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```
% ECE414 - Bayesian Machine Learning
% Authors : Junbum Kim, Andy Jeong
% Project 3 : Classification (Generative, IRLS)
% Date : October 30, 2019
% Reference : Pattern Recognition and Machine Learning
% by Chris. M. Bishop (2006)
clear all; close all; clc; warning('off','all');
```

#### **Equations**

## 1 Generative Model

Shared Covariance 
$$\Sigma = \pi \Sigma_1 * (1 - \pi) * \Sigma_2$$

where  $\pi = \text{class prior probability}$ 

Maximize for data points from each class:

$$p(x_n, C_i) = p(C_i)p(x_n|C_i) = \pi N(x_n|\mu_1.\Sigma)$$
  
Posterior:  $p(C_i|\phi) = y(\phi) = \sigma(w^T\phi)$ 

# 2 Iterative Reweighted Least Squares (IRLS)

$$\text{Design Matrix (N x M) } \Phi = \begin{bmatrix} \phi_0(x_1) & \phi_1(x_1) & \dots & \phi_{M-1}(x_1) \\ \phi_0(x_2) & \phi_1(x_2) & \dots & \phi_{M-1}(x_2) \\ \vdots & \vdots & \vdots & \vdots \\ \phi_0(x_N) & \phi_1(x_N) & \dots & \phi_{M-1}(x_N) \end{bmatrix}$$

Update eqn for the Newton-Raphson method, minimizing the cross-entropy error function E(w):

$$w^{(new)} = w^{(old)} - H^{-1}\nabla E(w)$$

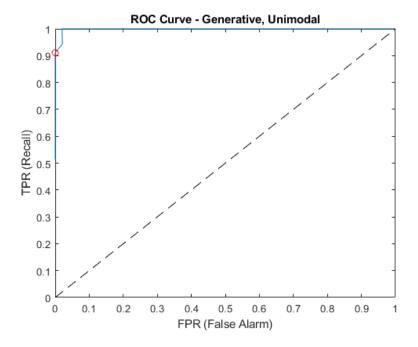
Gradient (of the error fcn) 
$$\nabla E(w) = \sum_{n=1}^{N} (y_n - t_n) \phi_n = \Phi^T(y - t)$$

Hessian Matrix (of the error fcn) 
$$H = \nabla \nabla E(w) = \sum_{n=1}^{N} (y_n (1-y_n)\phi_n \phi_n^T) = \Phi^T R \Phi$$

where 
$$R_{nn}$$
 (N x N matrix) =  $y_n(1 - y_n)$ 

Data type: Unimodal

```
% load data
load('mlData.mat');
x = unimodal.x;
v = unimodal.v;
% set seed for reproducibility
rng(42); % always the answer
% split train and test set by randomly sampling the train/test indices
% * ratio: 75% train - 25% test
train idx = randsample(400,300);
test idx = setdiff(1:400, train idx);
% set train and test subsets
train_x = x(train_idx, :);
train y = y(train idx);
test x = x(\text{test idx, :});
test_y = y(test_idx);
% MLE estimate
% set class labels for the training set
class1 = train y == 0;
class2 = train_y == 1;
% PI = prior probability of class 1 (labelled as '0')
% mu1, mu2 = mean vector of class 1, class 2, respectively
% S1, S2 = covariance matrix of class 1, class 2, respectively
% S = probability distribution given prior and covariance of each class
PI = mean(class1);
mu1 = mean(train_x(class1,:))';
mu2 = mean(train x(class2,:))';
S1 = cov(train_x(class1,:));
S2 = cov(train x(class2,:));
S = PI * S1 + (1-PI) * S2;
% p(xn, Ci): probability of data points from each class 1 and 2 (with mu1, mu2 as mean
% vectors, respectively), with Gaussian class conditional densities
\ \ \ p\left(x\mid \text{Ci}\right) and shared covariance matrix S
% -- take logarithmic, and pass through activation function (sigmoid)
pC1 = PI * mvnpdf(test x,mu1',S);
pC2 = (1-PI) * mvnpdf(test_x,mu2',S);
a = log(pC1./pC2);
pred1 = round(sigmoid(a));
pred2 = round(1-sigmoid(a));
unimodal1 = mean(pred2==test y)
% plot ROC
% red dot represents the test accuracy, blue is the ROC curve
roc_data = roc_curve(test_y, a);
idx = find(roc_data.accuracy==unimodal1, 1);
figure; plot(1-roc data.specificity, roc data.recall);
hold on; plot(1-roc_data.specificity(idx), roc_data.recall(idx),'ro');
ref = refline(1,0); ref.LineStyle = '--'; ref.Color = 'k';
xlim([0 1]); ylim([0 1]); ylabel('TPR (Recall)'); xlabel('FPR (False Alarm)');
title('ROC Curve - Generative, Unimodal');
% Tabular summary for Generative Model on unimodal data
datatype = {'Unimodal'};
method = {'Generative'};
accuracy = roc_data.accuracy(idx);
f1 = roc_data.F1(idx);
precision = roc_data.precision(idx);
recall = roc_data.precision(idx);
specificity = roc_data.specificity(idx);
sensitivity = roc_data.sensitivity(idx);
g mean = roc_data.g_mean(idx);
T1 = table(datatype, method, accuracy, recall, precision, f1, specificity, sensitivity, g_mean);
snapnow;
```

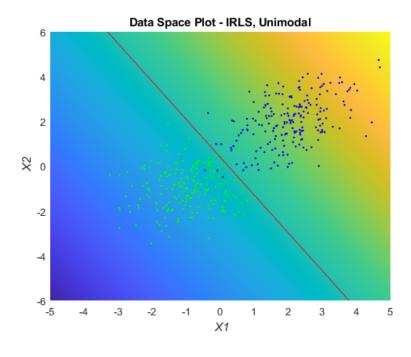


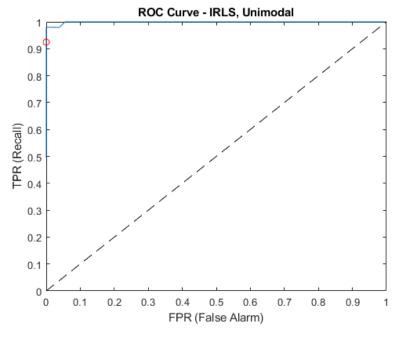
## 1b) IRLS method - Unimodal Data

Data type: Unimodal

```
% set seed for reproducibility
rng(42);
% add bias to adjust for shift in data points
% split train and test set
x = [ones(400,1), unimodal.x];
y = unimodal.y;
% set parameters for training
% batch size and learning rate set for better convergence of IRLS
epoch = 30;
sampling_rate = 100;
batch size = 8;
learning_rate = 0.01;
% set train and test subsets
train_x = x(train_idx,:);
train_y = y(train_idx);
test_x = x(test_idx,:);
test_y = y(test_idx);
% pass through IRLS algorithm with the defined parameters
w = irls(train_x, train_y, epoch, learning_rate, batch_size);
% identify 2D grid, with the updated w parameters from IRLS
[w0, w1] = meshgrid(linspace(-5,5,sampling_rate)',linspace(-6,6,sampling_rate));
grid1 = ones(sampling_rate);
grid2 = w0;
grid3 = w1;
grid = grid1 * w(1) + grid2 * w(2) + grid3 * w(3);
% variables for the decision boundary (linear)
x_{decision} = linspace(-5,5,1000);
y_{decision} = -(w(1) + w(2) * x_{decision})/w(3);
% plot the classified data points and decision boundary
figure;
pcolor(w0,w1,grid); shading interp; hold on;
plot(x(y==0, 2), x(y==0, 3), "g.", ...
     x(y==1, 2), x(y==1, 3), "b.", ...
     x_{decision}, y_{decision}, r-'); hold off;
title('Data Space Plot - IRLS, Unimodal');
ylim([-6,6]); xlabel('{\it X1}'); ylabel('{\it X2}');
% evaluate (prediction)
prediction = test_x * w;
unimodal2 = mean(prediction > 0 == test_y);
% plot ROC
\mbox{\$} red dot represents the test accuracy, blue is the ROC curve
roc_data = roc_curve(~test_y, prediction);
```

```
idx = find(roc data.accuracy==unimodal2, 1);
figure; plot(1-roc_data.specificity, roc_data.recall); hold on;
plot(1-roc_data.specificity(idx), roc_data.recall(idx),'ro');
xlim([0 1]); ylim([0 1]);
ref = refline(1,0); ref.LineStyle = '--'; ref.Color = 'k';
title('ROC Curve - IRLS, Unimodal'); ylabel('TPR (Recall)'); xlabel('FPR (False Alarm)');
hold off;
% Tabular summary for IRLS on unimodal data
datatype = {'Unimodal'};
method = {'IRLS'};
accuracy = roc_data.accuracy(idx);
f1 = roc_data.F1(idx);
precision = roc_data.precision(idx);
recall = roc_data.precision(idx);
specificity = roc_data.specificity(idx);
sensitivity = roc_data.sensitivity(idx);
g mean = roc data.g mean(idx);
{\tt T2 = table\,(datatype,\ method,\ accuracy,\ recall,\ precision,\ f1,\ specificity,\ sensitivity,\ g\_mean);}
```



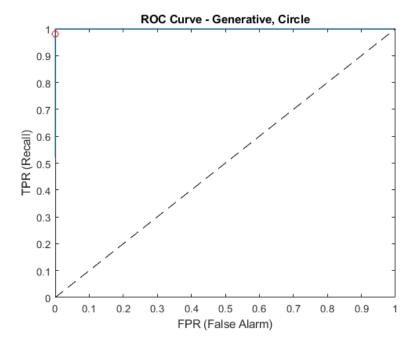


## 2a) Gaussian Generative Model - Circle Data

Data type: Circle

```
% load data
% Generative Models split train and test set, and add r2 as a feature
```

```
load('mlData.mat');
x = [circles.x, circles.x(:,1).^2 + circles.x(:,2).^2];
y = circles.y;
% set seed for reproducibility
rng(42);
% split train and test set by randomly sampling the train/test indices
% * ratio: 75% train - 25% test
train idx = randsample(400,300);
test_idx = setdiff(1:400, train_idx);
% set train and test subsets
train_x = x(train_idx,:);
train_y = y(train_idx);
test_x = x(test_idx,:);
test_y = y(test_idx);
% MLE estimate
\mbox{\$} set class labels for the training set
class1 = train_y == 0;
class2 = train_y == 1;
% PI = prior probability of class 1 (labelled as '0')
% \ \text{mu1, mu2} = \text{mean vector of class 1, class 2, respectively}
% S1, S2 = covariance matrix of class 1, class 2, respectively
% S = probability distribution given prior and covariance of each class
PI = mean(class1);
mu1 = mean(train_x(class1,:))';
mu2 = mean(train_x(class2,:))';
S1 = cov(train_x(class1,:));
S2 = cov(train x(class2,:));
S = PI * S1 + (1-PI) * S2;
% p(xn, Ci): probability of data points from each class 1 and 2 (with mu1, mu2 as mean
% vectors, respectively), with Gaussian class conditional densities
% p(x|Ci) and shared covariance matrix S
pC1 = PI * mvnpdf(test x,mu1',S);
pC2 = (1-PI) * mvnpdf(test_x,mu2',S);
a = log(pC1./pC2);
pred1 = round(sigmoid(a));
pred2 = round(1-sigmoid(a));
circle1 = mean(pred2==test_y)
% plot ROC
% red dot represents the test accuracy, blue is the ROC curve
roc_data = roc_curve(test_y, a);
idx = find(roc_data.accuracy==circle1, 1);
figure; plot(1-roc_data.specificity, roc_data.recall);
hold on; plot(1-roc_data.specificity(idx), roc_data.recall(idx),'ro');
xlim([0 1]); ylim([0 1]);
ref = refline(1,0); ref.LineStyle = '--'; ref.Color = 'k';
title('ROC Curve - Generative, Circle');
ylabel('TPR (Recall)'); xlabel('FPR (False Alarm)');
% Tabular summary for Generative Model on circle data
datatype = {'Circle'};
method = {'Generative'};
accuracy = roc_data.accuracy(idx);
f1 = roc_data.F1(idx);
precision = roc_data.precision(idx);
recall = roc_data.precision(idx);
specificity = roc_data.specificity(idx);
sensitivity = roc_data.sensitivity(idx);
g_mean = roc_data.g_mean(idx);
T3 = table(datatype, method, accuracy, recall, precision, f1, specificity, sensitivity, g_mean);
snapnow;
```



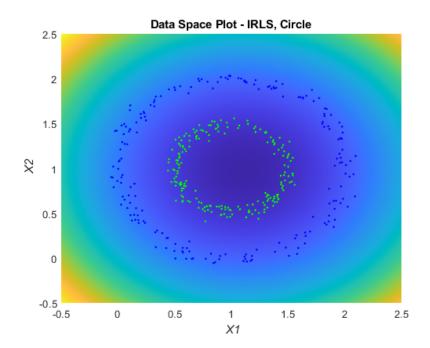
## 2b) IRLS method - Circle Data

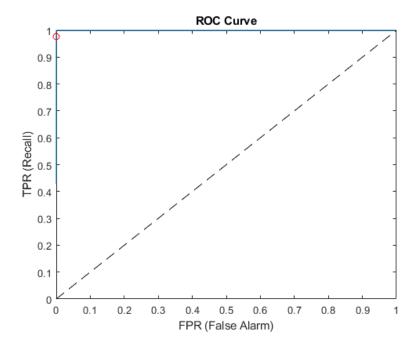
Data type: Circle

```
% load data
% adjustments: (1) add another feature (sum of square terms)
                   with shift to the right (1,1) to fit to the given data
                (2) add bias (1's) to adjust for data shift
x = [ones(400,1), circles.x, (circles.x(:,1)-1).^2 + (circles.x(:,2)-1).^2];
y = circles.y;
% parameters for training
% batch size and learning rate set for better convergence of IRLS
epoch = 200;
sampling_rate = 100;
batch_size = 8;
learning rate = 0.01;
\mbox{\ensuremath{\upsigma}} randomly sample training and test sets
% with ratio 75% train - 25% test (~ 80-20 rule)
train_idx = randsample(400,300);
test_idx = setdiff(1:400, train_idx);
\mbox{\%} set train and test subsets
train_x = x(train_idx,:);
train_y = y(train_idx);
test_x = x(test_idx,:);
test_y = y(test_idx,:);
\ensuremath{\mathtt{\$}} pass through IRLS algorithm with the defined parameters
w = irls(train_x, train_y, epoch, learning_rate, batch_size);
% define a 2D grid, with the updated w parameters from IRLS
[w0, w1] = meshgrid(linspace(-0.5, 2.5, sampling rate)', linspace(-0.5, 2.5, sampling rate));
grid1 = ones(sampling_rate);
grid2 = w0;
grid3 = w1;
grid4 = (w0-1).^2 + (w1-1).^2;
grid = grid1 * w(1) + grid2 * w(2) + grid3 * w(3) + grid4 * w(4);
% plot the classified data points and decision boundary
figure;
pcolor(w0,w1,grid); hold on; shading interp;
\verb"plot(circles.x(y==0,\ 1),\ circles.x(y==0,\ 2),\ "g.",\ \dots
     circles.x(y==1, 1), circles.x(y==1, 2), "b."); hold off;
title('Data Space Plot - IRLS, Circle');
\verb|xlabel('{\dot X1}'); | ylabel('{\dot X2}'); | hold off; |
% evaluate (prediction accuracy)
prediction = test_x * w;
circle2 = mean(prediction > 0 == test_y)
% plot ROC
% red dot represents the test accuracy, blue is the ROC curve
roc data = roc_curve(~test_y, prediction);
```

```
idx = find(roc_data.accuracy==circle2, 1);
figure; plot(1-roc_data.specificity, roc_data.recall);
hold on; plot(1-roc_data.specificity(idx), roc_data.recall(idx),'ro');
xlim([0 1]); ylim([0 1]);
ref = refline(1,0); ref.LineStyle = '--'; ref.Color = 'k';
title('ROC Curve'); ylabel('TPR (Recall)'); xlabel('FPR (False Alarm)');
\mbox{\ensuremath{\$}} Tabular summary for IRLS on circle data
datatype = {'Circle'};
method = {'IRLS'};
accuracy = roc_data.accuracy(idx);
f1 = roc_data.F1(idx);
precision = roc_data.precision(idx);
recall = roc_data.precision(idx);
specificity = roc_data.specificity(idx);
sensitivity = roc_data.sensitivity(idx);
g_mean = roc_data.g_mean(idx);
T4 = table(datatype, method, accuracy, recall, precision, f1, specificity, sensitivity, g_mean);
snapnow;
```

circle2 =





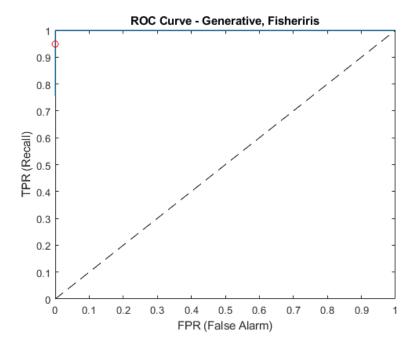
#### Application to 'iris' dataset

```
load("fisheriris.mat");
% set seed for reproducibility
rng(42);
```

#### 3a) Gaussian Generative Model - iris

4D feature space is reduced to 2D so that it closely follows previous unimodal and circle data, using principal component analysis

```
[~, score, ~] = pca(meas);
x = score(:, 1:2);
y = species == "setosa"; % only consider 'setosa' class
\mbox{\ensuremath{\$}} randomly sample training and test sets
% with ratio 2/3 train - 1/3 test
train_idx = randsample(150,100);
test_idx = setdiff(1:150, train_idx);
% set train and test subsets
train_x = x(train_idx,:);
train y = y(train idx);
test_x = x(test_idx,:);
test_y = y(test_idx);
% MLE estimate
% set class labels for the training set
class1 = train y == 0;
class2 = train_y == 1;
% PI = prior probability of class 1 (labelled as '0')
\mbox{\%} mu1, mu2 = mean vector of class 1, class 2, respectively
% S1, S2 = covariance matrix of class 1, class 2, respectively
% S = probability distribution given prior and covariance of each class
PI = mean(class1);
mu1 = mean(train_x(class1,:))';
mu2 = mean(train x(class2,:))';
S1 = cov(train_x(class1,:));
S2 = cov(train x(class2,:));
S = PI * S1 + (1-PI) * S2;
% p(xn, Ci): probability of data points from each class 1 and 2 (with mu1, mu2 as mean
% vectors, respectively), with Gaussian class conditional densities
\mbox{\ensuremath{\$}} p(x|Ci) and shared covariance matrix \mbox{\ensuremath{\mathtt{S}}}
% -- take logarithmic, and pass through activation function (sigmoid)
pC1 = PI * mvnpdf(test_x,mu1',S);
pC2 = (1-PI) * mvnpdf(test_x,mu2',S);
a = log(pC1./pC2);
pred1 = round(sigmoid(a));
pred2 = round(1-sigmoid(a));
iris1 = mean(pred2==test y)
% plot ROC
% red dot represents the test accuracy, blue is the ROC curve
roc_data = roc_curve(test_y, a);
idx = find(roc_data.accuracy==iris1, 1);
figure; plot(1-roc data.specificity, roc data.recall);
hold on; plot(1-roc_data.specificity(idx), roc_data.recall(idx),'ro');
xlim([0 1]); ylim([0 1]);
ref = refline(1,0); ref.LineStyle = '--'; ref.Color = 'k';
title('ROC Curve - Generative, Fisheriris');
ylabel('TPR (Recall)'); xlabel('FPR (False Alarm)');
% Tabular summary for Generative Model on iris data
datatype = {'Fisheriris'};
method = {'Generative'};
accuracy = roc_data.accuracy(idx);
f1 = roc data.F1(idx);
precision = roc data.precision(idx);
recall = roc_data.precision(idx);
specificity = roc_data.specificity(idx);
sensitivity = roc_data.sensitivity(idx);
g_mean = roc_data.g_mean(idx);
T5 = table(datatype, method, accuracy, recall, precision, f1, specificity, sensitivity, g_mean);
snapnow;
```



#### 3b) IRLS method - iris

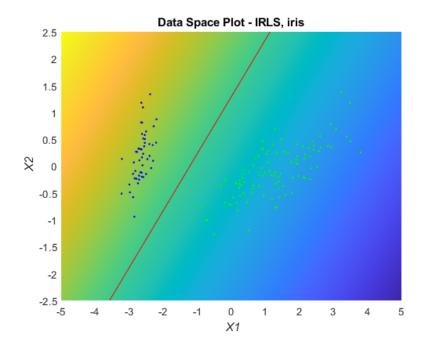
4D feature space is reduced to 2D so that it closely follows previous unimodal and circle data, using principal component analysis

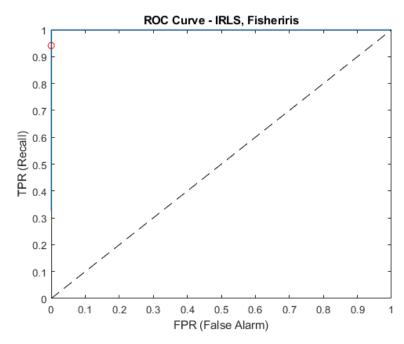
```
[~, score, ~] = pca(meas);
x = [ones(150,1), score(:,1:2)];
y = species=="setosa"; % only consider 'setosa' class
train_idx = randsample(150,100);
test_idx = setdiff(1:150, train_idx);
% set train and test subsets
train_x = x(train_idx,:);
train y = y(train idx);
test_x = x(test_idx,:);
test_y = y(test_idx);
% parameter for plotting
% batch size and learning rate set for better convergence of IRLS
epoch = 100;
sampling_rate = 100;
batch_size = 8;
learning rate = 0.05;
\ensuremath{\$} pass through IRLS algorithm with the defined parameters
w = irls(train_x, train_y, epoch, learning_rate, batch_size);
% variables for the decision boundary (linear)
x decision = linspace(-5, 5, 1000);
y_{decision} = -(w(1) + w(2) * x_{decision})/w(3);
% identify 2D grid, with the updated w parameters from IRLS
[w0, w1] = meshgrid(linspace(-5,5,sampling_rate)',linspace(-2.5,2.5,sampling_rate));
grid1 = ones(sampling_rate);
grid2 = w0;
grid3 = w1;
grid = grid1 * w(1) + grid2 * w(2) + grid3 * w(3);
\mbox{\$} plot the classified data points and decision boundary
figure; pcolor(w0,w1,grid); hold on; shading interp;
\verb"plot(x(y==0,2)", x(y==0,3)", "g.", x(y==1,2)", x(y==1,3)", "b.", x_decision, y_decision, 'r');
hold off; title('Data Space Plot - IRLS, iris');
ylim([-2.5,2.5]); xlabel('{\it X1}'); ylabel('{\it X2}'); hold off;
% evaluate (prediction)
prediction = test_x * w;
iris2 = mean(prediction > 0 == test_y)
% plot ROC
% red dot represents the test accuracy, blue is the ROC curve
roc_data = roc_curve(~test_y, prediction);
```

```
idx = find(roc_data.accuracy==iris2, 1);
figure; plot(1-roc_data.specificity, roc_data.recall);
hold on; plot(1-roc_data.specificity(idx), roc_data.recall(idx),'ro');
xlim([0 1]); ylim([0 1]);
ref = refline(1,0); ref.LineStyle = '--'; ref.Color = 'k';
title('ROC Curve - IRLS, Fisheriris'); ylabel('TPR (Recall)'); xlabel('FPR (False Alarm)');
% Tabular summary for IRLS on iris data
datatype = {'Fisheriris'};
method = {'IRLS'};
accuracy = roc_data.accuracy(idx);
f1 = roc_data.F1(idx);
precision = roc_data.precision(idx);
recall = roc_data.precision(idx);
specificity = roc_data.specificity(idx);
sensitivity = roc_data.sensitivity(idx);
g_mean = roc_data.g_mean(idx);
T6 = table(datatype, method, accuracy, recall, precision, f1, specificity, sensitivity, g_mean);
```

iris2 =

1





### **Results (Evaluation Statistics)**

```
Results = [T1;T2;T3;T4;T5;T6]
hold off; warning('on','all');
snapnow;
```

```
Results = 6 \times 9 table
```

datatype	method	accuracy	recall	precision	f1	specificity	sensitivity	g_mean
{'Unimodal' }	{'Generative'}	0.96	0.98039	0.98039	0.94427	1	0.9434	0.95431
{'Unimodal' }	{'IRLS'}	0.97	1	1	0.96078	1	0.94231	0.96152
{'Circle' }	{'Generative'}	1	1	1	0.99029	1	1	0.99034
{'Circle' }	{'IRLS'}	1	1	1	0.98824	1	1	0.9883
{'Fisheriris'}	{'Generative'}	1	1	1	0.97368	1	1	0.97402
{'Fisheriris'}	{'IRLS'}	1	1	1	0.9697	1	1	0.97014

### **Utility Functions**

```
% see Equation 2 for IRLS
function [w] = irls(iota, y, epoch, lr, batch size)
    sz = size(iota);
    w = rand([sz(2),1]) * 10 - 5; % -5 to 5
    for i = 2:epoch
        batch = randsample(sz(1),batch size);
        iota i = iota(batch,:);
        t_i = y(batch);
        y_i = sigmoid(iota_i * w);
        R_i = diag(y_i .* (1-y_i));
        gradient = iota_i' * (y_i - t_i);
        hessian = iota_i' * R_i * iota_i;
        w = w - lr * pinv(hessian) * gradient;
end
% activation function: sigmoid
function [out] = sigmoid(x)
   out = 1./(1+\exp(-x));
% evaluation metric calculations
function ROC_data = roc_curve(target, prediction)
    thresholds = linspace(min(prediction), max(prediction), 100);
    % start point at (0,0)
    start.recall = 0; start.specificity = 1;
    recall = [start.recall, zeros(size(thresholds))];
    specificity = [start.specificity, zeros(size(thresholds))];
    sensitivity = zeros(size(thresholds));
    precision = zeros(size(thresholds));
    F1 = zeros(size(thresholds));
    g_mean = zeros(size(thresholds));
    accuracy = zeros(size(thresholds));
    for idx = 1:length(thresholds)
        thresh = prediction >= thresholds(idx);
        pos idx = find(thresh==1);
        neg_idx = find(thresh==0);
        TP = length(intersect(find(target == 0), pos_idx));
        FP = length(intersect(find(target == 0), neg_idx));
        TN = length(intersect(find(target == 1), neg_idx));
        FN = length(intersect(find(target == 1), pos idx));
        recall(idx+1) = TP / (TP+FN);
        specificity(idx+1) = TN / (FP+TN);
        sensitivity(idx) = TP / (TP+FN);
        precision(idx) = TP / (TP+FP);
accuracy(idx) = (TP+TN) / (TP+TN+FP+FN);
        F1(idx) = 2 / (recall(idx)^-1 + precision(idx)^-1);
        g_mean(idx) = sqrt(specificity(idx) * recall(idx));
```

```
end
% mark end point at (1,1)
recall(end+1) = 1; specificity(end+1) = 0;
ROC_data.recall = recall;
ROC_data.specificity = specificity;
ROC_data.sensitivity = sensitivity;
ROC_data.precision = precision;
ROC_data.accuracy = accuracy;
ROC_data.F1 = F1;
ROC_data.g_mean = g_mean;
end
```

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