# References and Exceptions

## CS 565 Lecture 14



#### References



In most languages, variables are mutable:

- it serves as a name for a location
- the contents of the location can be overwritten, and still be referred to by the same name

In ML, variables only name values:

- bindings are immutable
- introduce a new class of values called references.
- A variable bound to mutable location will have type ref τ

## Basic Operations



#### Create a reference:

- ref s: returns a reference to a location that contains the value denoted by s.
- If s has type τ, then ref s : τ ref

#### Dereference:

- !r: returns the contents of the location referenced by r
- If r has type τ ref, then !r : τ

#### Assignment:

- r := s: changes the contents of the location referenced by r to hold the value denoted by s.
- If r has type  $\tau$  ref, and s has type  $\tau$ , then r := s has value unit of type Unit.
- No explicit deallocation operation.

### References and Stores



Distinction between a reference and the location pointed to by that reference:

- r = s: binds a reference to the location pointed to by r to s.
- Thus,

r and s are aliases for the same location

#### References and Shared State



Implement implicit communication channels:

```
c = ref 0

incc = \lambda x:Unit . (c:=succ(!c); !c)

decc = \lambda x:Unit . (c:=pred(!c); !c)

incc unit \rightarrow 1

decc unit \rightarrow 0
```

Package both operations together:

```
o = \{i = incc, d = decc\}
```

We have now have a simple form of object: a collection of operations that share access to common state

# References to Complex Types



A location can hold values of any type Example:

```
newarray = λz:Unit. ref (λn:Nat. 0)
newarray : Unit → (Nat→Nat) ref

lookup = λa:ref(Nat→Nat).λn:Nat.(!a) n;
lookup: (Nat→Nat)ref → Nat → Nat

update = λ a:(Nat → Nat) ref.

λm:Nat. λv:Nat. let old = !a in
 a:=(λn:Nat.if equal m n then v else old n)
update:(Nat→Nat)ref → Nat → Nat → Unit
```

# Typing Rules



$$\frac{\Gamma \vdash t : T \operatorname{\mathbf{ref}}}{\Gamma \vdash ! t : T} \quad \text{T_DEREF}$$

$$\frac{\Gamma \vdash t : T}{\Gamma \vdash \mathbf{ref} \ t : T \mathbf{ref}} \quad \text{T\_Ref}$$

$$\frac{\Gamma \vdash t : T \mathbf{ref}}{\Gamma \vdash t := t' : \mathbf{Unit}} \qquad \text{T\_Assign}$$

#### Evaluation



How do we capture the operational (runtime) behavior of reference operations?

- What does it mean to "allocate" storage?
- What does it mean to "assign" to a location?

Think of the store as an array of values

 rather than think of references as addresses (numbers), think of them as elements of a set L of store locations

## Evaluation



t ::=			terms:
	${f true}$		constant true
	false		constant false
	if $t_1$ then $t_2$ else $t_3$		conditional
	X		variable
	$\lambda \mathbf{x} : T . t$		abstraction
	$t_1 t_2$		application
	$[\mathbf{x} \mapsto v]t$	Μ	
	nv		integer
	t + t'		addition
	(t)	Μ	
	$!\ t$		dereference
	$\mathbf{ref}\ t$		new reference
	t := t'		assignment
	${f unit}$		unit
	l		address
v ::=			values:
	true		true value
i	false		false value
ì	$\lambda \mathbf{x} : T . t$		abstraction value
į	nv		integer value
į	$\mathbf{unit}$		unit
j	l		address

# Evaluation



$$t, \mu \downarrow t', \mu'$$
 Evaluation

$$\frac{\lambda \mathbf{x} : T \cdot t, \mu \Downarrow \lambda \mathbf{x} : T \cdot t, \mu}{\lambda \mathbf{x} : T \cdot t'_{1}, \mu'} \quad \text{E-Lam}$$

$$\frac{t_{1}, \mu \Downarrow \lambda \mathbf{x} : T \cdot t'_{1}, \mu'}{t_{2}, \mu' \Downarrow v, \mu''} \quad \text{E-APP}$$

$$\frac{[\mathbf{x} \mapsto v] t'_{1}, \mu'' \Downarrow v', \mu'''}{t_{1} t_{2}, \mu \Downarrow v', \mu'''} \quad \text{E-IFT}$$

$$\frac{t_{1}, \mu \Downarrow \text{true}, \mu'}{t_{2}, \mu' \Downarrow v, \mu''} \quad \text{E-IFT}$$

$$\frac{t_{1}, \mu \Downarrow \text{false}, \mu'}{t_{3}, \mu' \Downarrow v, \mu''} \quad \text{E-IFF}$$

$$\frac{t_{1}, \mu \Downarrow \text{false}, \mu'}{t_{3}, \mu' \Downarrow v, \mu''} \quad \text{E-IFF}$$

$$\frac{t_{1}, \mu \Downarrow nv_{1}, \mu'}{t_{2}, \mu' \Downarrow nv_{2}, \mu''} \quad \text{E-PLUS}$$

$$\frac{nv_{1} + nv_{2} = nv_{3}}{t_{1} + t_{2}, \mu \Downarrow nv_{3}, \mu''} \quad \text{E-PLUS}$$

$$\frac{v, \mu \Downarrow v, \mu}{v, \mu} \quad \text{E-VAL}$$

#### Evaluation



$$\frac{\mu'(l) = v}{!t, \mu \Downarrow v, \mu'} \quad \text{E-DEREF}$$

$$\frac{t, \mu \Downarrow l, \mu'}{t', \mu' \Downarrow v, \mu''}$$

$$\frac{\mu''' = \mu''[l \mapsto v]}{t := t', \mu \Downarrow \mathbf{unit}, \mu'''} \quad \text{E-ASSIGN}$$

$$\frac{t, \mu \Downarrow v, \mu'}{\mu'' = \mu'[l \mapsto v]}$$

$$\frac{l \not\in \mathbf{dom}(\mu')}{\mathbf{ref} t, \mu \Downarrow l, \mu''} \quad \text{E-ALLOC}$$

### Locations



Extend typing rule to accommodate locations:

The type of a location depends upon the contents of the store:

- ▶ If  $\mu$ =[l<sub>1</sub>  $\mapsto$  Unit, l<sub>2</sub>  $\mapsto$  Unit], then l<sub>2</sub> has type Unit
- If μ=[l₁ → Unit,l₂ → Unit→Unit], then l₂ has type
  Unit→Unit

#### Problem



This type rule isn't very satisfactory

- large type derivations
- doesn't handle cycles in the store

Suppose the store is defined by:

```
[ l_1 \mapsto \lambda x : \text{Nat.} 99,

l_2 \mapsto \lambda x : \text{Nat.} (!l_1) x,

l_3 \mapsto \lambda x : \text{Nat.} (!l_2) x, ... ]
```

Now, typing In requires calculating types of  $l_1$ , ...,  $l_{n-1}$  Suppose we have:

```
[l_1 \rightarrow \lambda x:Nat.(!l_2) x, l_2 \rightarrow \lambda x:Nat.(!l_1)x]
```

#### Issues



How do we create cycles?

```
let r1 = ref (λx:Nat. 0)
    r2 = ref (λx:Nat.(!r1) x)
in (r1 := λx:Nat.(!r2) x;
    r2)
```

Unnecessary for us to recalculate the type of a location every time it is mentioned:

- we know its type at the point it is declared
- all other values stored in the location must share that type

## Store Typings



For a store that contains:

```
[ l_1 \mapsto \lambda x : \text{Nat.99}, l_2 \mapsto \lambda x : \text{Nat.}(!l_1) x, l_3 \mapsto \lambda x : \text{Nat.}(!l_2) x, \dots ]

a reasonable typing would be:
[ l_1 \mapsto \text{Nat} \rightarrow \text{Nat}, \ l_2 \mapsto \text{Nat} \rightarrow \text{Nat}, l_3 \mapsto \text{Nat} \rightarrow \text{Nat}, \dots ]
```

## Store Typings



A store typing  $\Sigma$  describes the store  $\mu$  in which we intend to evaluate term  $\pm$ . We use  $\Sigma$  to lookup the types of locations referenced in  $\pm$ .

$$\frac{\Sigma(l) = T}{\Gamma, \Sigma \vdash l : T \operatorname{ref}} \quad \text{T\_Address}$$

Need to propagate  $\Sigma$  to all the other type rules defined earlier.

## Store Typings



A given store may have multiple store typings:

Suppose

$$\mu = [1 \mapsto \lambda x : \text{Unit. (!1) } x]$$
 Then, 
$$\Sigma_1 = 1 \mapsto \text{Unit} \rightarrow \text{Unit}$$
 
$$\Sigma_2 = 1 \mapsto \text{Unit} \rightarrow \text{Unit} \rightarrow \text{Unit}$$

## Exceptions



An exception is a construct that allows programmers deal with exceptional conditions (e.g., errors)

- exception handler: code that is associated with an exception that is invoked when an exception is raised.
- raising an exception causes the computation to transfer control to the closest enclosing handler (in the dynamic context).

# First step: Errors



An error is a special term that when evaluated stops evaluation of the term.

```
Values: v := n \mid true \mid false \mid \lambda x: \tau. e \mid
```

Terms: 
$$t := x \mid \lambda x : \tau \cdot t \mid e e \mid error$$

Evaluation rules (Contextual)

```
E ::= [] \mid E t \mid (\lambda x:T. t) E
```

Reduction

```
error t \rightarrow error

v error \rightarrow error
```

Typing

```
\Gamma \vdash \text{error} : T (an error can be of any type)
```

What difficulties do we face in expressing error using a big-step semantics?

## **Typing**



Since error can be of any type, it breaks uniqueness property of types:

- subtyping: allow error to be "promoted" to any other type as necessary by defining it the "minimal" type
- polymorphism: give error the polymorphic type ∀x.x that can be "instantiated" to any other type as necessary

Why not just use annotations? Consider:

```
(\lambda x:Nat. x) ((\lambda y:Bool.13) (error as Bool))
```

## Exceptions



Evaluating error "unwinds" the call-stack until all frames have been discarded, and evaluation returns to the top-level.

Generalizing to exceptions, allows handlers to be inserted between activation frames in the call-stack

- control reverts to the handler that handles the exception raised
- use the first matching handler

## Error Handling



```
Values: v ::= n \mid true \mid false \mid \lambda x: \tau. e \mid

Terms: e ::= x \mid \lambda x:\tau.e \mid e e \mid error \mid

try e with e

Contexts and Reduction Rules:

E ::= \ldots \mid try \; E \; with \; e

r ::= \ldots \mid try \; error \; with \; e \mid try \; v \; with \; e

try v \; with \; e \rightarrow v

try v \; with \; e \rightarrow e

Type rule:

\Gamma \vdash try \; t \; with \; t':\tau \; iff \; \Gamma \vdash t:\tau \; and \; \Gamma \vdash t':\tau
```

# Exception-Carrying Values



Suppose we want to send information to a handler about the unusual event that triggered the exception

Allow exceptions to carry values

When an exception is raised, supply a value that is an argument to the handler.

#### **Evaluation Rules**



```
Values: v ::= n | true | false | \lambda x:T.t
Terms: t ::= x | \lambda x:T.t | t t | try t with t | raise t
```

Evaluation contexts and Reduction Rules:

```
try v with t \rightarrow v

try (raise v) with t \rightarrow t v

(raise v) t \rightarrow raise v

v (raise v1) \rightarrow raise v1

raise (raise v) \rightarrow raise v
```

E ::= ... | try E with t | raise E



$$\begin{array}{c|c} \hline \Gamma \vdash e : \tau_{\text{exn}} \\ \hline \Gamma \vdash \text{raise } e : \tau \end{array} \qquad \begin{array}{c|c} \hline \Gamma \vdash e : \tau & \Gamma \vdash e_{\text{h}} : \tau_{\text{exn}} \rightarrow \tau \\ \hline \hline \Gamma \vdash \text{try e with } e_{\text{h}} : \tau \end{array}$$

## Exception Types



What type should  $\tau_{exn}$  be?

- ▶ Take it to be Nat. Corresponds to errno convention in Unix.
- ▶ Take it to be String.
- Take it to be a variant type:

```
Texn = divideByZero: Unit + overflow : Unit +
    fileNotFound : String + ...
```

Not particularly flexible

Assume  $\tau_{exn}$  is an extensible variant:

- ▶ In ML, there is a single extensible variant type called exn.
- exception 1 of T means "make sure 1 is different from any other tag present in the variant type  $\tau_{exn}$ "

```
\tau_{\text{exn}} is henceforth \tau_{\text{exn}}\text{+l:T}
```

#### Continuations



Exceptions and errors are instantiations of a more general control feature that allows non-local transfer of control from point in the program to another.

structured jumps or gotos

Can we generalize (or reify) this notion into our core language?

result is a continuation: a reified representation (in the form of an abstraction) of a program's control-stack.

#### Continuations



Define a new primitive call/cc:

Takes as its argument a procedure

and binds to k a reified representation of the call-stack at the point of evaluation.

Can transfer control to this point via application.

## Examples



```
call/cc (\lambda k. (k 3) + 2) + 1 \rightarrow 4

val r = ref (\lambda v. 0)

call/cc (\lambda k. (r := k; (k 3) + 2)) + 1 \rightarrow 4

(!r 4) \rightarrow 5

let f = call/cc (\lambda k. \lambda x. k (\lambda y. x + y))

in f 6 \rightarrow
12
```

# Evaluation and Typing Rules



First, consider the evaluation rule in an untyped setting:

 $E[call/cc e] = E[e (\lambda v. abort (E[v])]$ 

where abort represents the "initial" continuation.

Typing is a bit harder because continuations bound by call/cc can be invoked in several different contexts

# An Example in ML



k is invoked in two contexts:

- one expects an integer
- other expects a list

Since continuations never return, how do we choose the result type?

One possible type:  $(\tau cont \rightarrow \tau) \rightarrow \tau$ 

• Will revisit this issue when we consider polymorphism.