DAC Func

DAC Func

Write a DAC example which have following features:

- · generate the wave
- based on TIMx and Interrupt

initialize the timer.

write a isr interrupt, and put the wave generate func inside.

产生波形

```
uint16_t DAC_data[];
u8 key;
void DAC_Channel1Init(void){
    DAC_Type()
}
```

波形种类

```
void Gen_Wave(u8 wave_mode, short volt_max, u16 wave[]){
    short i = 0;
    float temp;
    short temp2;
    switch(wave_mode){
        case Wave_sin:
            temp = 2*3.1415926/Dot_x;
            for(i=0;i<Dot_x;i++){
                  wave[i] = 0.5 * volt_max *(sin(temp*i)+1);
            }
            break;
        case Wave_Triangular:
    }
}</pre>
```

TIMER

Timer Initialization

```
An ESP32 timer group should be identified using timer_group_t.
```

```
typedef enum {
    TIMER_GROUP_0 = 0, /*!<Hw timer group 0*/
    TIMER_GROUP_1 = 1, /*!<Hw timer group 1*/
    TIMER_GROUP_MAX,
} timer_group_t;</pre>
```

An individual timer in a group should be identified with timer_idx_t.

```
typedef enum {
   TIMER_0 = 0, /*!<Select timer0 of GROUPx*/
   TIMER_1 = 1, /*!<Select timer1 of GROUPx*/
   TIMER_MAX,
} timer_idx_t;</pre>
```

The timer should be initialized by calling the function timer_init().

```
esp_err_t esp_timer_init(void)
    esp_err_t err;
    if (is_initialized()) {
        return ESP_ERR_INVALID_STATE;
#if CONFIG SPIRAM USE MALLOC
    memset(&s_timer_semaphore_memory, 0, sizeof(StaticQueue_t));
    s_timer_semaphore = xSemaphoreCreateCountingStatic(TIMER_EVENT_QUEUE_SIZE, 0,
&s_timer_semaphore_memory);
#else
    s_timer_semaphore = xSemaphoreCreateCounting(TIMER_EVENT_QUEUE_SIZE, 0);
#endif
    if (!s_timer_semaphore) {
        err = ESP_ERR_NO_MEM;
        goto out;
    int ret = xTaskCreatePinnedToCore(&timer task, "esp timer",
            ESP_TASK_TIMER_STACK, NULL, ESP_TASK_TIMER_PRIO, &s_timer_task, PRO_CPU_NUM);
    if (ret != pdPASS) {
        err = ESP_ERR_NO_MEM;
        goto out;
    err = esp_timer_impl_init(&timer_alarm_handler);
    if (err != ESP_OK) {
        goto out;
    return ESP_OK;
out:
    if (s_timer_task) {
        vTaskDelete(s_timer_task);
        s_timer_task = NULL;
    if (s_timer_semaphore) {
        vSemaphoreDelete(s_timer_semaphore);
        s_timer_semaphore = NULL;
    return ESP_ERR_NO_MEM;
}
```

//初始化tim,注册中断回调函数 //0.1um

Passing a structure timer_config_t to it to define how the timer should operate.

The following timer parameters can be set:

Timer Control

Once the timer is enabled, its counter starts running.

To enable the timer, call the function timer_init() with counter_en set to true, or call timer_start().

```
typedef enum {
   TIMER_0 = 0, /*!<Select timer0 of GROUPx*/
   TIMER_1 = 1, /*!<Select timer1 of GROUPx*/
   TIMER_MAX,
} timer_idx_t;</pre>
```

You can specify the timer's initial counter value by calling timer_set_counter_value()

```
typedef enum {
   TIMER_0 = 0, /*!<Select timer0 of GROUPx*/
   TIMER_1 = 1, /*!<Select timer1 of GROUPx*/
   TIMER_MAX,
} timer_idx_t;</pre>
```

To check the timer's current value, call timer_get_counter_value() or timer_get_counter_time_sec().

```
typedef enum {
   TIMER_0 = 0, /*!<Select timer0 of GROUPx*/
   TIMER_1 = 1, /*!<Select timer1 of GROUPx*/
   TIMER_MAX,
} timer_idx_t;</pre>
```

```
Pause the timer at any time, call timer_pause().
To resume it, call timer_start().
```

timer_group_example_main.c

```
/* Timer group-hardware timer example
   This example code is in the Public Domain (or CCO licensed, at your option.)
   Unless required by applicable law or agreed to in writing, this
```

```
software is distributed on an "AS IS" BASIS, WITHOUT WARRANTIES OR
   CONDITIONS OF ANY KIND, either express or implied.
#include <stdio.h>
#include "esp_types.h"
#include "freertos/FreeRTOS.h"
#include "freertos/task.h'
#include "freertos/queue.h"
#include "driver/periph_ctrl.h"
#include "driver/timer.h"
#define TIMER_DIVIDER
                                16 // Hardware timer clock divider
#define TIMER_SCALE
                                (TIMER_BASE_CLK / TIMER_DIVIDER) // convert counter value to seconds
                                (3.4179) // sample test interval for the first timer
#define TIMER_INTERVAL0_SEC
                                         // sample test interval for the second timer
// testing will be done without auto reload
#define TIMER_INTERVAL1_SEC
                                (5.78)
#define TEST_WITHOUT_RELOAD
                                0
                                          // testing will be done with auto reload
#define TEST_WITH_RELOAD
 * A sample structure to pass events
 * from the timer interrupt handler to the main program.
typedef struct {
    int type; // the type of timer's event
    int timer_group;
    int timer_idx;
    uint64 t timer counter value;
} timer_event_t;
xQueueHandle timer_queue;
 * A simple helper function to print the raw timer counter value
 * and the counter value converted to seconds
static void inline print_timer_counter(uint64_t counter_value)
    printf("Counter: 0x%08x%08x\n", (uint32_t) (counter_value >> 32),
                                       (uint32_t) (counter_value));
                  : %.8f s\n", (double) counter_value / TIMER_SCALE);
    printf("Time
}
 * Timer group0 ISR handler
 * Note:
 * We don't call the timer API here because they are not declared with IRAM_ATTR.
 * If we're okay with the timer irq not being serviced while SPI flash cache is disabled,
 * we can allocate this interrupt without the ESP INTR FLAG IRAM flag and use the normal API.
void IRAM ATTR timer group0 isr(void *para)
    int timer_idx = (int) para;
    /* Retrieve the interrupt status and the counter value
       from the timer that reported the interrupt */
    uint32_t intr_status = TIMERGO.int_st_timers.val;
    TIMERGO.hw_timer[timer_idx].update = 1;
uint64_t timer_counter_value =
        ((uint64_t) TIMERGO.hw_timer[timer_idx].cnt_high) << 32</pre>
         | TIMERGO.hw_timer[timer_idx].cnt_low;
    /* Prepare basic event data
       that will be then sent back to the main program task */
    timer_event_t evt;
    evt.timer_group = 0;
evt.timer_idx = timer_idx;
    evt.timer_counter_value = timer_counter_value;
    /* Clear the interrupt
       and update the alarm time for the timer with without reload */
    if ((intr_status & BIT(timer_idx)) && timer_idx == TIMER_0) {
        evt.type = TEST_WITHOUT_RELOAD;
        TIMERGO.int clr timers.t0 = 1;
        timer_counter_value += (uint64_t) (TIMER_INTERVAL0_SEC * TIMER_SCALE);
        TIMERGO.hw_timer[timer_idx].alarm_high = (uint32_t) (timer_counter_value >> 32);
TIMERGO.hw_timer[timer_idx].alarm_low = (uint32_t) timer_counter_value;
    } else if ((intr_status & BIT(timer_idx)) && timer_idx == TIMER_1) {
        evt.type = TEST_WITH_RELOAD;
        TIMERGO.int_clr_timers.t1 = 1;
```

```
} else {
        evt.type = -1; // not supported even type
    /* After the alarm has been triggered
      we need enable it again, so it is triggered the next time */
    TIMERGO.hw_timer[timer_idx].config.alarm_en = TIMER_ALARM_EN;
    /* Now just send the event data back to the main program task */
    xQueueSendFromISR(timer_queue, &evt, NULL);
}
 st Initialize selected timer of the timer group 0
 * timer_idx - the timer number to initialize
  auto_reload - should the timer auto reload on alarm?
 * timer_interval_sec - the interval of alarm to set
static void example_tg0_timer_init(int timer_idx,
    bool auto_reload, double timer_interval_sec)
    /* Select and initialize basic parameters of the timer */
    timer_config_t config;
    config.divider = TIMER_DIVIDER;
    config.counter_dir = TIMER_COUNT_UP;
    config.counter_en = TIMER_PAUSE;
    config.alarm en = TIMER ALARM EN;
    config.intr_type = TIMER_INTR_LEVEL;
    config.auto_reload = auto_reload;
    timer_init(TIMER_GROUP_0, timer_idx, &config);
    /* Timer's counter will initially start from value below.
       Also, if auto_reload is set, this value will be automatically reload on alarm */
    timer_set_counter_value(TIMER_GROUP_0, timer_idx, 0x00000000ULL);
    /* Configure the alarm value and the interrupt on alarm. */
timer_set_alarm_value(TIMER_GROUP_0, timer_idx, timer_interval_sec * TIMER_SCALE);
    timer_enable_intr(TIMER_GROUP_0, timer_idx);
    timer_isr_register(TIMER_GROUP_0, timer_idx, timer_group0_isr,
        (void *) timer_idx, ESP_INTR_FLAG_IRAM, NULL);
    timer_start(TIMER_GROUP_0, timer_idx);
}
 * The main task of this example program
static void timer_example_evt_task(void *arg)
    while (1) {
        timer event t evt;
        xQueueReceive(timer_queue, &evt, portMAX_DELAY);
        /st Print information that the timer reported an event st/
        if (evt.type == TEST_WITHOUT_RELOAD) {
                         Example timer without reload\n");
            printf("\n
        } else if (evt.type == TEST_WITH_RELOAD) {
            printf("\n
                          Example timer with auto reload\n");
          else {
            printf("\n
                          UNKNOWN EVENT TYPE\n");
        printf("Group[%d], timer[%d] alarm event\n", evt.timer_group, evt.timer_idx);
        /* Print the timer values passed by event */
        printf("----- EVENT TIME -----\n");
        print_timer_counter(evt.timer_counter_value);
        /* Print the timer values as visible by this task */
        printf("-----\n");
        uint64_t task_counter_value;
        timer_get_counter_value(evt.timer_group, evt.timer_idx, &task_counter_value);
        print_timer_counter(task_counter_value);
}
* In this example, we will test hardware timer0 and timer1 of timer group0.
void app_main()
```

```
timer_queue = xQueueCreate(10, sizeof(timer_event_t));
  example_tg0_timer_init(TIMER_0, TEST_WITHOUT_RELOAD, TIMER_INTERVAL0_SEC);
  example_tg0_timer_init(TIMER_1, TEST_WITH_RELOAD, TIMER_INTERVAL1_SEC);
  xTaskCreate(timer_example_evt_task, "timer_evt_task", 2048, NULL, 5, NULL);
}
```