view the world).

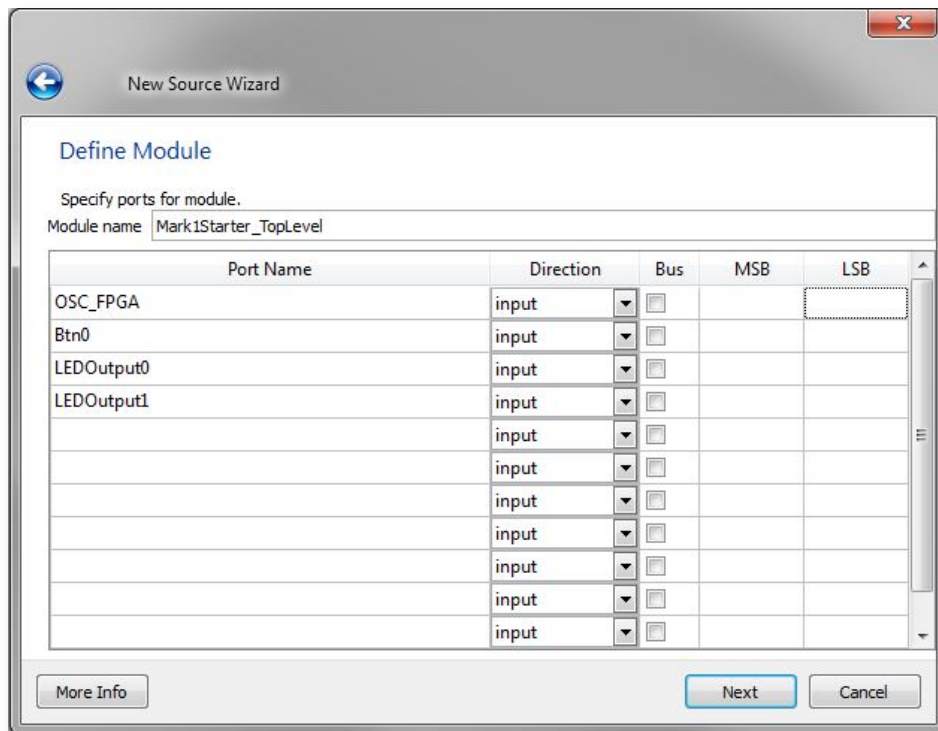


Figure 11 – A Top-Level Verilog Module’s IO Definition

In the Hierarchy view you will see a new Verilog source file called “Mark1Starter_TopLevel.v.” “.v” is the file extension for Verilog files. Double click it and its contents will be shown in the text editor on the pane to the right. Here is what you should see:

```

1  `timescale 1ns / 1ps
2  ///////////////////////////////////////////////////////////////////
3  // Company:
4  // Engineer:
5  //
6  // Create Date:    19:05:27 05/5/2013
7  // Design Name:
8  // Module Name:    Mark1Starter_TopLevel
9  // Project Name:
10 // Target Devices:
11 // Tool versions:
12 // Description:
13 //
14 // Dependencies:
15 //
16 // Revision:
17 // Revision 0.01 - File Created
18 // Additional Comments:
19 //
20 ///////////////////////////////////////////////////////////////////
21 module Mark1Starter_TopLevel(
22     input OSC_FPGA,
23     input Btn0,
24     output LEDOutput0,
25     output LEDOutput1,
26 );

```

Figure 12 – An Auto Generated Verilog Module

You will notice that the Verilog syntax is highlighted. Things marked in green are comments, blue are Verilog language keywords and the pink at the top used to denote the module’s timing information for simulating the design (we’re not going to touch on design simulation).

At this point you have your top-level Verilog module defined and all you need to do is add logic to it. The module takes in two bits and can output two bits. One could even think of these as wires coming in and going out of our module. We will use the “OSC_FPGA” input bit to define a system clock signal. This signal will be used to turn over the logic on a specific time base.

The “Btn0” input represents the wire coming from PushButton0 on the PCB. Similarly, “LEDOOutput0” and “LEDOOutput1” represent the wires going out to LED0 and LED1 on the PCB.

What we’re going to do with these signals is ground breaking... The goal is when the button is not pushed, LED0 will be illuminated and LED1 will not be illuminated. Then just when you least expect it, Btn0 will be pushed and the LEDs will flip-flop states; LED0 will become dark and LED1 will illuminate. Like I said, ground breaking stuff!

Although this truly novel goal can be accomplished without a clock signal we will implement the solution using a system clock. Add a few lines of code to your design as shown below:

```
21 module Mark1Starter_TopLevel(  
22     input OSC_FPGA,  
23     input Btn0,  
24     output LEDOutput0,  
25     output LEDOutput1  
26 );  
27  
28 //A one bit register (a place to store a bit)  
29 reg LED_reg;  
30  
31 //An "Always Block" (these are very common)  
32 always @(posedge OSC_FPGA)  
33 begin  
34     //Do this logic on every rising edge of the clock signal OSC_FPGA  
35     LED_reg = Btn0;  
36 end  
37  
38 //An assignment (think permanent wire connection - also very common)  
39 assign LEDOutput0 = LED_reg;  
40 //An assignment to LEDOutput1 of the inverse of LED_reg  
41 assign LEDOutput1 = !LED_reg;  
42  
43 endmodule  
44
```

Figure 13 – Verilog HDL Code for Example Design

4.4. So What Does This Simple Program Do?

The goal of this document is to get the user on their feet, not to teach Verilog HDL sorry... If you are really interested in learning Verilog see the section at the end called [Where To Go From Here](#). That said here is a quick description of what’s going on.

In the module’s definition we have two inputs and two outputs. For now, assume the Btn0 input is externally wired to the user PushButton0 on the PCB and OSC_FPGA is connected to our clock source – these are the inputs to the module. Also assume LEDOutput0 and LEDOutput1 are connected to LED0 and LED1 on the bank of LEDs – these are the outputs. These external connections to hardware IO are defined in the design’s “user constraints” file. Constraining a design is described below in the section [Constraining the Design](#).

Just below the module’s definition (line 29) we’ve defined a “register” that is one bit “wide” called LED_reg (registers like this can be defined as multi-bit registers if desired). This register can store the state of one bit of data and it is used as such.

After the register definition there is an “Always Block” (line 32). Verilog structures like this Always Block are a common way to define synchronous clocked circuitry. What this block describes is on every rising edge of the input clock signal, OSC_FPGA, the status of the Btn0 bit will be set to the one bit register LED_reg. OSC_FPGA is oscillating at 50MHz so the logic between the Begin and End in this Always Block is being “executed” fifty million times per second.

On the bottom we have two “Assign” statements. The simplest way to describe Assign statements is to think of them as wires being connected together permanently. The logic is not dependent on a clock. As soon as LED_reg’s value changes because of the Always Block above, the value immediately propagates to the output wires LEDOutput0 and LEDOutput1. Notice that LEDOutput1 is getting assigned the inverse state of LED_reg. The exclamation point operator denotes a logical NOT gate (as in many other computer languages).

Remember, Verilog is a hardware description language. The logic in this module can be imagined as an actual circuit that does exactly what is described.

When execution starts, LED0 will be on and LED1 will be off. This might be counter intuitive but there are two important things that cause this initial condition. First, the user PushButton0 input, Btn0, is electrically connected as negative logic (aka “[active low](#)” – when the button is pressed the wire changes to false, or zero volts. So under normal circumstances, when the button is not pressed this

IO point is true). And second, the LEDs on the PCB are electrically connected in a positive logic manner (or “[active high](#)” – when the LEDOutput0 changes to true, a positive voltage is put on the output pin and current will flow through the LED and illuminate it).

For these reasons, the initial condition for this circuit has LED0 on and LED1 off when PushButton0 is not pressed. When the module’s input wire, Btn0, changes from true to false because the user pressed PushButton0 on the PCB, the logic shown above will assign this false input to our LED_reg register on the rising edge of the next OSC_FPGA clock signal.

Finally, because the module logic has used an Assign statement to assign the value of LED_reg to the LEDOutput0 wire and its inverse to LEDOutput1, you will then see LED0 go dark and LED1 illuminate on the PCB when PushButton0 is pressed.

For more details on how the surrounding hardware is connected to the FPGA consult the [Mark 1 electrical schematic](#). For example, below is the electrical drawing that details the FPGA’s outputs to the bank of LEDs (found on page 5 of the schematic). Clearly, when the L7 output changes to a logic high level, current will flow through the LED0 to Ground and the LED will illuminate.

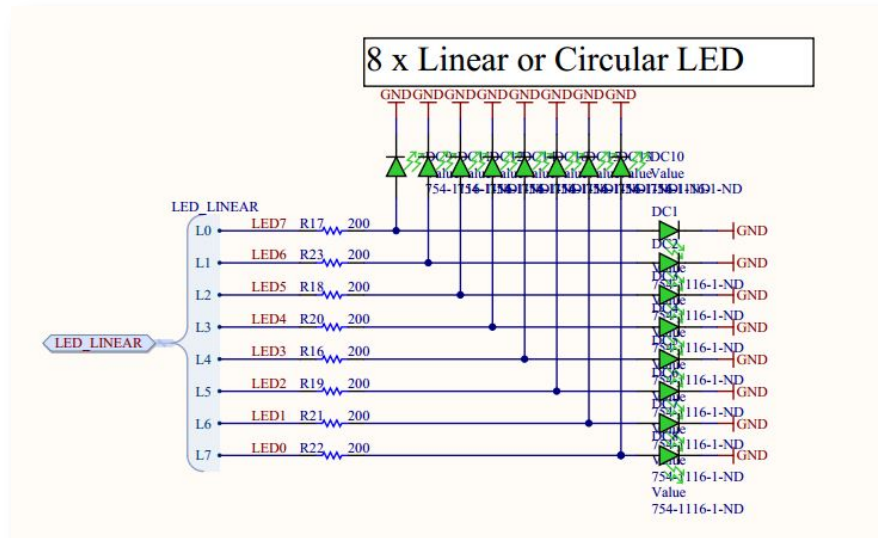


Figure 14 – Electrical Drawing of FPGA’s Outputs to Bank of LEDs

To illustrate the inverting nature of our user PushButton0 the following is a drawing of the input circuit (also found on page 5 of the electrical schematic). You can see that the FPGA’s input, PB0, has a 4.7kOhm “pull-up” resistor attached to it. This means the logic level on this wire is normally connected to 3.3v which is a logical true. Only when the user presses the button does this input wire’s voltage level fall to 0v, or false, because the button connects the wire to Ground.

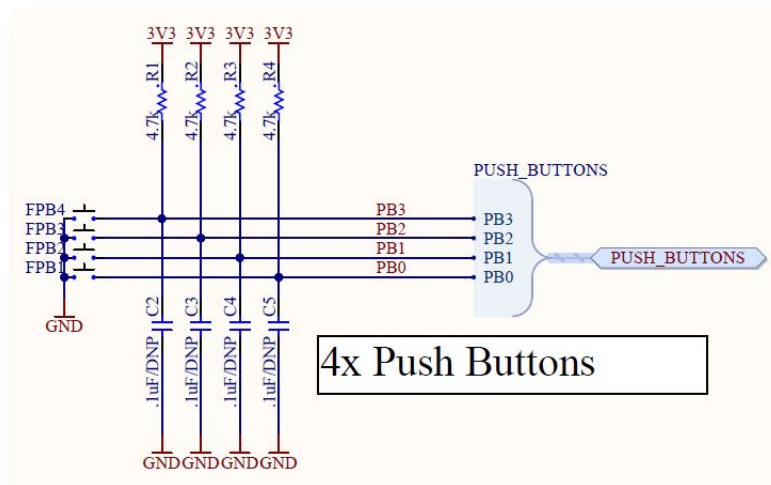


Figure 15 – Electrical Schematic of Active Low Push Button Inputs to FPGA

4.5. Constraining the Design

In the previous section we described a simple module that turns some LEDs on and off based on the state of an input push button. The Verilog that describes the circuit is simple. It was entirely defined in one top-level module with two inputs and two outputs. What we didn’t describe is how this simple design links the module’s inputs and outputs to physical IO points on the FPGA.

This is where the “Implementation Constrains File” comes in. These files have a .ucf file extension and describe the design’s “user constraints.” Design constrains are a set of rules the compilation process needs to take into account when building the design’s binary output file. This “.bit” file is output by the compilation process and is the file that gets downloaded and run on the FPGA as described in the section called [Running a Pre-Compiled Design on the Mark 1](#).

Some examples of types of things that can be constrained in an FPGA design are:

- Timing constraints
- Logical constraints
- Physical constraints
- Mapping and Routing constraints (or directives)
- Physical pin assignment

User constraint files can vary dramatically in complexity and detail. The topic is very vast and discussing it in detail is outside the scope of this document.

So there is a huge amount of information to know surrounding how to constrain designs, but fortunately for us, our design only needs to constrain a handful of items to work properly (this design is so simple we’re also not going to worry about enforcing any timing constraints either). All that we need to do is to define what hardware pins our top-level Verilog HDL module’s inputs and outputs link up to. We also give some details about the design’s clock input, OSC_FPGA.

Start by adding a constraints file to the project. Right click anywhere in the project Hierarchy view and choose New Source. This time, select Implementation Constraints File, give it a name and choose Next:

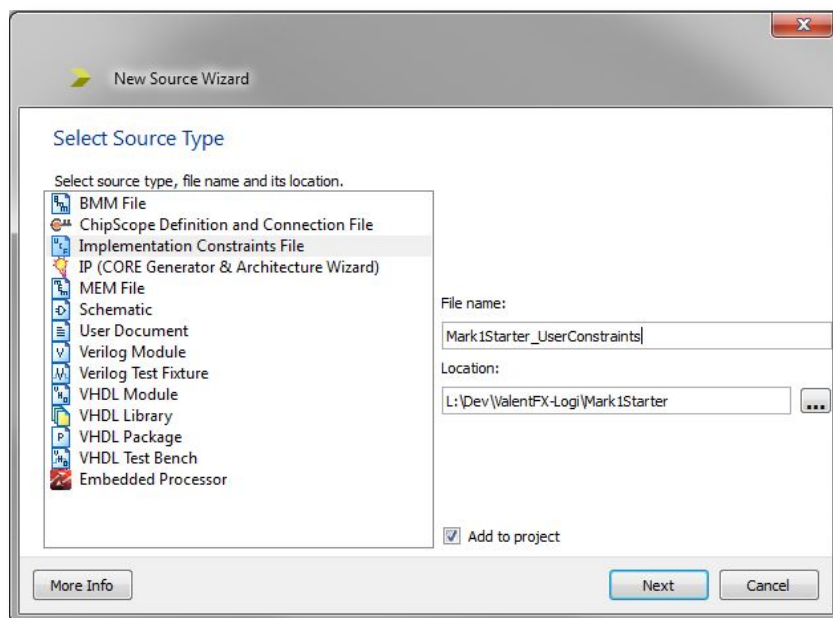


Figure 16 – Add a new constraints file to the design

A Summary window will appear. Click Finnish. Now in your project Hierarchy view you will see a new “.ucf” file. Double click it. The Text Editor view on the right window pane will show your file is totally empty. Add the following code to it then we will discuss what each piece means:

```

1  #Some simple constraints for the Mark1Starter Demo
2
3  # Grouping Constraints
4  NET OSC_FPGA TNM_NET = clk50_grp;
5
6  # Clock Period Constraints
7  TIMESPEC TS_PER_CLK50 = PERIOD "clk50_grp" 20.0 ns;
8
9  # Pin assignments
10 NET LEDOutput0 LOC = "P41";      # IO_L64P_D8_2
11 NET LEDOutput1 LOC = "P43";      # IO_L62N_D6_2
12 NET Btn0 LOC = "P58";           # IO_L14P_D11_2
13 NET OSC_FPGA LOC = "P55";       # IO_L30N_GCLK0_USERCCLK_2
14

```

Figure 17 – Implementation constraints file

As is tradition, the green denotes comments and the language syntax are highlighted appropriately. Thank goodness for modern IDE's... and remember to end each statement with a semicolon! The 4th line defines a "net" called OSC_FPGA and its TNM_NET parameter gets the name clk50_grp. TNM_NET is a keyword used for defining a design's clock signals. Again, there are many keywords that can be used in an infinite number of ways in these constraints files. Don't worry about the details of this line until you take the time to actually study more advanced FPGA principles such as [Timing Closure](#) or consult a recent copy of the official Xilinx [Constraints Guide](#).

After the OSC_FPGA net declaration is a new TIMESPEC definition (line 7). This constraint essentially calls out how fast our OSC_FPGA clock signal is. A 20 nanosecond clock period means the clock is running at 50MHz. You're free to research exactly what this keyword means but for our purposes, you can regard this line as "magic."

Lines 10 through 13 define some new nets and use the LOC keyword to assign them to the FPGA's physical pins. This is how we link our top-level Verilog module's inputs and outputs to physical pins on the IC. The names of these nets must be identical to the names of your module's input and output ports! The pin number can be found by referencing the electrical schematic; the following is taken from page 7:

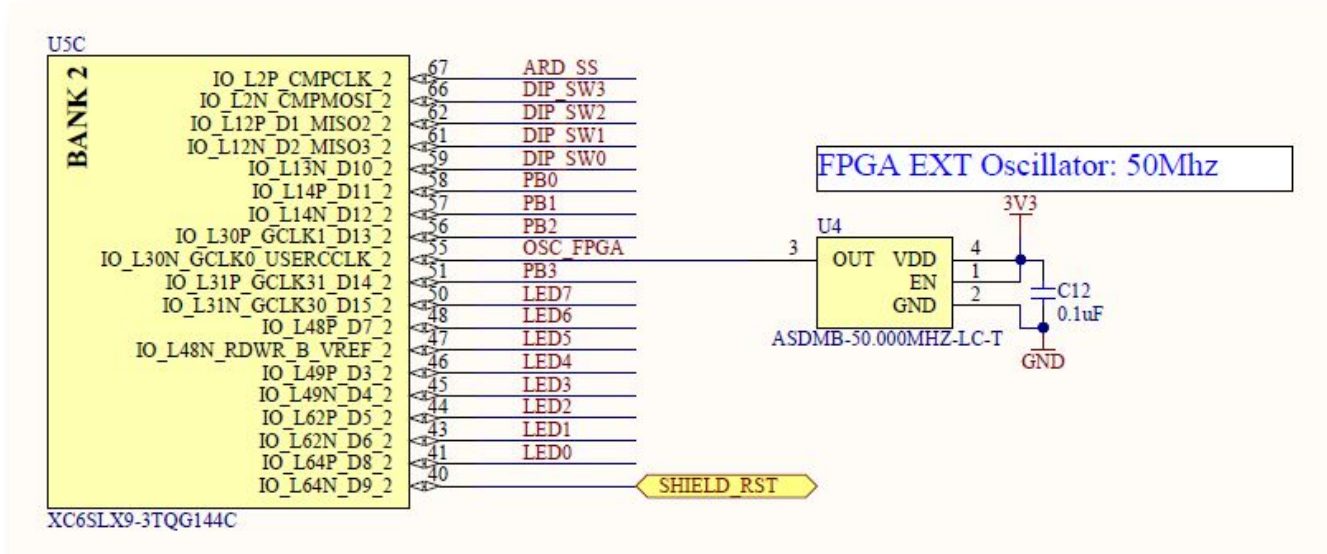


Figure 18– FPGA Bank 2 Electrical Drawing

Here you can see all the connections to Bank 2 of our FPGA. You can see wires connecting the FPGA to all 7 LEDs on the board. Note that the LED wires are connected to the pin number called out above. Furthermore, you can see the pins' official name next to the input. These match what's written in the comments of the constraints file. This is common practice.

For example our design uses LED0. This LED is connected to pin 41 and that pin's name is IO_L64P_D8_2. In our constraints file we can see that we've called out the net LEDOutput0 to land on "P41" using the LOC keyword. In the above schematic you can also see the FPGA's clock input on pin 55 and the oscillator IC it's connected to.

4.6. Build Your Project

We're almost done! Phew! All that's left is to compile the design and then we're ready to run. If you've followed the directions above carefully this step should be simple!

The final step is for the Xilinx software toolchain to take all of your design files and compile them into one single "bit-stream" file, or "binary" file as it's often called. With a file type of .bit, this is the file that gets downloaded to the FPGA and run. Remember, at power up, an FPGA doesn't have a program loaded onto it. The vast arrays of programmable logic blocks in an FPGA need to receive a configuration before the chip does anything useful. Once configured, the FPGA starts executing your program.

There are a handful of software build steps that need to be complete for the toolchain to output a bit-stream file. Novels have been written about each topic but here's a rapid summary:

1. Synthesize – This step is where the Xilinx XST tool converts HDL logic into a gate-level netlist. This low level netlist is represented in terms of the UNISIM component library. If your HDL code has syntax errors this step will not complete. Fortunately, the Output window pane at the bottom of the ISE will tell you where the error is.
2. Implementation – This step converts the gate-level netlist into a placed and routed design that fits on the chip selected. This is composed of three discrete build steps.

- a. Translate – The NGDBUILD software tool is used to translate the netlist from using the UNISIM library to the SIMPRIM library.
 - b. Map – the MAP software tool is used to take the SIMPRIM primitives and decide how the chip’s physical resources (flip-flops, BRAMs, Multipliers, LUTs etc.) will be used.
 - c. Place and route – the PAR software program runs a lot of computation to layout where all the chips resources will be used and how the design components get placed, routed and interconnected.
3. Generate Programming File – The final step takes the output from the previous steps and puts them together into a single binary that can be used to program the device.

The ISE Project Navigator has an entire window pane dedicated to this process. This is because when designs get very large these discrete steps can take hours! An engineer would not like to have to re-run every step of the compilation process if it’s not necessary.

The following view can be used to explicitly run individual steps of the build process and see the status of what’s currently running or even what’s failed (note in order to see the following view you must have the Mark1Starter_TopLevel.v file selected in the Hierarchy view):

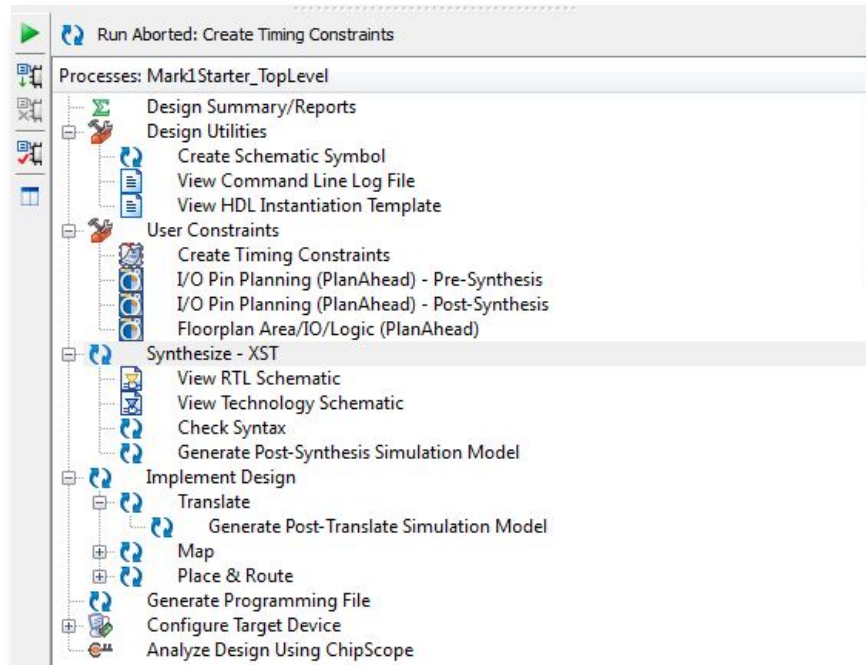


Figure 19 – The Process View

Simply click the little green play button in the top left corner to compile the whole design. On a modern computer this should take less than 2 minutes to run for this project. If the process completes without any errors you will get green check boxes next to the major steps in the compilation process:

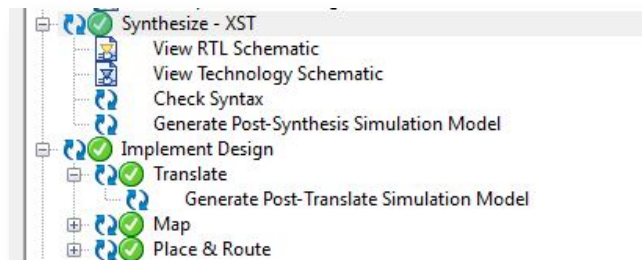


Figure 20 – A Successful Build

Also you will note the Console view pane on the bottom of the ISE will show output like the following:

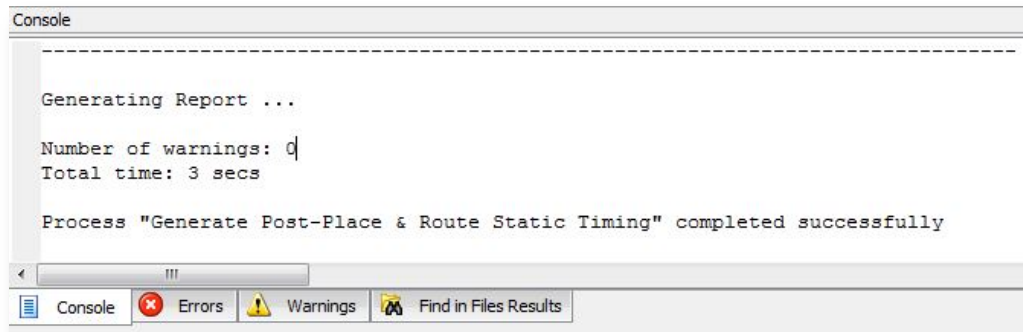


Figure 21 – Console Output at the End of a Successful Build

4.6.1. Errors!

Chances are you're going to make a mistake at some point along the way. If not in this tutorial, someday, you will make a mistake and get a compiler error, sorry. In this case one of your build steps will have a red X next to it. The X isn't entirely helpful to a beginner. It does tell you which build step failed and to the trained developer this can greatly narrow the scope of what's gone wrong. More often though you will immediately query the error log to find out what's going on.

For example, if you try to recompile your design with an extra comma in your module definition (immediately after LEDOutput1 and before then module definition's end parentheses...) the error tab yields this relatively clear message:

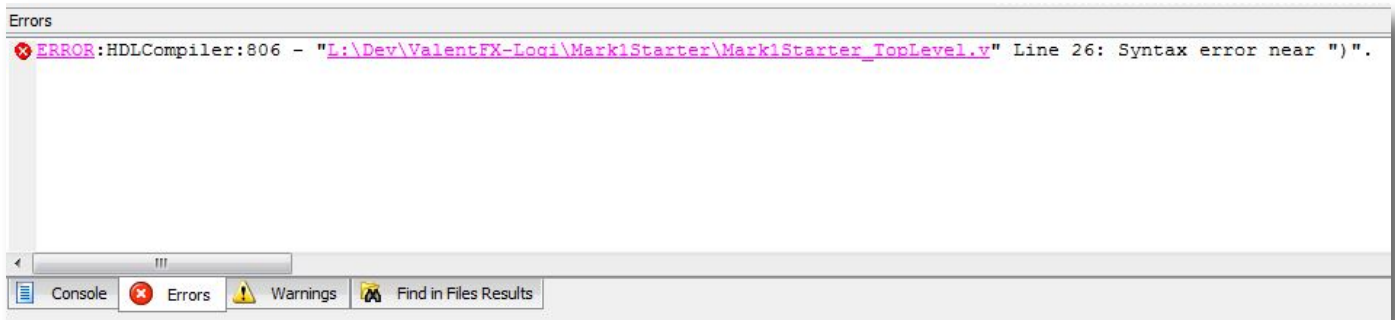


Figure 22 – Syntax Error Found During Synthesis

The problem is indeed on line 26, this is an easy one to find and fix if you know Verilog.

If you get errors, don't fret. This is normal. It happens all the time. Read the error message carefully and try to understand what the compiler isn't happy about. Non-developers tend to forget this but error messages are designed to point you to the problem so you can resolve it! Imagine a world without error messages!

You will find that when you're new to a programming language, working through compiler errors teaches you about what's allowed and what's not allowed slowly, but effectively. However, in general, it's advisable to save yourself some headache, buy a beginners book on the language and power through it before taking on any serious projects.

5. Run Your Project

If you've gotten this far it means you've created your very own FPGA design in the Xilinx ISE. You've added a Verilog HDL module to the design, constrained it, compiled it and now you're ready to run it!

But before you do, you need to generate the programming "binary" file that gets downloaded to the target. Simply double click the build step called "Generate Programming File" in the Process view (it's directly under Place & Route).

When this finishes successfully, open Windows Explorer and navigate to the folder where you've saved your project files. In this folder you will see a .bit file with the same name as your top-level module, "Mark1Starter_TopLevel.bit" in this tutorial's case.

This bit file can be used to configure the FPGA as described above in the section [Running a Pre-Compiled Design on the Mark 1](#).

Essentially you plug your Mark 1 into a USB port on your computer. When the Mark 1 appears in the Windows Explorer as a removable disk, copy and paste the Mark1Starter_TopLevel.bit file onto the removable disk. Once it's on the removable disk, change the file's name to "config.bit."

Now power cycle your Mark 1 and see, once the FPGA is configured that, YAY!!!! LED0 is on!!!! AND when you press PushButton0, LED0 turns off and LED1 turns on! Wow super cool!

6. Where to Go From Here

There are many places you can go from here. You've successfully programmed an FPGA and now the sky is the limit. Have a look over the following sections to see what else is possible with the Mark 1 platform.

6.1. Integrating the Mark 1 with a Host

The Mark 1 was designed to be mounted on a number of host circuit boards such as the Beaglebone, the Raspberry Pi, and the Arduino Uno.

When integrated with these powerful microcomputers and microcontrollers, the Mark 1 platform can do some truly amazing things. Combining the signal routing and interfacing capabilities of the Mark 1 with a high speed processor allows a design to do many more things than either component can do on its own.

Here's a short list of open source projects where a computing platform has been integrated with the Mark 1:

- **[Bitcoin Miner](#)** – An FPGA based Bitcoin miner design for the Mark 1 and Beaglebone
 - <http://valentfx.com/logi-blog/item/fpga-logi-family-bitcoin-mining-application>
- **Autonomous Vehicle Platform** – A design to drive a car through a course. Integrates sensors and the Raspberry Pi
 - <http://valentfx.com/logi-blog/item/logi-bot-autonomous-vehicle-project-for-logi-boards>
- **Image Processing Application** – Implementation of a [Sobel Filter](#) for the Mark 1 and Beaglebone
 - <http://valentfx.com/logi-blog/item/logi-guide-image-processing-sobel-filter-demo>
- **Camera Interface Board** – A PMOD camera interface board
 - <http://valentfx.com/logi-blog/item/logi-camera-pmod-pcb>

As you can see, clearly the Mark 1's flexibility and power is highlighted when the device has a host platform. To be sure, there will be many more projects like the above to come. If you are a more advanced user you will likely be using a host platform in your design already. ValentF(x) has plans to release an official integration guide with source code for each of these popular microcomputer platforms. The data link will likely be SPI, GPMC or I2C.

Another advantage integrating the Mark 1 with a microcomputer has is beginners can then see examples of writing software in languages like C and C++ along with their HDL development. Furthermore, for anyone working in the electronics or software industries, having a working knowledge of Linux is certainly worthwhile as well. And these host platforms provide exposure to embedded Linux! The Mark 1 coupled with a host, is truly great way to study Linux software development and computer science in general.

6.2. Integrate a PMod Device

The PMOD headers on the side of the Mark 1 allow for easy connectivity to “caned” electronics modules. You can add things like GPS, Audio Amplifiers, OLED displays, Wifi, Networking, RS232, DACs, ADCs Accelerometers, Motor Drivers etc. to your design!

Have a look through all the PMOD possibilities at the [Diligent site](#).

6.3. Read Pong P. Chu's Book

There's a great intro book by Pong P. Chu that you should read if you want to develop a sound understanding of the Verilog or VHDL languages. ValentF(X) and open source supporters are porting a number of the examples from this book so they can be run right on the Mark 1 platform.

7. Conclusion

I hope you were able to work through this tutorial at a reasonable pace. I also hope the detail was such that you could grasp the major topics surrounding the FPGA development workflow without too much headache. This document will certainly be revised as this platform evolves. Also stay tuned for a Beaglebone or Raspberry Pi integration guide. Feel free to contact me with questions, comments or corrections. Good luck and have fun exploring the world of FPGA design!