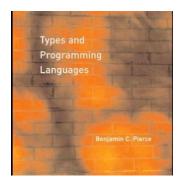
References and Exceptions

CS 565 Lecture 14



References



In most languages, variables are mutable:

- it serves as a name for a location
- the contents of the location can be overwritten, and still be referred to by the same name

In ML, variables only name values:

- bindings are immutable
- introduce a new class of values called references.
- A variable bound to mutable location will have type ref τ

Basic Operations



Create a reference:

- ref s: returns a reference to a location that contains the value denoted by s.
- If s has type τ, then ref s : τ ref

Dereference:

- !r: returns the contents of the location referenced by r
- If r has type τ ref, then !r : τ

Assignment:

- r := s: changes the contents of the location referenced by r to hold the value denoted by s.
- If r has type τ ref, and s has type τ , then r := s has value unit of type Unit.
- No explicit deallocation operation.

References and Stores



Distinction between a reference and the location pointed to by that reference:

- r = s: binds a reference to the location pointed to by r to s.
- Thus,

r and s are aliases for the same location





Implement implicit communication channels:

```
c = ref 0

incc = \lambda x:Unit . (c:=succ(!c); !c)

decc = \lambda x:Unit . (c:=pred(!c); !c)

incc unit \rightarrow 1

decc unit \rightarrow 0
```

Package both operations together:

```
o = \{i = incc, d = decc\}
```

We have now have a simple form of object: a collection of operations that share access to common state



References to Complex Types

A location can hold values of any type Example:

```
newarray = \lambda z:Unit. ref (\lambda n:Nat. 0)
newarray : Unit → (Nat→Nat) ref
lookup = \lambda a: ref(Nat \rightarrow Nat).\lambda n: Nat.(!a) n;
lookup: (Nat→Nat)ref → Nat → Nat
update = \lambda a:(Nat \rightarrow Nat) ref.
  \lambda m: Nat. \lambda v: Nat. let old = !a in
   a:=(\lambda n: Nat.if equal m n then v else old n)
update:(Nat→Nat)ref → Nat → Nat → Unit
```

Typing Rules



$$\frac{\Gamma \vdash t : T \mathbf{ref}}{\Gamma \vdash ! t : T} \quad \text{T_DEREF}$$

$$\Gamma \vdash t : T$$

$$\Gamma \vdash \mathbf{ref} \ t : T \mathbf{ref}$$

$$\Gamma \vdash t : T \mathbf{ref}$$

$$\Gamma \vdash t' : T$$

$$\Gamma \vdash t := t' : \mathbf{Unit}$$

T_Ref

T_Assign



How do we capture the operational (runtime) behavior of reference operations?

- What does it mean to "allocate" storage?
- What does it mean to "assign" to a location?

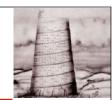
Think of the store as an array of values

 rather than think of references as addresses (numbers), think of them as elements of a set L of store locations



```
terms:
true
                                  constant true
false
                                  constant false
if t_1 then t_2 else t_3
                                  conditional
                                  variable
\mathbf{X}
\lambda \mathbf{x} : T . t
                                  abstraction
                                  application
t_1 t_2
[\mathbf{x} \mapsto v] t
                         М
                                  integer
nv
t + t'
                                  addition
                          M
(t)
! t
                                  dereference
                                  new reference
\mathbf{ref}\ t
t := t'
                                  assignment
unit
                                  unit
                                  address
```

v	::=	values:
	true	true value
	false	false value
	$\lambda \mathbf{x} : T . t$	abstraction value
	nv	integer value
	unit	unit
	l	$\operatorname{address}$



$$|t, \mu \downarrow t', \mu'|$$
 Evaluation

$$\frac{\lambda \mathbf{x} : T \cdot t, \mu \Downarrow \lambda \mathbf{x} : T \cdot t, \mu}{t_{1}, \mu \Downarrow \lambda \mathbf{x} : T \cdot t'_{1}, \mu'} \\
\frac{t_{1}, \mu \Downarrow \lambda \mathbf{x} : T \cdot t'_{1}, \mu'}{t_{2}, \mu' \Downarrow v, \mu''} \\
\frac{[\mathbf{x} \mapsto v] t'_{1}, \mu'' \Downarrow v', \mu'''}{t_{1} t_{2}, \mu \Downarrow v', \mu'''} \\
\frac{t_{1}, \mu \Downarrow \mathbf{true}, \mu'}{t_{2}, \mu' \Downarrow v, \mu''} \\
\frac{t_{1}, \mu \Downarrow \mathbf{false}, \mu'}{t_{3}, \mu' \Downarrow v, \mu''} \\
\frac{t_{1}, \mu \Downarrow \mathbf{false}, \mu'}{t_{3}, \mu' \Downarrow v, \mu''} \\
\frac{t_{1}, \mu \Downarrow \mathbf{false}, \mu'}{\mathbf{if} t_{1} \mathbf{then} t_{2} \mathbf{else} t_{3}, \mu \Downarrow v, \mu''} \\
\frac{t_{1}, \mu \Downarrow nv_{1}, \mu'}{t_{2}, \mu' \Downarrow nv_{2}, \mu''} \\
\frac{nv_{1} + nv_{2} = nv_{3}}{t_{1} + t_{2}, \mu \Downarrow nv_{3}, \mu''} \\
\frac{\pi v, \mu \Downarrow v, \mu}{t_{2}, \mu' \Downarrow v, \mu} \\
\frac{\pi v, \mu \Downarrow v, \mu}{t_{2}, \mu' \Downarrow v, \mu} \\
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\frac{\pi v, \mu}{t_{2},$$



$$\frac{\mu'(l) = v}{!t, \mu \Downarrow v, \mu'} \quad \text{E-DEREF}$$

$$\frac{t, \mu \Downarrow l, \mu'}{t', \mu' \Downarrow v, \mu''}$$

$$\frac{\mu''' = \mu''[l \mapsto v]}{t := t', \mu \Downarrow \mathbf{unit}, \mu'''} \quad \text{E-ASSIGN}$$

$$\frac{t, \mu \Downarrow v, \mu'}{\mu'' = \mu'[l \mapsto v]}$$

$$\frac{l \not\in \mathbf{dom}(\mu')}{\mathbf{ref} t, \mu \Downarrow l, \mu''} \quad \text{E-ALLOC}$$

Locations



Extend typing rule to accommodate locations:

The type of a location depends upon the contents of the store:

- ▶ If $\mu=[l_1 \mapsto Unit, l_2 \mapsto Unit]$, then l_2 has type Unit
- If μ =[l₁ \mapsto Unit, l₂ \mapsto Unit \to Unit], then l₂ has type Unit \to Unit

Problem



This type rule isn't very satisfactory

- large type derivations
- doesn't handle cycles in the store

Suppose the store is defined by:

```
[ l_1 \mapsto \lambda x: Nat.99,

l_2 \mapsto \lambda x: Nat.(!l_1) x,

l_3 \mapsto \lambda x: Nat.(!l_2) x, ... ]
```

Now, typing In requires calculating types of l_1 , ..., l_{n-1} Suppose we have:

```
[l_1 \mapsto \lambda x:Nat.(!l_2) \times, l_2 \mapsto \lambda x:Nat.(!l_1) \times]
```

Issues



How do we create cycles?

```
let r1 = ref (\lambdax:Nat. 0)

r2 = ref (\lambdax:Nat.(!r1) x)

in (r1 := \lambdax:Nat.(!r2) x;

r2)
```

Unnecessary for us to recalculate the type of a location every time it is mentioned:

- we know its type at the point it is declared
- all other values stored in the location must share that type

Store Typings



For a store that contains:

```
[ l_1 \mapsto \lambda x : \text{Nat.} 99, l_2 \mapsto \lambda x : \text{Nat.} (!l_1) x, l_3 \mapsto \lambda x : \text{Nat.} (!l_2) x, ... ] a reasonable typing would be:

[ l_1 \mapsto \text{Nat} \rightarrow \text{Nat}, l_2 \mapsto \text{Nat} \rightarrow \text{Nat}, l_3 \mapsto \text{Nat} \rightarrow \text{Nat}, ... ]
```

Store Typings



A store typing Σ describes the store μ in which we intend to evaluate term t. We use Σ to lookup the types of locations referenced in t.

$$\frac{\Sigma(l) = T}{\Gamma, \Sigma \vdash l : T \mathbf{ref}} \quad \text{T_Address}$$

Need to propagate Σ to all the other type rules defined earlier.

Store Typings



A given store may have multiple store typings:

Suppose

```
\mu = [1 \mapsto \lambda x : Unit. (!1) x]
```

Then,

$$\Sigma_1 = 1 \mapsto Unit \rightarrow Unit$$

$$\Sigma_2 = 1 \mapsto Unit \rightarrow Unit \rightarrow Unit$$

Exceptions



An exception is a construct that allows programmers deal with exceptional conditions (e.g., errors)

- exception handler: code that is associated with an exception that is invoked when an exception is raised.
- raising an exception causes the computation to transfer control to the closest enclosing handler (in the dynamic context).

First step: Errors



An error is a special term that when evaluated stops evaluation of the term.

- Values: $v := n \mid true \mid false \mid \lambda x : \tau. e \mid$
- Terms: $t := x \mid \lambda x : \tau \cdot t \mid e e \mid error$
- Evaluation rules (Contextual)

E ::= [] | E t |
$$(\lambda x:\tau. t)$$
 E

Reduction

```
error t \rightarrow error

verror \rightarrow error
```

Typing

```
\Gamma \vdash \text{error} : T (an error can be of any type)
```

What difficulties do we face in expressing error using a big-step semantics?

Typing



Since error can be of any type, it breaks uniqueness property of types:

- subtyping: allow error to be "promoted" to any other type as necessary by defining it the "minimal" type
- polymorphism: give error the polymorphic type ∀x.x that can be "instantiated" to any other type as necessary

Why not just use annotations? Consider:

```
(\lambda x:Nat. x) ((\lambda y:Bool.13) (error as Bool))
```

Exceptions



Evaluating error "unwinds" the call-stack until all frames have been discarded, and evaluation returns to the top-level.

Generalizing to exceptions, allows handlers to be inserted between activation frames in the call-stack

- control reverts to the handler that handles the exception raised
- use the first matching handler

Error Handling



```
Values: v ::= n | true | false | \lambda x: \tau. e |
Terms: e := x \mid \lambda x : \tau . e \mid e \mid e \mid error \mid
                        try e with e
Contexts and Reduction Rules:
   E ::= ... | try E with e
   r ::= ... | try error with e | try v with e
   try v with e \rightarrow v
   try error with e \rightarrow e
Type rule:
   \Gamma \vdash try t with t':T iff \Gamma \vdasht:T and \Gamma \vdash t':T
```

Exception-Carrying Values



Suppose we want to send information to a handler about the unusual event that triggered the exception

Allow exceptions to carry values

When an exception is raised, supply a value that is an argument to the handler.

Evaluation Rules



```
Values: v ::= n \mid true \mid false \mid \lambda x:\tau.t
Terms: t ::= x \mid \lambda x:\tau.t \mid t t \mid try t with t \mid raise t
```

Evaluation contexts and Reduction Rules:

```
E::= ... | try E with t | raise E
```

```
try v with t \rightarrow v

try (raise v) with t \rightarrow t v

(raise v) t \rightarrow raise v

v (raise v1) \rightarrow raise v1

raise (raise v) \rightarrow raise v
```

Typing Rules



$$\Gamma \vdash \mathbf{e} : \mathbf{ au_{exn}}$$
 $\Gamma \vdash \mathsf{raise} \; \mathbf{e} : \mathbf{ au}$

$$\Gamma \vdash e : \tau \quad \Gamma \vdash e_h : \tau_{exn} \rightarrow \tau$$
 $\Gamma \vdash try e with e_h : \tau$

Exception Types



What type should τ_{exn} be?

- ▶ Take it to be Nat. Corresponds to errno convention in Unix.
- Take it to be String.
- Take it to be a variant type:

```
Texn = divideByZero: Unit + overflow : Unit +
    fileNotFound : String + ...
```

Not particularly flexible

Assume τ_{exn} is an extensible variant:

- In ML, there is a single extensible variant type called exn.
- exception 1 of T means "make sure 1 is different from any other tag present in the variant type $\tau_{\rm exn}$ "

```
\tau_{\rm exn} is henceforth \tau_{\rm exn}+1:T
```

Continuations



Exceptions and errors are instantiations of a more general control feature that allows non-local transfer of control from point in the program to another.

structured jumps or gotos

Can we generalize (or reify) this notion into our core language?

 result is a continuation: a reified representation (in the form of an abstraction) of a program's control-stack.

Continuations



Define a new primitive call/cc:

Takes as its argument a procedure

and binds to k a reified representation of the call-stack at the point of evaluation.

Can transfer control to this point via application.

Examples



```
call/cc (\lambda k. (k 3) + 2) + 1 \rightarrow 4

val r = ref (\lambda v. 0)

call/cc (\lambda k. (r := k; (k 3) + 2)) + 1 \rightarrow 4

(!r 4) \rightarrow 5

let f = call/cc (\lambda k. \lambda x. k (\lambda y. x + y))

in f 6 \rightarrow
12
```

Evaluation and Typing Rules



First, consider the evaluation rule in an untyped setting:

 $E[call/cc e] = E[e (\lambda v. abort (E[v])]$

where abort represents the "initial" continuation.

Typing is a bit harder because continuations bound by call/cc can be invoked in several different contexts

An Example in ML



k is invoked in two contexts:

- one expects an integer
- other expects a list

Since continuations never return, how do we choose the result type?

One possible type: (T cont→T) → T

Will revisit this issue when we consider polymorphism.