A Theoretical Basis of Communication-Centred Programming for Web Service

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Structure of Lectures

- Part 1 Basic Theory (Processes and Types)
 - \geq 1 Introduction to the π -Calculus
 - 2 Idioms for Interactions
 - Session Types
- Part 2 Web Services and the π -Calculus
 - Web Services Choreography Description Language
 - Clobal Language and the End-Point Calculus
 - End-Point Projection and Correctness

Web Service (1)

Concurrency in theory and practice:

- 1. Understanding (CCS, CSP, ACP, Pi-Calculus...)
 - Message/event based: no shared memory.
 - Rich theories of communication behaviour.
 - Connection to other fields (games, Linear Logic, ...).
- 2. Building (Java, C/pthreads, OpenMP, ...)
 - Threads and shared variables.
 - Fits SMP (e.g. OpenMP).
 - Recent development (e.g. lock-free algorithms, software transaction, ...)

Web Service (2)

Key Characteristics of WS:

- Infrastructural basis: URI (naming), XML (message format), HTTP/TCP (message delivery).
- Applications purely based on communication ("business protocols").
- Inter-organisational nature demanding standardisation and clear, rigorous understanding.

WS-CDL: Summary

- XML-based description language for business protocols.
- ➤ Developed by W3C's CDL WG (2003~, chaired by Steve Ross-Talbot and Martin Chapman).
- Central idea: choreography (cf. orchestration).
 Dancers dance following a global scenario without a single point of control.
- ➤ Pi-calculus experts invited in 2004. Now CR, reaching a W3C standard soon.
- Offers general global programming unlike sequence diagrams etc.

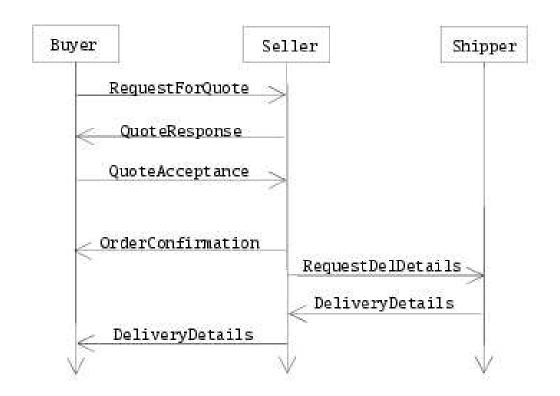
Global Description (1)

Notations for cryptographic protocols.

- 1. Alice \rightarrow Trent : Alice, Bob, N_A .
- 2. Trent \rightarrow Alice : $\{N_A, K_{AB}\}_{K_A}, \{K_{AB}\}_{K_B}$.
- 3. Alice \rightarrow Bob : $\{K_{AB}\}_{K_B}$.

Global Description (2)

UML sequence diagrams.



How To Use Types

Question:

We have two programs/specifications, P_1 and P_2 . Does $P_1|P_2$ behave all right?

Answer without Types.

...well let's run $P_1 | P_2$ and see what happens.

Answer with Types. We put a small tag t_1 to P_1 , t_2 to P_2 .

Let's check $t_1|t_2$ makes sense. If it does, $P_1|P_2$ behaves well, and has a new tag $t_1|t_2$.

NB. Checking consistency of tags is very efficient.

Session Types

- A simple type abstraction of a structured collection of interactions, or a session.
- Studied for a variety of calculi and languages.
- > Started from decomposition of communication idioms in the π -calculus (1994 \sim).
- Many real-world application-level communications are based on sessions (TCP sessions, cookies, ...).
- Gives a simple and robust basis for further analysis and verification.

End-Point Projection (EPP)

A notion informally (introduced and) discussed in WS-CDL WG.

How can we project a global description to endpoints so that their interactions precisely realise the original global description?

- ➤ Basis for execution, monitoring, validation, reuse, conformance, interoperability,...
- Demands formalisation of global and end-point descriptions.

Global Calculus: Syntax (1)

```
I ::= A \rightarrow B : \operatorname{ch}(\tilde{s}).I
                                                           session initiation
            A \rightarrow B : s\langle \mathsf{op}, e, y \rangle . I
                                                           communication
            x@A := e.I
                                                           assignment
             if e@A then I_1 else I_2
                                                           conditional
            I_1 + I_2
                                                           sum
            I_1 \mid I_2
                                                           parallel
            (\mathbf{v} s)I
                                                           hiding
            \operatorname{rec} X^A J
                                                           recursion
            X^{A}
                                                           term variable
             0
                                                           inaction
```

Global Calculus: Syntax (2)

We have *not* included, but can treat:

- New variable declaration.
- Channel/session passing, general sequencing (fork/join, parbegin/parend, async/finish).
- Mutex and/or "atomic" constructs.

Reduction is between configurations:

$$(I, \sigma) \rightarrow (I', \sigma')$$

$$(A
ightharpoonup B : \operatorname{ch}(\widetilde{s}).I, \, \sigma)
ightharpoonup ((v\,\widetilde{s})I, \, \sigma)$$
 $(A
ightharpoonup B : s\langle \operatorname{op}, V, x \rangle.I, \, \sigma)
ightharpoonup (I, \, \sigma[x@B \mapsto V])$
 $(x@A := V.I, \, \sigma)
ightharpoonup (I, \, \sigma[x@A \mapsto V])$
 $(I_1 + I_2, \, \sigma)
ightharpoonup (I_1, \, \sigma)$
 $(I_1 | I_2, \, \sigma)
ightharpoonup (I_1' | I_2, \, \sigma') \quad \text{if } (I_1, \, \sigma)
ightharpoonup (I_1', \, \sigma')$

Reduction is between configurations:

$$(I, \sigma) \rightarrow (I', \sigma')$$

$$(A
ightharpoonup B : \operatorname{ch}(\widetilde{s}).I, \sigma)
ightharpoonup ((v\,\widetilde{s})I, \sigma)$$
 $(A
ightharpoonup B : s\langle \operatorname{op}, V, x \rangle.I, \sigma)
ightharpoonup (I, \sigma[x@B \mapsto V])$
 $(x@A := V.I, \sigma)
ightharpoonup (I, \sigma[x@A \mapsto V])$
 $(I_1 + I_2, \sigma)
ightharpoonup (I_1, \sigma)$
 $(I_1|I_2, \sigma)
ightharpoonup (I_1'|I_2, \sigma') \text{ if } (I_1, \sigma)
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Reduction is between configurations:

$$(I, \sigma) \rightarrow (I', \sigma')$$

$$(A
ightharpoonup B : \operatorname{ch}(\widetilde{s}).I, \, \sigma)
ightharpoonup ((\mathbf{v}\,\widetilde{s})I, \, \sigma)$$
 $(A
ightharpoonup B : s\langle \operatorname{op}, V, x \rangle.I, \, \sigma)
ightharpoonup (I, \, \sigma[x@B \mapsto V])$
 $(x@A := V.I, \, \sigma)
ightharpoonup (I, \, \sigma[x@A \mapsto V])$
 $(I_1 + I_2, \, \sigma)
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 $(A
ightharpoonup B: s\langle \operatorname{op}, V, x \rangle.I, \,\sigma)
ightharpoonup (I, \,\sigma[x@B \mapsto V])$
 $(x@A := V.I, \,\sigma)
ightharpoonup (I, \,\sigma[x@A \mapsto V])$
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ightharpoonup (I_1, \,\sigma)$
 $(I_1|I_2, \,\sigma)
ightharpoonup (I_1'|I_2, \,\sigma') \text{ if } (I_1, \,\sigma)
ightharpoonup (I_1', \,\sigma')$

Reduction is between configurations:

$$(I, \sigma) \rightarrow (I', \sigma')$$

$$(A \rightarrow B : \operatorname{ch}(\tilde{s}).I, \sigma) \rightarrow ((v \, \tilde{s})I, \sigma)$$
 $(A \rightarrow B : s \langle \operatorname{op}, V, x \rangle.I, \sigma) \rightarrow (I, \sigma[x@B \mapsto V])$
 $(x@A := V.I, \sigma) \rightarrow (I, \sigma[x@A \mapsto V])$
 $(I_1 + I_2, \sigma) \rightarrow (I_1, \sigma)$
 $(I_1|I_2, \sigma) \rightarrow (I_1'|I_2, \sigma') \text{ if } (I_1, \sigma) \rightarrow (I_1', \sigma')$

Reduction is between configurations:

$$(I, \sigma) \rightarrow (I', \sigma')$$

$$(A
ightharpoonup B : \operatorname{ch}(\widetilde{s}).I, \, \sigma)
ightharpoonup ((V\,\widetilde{s})I, \, \sigma)$$
 $(A
ightharpoonup B : s \langle \operatorname{op}, V, x \rangle.I, \, \sigma)
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ightharpoonup (I_1, \, \sigma)$
 $(I_1|I_2, \, \sigma)
ightharpoonup (I_1'|I_2, \, \sigma') \quad \text{if } (I_1, \, \sigma)
ightharpoonup (I_1', \, \sigma')$

Examples of Reduction

```
Buyer \rightarrow Seller : QuoteCh(vs).

Seller \rightarrow Buyer : s\langle Quote, 300, x \rangle . I',

\downarrow

( (vs) Seller \rightarrow Buyer : s\langle Quote, 300, x \rangle . I'),

\sigma)

\downarrow

( (vs) I', \sigma[x@Buyer \mapsto 300])
```

Global Calculus: Example (1)

```
Buyer \rightarrow Seller : ch1(v s, t).
Buyer \rightarrow Seller : s\langle QuoteReq, prod@B, prod@S \rangle.
Seller \rightarrow Buyer : t\langle QuoteRes, quote@S, quote@B \rangle.
Buyer \rightarrow Seller : s\langle QuoteAcc, cred; adr@B, cred; adr@S \rangle.
Seller \rightarrow Shipper : ch2(r).
Seller \rightarrow Shipper : r\langle ShipReq, prod; adr@S, prod; adr@Sh\rangle.
Shipper \rightarrow Seller : r\langle ShipConf\rangle.
Seller \rightarrow Buyer : t\langle \mathsf{OrderConf} \rangle. 0
```

Global Calculus: Example (2)

```
Buyer \rightarrow Seller : ch1(s, t).
Buyer \rightarrow Seller : s\langle QuoteReq, prod@B, prod@S \rangle.
Seller \rightarrow Buyer : t\langle QuoteRes, quote@S, quote@B \rangle.
choice
   Buyer \rightarrow Seller : s\langle QuoteAcc, cred; adr@B, cred; adr@S \rangle.
   Seller → Shipper : ch2(r).
   \cdots (as before) \cdots
   Buyer \rightarrow Seller : s\langle QuoteNoGood \rangle.0
endchoice
```

Global Calculus: Example (3)

```
Buyer \rightarrow Seller : ch1(s, t).
Buyer \rightarrow Seller : s\langle QuoteReq, prod@B, prod@S \rangle.
Seller \rightarrow Buyer : t\langle QuoteRes, quote@S, quote@B \rangle.
if reasonable(quote)@Buyer then
   Buyer \rightarrow Seller : s\langle QuoteAcc, cred; adr@B, cred; adr@S \rangle.
   Seller → Shipper : ch2(r).
   \cdots (as before) \cdots
else
   Buyer \rightarrow Seller : s\langle QuoteNoGood \rangle.0
endif
```

Global Calculus: Example (4)

```
Buyer \rightarrow Seller : ch1(s,t).
Buyer \rightarrow Seller : s\langle QuoteReq, prod, prod \rangle.
rec X.
Seller \rightarrow Buyer : t\langle QuoteRes, quote, quote \rangle.
if reasonable(quote)@Buyer then
   Buyer \rightarrow Seller : s\langle QuoteAcc, cred; adr@B, cred; adr@S \rangle.
   Seller \rightarrow Shipper : \operatorname{ch2}(r).
       \cdots (as before) \cdots
else
       Buyer \rightarrow Seller : s\langle QuoteNoGood \rangle.X
endif
```

Global Calculus: Example (5)

```
Buyer \rightarrow Seller : ch1(s, t).
Buyer \rightarrow Seller : s\langle QuoteReq, prod, prod \rangle.
Seller \rightarrow Vendor : ch2(u).
rec X.
Seller \rightarrow Vendor : u\langle QuoteReq, prod, prod \rangle.
Vendor \rightarrow Seller : u\langle QuoteRes, orgq, orgq \rangle.
Seller \rightarrow Buyer : t\langle QuoteRes, orgq + 100, quote \rangle.
if reasonable(quote)@Buyer then
   Buyer \rightarrow Seller : s\langle QuoteAcc, cred; adr@B, cred; adr@S \rangle.
   Seller \rightarrow Vendor : u\langle Done! \rangle.
       \cdots (as before) \cdots
else
       Buyer \rightarrow Seller : s\langle QuoteNoGood \rangle.X
endif
```

Global Calculus: Example (6)

```
Buyer \rightarrow Seller : ch1(st); s\langle QuoteReq, prod, prod \rangle.
Seller \rightarrow Buyer : t\langle QuoteRes, quote, quote\rangle.
if reasonable(quote)@Buyer then
   Buyer \rightarrow Seller : s\langle QuoteAcc, cred; adr@B, cred; adr@S \rangle.
   Seller \rightarrow CCA : ch2(u); u\langleplsCheck, cred, cred\rangle.
   if cleared(cred)@CCA then
       \mathbf{CCA} \rightarrow \mathbf{Seller} : u \langle \mathsf{credOK} \rangle.
       Seller \rightarrow Shipper : ch3(r); r\langle ShipReq, prod; adr@S, prod; adr@Sh\rangle.
    \cdots (as before) \cdots
   else
       \mathbf{CCA} \rightarrow \mathbf{Seller} : r \langle \mathsf{credNotOK} \rangle.
       Seller \rightarrow Buyer : t\langle cannot Process\rangle.0
else
   Buyer \rightarrow Seller : s\langle QuoteNoGood \rangle.0
```

Global Calculus: Typing (1)

 \triangleright Session types $(\theta, \theta_i, ...$ are value types):

$$\alpha ::= s \triangleright \Sigma_i \langle \mathsf{op_i}, \theta_i \rangle. \ \alpha_i \mid s \blacktriangleleft \Sigma_i \langle \mathsf{op_i}, \theta_i \rangle. \ \alpha_i$$
$$\mid \alpha_1 \mid \alpha_2 \mid \mathbf{rec} \ t. \alpha \mid t \mid \mathbf{end}$$

- Typing: Γ , $\mathrm{ch}@A:(\tilde{s})\alpha\vdash I\rhd\Delta,\ \tilde{s}[A,B]:\alpha.$
 - ightharpoonup ch@ $A: (\tilde{s})\alpha$ says a service channel ch at A may be invoked with fresh \tilde{s} followed by a session α .
 - $\gg \tilde{s}[A,B]: \alpha$ says a session α from A to B occurs using \tilde{s} .
- Properties: Subject Reduction, Minimal Typing, ...

Global Calculus: Typing (2)

A term:

$$A \rightarrow B : \mathbf{b}(s_1 s_2).(A \rightarrow B : s_1 \langle go \rangle.B \rightarrow A : s_2 \langle ok \rangle.\mathbf{0} + A \rightarrow B : s_1 \langle stop \rangle.B \rightarrow A : s_2 \langle no \rangle.\mathbf{0})$$

can be given a typing (ϵ is the empty string):

$$\mathbf{b}@B: (s_1s_2) \ s_1 \blacktriangleright \begin{bmatrix} \langle \mathsf{go}, \boldsymbol{\epsilon} \rangle. \ s_2 \blacktriangleleft \langle \mathsf{ok}, \boldsymbol{\epsilon} \rangle. \ \mathbf{end} \\ + \\ \langle \mathsf{stop}, \boldsymbol{\epsilon} \rangle. \ s_2 \blacktriangleleft \langle \mathsf{no}, \boldsymbol{\epsilon} \rangle. \ \mathbf{end} \\ + \\ \langle \mathsf{run}, \boldsymbol{\epsilon} \rangle. \ s_2 \blacktriangleleft \langle \mathsf{fine}, \boldsymbol{\epsilon} \rangle. \ \mathbf{end} \end{bmatrix}$$

Without the **red** part, the typing is minimal.

Global Calculus: Typing (3)

Types for the simple Buyer-Seller:

```
ch @ Buyer : (st)  s \uparrow QuoteReq(string); t \downarrow QuoteRes(int); s \uparrow QuoteAcc(string)

ch @ Seller : (st)  s \downarrow QuoteReq(string); t \uparrow QuoteRes(int); s \downarrow QuoteAcc(string)
```

Global Calculus: Typing (4)

Types for the Buyer-Seller with choice/conditional.

```
ch @ Buyer : (st) s \uparrow QuoteReq(string);

t \downarrow QuoteRes(int);

s \uparrow QuoteAcc(string) \oplus s \uparrow QuoteNG(void)

ch @ Seller : (st) s \downarrow QuoteReq(string);

t \uparrow QuoteRes(int);

s \downarrow QuoteAcc(string) \& s \downarrow QuoteNG(void)
```

Global Calculus: Typing (5)

Types for the Buyer-Seller with loop.

```
ch @ Buyer : (st) s \uparrow QReq(string);

\mu X. \ t \downarrow QRes(int); s \uparrow QAcc(string) \oplus s \uparrow QNoGood(void); x

ch @ Seller : (st) s \downarrow QReq(string);

\mu X. \ t \uparrow QRes(int); s \downarrow QAcc(string) \& s \downarrow QNoGood(void)
```

$$P ::= !\operatorname{ch}(\tilde{s}).P \mid \overline{\operatorname{ch}}(\mathsf{v}\,\tilde{s}).P \mid s \rhd \Sigma_i \operatorname{op}_i \langle y_i \rangle.P_i \mid s \lhd \operatorname{op} \langle e \rangle.P$$

$$\mid x := e.P \mid \text{if } e \text{ then } P_1 \text{ else } P_2 \mid P \oplus Q$$

$$\mid P \mid Q \mid (\mathsf{v}\,s)P \mid X \mid \operatorname{rec} X.P \mid \mathbf{0}$$

$$M ::= A[P]_{\sigma} \mid M_1 \mid M_2 \mid (\mathsf{v}\,s)M \mid \mathbf{0}$$

$$A[!\operatorname{ch}(\widetilde{s}).P|R]_{\sigma_{A}} \mid B[\overline{\operatorname{ch}}(v\,\widetilde{s}).Q|S]_{\sigma_{B}} \
ightarrow (v\,\widetilde{s})(A[P|!\operatorname{ch}(\widetilde{s}).P|R]_{\sigma_{A}} \mid B[Q|S]_{\sigma_{B}}) \ A[s
hd \Sigma_{i}\operatorname{op}_{i}\langle y_{i}\rangle.P_{i} \mid R]_{\sigma_{A}} \mid B[s \lhd \operatorname{op}_{j}\langle V\rangle Q \mid S]_{\sigma_{B}} \
ightarrow A[P_{i} \mid R]_{\sigma_{A}}[v\mapsto V] \mid B[Q|S]_{\sigma_{B}}$$

$$P ::= !\operatorname{ch}(\tilde{s}).P \mid \overline{\operatorname{ch}}(v\,\tilde{s}).P \mid s \rhd \Sigma_{i}\operatorname{op}_{i}\langle y_{i}\rangle.P_{i} \mid s \lhd \operatorname{op}\langle e\rangle.P$$

$$\mid x := e.P \mid \text{if } e \text{ then } P_{1} \text{ else } P_{2} \mid P \oplus Q$$

$$\mid P \mid Q \mid (v\,s)P \mid X \mid \operatorname{rec} X.P \mid \mathbf{0}$$

$$M ::= A[P]_{\sigma} \mid M_{1} \mid M_{2} \mid (v\,s)M \mid \mathbf{0}$$

$$A[!\operatorname{ch}(\tilde{s}).P \mid R]_{\sigma_{A}} \mid B[\overline{\operatorname{ch}}(\mathbf{v}\,\tilde{s}).Q \mid S]_{\sigma_{B}}$$
 $ightharpoonup (\mathbf{v}\,\tilde{s})(A[P \mid !\operatorname{ch}(\tilde{s}).P \mid R]_{\sigma_{A}} \mid B[Q \mid S]_{\sigma_{B}})$
 $A[s \triangleright \Sigma_{i}\operatorname{op}_{i}\langle y_{i}\rangle.P_{i} \mid R]_{\sigma_{A}} \mid B[s \lhd \operatorname{op}_{j}\langle V\rangle Q \mid S]_{\sigma_{B}}$
 $ightharpoonup A[P_{i} \mid R]_{\sigma_{A}[y \mapsto V]} \mid B[Q \mid S]_{\sigma_{B}}$

$$P ::= !\operatorname{ch}(\tilde{s}).P \mid \overline{\operatorname{ch}}(v\,\tilde{s}).P \mid s \triangleright \Sigma_{i}\operatorname{op}_{i}\langle y_{i}\rangle.P_{i} \mid s \triangleleft \operatorname{op}\langle e\rangle.P$$

$$\mid x := e.P \mid \text{if } e \text{ then } P_{1} \text{ else } P_{2} \mid P \oplus Q$$

$$\mid P \mid Q \mid (v\,s)P \mid X \mid \operatorname{rec} X.P \mid \mathbf{0}$$

$$M ::= A[P]_{\sigma} \mid M_{1} \mid M_{2} \mid (v\,s)M \mid \mathbf{0}$$

$$A[!\operatorname{ch}(\tilde{s}).P | R]_{\sigma_{A}} | B[\overline{\operatorname{ch}}(v \, \tilde{s}).Q | S]_{\sigma_{B}}$$

$$\to (v \, \tilde{s})(A[P | !\operatorname{ch}(\tilde{s}).P | R]_{\sigma_{A}} | B[Q | S]_{\sigma_{B}})$$
 $A[s \rhd \Sigma_{i}\operatorname{op}_{i}\langle y_{i}\rangle.P_{i} | R]_{\sigma_{A}} | B[s \lhd \operatorname{op}_{j}\langle V\rangle Q | S]_{\sigma_{B}}$

$$\to A[P_{i} | R]_{\sigma_{A}[y \mapsto V]} | B[Q | S]_{\sigma_{B}}$$

$$P ::= !\operatorname{ch}(\tilde{s}).P \mid \overline{\operatorname{ch}}(v\,\tilde{s}).P \mid s \rhd \Sigma_{i}\operatorname{op}_{i}\langle y_{i}\rangle.P_{i} \mid s \lhd \operatorname{op}\langle e\rangle.P$$

$$\mid x := e.P \mid \text{if } e \text{ then } P_{1} \text{ else } P_{2} \mid P \oplus Q$$

$$\mid P \mid Q \mid (v\,s)P \mid X \mid \operatorname{rec} X.P \mid \mathbf{0}$$

$$M ::= A[P]_{\sigma} \mid M_{1} \mid M_{2} \mid (v\,s)M \mid \mathbf{0}$$

$$A[!\operatorname{ch}(\tilde{s}).P | R]_{\sigma_{A}} | B[\overline{\operatorname{ch}}(v \, \tilde{s}).Q | S]_{\sigma_{B}}$$

$$\to (v \, \tilde{s})(A[P | !\operatorname{ch}(\tilde{s}).P | R]_{\sigma_{A}} | B[Q | S]_{\sigma_{B}})$$

$$A[s \triangleright \Sigma_{i} \operatorname{op}_{i} \langle y_{i} \rangle.P_{i} | R]_{\sigma_{A}} | B[s \triangleleft \operatorname{op}_{j} \langle V \rangle Q | S]_{\sigma_{B}}$$

$$\to A[P_{i} | R]_{\sigma_{A}[y \mapsto V]} | B[Q | S]_{\sigma_{B}}$$

End-Point Calculus: syntax & reduction

$$P ::= !\operatorname{ch}(\tilde{s}).P \mid \overline{\operatorname{ch}}(v\,\tilde{s}).P \mid s \rhd \Sigma_{i}\operatorname{op}_{i}\langle y_{i}\rangle.P_{i} \mid s \lhd \operatorname{op}\langle e\rangle.P$$

$$\mid x := e.P \mid \text{if } e \text{ then } P_{1} \text{ else } P_{2} \mid P \oplus Q$$

$$\mid P \mid Q \mid (v\,s)P \mid X \mid \operatorname{rec} X.P \mid \mathbf{0}$$

$$M ::= A[P]_{\sigma} \mid M_{1} \mid M_{2} \mid (v\,s)M \mid \mathbf{0}$$

Reduction rules (part):

$$A[!\operatorname{ch}(\tilde{s}).P | R]_{\sigma_{A}} | B[\overline{\operatorname{ch}}(v \, \tilde{s}).Q | S]_{\sigma_{B}}$$

$$\to (v \, \tilde{s})(A[P | !\operatorname{ch}(\tilde{s}).P | R]_{\sigma_{A}} | B[Q | S]_{\sigma_{B}})$$
 $A[s \rhd \Sigma_{i} \operatorname{op}_{i} \langle y_{i} \rangle.P_{i} | R]_{\sigma_{A}} | B[s \lhd \operatorname{op}_{j} \langle V \rangle Q | S]_{\sigma_{B}}$

$$\to A[P_{i} | R]_{\sigma_{A}[y \mapsto V]} | B[Q | S]_{\sigma_{B}}$$

End-Point Calculus: typing (1)

Session types: as before.

$$\alpha ::= s \triangleright \Sigma_i \langle \mathsf{op_i}, \theta_i \rangle. \ \alpha_i \mid s \blacktriangleleft \Sigma_i \langle \mathsf{op_i}, \theta_i \rangle. \ \alpha_i$$
$$\mid \alpha_1 \mid \alpha_2 \mid \mathbf{rec} \ t. \alpha \mid t \mid \mathbf{end}$$

Typing: standard session typing with multiple session channels, with the initialisation rule:

(INIT)
$$\frac{\Gamma \vdash_A P \triangleright \tilde{s} : \alpha}{\Gamma, ch@A : (\tilde{s})\alpha \vdash_A ! ch(\tilde{s}) . P \triangleright \emptyset}$$

Properties: Subject Reduction, Communication Error Freedom, Minimal Typing w.r.t. session subtyping, ...

End-Point Calculus: Typing (2)

A term:

$$B[!\mathbf{b}(s_1s_2).s_1 \rhd [go. s_2 \lhd ok.\mathbf{0} + stop. s_2 \lhd no.\mathbf{0}]]$$

can be given a typing (ϵ is the empty string):

$$\mathbf{b}@B: (s_1s_2) \ s_1 \blacktriangleright \begin{bmatrix} \langle \mathsf{go}, \varepsilon \rangle. \ s_2 \blacktriangleleft \langle \mathsf{ok}, \varepsilon \rangle. \ \mathbf{end} \\ + \\ \langle \mathsf{stop}, \varepsilon \rangle. \ s_2 \blacktriangleleft \langle \mathsf{no}, \varepsilon \rangle. \ \mathbf{end} \end{bmatrix}$$

This is the minimal typing (the **green** part can be taken off by subtyping).

Formalising EPP

EPP projects a global description to multiple end-points:

$$(I, \sigma) \mapsto A[P]_{\sigma@A} \mid B[Q]_{\sigma@B} \mid C[R]_{\sigma@C} \mid \cdots$$

Desirable properties:

- Type preservation: the typing is preserved through EPP.
- Soundness: nothing but behaviours in I are in its EPP.
- Completeness: all behaviours in I are in its EPP.

Three descriptive principles guarantee them.

Three Principles

Well-structuredness conditions for global descriptions.

- 1. Connectedness: Basic local causality principle.
- 2. Well-threadedness: Stronger local causality principle based on session types (by which we can consistently extract a thread of local actions from a global code).
- 3. Coherence: Consistency among descriptions for a single code scattered over a global description.

All three properties can be efficiently (in)validated.

Descriptive Principle (1): Connectedness

First observed by Ross-Talbot (2004).

Bad...

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s)$$
.

$$\mathbf{A} \rightarrow \mathbf{B} : s\langle go \rangle$$
.

$$\mathbf{C} \rightarrow \mathbf{D} : t \langle \mathsf{hello} \rangle$$
.

• • •

Good...

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s)$$
.

$$\mathbf{A} \rightarrow \mathbf{B} : s\langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{C} : \mathbf{c}(t).$$

Descriptive Principle (1): Connectedness

First observed by Ross-Talbot (2004).

Bad...

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s)$$
.

$$\mathbf{A} \rightarrow \mathbf{B} : s\langle go \rangle$$
.

$$\mathbf{C} \rightarrow \mathbf{D} : t \langle \mathsf{hello} \rangle$$
.

. . .

Good...

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s).$$

$$\mathbf{A} \rightarrow \mathbf{B} : s\langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{C} : \mathbf{c}(t).$$

Desc. Principle (2): Well-Threadedness

Bad...

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s)$$
.

$$\mathbf{A} \rightarrow \mathbf{B} : s\langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{C} : \mathbf{c}(t)$$
.

$$\mathbf{C} \rightarrow \mathbf{A} : \mathbf{a}(r).$$

$$\mathbf{A} \rightarrow \mathbf{C} : r\langle \mathsf{hi} \rangle$$
.

$$\mathbf{C} \rightarrow \mathbf{A} : r\langle \mathsf{hi} \rangle$$
.

$$\mathbf{A} \rightarrow \mathbf{B} : s\langle \mathsf{hello} \rangle$$

. . .

Good...

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s)$$
.

$$\mathbf{A} \rightarrow \mathbf{B} : s\langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{C} : \mathbf{c}(t)$$
.

$$\mathbf{C} \rightarrow \mathbf{A} : \mathbf{a}(r).$$

$$\mathbf{A} \rightarrow \mathbf{C} : r\langle \mathsf{hi} \rangle$$
.

$$\mathbf{C} \rightarrow \mathbf{B} : t\langle \mathsf{acc} \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s\langle \mathsf{ok} \rangle$$
.

Desc. Principle (2): Well-Threadedness

Bad...

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s)$$
.

$$\mathbf{A} \rightarrow \mathbf{B} : s\langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{C} : \mathbf{c}(t)$$
.

$$\mathbf{C} \rightarrow \mathbf{A} : \mathbf{a}(r).$$

$$\mathbf{A} \rightarrow \mathbf{C} : r\langle \mathsf{hi} \rangle$$
.

$$\mathbf{C} \rightarrow \mathbf{A} : r\langle \mathsf{hi} \rangle$$
.

$$\mathbf{A} \rightarrow \mathbf{B} : s\langle \mathsf{hello} \rangle$$
.

. . .

Good...

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s)$$
.

$$\mathbf{A} \rightarrow \mathbf{B} : s\langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{C} : \mathbf{c}(t).$$

$$\mathbf{C} \rightarrow \mathbf{A} : \mathbf{a}(r).$$

$$\mathbf{A} \rightarrow \mathbf{C} : r\langle \mathsf{hi} \rangle$$
.

$$\mathbf{C} \rightarrow \mathbf{B} : t\langle \mathsf{acc} \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s\langle \mathsf{ok} \rangle$$
.

Projecting Threads (1)

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s)$$
.

$$\mathbf{A} \rightarrow \mathbf{B} : s\langle \mathsf{go} \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{C} : \mathbf{c}(t).$$

$$\mathbf{C} \rightarrow \mathbf{A} : \mathbf{a}(r).$$

$$\mathbf{A} \rightarrow \mathbf{C} : r\langle \mathsf{hi} \rangle$$
.

$$\mathbf{C} \rightarrow \mathbf{A} : r\langle \mathsf{hi} \rangle$$
.

$$\mathbf{A} \rightarrow \mathbf{B} : s\langle \mathsf{hello} \rangle$$
.

$$\mathbf{A} \begin{bmatrix} \overline{\mathbf{b}}(s).s \lhd go.\underline{s} \lhd hello.P \\ !\mathbf{a}(r).r \lhd hi.r \rhd hi.P' \end{bmatrix}$$

$$\mathbf{B} \left[\begin{array}{c} !\mathbf{b}(s). \ s \triangleright \mathsf{go}. \\ \overline{\mathbf{c}}(t). \ \underline{s} \triangleright \mathsf{hello}. Q \end{array} \right]$$

C [
$$!\mathbf{c}(t).\overline{\mathbf{a}}(r).r \triangleright \mathsf{hi}.r \triangleleft \mathsf{hi}.S$$
]

Projecting Threads (2)

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s)$$
.

$$\mathbf{A} \rightarrow \mathbf{B} : s\langle \mathsf{go} \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{C} : \mathbf{c}(t).$$

$$\mathbf{C} \rightarrow \mathbf{A} : \mathbf{a}(r).$$

$$\mathbf{A} \rightarrow \mathbf{C} : r\langle \mathsf{hi} \rangle$$
.

$$\mathbf{C} \rightarrow \mathbf{B} : t\langle \mathsf{acc} \rangle.$$

$$\mathbf{B} \rightarrow \mathbf{A} : s\langle \mathsf{ok} \rangle.$$

$$\mathbf{A} \left[\begin{array}{c} \overline{\mathbf{b}}(s). s \lhd \mathsf{go}. s \rhd \mathsf{ok}. P \\ !\mathbf{a}(r). r \lhd \mathsf{hi}. P' \end{array} \right]$$

$$\mathbf{B} \left[\begin{array}{c} !\mathbf{b}(s). \ s \rhd \mathsf{go}. \\ \overline{\mathbf{c}}(t). \ t \rhd \mathsf{acc}.s \lhd \mathsf{ok}.Q \end{array} \right]$$

C [
$$!$$
c (t) . $\overline{\mathbf{a}}(r)$. $r > \text{hi.} t < \text{acc.} S$]

Descriptive Principle (3): Coherence

Bad...

if x@A then

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s_1 s_2).$$

$$\mathbf{A} \rightarrow \mathbf{B} : s_1 \langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s_2 \langle \mathsf{ok} \rangle. \mathbf{0}$$

else

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s_1 s_2).$$

$$\mathbf{A} \rightarrow \mathbf{B} : s_1 \langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s_2 \langle \mathsf{no} \rangle$$
. **0**

end

Good...

if x@A then

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s_1 s_2).$$

$$\mathbf{A} \rightarrow \mathbf{B} : s_1 \langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s_2 \langle \mathsf{ok} \rangle. \mathbf{0}$$

else

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s_1 s_2).$$

$$\mathbf{A} \rightarrow \mathbf{B} : s_1 \langle \mathsf{stop} \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s_2 \langle \mathsf{no} \rangle$$
. **0**

end

Descriptive Principle (3): Coherence

Bad...

if x@A then

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s_1 s_2).$$

$$\mathbf{A} \rightarrow \mathbf{B} : s_1 \langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s_2 \langle \mathsf{ok} \rangle. \mathbf{0}$$

else

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s_1 s_2).$$

$$\mathbf{A} \rightarrow \mathbf{B} : s_1 \langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s_2 \langle \mathsf{no} \rangle$$
. **0**

end

Good...

if x@A then

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s_1 s_2).$$

$$\mathbf{A} \rightarrow \mathbf{B} : s_1 \langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s_2 \langle \mathsf{ok} \rangle. \mathbf{0}$$

else

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s_1 s_2).$$

$$\mathbf{A} \rightarrow \mathbf{B} : s_1 \langle \mathsf{stop} \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s_2 \langle \mathsf{no} \rangle$$
. **0**

end

Descriptive Principle (3): Coherence

Bad...

if x@A then

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s_1 s_2).$$

$$\mathbf{A} \rightarrow \mathbf{B} : s_1 \langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s_2 \langle \mathsf{ok} \rangle. \mathbf{0}$$

else

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s_1 s_2).$$

$$\mathbf{A} \rightarrow \mathbf{B} : s_1 \langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s_2 \langle \mathsf{no} \rangle$$
. **0**

end

Good...

if x@A then

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s_1 s_2).$$

$$\mathbf{A} \rightarrow \mathbf{B} : s_1 \langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s_2 \langle \mathsf{ok} \rangle. \mathbf{0}$$

else

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s_1 s_2).$$

$$\mathbf{A} \rightarrow \mathbf{B} : s_1 \langle \mathsf{stop} \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s_2 \langle \mathsf{no} \rangle$$
. **0**

end

Merging Coherent Threads

We project each branch onto **B** and merge the results.

if x@A then

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s_1 s_2).$$

$$\mathbf{A} \rightarrow \mathbf{B} : s_1 \langle go \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s_2 \langle \mathsf{ok} \rangle.\mathbf{0}$$

else

$$\mathbf{A} \rightarrow \mathbf{B} : \mathbf{b}(s_1 s_2).$$

$$\mathbf{A} \rightarrow \mathbf{B} : s_1 \langle \mathsf{stop} \rangle$$
.

$$\mathbf{B} \rightarrow \mathbf{A} : s_2 \langle \mathsf{no} \rangle. \mathbf{0}$$

end

if-branch.

$$!\mathbf{b}(s_1s_2). \ s_1 \triangleright \mathsf{go}. \ s_2 \triangleleft \mathsf{ok}. \ \mathbf{0}$$

else-branch.

$$!$$
b(s_1s_2). s_1 >stop. s_2 < no. **0**

merging the two.

$$\mathbf{!b}(s_1s_2). \ s_1 \rhd \begin{bmatrix} \mathsf{go.} \ s_2 \lhd \mathsf{ok.} \ \mathbf{0} + \\ \mathsf{stop.} \ s_2 \lhd \mathsf{no.} \ \mathbf{0} \end{bmatrix}$$

Three Principles: Summary

Definition. A term *I* in the global calculus is:

- 1. *Connected* if, in each prefix, either we have (1) e.g. $A \rightarrow B$; $A \rightarrow B$; or (2) e.g. $A \rightarrow B$; $B \rightarrow C$.
- 2. Well-threaded if it has a consistent colouring.
- 3. *Coherent* if its two threads for the same subject are always compatible.

A typable *I* is *well-formed* if it satisfies all three conditions.

A well-formed *I* is *annotated* if it is appropriately coloured.

EPP: Definition

Definition. Let I be well-formed, be annotated and does not contain hiding. Let $((v\tilde{s})I, \sigma)$ be well-typed. We set:

$$\begin{split} \operatorname{Epp}((\operatorname{v}\,\widetilde{s})I,\sigma) &\stackrel{\operatorname{def}}{=} (\operatorname{v}\,\widetilde{s}) \; \Pi_{A \in \operatorname{part}(I)} A [\operatorname{epp}(I,A)]_{\sigma@A} \\ &\operatorname{epp}(I,A) \stackrel{\operatorname{def}}{=} \Pi_{g \in \operatorname{tg}(I,A)} \operatorname{merge}(\{\operatorname{tp}(I,i) \mid i \in g\}) \end{split}$$

where tg(I,A) are thread groups for A: and tp(I,i) projects I onto the i-th thread.

Pruning

Definition. (pruning)

 $P \ll Q | !R$ when (1) $\Gamma \vdash_{\min} P$, $\Gamma \vdash Q$ and $\operatorname{fn}(Q) \cap \operatorname{sbj}(!R) = \emptyset$;

(2) Cutting off Q's input branches not in Γ coincides with P.

Pruning

Definition. (pruning)

 $P \ll Q | !R \text{ when } (1) \Gamma \vdash_{\min} P, \Gamma \vdash Q \text{ and } \operatorname{fn}(Q) \cap \operatorname{sbj}(!R) = \emptyset;$

(2) Cutting off Q's input branches not in Γ coincides with P.

E.g.
$$!\mathbf{b}(s).s \triangleright go.P_1 \mid \overline{\mathbf{b}}(s).s \triangleleft go.Q \ll |\mathbf{b}(s).s \triangleright [go.P_1 + stop.P_2] \mid \overline{\mathbf{b}}(s).s \triangleleft go.Q \mid !R$$

Pruning

Definition. (pruning)

 $P \ll Q | !R \text{ when } (1) \Gamma \vdash_{\min} P, \Gamma \vdash Q \text{ and } \operatorname{fn}(Q) \cap \operatorname{sbj}(!R) = \emptyset;$

(2) Cutting off Q's input branches not in Γ coincides with P.

E.g.
$$!\mathbf{b}(s).s \triangleright go.P_1 \mid \overline{\mathbf{b}}(s).s \triangleleft go.Q \ll |\mathbf{b}(s).s \triangleright [go.P_1 + stop.P_2] \mid \overline{\mathbf{b}}(s).s \triangleleft go.Q \mid !R$$

Lemma. (pruning lemma)

(1) The relation \ll is a strong bisimulation if we do not count visible actions at pruned inputs. (2) \ll is transitive.

EPP Theorem

Theorem. Assume *I* is well-formed and $\Gamma \vdash \sigma$. Then:

- 1. $\Gamma \vdash_{\min} I \text{ implies } \Gamma \vdash_{\min} \text{Epp}(I, \sigma).$
- 2. $(I, \sigma) \to (I', \sigma')$ implies $\text{Epp}(I, \sigma) \to M \gg \text{Epp}(I', \sigma')$.
- 3. $\operatorname{Epp}(I, \sigma) \to M$ implies $(I, \sigma) \to (I', \sigma')$ s.t. $\operatorname{Epp}(I', \sigma') \ll M$.

Corollary. If $\Gamma \vdash I$ is well-formed and $\Gamma \vdash \sigma$:

- 1. $\text{Epp}(I, \sigma)$ never goes wrong.
- 2. $(I, \sigma) \rightarrow^n (I', \sigma')$ implies $\text{Epp}(I, \sigma) \rightarrow^n M \gg \text{Epp}(I', \sigma')$. Conversely $\text{Epp}(I, \sigma) \rightarrow^n M$ implies $(I, \sigma) \rightarrow^n (I', \sigma')$ such that $\text{Epp}(I', \sigma') \ll M$.

So what does EPP theorem means?

We first write down a global description and ...

- Produce a prototype code (only communication behaviour).
- Produce a full application.
- Produce a run-time monitor.
- Do a debugging (how is everybody behaving?)
- Do a conformance checking (can we really use that web service for this protocol?)
- Do a conformance checking for team programming (is my code conformant to a global specification?).

Conformance (for safety)

- 1. We say *P conforms to Q* when *Q* weakly simulates *P*, i.e. all visible typed communication behaviours of *P* can be simulated by those of *Q*.
- 2. We say P conforms to I at A when P conforms to $ext{epp}(I,A)$ (up to the minimum type of the latter).
- 3. We can use model checking, syntactic approximation, hand calculation (coinduction), ... to validate or invalidate conformance.

CDL Requirements and EPP

C-CSF-007: To be successful a CDL description MUST be verifiable at runtime.

→ Use LTS and process equivalence via EPP.

C-CSF-008: To be successful a CDL description MUST enable static verification of correctness properties.

⇒ Use types and logics for processes via EPP.

Current Status

- The current implementation of EPP in the pi4soa tool is independently designed by Gary Brown, and closely follows the presented framework.
- The implementation of a formally-based EPP is currently underway for the pi4soa code base.
- ➤ A W3C working note presenting an EPP theory is planned, augmenting the WS-CDL 1.0 specification.

References

- ➤ [Bhargavan/Fournet/Gordon 2006] Verification of web service secruity.
- ➤ [Laneve/Padovani 2006] Analysis of orchastration.
- ➤ [Busi et al. 2006] Conformance check in web service (between choreographies and orchestration).

The technical paper on the presented material:

http://www.doc.ic.ac.uk/~yoshida/tic

Conclusion

Part 1 Basic Theory (Processes and Types)

- \triangleright The π -Calulus
- Idioms for Interactions
- Session Types

Part 2 Web Services and the π -Calculus

- Web Services Choreography Description Language
- Global Language and the End-Point Calculus
- Correctness