

Verilog HDL (3)

Hsi-Pin Ma

<http://lms.nthu.edu.tw/course/21094>

Department of Electrical Engineering
National Tsing Hua University

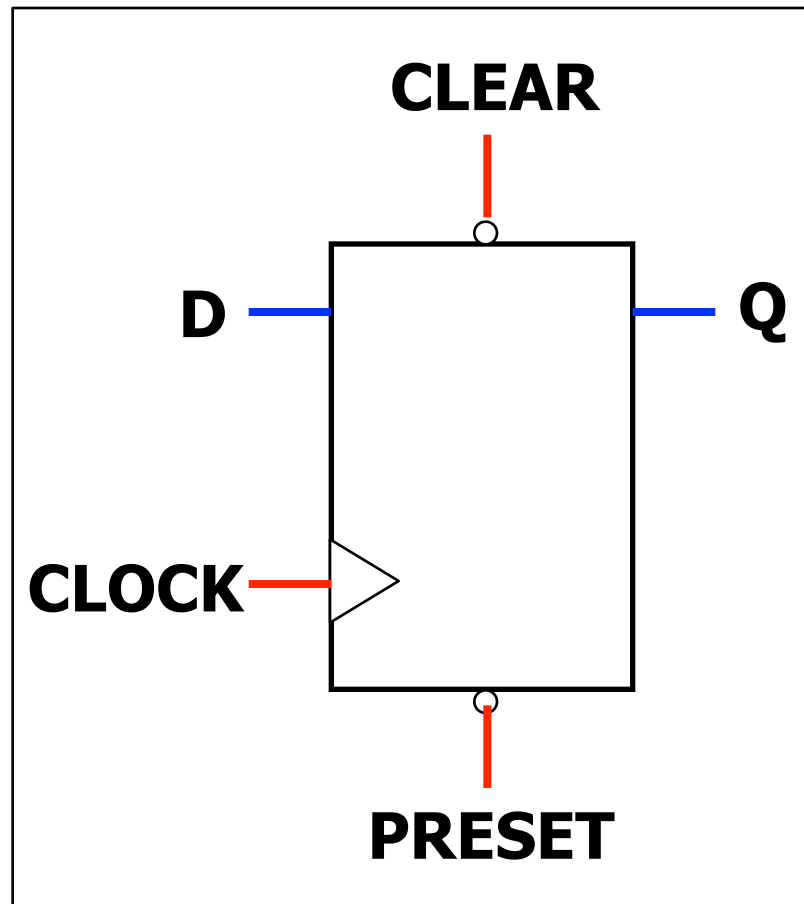
Behavior Modeling

At every positive edge of CLOCK

If PRESET and CLEAR are not low
set Q to the value of D

Whenever PRESET goes low
set Q to logic 1

Whenever CLEAR goes low
set Q to logic 0

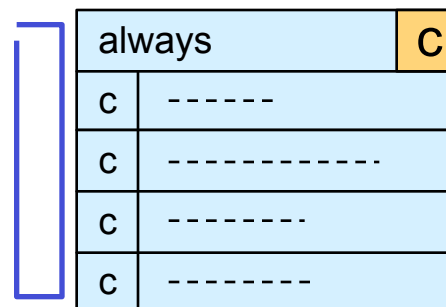
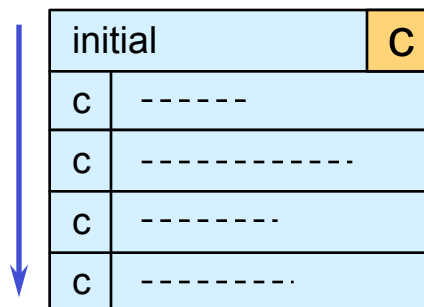


Behavior Modeling

- In behavior modeling, you must specify your circuit's
 - Action
 - How to model the circuit's behavior
 - Timing control
 - Timing
 - Condition
- Verilog supports the following structures for behavior modeling
 - Procedural block
 - Procedural assignment
 - Timing control
 - Control statement

Procedural Blocks

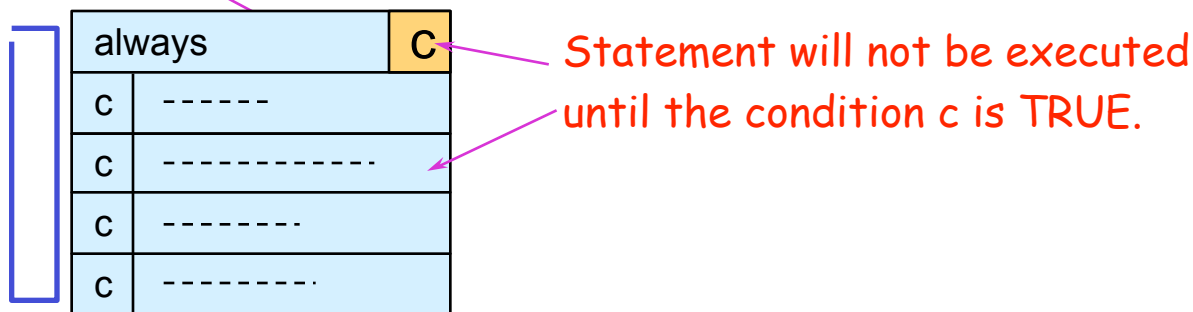
- In Verilog, procedural blocks are basis of behavior modeling
- Procedural blocks are of two types
 - initial procedural block, which execute only once
 - always procedural block, which execute in a loop



Procedural Blocks

- All procedural blocks are activated at simulation time 0.
 - The block will not be executed until the enabling condition evaluates TRUE.
 - Without the enabling condition, the block will be executed immediately.

Activated at simulation time 0



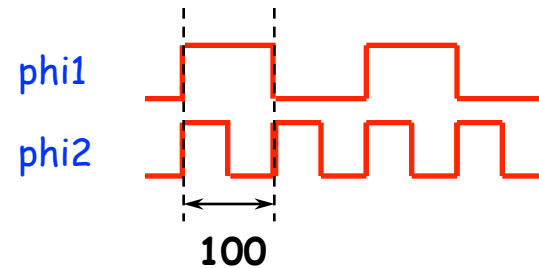
Procedural Blocks

```
module clock_gen(phi1,phi2);  
output    phi1,phi2;  
reg phi1,phi2;
```

```
initial  
begin  
    phi1=0;phi2=0  
end
```

```
always  
    #100 phi1=~phi1;
```

```
always    @(posedge phi1)  
begin  
    phi2=1;  
    #50    phi2=0;  
    #50    phi2=1;  
    #50    phi2=0;  
end  
endmodule
```



These procedural blocks are activated and executed at simulation time 0

This procedural block is activated at simulation time 0 but executed at positive edge of phi1

Procedural Blocks

- Three components
 - Procedural assignment statements
 - High-level programming language constructs
 - Timing controls
- Using the first two components to model the actions of the circuit.
- Using timing controls to model when should these actions happen.

Procedural Timing Control

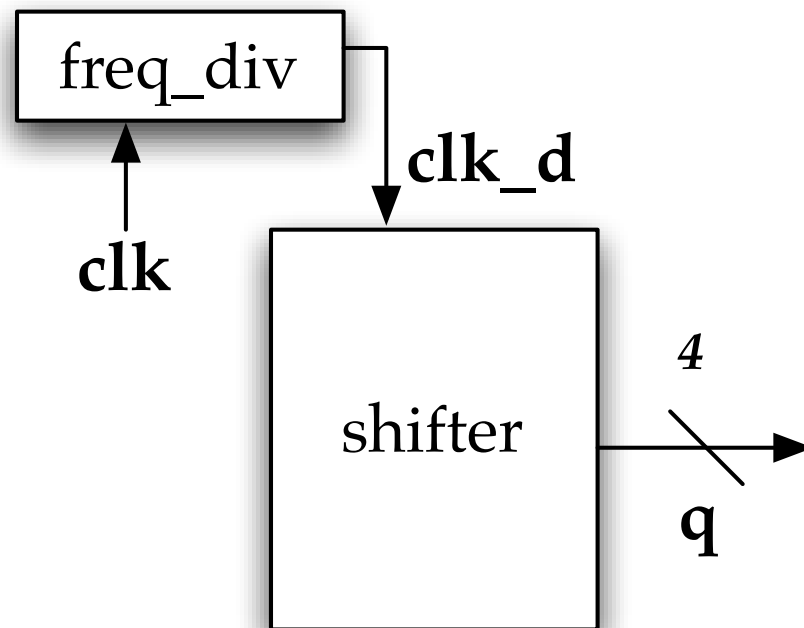
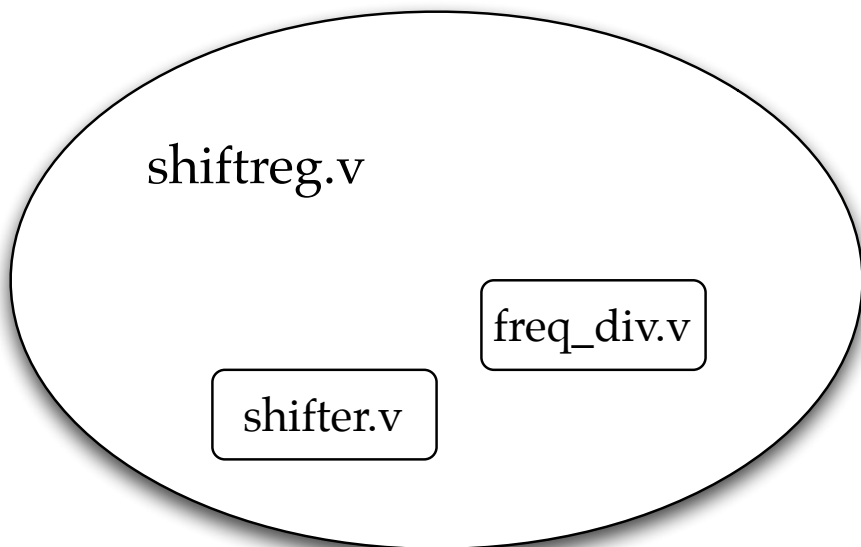
- Three types
 - Simple delay control
 - #50 clk=~clk;
 - Event control
 - @(a or b or ci) sum=a+b+ci;
 - @(posedge clk) q=d;
 - Level-sensitive timing control



Modularized Shift Register Design

Shift Register

Shift Register



```

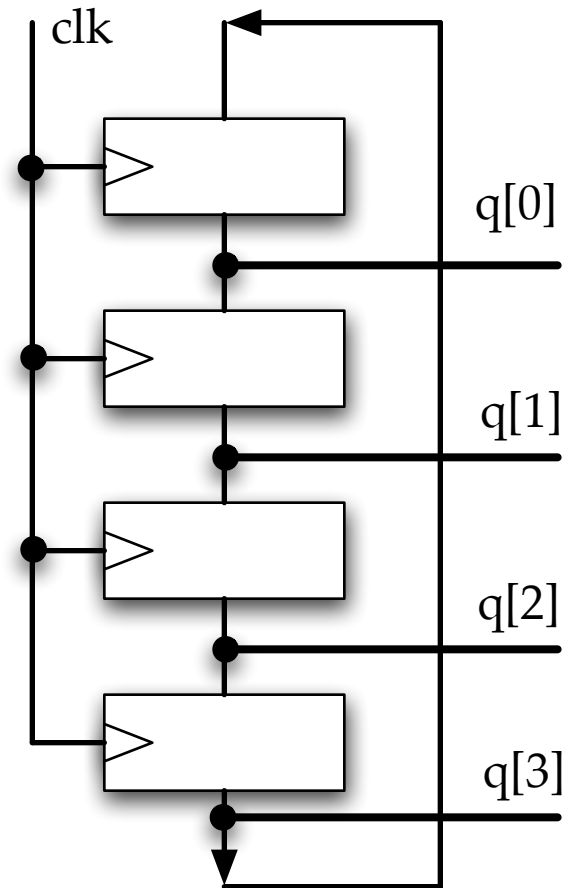
`define BIT_WIDTH 4
module shifter(
  q, // shifter output
  clk, // global clock
  rst_n // active low reset
);

output [`BIT_WIDTH-1:0] q; // output
input clk; // global clock
input rst_n; // active low reset

reg [`BIT_WIDTH-1:0] q; // output

// Sequential logics: Flip flops
always @(posedge clk or negedge rst_n)
  if (~rst_n)
    begin
      q<=`BIT_WIDTH'b0101;
    end
    else
    begin
      q[0]<=q[3];
      q[1]<=q[0];
      q[2]<=q[1];
      q[3]<=q[2];
    end
endmodule
  
```

shifter.v



shiftreg.v

```
`define BIT_WIDTH 4
module shift_reg(
    q, // LED output
    clk, // global clock
    rst_n // active low reset
);

output [`BIT_WIDTH-1:0] q; // LED output
input clk; // global clock
input rst_n; // active low reset

wire clk_d; // divided clock
wire [`BIT_WIDTH-1:0] q; // LED output
```

1

```
// Insert frequency divider (freq_div.v)
freq_div U_FD(
    .clk_out(clk_d), // divided clock output
    .clk(clk), // clock from the crystal
    .rst_n(rst_n) // active low reset
);

// Insert shifter (shifter.v)
shifter U_D(
    .q(q), // shifter output
    .clk(clk_d), // clock from the frequency divider
    .rst_n(rst_n) // active low reset
);

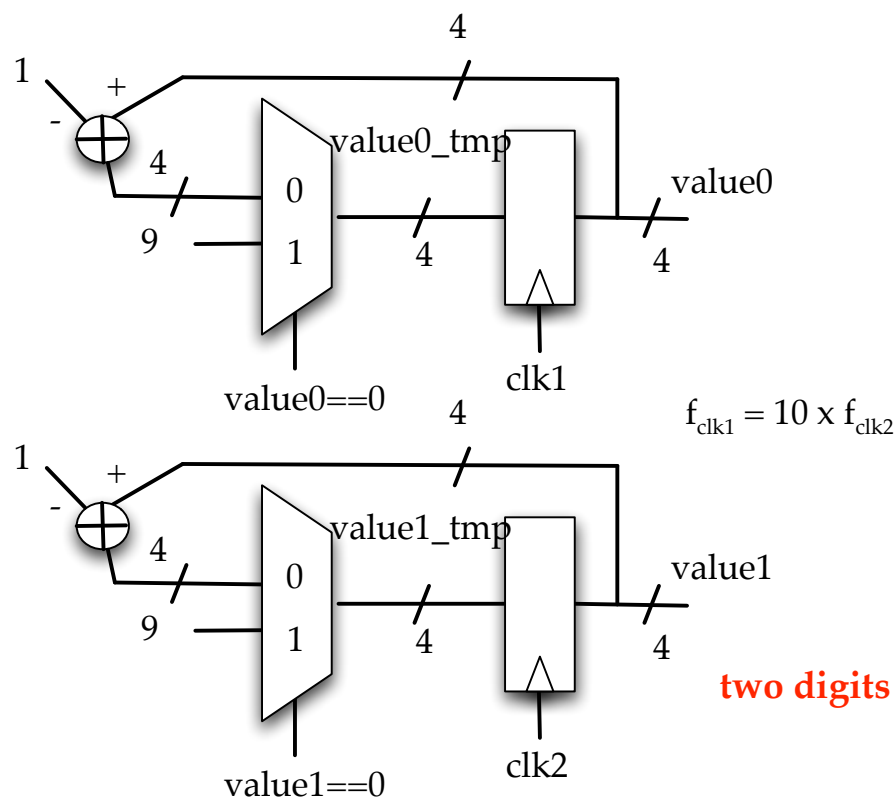
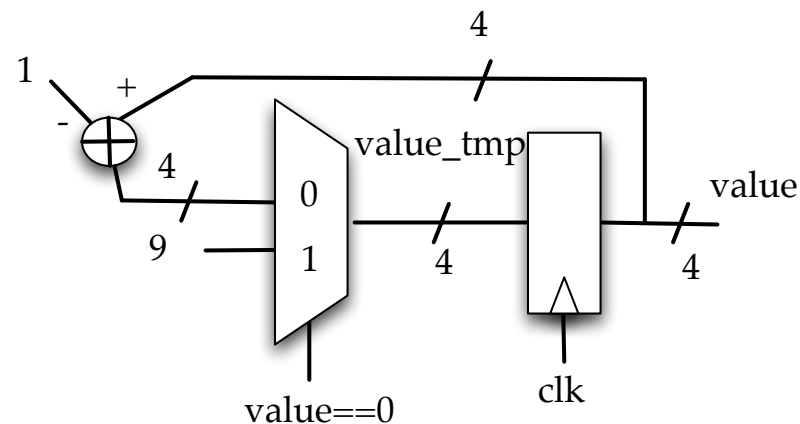
endmodule
```

2

Modulized BCD Down Counter

BCD Down-Counter

single digit



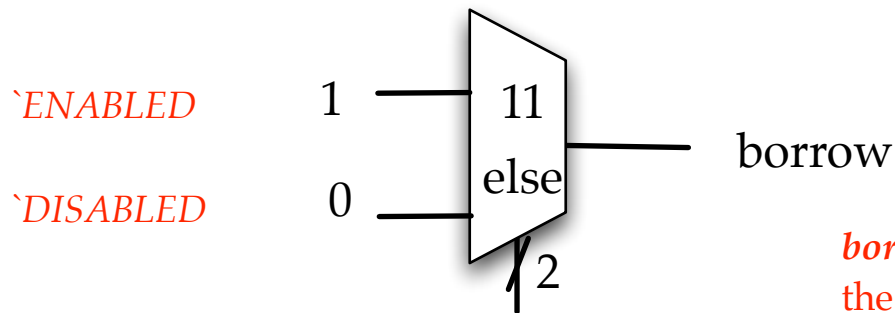
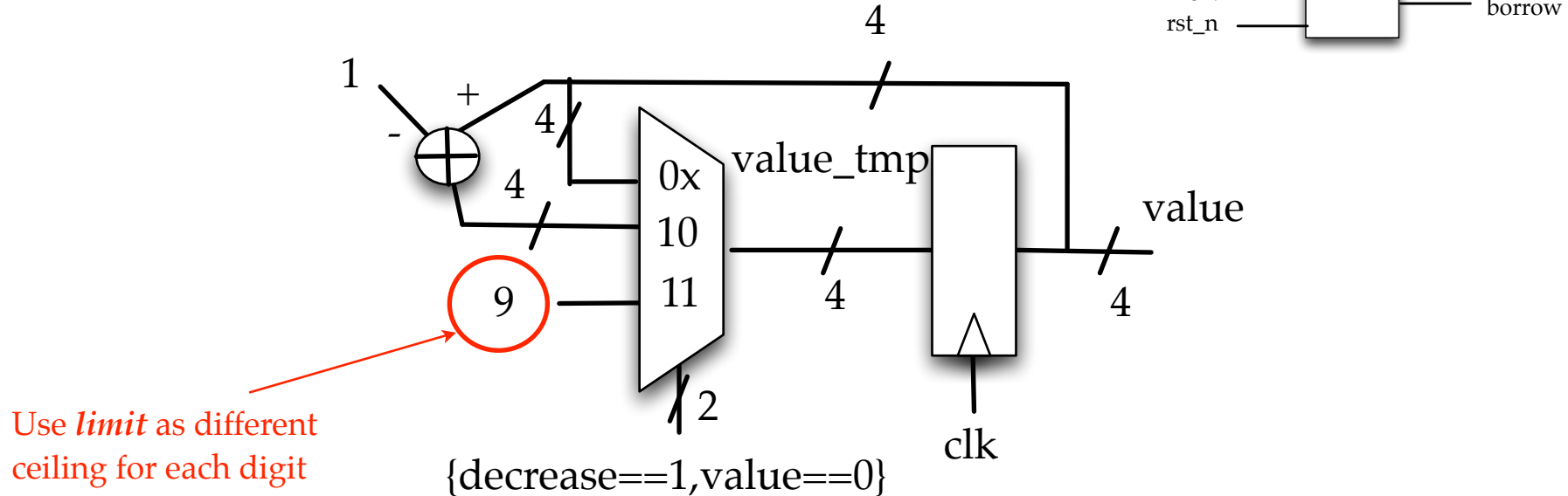
two digits

```
// Combinational logics
always @*
  if (value==`BCD_ZERO)
    value_tmp = `BCD_NINE;
  else
    value_tmp = value - `INCREMENT;

// register part for BCD counter
always @(posedge clk or negedge rst_n)
  if (~rst_n) value <= `BCD_ZERO;
  else value <= value_tmp;
```

BCD Down-Counter

How to use one single clock for different digit counting?



$\{decrease==1, value==0\}$

borrow signal in lower digit is the *decrease* control in the upper digit

BCD Down-Counter

```

module dncounter(
    value, // counter output
    borrow, // borrow indicator
    clk, // global clock
    rst_n, // active low reset
    decrease, // counter enable control
    limit // limit for the counter
);
... ..
// Combinational logics
always @*
    if (value==`BCD_ZERO && decrease)
        begin
            value_tmp = limit;
            borrow = `ENABLED;
        end
    else if (value!=`BCD_ZERO && decrease)
        begin
            value_tmp = value - `INCREMENT;
            borrow = `DISABLED;
        end
    else
        begin
            value_tmp = value;
            borrow = `DISABLED;
        end
end

```

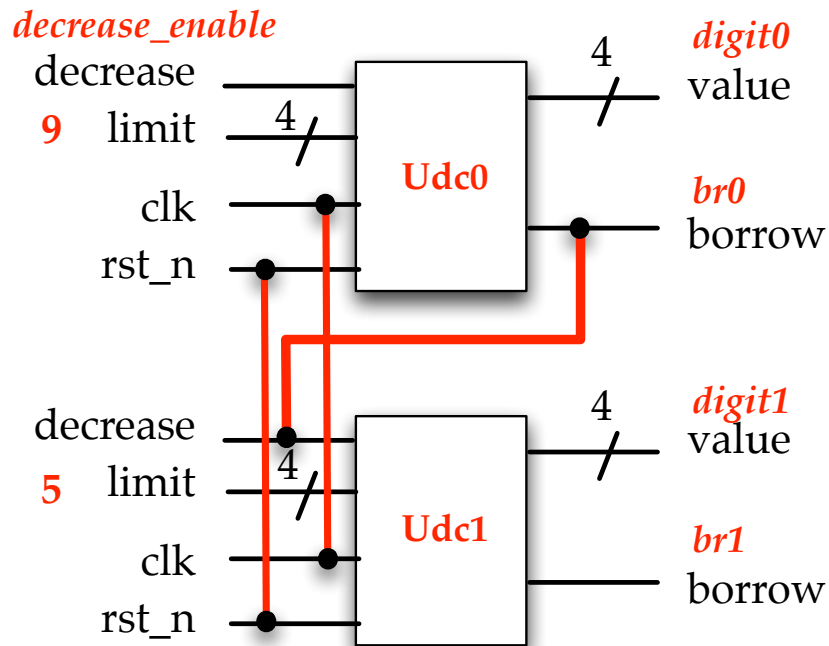
```

// register part for BCD counter
always @(posedge clk or negedge rst_n)
    if (~rst_n) value <= `BCD_ZERO;
    else value <= value_tmp;

endmodule

```

BCD Down-Counter



```
// 30 sec down counter
downcounter Udc0(
    .value(digit0), // counter value
    .borrow(br0), // borrow indicator
    .clk(clk), // global clock signal
    .rst_n(rst_n), // low active reset
    .decrease(decrease_enable), // counter enable control
    .limit(BCD_NINE) // limit for the counter
);

downcounter Udc1(
    .value(digit1), // counter value
    .borrow(br1), // borrow indicator
    .clk(clk), // global clock signal
    .rst_n(rst_n), // low active reset
    .decrease(br0), // counter enable control
    .limit(BCD_FIVE) // limit for the counter
);
```